Brain Tumor Segmentation

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Project Relevance

Brain tumor segmentation is a crucial task in medical imaging that assists in the diagnosis and treatment of patients. Accurate segmentation helps radiologists and clinicians understand tumor regions, identify malignancies, and monitor treatment progress. The project aims to implement deep learnoing models (3D FCNNs, Unet, Residual Unet) to segment various regions of brain tumors from multimodal MRI scans.

Dataset Description

This project utilizes the BraTS dataset, which contains pre-processed multi-modal MRI scans for brain tumor segmentation. The dataset includes the following modalities:

- T1-weighted (t1n)
- T1-weighted post-contrast (t1c)
- T2-weighted (t2w)
- Fluid-attenuated inversion recovery (t2f)

Types of Scans and Tumor Regions

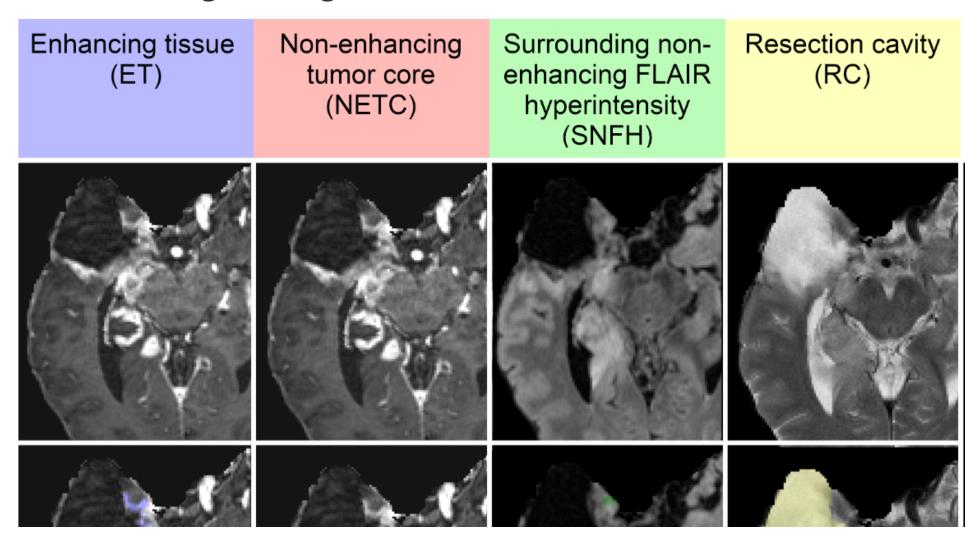
The dataset includes annotations for various tumor regions:

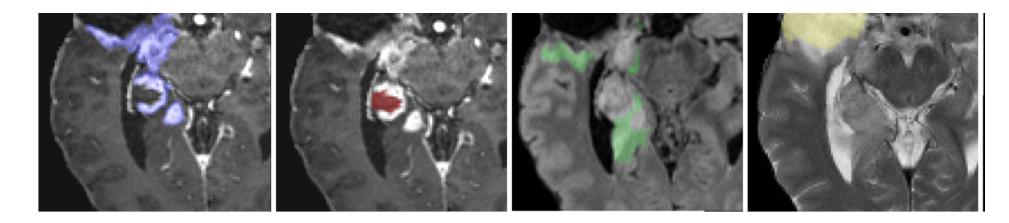
- Whole Tumor (WT): All visible tumor regions.
- Necrotic and Non-enhancing Tumor Core (NETC): Central dead tissue and non-enhancing regions.
- Enhancing Tumor (ET): Actively growing tumor cells.
- Surrounding Non-tumor Fluid Heterogeneity (SNFH): Swelling or fluid accumulation around the tumor.

- Resection Cavity: Post-surgical void in the brain.
 Select Tumor Region:
 Whole Tumor (WT)
- Necrotic and Non-enhancing Tumor Core (NETC)
- Enhancing Tumor (ET)
- Surrounding Non-tumor Fluid Heterogeneity (SNFH)
- Resection Cavity

Description of Selected Region: Central dead tissue and non-enhancing regions.

Tumor Sub-region Image





Tumor Sub-region Image

Image Viewer

Select a view category

Axial



Shape of the Raw image: (182, 218, 182)

Image Resgistration

```
for mod in self.modalities:
    mod_path = os.path.join(self.image_dir, f'{patient_id}_{mod}.nii')
    image = load_image(mod_path)

# Keep the original image
```

```
original_image = resize_image(image, self.target_size)
   original_image_np = sitk.GetArrayFromImage(original_image)
   normalized_original = normalize_image(original_image_np)
   images_original.append(normalized_original)
   # Apply transformations
   transformations = apply_transformations(image)
   transformed_image = random.choice(list(transformations.values()))
   transformed_image = resize_image(transformed_image, self.target_size)
   transformed_image_np = sitk.GetArrayFromImage(transformed_image)
   normalized_transformed = normalize_image(transformed_image_np)
   images_transformed.append(normalized_transformed)
# Stack original and transformed images
image_stack_original = np.stack(images_original, axis=0)
image_stack_transformed = np.stack(images_transformed, axis=0)
```

Image Augmentation Viewer

Select a directory

BraTS-GLI-02553-101 Select a view category Axial Select the type of augmentation Rotation

Category: seg

Apply Transformation

Category: t1c Category: t1n Category: t2f Category: t2w



Modeling Brain Tumors with 3D U-Net and Residual 3D U-Net

Why 3D U-Net for the BRATS 2024 dataset?

- Contextual Preservation:
- Precise localization:

Understanding U-Net Architecture

U-Net architecture consists of a contracting path to capture context and a symmetric expanding path that enables precise localization. The key components include:

- . Contracting Path: Captures the context in the image, which helps in understanding the global structure of the brain and the tumor.
- Expanding Path: Allows for precise localization using transposed convolutions to recover spatial resolution.
- Skip Connections: Provide essential high-resolution features to the expanding path, improving the accuracy of segmentation.

Implementing U-Net for BRATS 2024

```
class DoubleConv(nn.Module):
    """(convolution => [BN] => ReLU) * 2"""
    def __init__(self, in_channels, out_channels, mid_channels=None):
        super().__init__()
        if not mid_channels:
            mid_channels = out_channels
        self.double_conv = nn.Sequential(
            nn.Conv3d(in_channels, mid_channels, kernel_size=3, padding=1),
            nn.BatchNorm3d(mid_channels),
            nn.ReLU(inplace=True),
            nn.Conv3d(mid_channels, out_channels, kernel_size=3, padding=1),
            nn.BatchNorm3d(out_channels),
            nn.ReLU(inplace=True)
    def forward(self, x):
        return self.double conv(x)
        . . . . . . . . . . . . . . . .
        class UNet3D(nn.Module):
   def __init__(self, n_channels, n_classes, bilinear=True):
        super(UNet3D, self).__init__()
        self.n_channels = n_channels
        self.n_classes = n_classes
```

```
self.bilinear = bilinear
    self.inc = DoubleConv(n_channels, 64)
    self.down1 = Down(64, 128)
    self.down2 = Down(128, 256)
    self.down3 = Down(256, 512)
    self.down4 = Down(512, 512)
    self.up1 = Up(1024, 256, bilinear)
    self.up2 = Up(512, 128, bilinear)
    self.up3 = Up(256, 64, bilinear)
    self.up4 = Up(128, 64, bilinear)
    self.outc = OutConv(64, n_classes)
def forward(self, x):
    x1 = self.inc(x)
    x2 = self.down1(x1)
    x3 = self.down2(x2)
    x4 = self.down3(x3)
    x5 = self.down4(x4)
    x = self.up1(x5, x4)
    x = self.up2(x, x3)
    x = self.up3(x, x2)
    x = self.up4(x, x1)
    logits = self.outc(x)
    return logits
```

Evaluating Model Performance

Model performance is assessed using the Dice coefficient, which measures the overlap between the predicted segmentation and the ground truth labels. This metric is crucial for understanding the effectiveness of the model in medical segmentation tasks.

```
def dice_coefficient(preds, targets, num_classes):
    # Compute Dice Coefficient
    ...
    return dice / (num_classes - 1)
```

Data Preprocessing and Augmentation

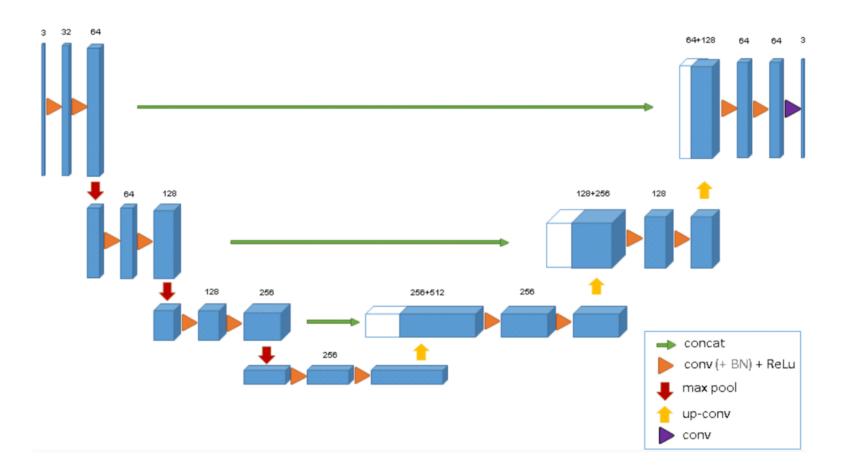
Effective data preprocessing and augmentation are crucial for training robust models. Here's how data is prepared:

- Normalization: Ensures that MRI scans have similar intensity ranges, enhancing model training stability.
- Augmentation: Includes zooming, cropping, and rotation, which helps the model generalize better by presenting varied examples during training.

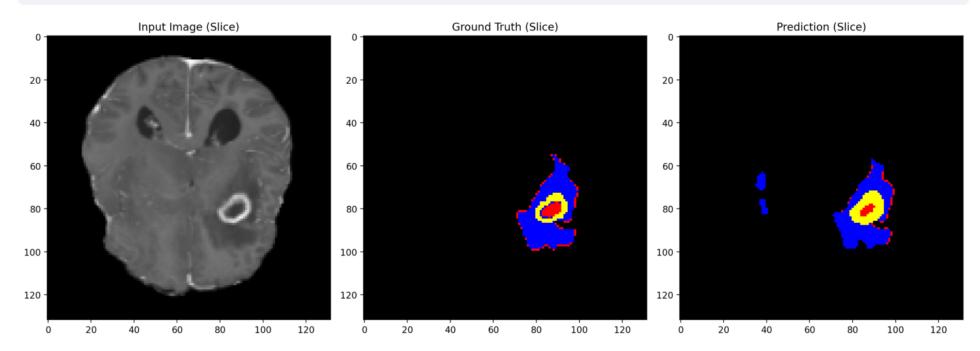
Additional Resources and References

- <u>Original U-Net Paper</u>
- <u>3D U-Net: Learning Dense Volumetric Segmentation from Sparse Annotation</u>
- <u>TensorFlow U-Net Tutorial</u>

3D u net Architecture



BraTS-GLI-02748-100_t2f.nii



Results

Dice Coefficient class 1: 0.3426

Dice Coefficient class 2: 0.8501

Dice Coefficient class 3: 0.7657

Dice Coefficient class 4: 0.0000

*hausdorff_dist score * class 1: 12.0830

*hausdorff_dist score * class 2: 44.3283

*hausdorff_dist score * class 3: 4.1231

*hausdorff_dist score * class 4: inf

3D U-Net Prediction with Image Transformation

BraTS-GLI-02759-101_t2f.nii

Select the type of transformation to apply

Rotation

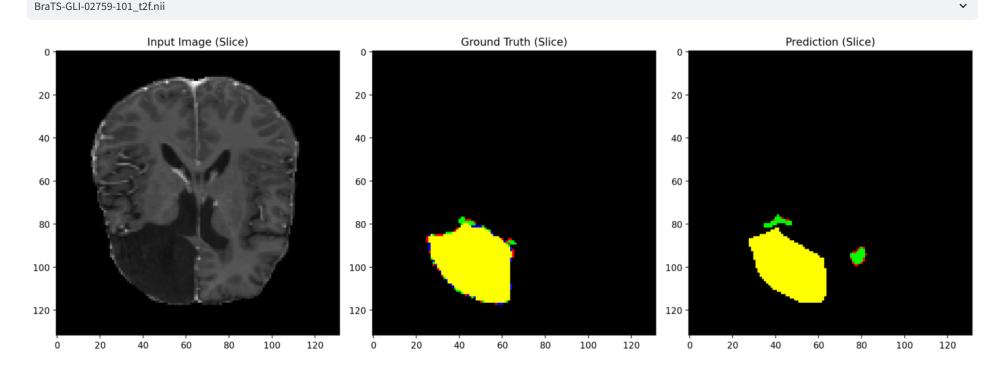
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Apply Transformation and Predict

3D U-Net with Residual Blocks

Select an NII file for prediction with 3D Unet with Residual Blocks

'



Results

Dice Coefficient class 1: 0.0803

Dice Coefficient class 2: 0.3071

Dice Coefficient class 3: 0.0000

*hausdorff_dist score * class 1: 34.5543

*hausdorff_dist score * class 2: 31.3369

*hausdorff_dist score * class 3: 41.0609

*hausdorff dist score * class 4: 6.5574

3D U-Net with Residual Blocks Prediction with Image Transformation



