3 - Matrices, Optimal Portfolios

Espen Sirnes

2024-09-18

Table of contents

1	Matrices						
2	Algebra with Matrices						
	2.1	Matrix Multiplication	3				
	2.2	Adding and Subtracting Matrices	4				
	2.3	Dividing with a Matrix	5				
	2.4	Solving Equations with Matrix Algebra	5				
	2.5	Transposing	7				
3	Calculus and matrices						
4	Opt	Optimal portfolios with more than one asset					
	4.1	Optimal Portfolios with Any Number of Assets	9				
5	Em	pirical example - optimal porfolio and the portfolio front	11				
	5.1	The historic mean and covariance matrix	13				
	5.2	Plotting the portfolio front	15				
	5.3	Adding the optimal portfolio to the chart	17				
	5.4	Adding the tangency line	19				
	5.5	Adding the stocks spanning the portfolio front	20				

This lecture explores the strategic behavior of an investor in the stock market, particularly under the assumption of risk aversion, as discussed in the previous note on utility theory. Risk lovers generally prefer the most risky assets, while risk-neutral investors opt for assets with the highest returns. In contrast, a risk-

averse investor seeks to maximize returns without disproportionately increasing volatility, typically measured as variance.

1 Matrices

To calculate optimal portfolios for any number of assets, a basic understanding of matrix algebra is essential. Matrix algebra simplifies the resolution of several equations simultaneously, a process that becomes increasingly complex with the addition of variables. Using matrix functions in software like Excel and various statistical packages allows us to solve systems of equations efficiently without manually computing each one.

Matrices not only streamline the computation but also simplify notation, making the formulation of equations for optimal portfolios more manageable.

A matrix is a structured array of numbers arranged in rows and columns, essentially a set of vectors. Here's an example of a vector:

```
import numpy as np
np.random.randint(0,100,3)
array([77, 63, 92])
```

Combining several vectors side-by-side forms a matrix:

This format is sometimes denoted as $\mathbf{X}_{N\times K}$ to indicate the number of rows (N) and columns (K).

2 Algebra with Matrices

Matrix algebra operates under similar principles to ordinary algebra—allowing addition, subtraction, multiplication, and division (through inversion)—but it also requires adherence to specific rules.

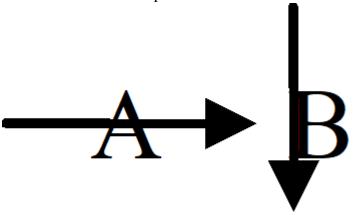
2.1 Matrix Multiplication

The core operation in matrix algebra is matrix multiplication, which combines elements from the rows of the first matrix with the columns of the second. For example, multiplying a 2×3 matrix by a 3×2 matrix yields:

```
X = np.random.randint(0,5,(2,3))
Y = np.random.randint(0,5,(3,2))
result = X @ Y
print(X)
print(Y)
print(result)
```

```
[[4 2 2]
[2 3 4]]
[[3 1]
[2 2]
[3 0]]
[[22 8]
[24 8]]
```

What happens is that we sum the product of the elements in each row of the first matrix and each column of the second. You can for example check that element [0,0] of the result is the sum of the product of the first row of the first matrix, and the first column of the second. An easy way to remember this is to think of the multiplication of $A \times B$ is to follow the lines of the letters:



Due to the rules for matrix multiplication, it requires the number of columns in the first matrix to match the number of rows in the second.

The matrix multiplication is different from the normal multiplication in Python. Normal multiplication can be done with the normal multiplication operator \star . It will then multiply each element in X with the corresponding element of Y, and both matrices must be of the same size:

```
X = np.random.randint(0,5,(2,3))
Y = np.random.randint(0,5,(2,3))
result = X*Y
print(X)
print(Y)
print(result)

[[3 1 2]
  [1 0 3]]
[[1 3 3]
  [4 1 0]]
[[3 3 6]
  [4 0 0]]
```

The reason for using the former method, is that the former is required for solving sets of equations.

2.2 Adding and Subtracting Matrices

Adding or subtracting matrices is straightforward; simply add or subtract corresponding elements. In Python, the multiplication requires numpy function, but if the matrices are numpy variables, subtraction and addition can be done with the normal operators.

```
import numpy as np

X = np.random.randint(0,100,(2,2))
Y = np.random.randint(0,100,(2,2))

# Addition of matrices
result_add = X + Y
print(X)
print(Y)
print(result_add)
```

[[41 35]

```
[32 80]]
[[86 29]
[89 50]]
[[127 64]
[121 130]]
```

2.3 Dividing with a Matrix

While direct division isn't defined in matrix operations, we can achieve a similar result by multiplying by the inverse of a matrix. The inverse of a matrix X, denoted X^{-1} , satisfies:

$$\mathbf{X} \times \mathbf{X}^{-1} = \mathbf{I} = \begin{pmatrix} 1 & 0 & \cdots & 0 \\ 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 1 \end{pmatrix}$$

where I is the identity matrix. Multiplying any matrix by I results in the original matrix, akin to multiplying any number by 1.

In practice, while the concept is straightforward, the actual calculation of a matrix inverse can become complex for larger matrices and is typically handled by computers. We will not go through the method of obtaining the inverse in this course, we will in stead just utilize the numpy function for calculating the inverse. Specifically, we use np.linalg.inv(X). We can check that it actually complies with the definition like this:

```
X = np.random.randint(0,10,(3,3))
# Calculating inverse of X
X_inv = np.linalg.inv(X)
# Testing
np.round(X_inv @ X,1)
```

2.4 Solving Equations with Matrix Algebra

The foundation we've established for matrix algebra now allows us to efficiently solve systems of equations. Consider solving the following pair of simultaneous equations:

$$x_{11}a_1 + x_{12}a_2 = b_1x_{21}a_1 + x_{22}a_2 = b_2$$

Here, we know the values of x and b but need to find the values of a. These equations can be succinctly expressed using matrix notation:

$$\mathbf{X} \times \mathbf{a} = \mathbf{b} \tag{1}$$

where a and b are column vectors. Let us define the right hand side vector b and the coeficient matrix X randomly in python as

```
b = np.random.randint(0,100,(2,1))
# Define matrix X
X = np.random.randint(0,100,(2,2))
print(X)
print(b)

[[66 63]
  [21 18]]
[[58]
  [91]]
```

To solve for a, we use the inverse of X, provided it exists, and multiplies it with the left and right hand sides of the equation, just as we would divide with X on both sides to solve for a single equation:

$$\mathbf{X}^{-1} \times \mathbf{X} \times \mathbf{a} = \mathbf{X}^{-1}\mathbf{b}$$

Since we know that \mathbf{X}^{-1} is the solution to $\mathbf{X}^{-1} \times \mathbf{X} = \mathbf{I}$, premultiplying with \mathbf{X}^{-1} yields:

$$\mathbf{a} = \mathbf{X}^{-1}\mathbf{b}$$

Hence, we have found an easy way to solve any linear equation. We can test that it works in python. Let us first find a using this approach:

```
a = np.linalg.inv(X) @ b
a
```

```
array([[ 34.73333333], [-35.46666667]])
```

If you get a "Singular matrix" error its because we are generating X with a few random integers, which sometimes creates unsolvable systems, so just generate X and b again.

Now we can test, if the solution for a actually works, by applying it on the original equation $X \times a = b$. This should yield the right hand side of th equation, b:

Compare this with the actual b:

b

```
array([[58], [91]])
```

Thus, we have identified an effective method to solve any system of equations, provided that \mathbf{X} is invertible. If \mathbf{X} cannot be inverted, it indicates that two or more equations are essentially identical, leading to an "underdetermined" system. In such cases, some equations are redundant, and there are not enough independent equations to determine the values of all variables. Remember the fundamental rule: we need an equal number of equations and unknowns to uniquely solve for each variable.

2.5 Transposing

Transposing a matrix involves swapping its rows and columns. For example, a 2×3 matrix:

$$\mathbf{X}_{2\times3} = \begin{pmatrix} x_{11} & x_{12} & x_{13} \\ x_{21} & x_{22} & x_{23} \end{pmatrix}$$

transposes to:

$$\mathbf{X}_{2\times3}' = \begin{pmatrix} x_{11} & x_{21} \\ x_{12} & x_{22} \\ x_{13} & x_{23} \end{pmatrix}$$

where ' denotes the transposed matrix. For a column vector a, transposing and then multiplying by itself, a'a, calculates the sum of squares of its components.

```
# Example of matrix transposition
X_2x3 = np.random.randint(0,100,(2,3))
X_transposed = X_2x3.T
X_transposed
```

```
array([[24, 79],
[98, 37],
[98, 75]])
```

Transposition is often used to conform to the requirements of matrix multiplication, where the number of columns in the first matrix must match the number of rows in the second. If this is not the case, one might transpose the first matrix to facilitate multiplication.

3 Calculus and matrices

Deriving matrices follows similar principles to deriving polynomials. For instance:

$$\frac{d\left(a^{2}\sigma^{2}\right)}{da} = 2a\sigma^{2}$$

applies to scalar variables, and for a matrix Σ and a column vector \mathbf{a} , we have:

$$\frac{d\left(\mathbf{a}'\Sigma\mathbf{a}\right)}{d\mathbf{a}'} = 2\Sigma\mathbf{a}$$

assuming Σ is symmetric. In practical terms, the derivative with respect to a here, given some values for a, is

```
# Derivation with matrix and vector
a = np.random.randint(0,100,(2,1))
Sigma = np.random.randint(0,100,(2,2))

# Derivative of a' Sigma a with respect to a
derivative = 2 * Sigma @ a
derivative
```

We can rewrite the matrix formulation in scalar form, to check that the rule is correct. The scalar form of $a'\Sigma a$ is

$$\mathbf{a}' \Sigma \mathbf{a} = \sum_{j=0}^{N} a_j \left(\sum_{i=0}^{N} a_i \sigma_{ij} \right)$$

You can verify that

$$\frac{d(\mathbf{a}'\Sigma\mathbf{a})}{d\mathbf{a}} = 2\left[\sum_{i=0}^{N} a_i \sigma_{i0}, ..., \sum_{i=0}^{N} a_i \sigma_{iN}\right]$$

4 Optimal portfolios with more than one asset

We remember from above the previous chapter that with one asset, the optimal portfolio was

$$a_{opt} = \frac{(\mu - r)}{\lambda \sigma^2}$$

From this we concluded that:

- 1. The more risk-averse the person is, the less they should invest.
- 2. The larger the expected return of the asset, the more should be invested.
- 3. The greater the risk associated with the asset, represented by σ^2 , the less should be invested.

Now, let us consider the optimal investments if we have more than one asset.

4.1 Optimal Portfolios with Any Number of Assets

Let us now assume that the investor in the previous section has a portfolio of N assets, not just one. Their wealth next period, assuming the entire amount is borrowed, is then expressed in matrix notation as:

$$W_1 = \mathbf{a}'\mathbf{x} - \mathbf{1}r$$

where a represents the portfolio weights, x represents the returns, and 1 is a column vector of ones, such that 1r is a column vector of the risk-free interest rate r. Recall from earlier that the investor aims to maximize the difference between expected return and variance:

$$\max_{\mathbf{a}} Z = \mathbb{E}W_1 - \lambda \frac{1}{2} \operatorname{var}(W_1)$$

x now is a column vector of many normally distributed variables with different variances and expectations. We denote the expected returns by μ_i for asset i, and the associated vector of these returns by μ . Given a portfolio a, the expected return on the portfolio then becomes:

$$\mathbb{E}W_1 = \mathbf{a}'(\mathbb{E}\mathbf{x} - \mathbf{1}r) = \mathbf{a}'(\mu - \mathbf{1}r)$$

For the variance, the risk free return r is not relevant, since means are subtracted anyway. We define the covariance matrix, all the combinations of variance and covariance between the stocks as

$$\operatorname{var} W_{1} = \mathbf{a}' \Sigma \mathbf{a} = \mathbf{a}' \begin{bmatrix} \sigma_{0} 0 & \sigma_{1} 2 & \cdots & \sigma_{1} N \\ \sigma_{1} 2 & \sigma_{2} 2 & \cdots & \vdots \\ \vdots & \vdots & \ddots & \vdots \\ \sigma_{1} N & \cdots & \cdots & \sigma_{NN} \end{bmatrix} \mathbf{a}$$

Where σ_{ij} is the covariance between i and j, and σ_i^2 is the variance of asset i. This is the covariance matrix, denoted by the capital sigma, Σ .

When a vector is normally distributed we write it as $\mathbf{x} \sim N(\mu, \Sigma)$.

We have now derived expressions for $\mathbb{E}(W_1)$ and $\text{var}(W_1)$ using matrix notation. Building on the concepts from the previous lecture, we can now formulate our portfolio optimization problem as:

$$\max_{\mathbf{a}} Z = \mathbf{a}'(\mu - \mathbf{1}r) - \lambda \frac{1}{2} \mathbf{a}' \Sigma \mathbf{a}$$

Taking the derivative with respect to a' yields the N first order conditions:

$$\frac{dZ}{d\mathbf{a}} = (\mu - \mathbf{1}r) - \lambda \Sigma a = 0$$

Hence, in optimum:

$$\Sigma \mathbf{a} = \frac{1}{\lambda} (\mu - \mathbf{1}r)$$

By premultiplying with the inverse of Σ , we obtain the optimal portfolio:

$$\mathbf{a_{opt}} = \frac{1}{\lambda} \Sigma^{-1} (\mu - \mathbf{1}r)$$

Note that this formula looks very similar to the formula for an optimal portfolio with only one asset:

$$a_{opt} = \frac{\mu - r}{\lambda \sigma^2}$$

In general, we may draw the same conclusions as in the case of one asset:

- 1. The more risk-averse the person is (large λ), the less they should invest.
- 2. The larger the expected return the asset has, the more should be invested.
- 3. The more risk is associated with the asset, the less should be invested.

5 Empirical example - optimal porfolio and the portfolio front

We will create an optimal portfolio and draw the "portfolio front" - which are the smallest possible volatility of a set of assets, for all return leves. We use the script feature of Titlon to fetch the data, and storing it in 'output/stocks.df'

We now reload the data, and pick the four stocks

1. has been traded at the first and last day of the sample 2. that are most traded (sorted on sum of Turnover)

We can obtain that with this code:

```
import numpy as np
import pandas as pd

df = pd.read_pickle('output/stocks.df')
# Defining annual risk free rate.
rf = df['NOWA_DayLnrate'].mean()*7

isin_with_first_date = df[df['Date'] == df['Date'].min()]['ISIN'].unique
isin_with_last_date = df[df['Date'] == df['Date'].max()]['ISIN'].unique
valid_isins = set(isin_with_first_date).intersection(isin_with_last_date)
df = df[df['ISIN'].isin(valid_isins)]

df['Name (ISIN)'] = df['Name'].str.upper().str.strip() + '(' + df['ISIN'])
# keeping only the most traded shares
```

	Turnover
Name (ISIN)	
EQUINOR(NO0010096985)	1.523274e+12
NORSK HYDRO(NO0005052605)	5.525255e+11
TELENOR(NO0010063308)	4.934189e+11
YARA INTERNATIONAL(NO0010208051)	4.753943e+11

5.1 The historic mean and covariance matrix

We will now calculate the covariance matrix and the mean vector. To begin, we'll create a function that reformats the data from its long format (where stock prices are listed sequentially in a single column) to a wide format. In this wide format, unique dates will be in the first column, with subsequent columns containing prices for each stock.

```
# Annualized weekly returns
df_weekly = pivot_df.resample('W').sum()

return df_weekly

#X is a matrxi with e

X_df = get_matrix(df, 'lnDeltaP')

X_df = X_df.sort_index()

X_df
```

Symbol Date	EQNR	NHY	TEL	YAR
2016-01-10	-0.118288	-0.137636	-0.008125	-0.058065
2016-01-17	-0.060966	-0.054818	-0.085838	-0.047905
2016-01-24	0.060966	0.023505	0.049143	0.001741
2016-01-31	0.074498	0.024710	-0.007077	-0.053584
2016-02-07	0.027490	0.065780	-0.029552	0.024170
2024-03-10	0.026170	0.016989	-0.026157	-0.040846
2024-03-17	0.023882	0.038669	0.019681	0.016898
2024-03-24	0.032784	0.048790	0.022694	0.026865
2024-03-31	-0.003143	-0.023257	0.026117	-0.004525
2024-04-07	0.046639	0.126744	0.025854	0.044496

Wit this data, it is relatively easy to calculate covariance and the means vector

```
# Converting X to a numpy array:
X = np.array(X_df)

# Calculating the covariance
cov_matrix = np.cov(X, rowvar=False)

# Calculating the means vector, and reshaping it to a
# column vector.

means = np.mean(X, axis=0).reshape((X.shape[1],1))
```

5.2 Plotting the portfolio front

We now turn to portfolio front. The portfolio front represents the volatility of the portfolio with the least variance, for a given portfolio return. Hence, we want a function of portfolio return that represent the minimum variance portfolios.

It turns out that by defining a few simple scalars, there is a reasonably simple expression for the set of minimum variance portfolios. The scalars are:

$$A = \mathbf{1}' \Sigma^{-1} \mathbf{1}$$

$$B = \mathbf{1}' \Sigma^{-1} \mu - \mathbf{1} r$$

$$C = \mu - \mathbf{1} r' \Sigma^{-1} \mu - \mathbf{1} r$$
(2)

With these definition, the portfolio front, representing all minimum variance portfolios for a given expected return and a total investment of 1, is

$$\sigma_{opt} = \frac{1}{A} + \frac{\left(\mu_{opt} - \frac{B}{A}\right)^2}{C - \frac{B^2}{A}}$$

where $\mu_{opt} = \mu' \mathbf{a}$

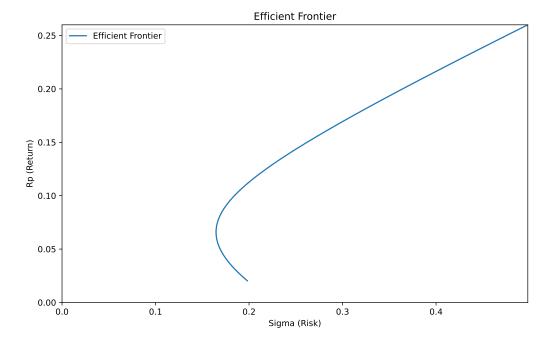
This formula automatically ensures that the sum of all the portfolio weights are 1. Now, let us define these variables, and the function. A, B and C in python:

The portfolio front function, that returns the volatility associated with the minimum variance portfolio for a given expected_excess_return can then be defined as:

Let us plot this

With a defined portfolio frontier function, we can now plot the portfolio frontier. To make the weekly returns comparable on an annual scale, we multiply them by a scaling factor, plot_scale, set to 52. We can simply multiply the returns, because returns in Titlon are conveniently defined as log returns, calculated as $\log(x_t) - \log(x_{t-1})$, rather than the typical relative return $\frac{x_t - x_{t-1}}{x_{t-1}}$.

```
from matplotlib import pyplot as plt
#Creating plot
fig, ax = plt.subplots(figsize=(10, 6))
plot_scale = 52
MAX\_AXIS = 0.005
#applying the function
rp_values = np.linspace(0, MAX_AXIS-rf, 100)
sigma_values = portfolio_front(rp_values, A, B, C)
#plotting, after annualizing the weekly data
ax.plot(plot_scale**0.5*(sigma_values), plot_scale*(rp_values+rf),
                        label='Efficient Frontier')
#plot settings:
ax.set_xlim([0, np.max(sigma_values*plot_scale**0.5)])
ax.set_ylim([0, (np.max(rp_values)+rf)*plot_scale])
ax.set_xlabel('Sigma (Risk)')
ax.set_ylabel('Rp (Return)')
ax.set_title('Efficient Frontier')
ax.legend()
```



A key advantage of using log returns is that they account for symmetry in gains and losses. For example, with relative returns, a 10% gain followed by a 10% loss results in a net loss of 1%. However, with log returns, a 10% gain and a 10% loss precisely offset each other, leaving you with no net change from the starting point.

5.3 Adding the optimal portfolio to the chart

Let us now add the point for the optimal portfolio. The optimal portfolio is

$$\mathbf{a}_{opt} = \frac{1}{\lambda} \Sigma^{-1} (\mu - \mathbf{1}r)$$

The total cost (sum) of this portfolio is

$$\mathbf{1}'\mathbf{a}_{opt} = \frac{1}{\lambda}\mathbf{1}'\Sigma^{-1}(\mu - \mathbf{1}r) = B$$
(3)

Where the last equality follows from Equation 2. The normalized optimal portfolio is then

$$\mathbf{a}_{norm} = \frac{\Sigma^{-1}(\mu - \mathbf{1}r)}{\mathbf{1}'\Sigma^{-1}(\mu - \mathbf{1}r)} = \frac{1}{B}\Sigma^{-1}(\mu - \mathbf{1}r)$$
(4)

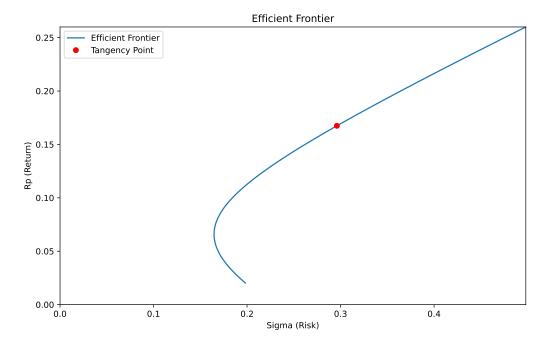
The expected return of the optimal portfolio on the frontier, is then

$$\mu_{port} = (\mu - \mathbf{1}r)' \mathbf{a_{norm}} = \frac{(\mu - \mathbf{1}r)' \Sigma^{-1} (\mu - \mathbf{1}r)}{\mathbf{1}' \Sigma^{-1} (\mu - \mathbf{1}r)}$$

Which is simply, according to the previous definitions of B and C:

$$\mu_{port} = \frac{C}{B}$$

Let us add that to the plot

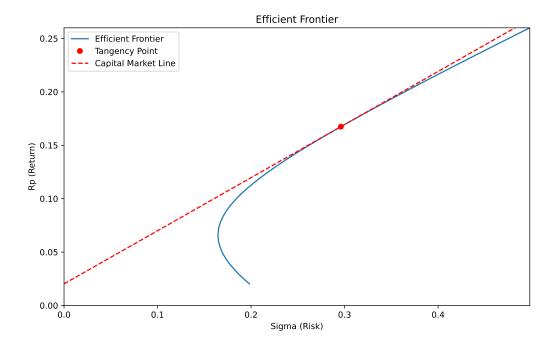


5.4 Adding the tangency line

Let us now draw a tangency line from the risk free interest rate rf to the optimal portfolio point. The slope will be the Sharp-ratio

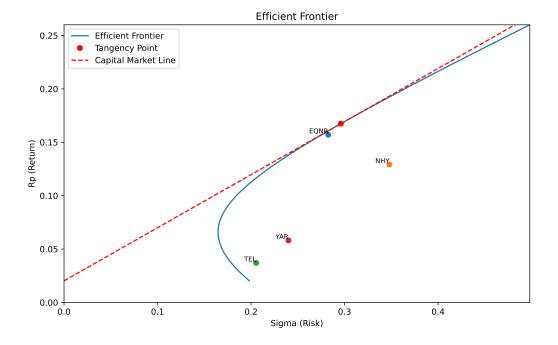
$$S = \frac{C/B}{f(C/B)}$$

where f(C/B) is the portfolio front function portfolio_front (C/B, A, B, C) at C/B



5.5 Adding the stocks spanning the portfolio front

It is interesting to check where the original stocks that span the front, are in the picture. Let us add the cooridnates of these. We first calculate their mean and standard devaition, and then plot them.



5.6 The optimal portfolio

Finally, we might want to evaluate the actual amounts that we should invest in each company, if we wanted to invest in the optimal portfolio. The actual portfolio, normalized to sum to one, is as previously implied

$$\mathbf{a}_{norm} = \frac{1}{B} \Sigma^{-1} (\mu - \mathbf{1}r)$$

where B is the sum of the optimal portfolio, as previously defined in 2

We can code that as

```
#Calculating the normalized optimal portfolio
opt_port = np.linalg.inv(cov_matrix) @ (means-rf)/B

#Calculating the returns of the optimal portfolio:
X_df['Optimal'] = X @ opt_port

#Saving the dataframe for later use:
pd.to_pickle(X_df, 'output/X.df')
```

```
# inserting the portfolio into a data frame for display
d = {}
for i in range(len(opt_port)):
    d[X_df.columns[i]] = [f"{np.round(opt_port[i][0]*100,0)}%"]
print("Hence the optimal portfolio in this case is")
pd.DataFrame(d)
```

Hence the optimal portfolio in this case is

	EQNR	NHY	TEL	YAR
0	93.0%	22.0%	-7.0%	-8.0%

Coding Challenges:

- Challenge 1: Obtain a three or four return series for portfolios, for example your portfolio, the market portfolio and the factors at titlon and calculate the variance-covariance matrix and the means
- **Challenge 2**: Use your calculated covariance matrix and means, and the code provided above, to draw a portfolio front.
- Challenge 3: Use the same information to plot the points of each portfolio in the same chart.
- Challenge 4: Calculate the optimal portfolio and place it in the chart, together with the capital market line