

# MOR of Electro-Thermal Actuator using ANSYS and Simplorer

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#### Device – Electro-Thermal Actuator

- The conventional MEMS polysilicon electro-thermal microactuator uses Joule heating to generate thermal expansion and movement.<sup>[1]</sup>
- Electrical boundary conditions determine how the device is actuated. Mechanical boundary conditions control how the device is constrained from movement.

#### Applications:

- Switches
- Stepper motors<sup>[2]</sup>
- Safety Shut Off Devices
- Radiator temperature control.

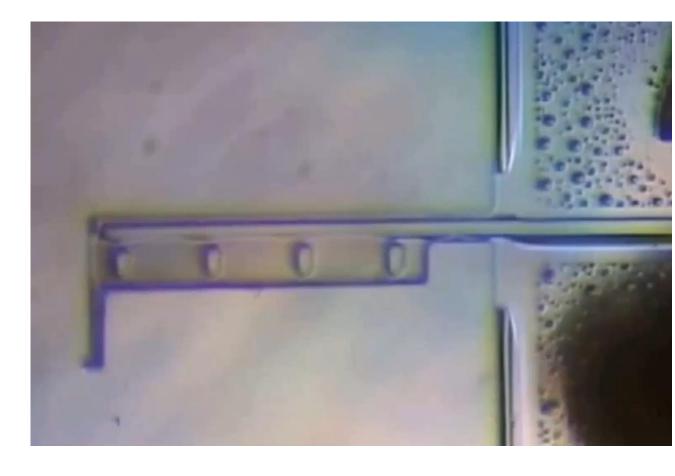


Fig.1: Thermal Actuator<sup>[\*]</sup>

#### Objective

- Obtain the maximum temperature across the device based on the given BC.
- Reduce the full scale ANSYS model using MORACT (Two inputs and an Extra output as T\_max) and export the model to Simplorer.
- Compare the results of reduced model integrated in Simplorer with ANSYS transient solution using the expansion result button in ANSYS workbench.
- Develop a temperature control (operation at fixed temperature), using the PI controller library element in Simplorer
- Goal: Maximum actuator temperature should quickly increase to 300°C and show minimum overshoot (use optimization for controller parametrization in Simplorer 2017)

#### Case Setup

- Boundary Conditions
  - Thermal: 0 K temperature on both bottom pads.
- Mesh
  - 5455 Nodes
  - 844 Elements
  - Hexahedral mesh elements
- Transient-Thermal Analysis
  - Internal Heat generation
    - Narrow arms–  $10^{13}$  W/m<sup>3</sup>
    - Wide arm- 2.5x10<sup>12</sup> W/m<sup>3</sup>

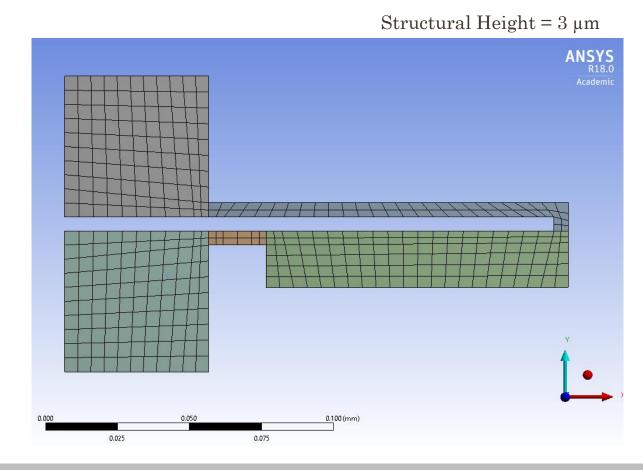
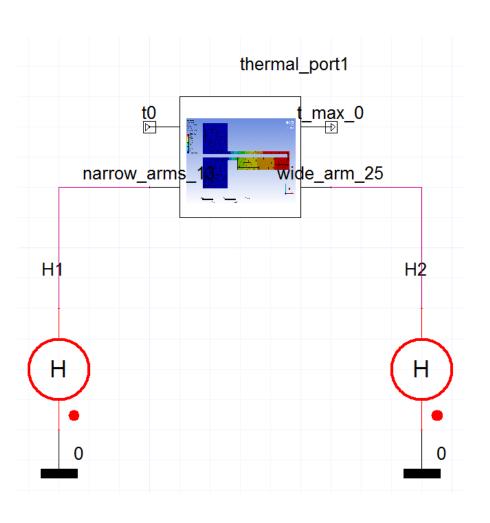


Fig.4: Mesh

### Model in Simplorer



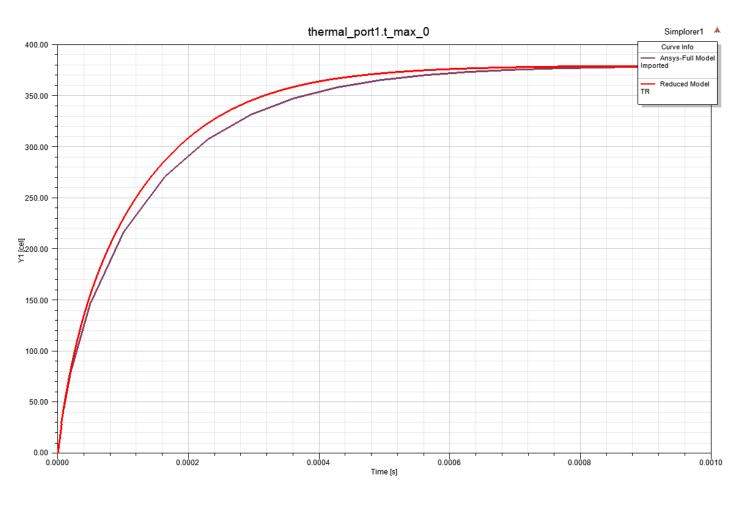


Fig.5: Simplorer model

Fig.6: MORACT Model vs Full Model

### Temperature Control for Actuator

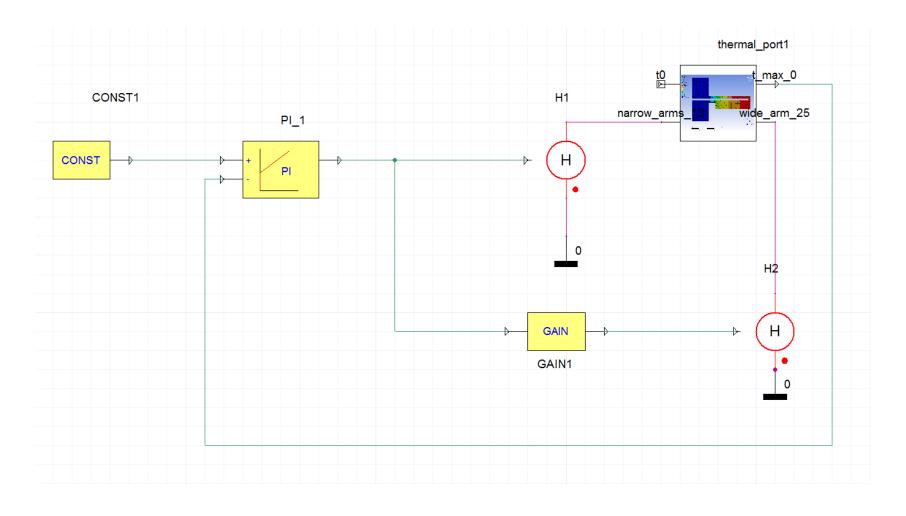


Fig.7: Temperature Control using PI controller

# Optimization Curves

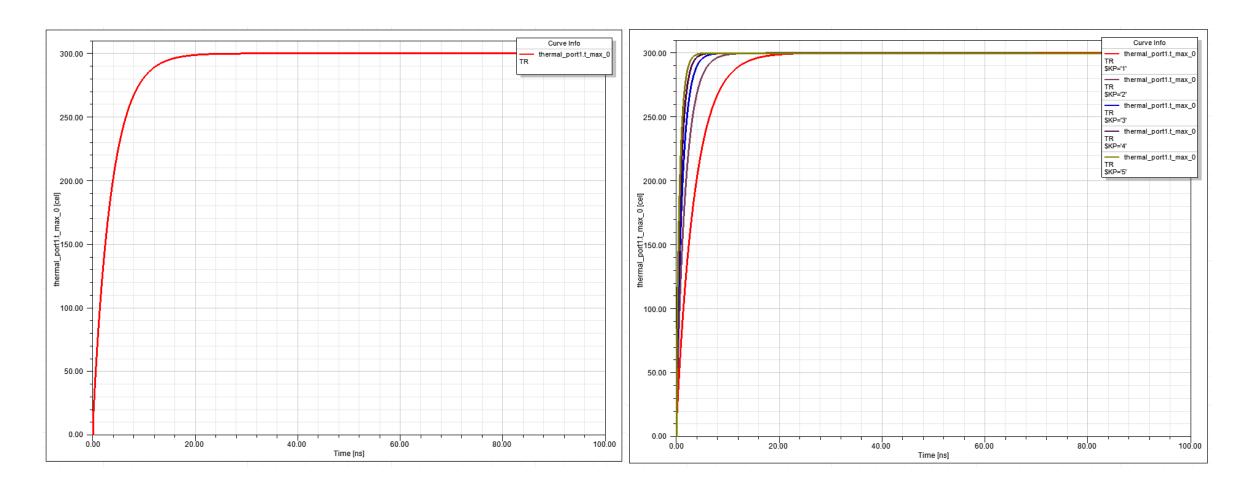


Fig.8: Temperature Distribution limiting at 300°C

Fig.9: Optimized curves

# Result Comparison

Result Comparison between the Reduced model-expanded result from the Simplorer and ANSYS Full model result.

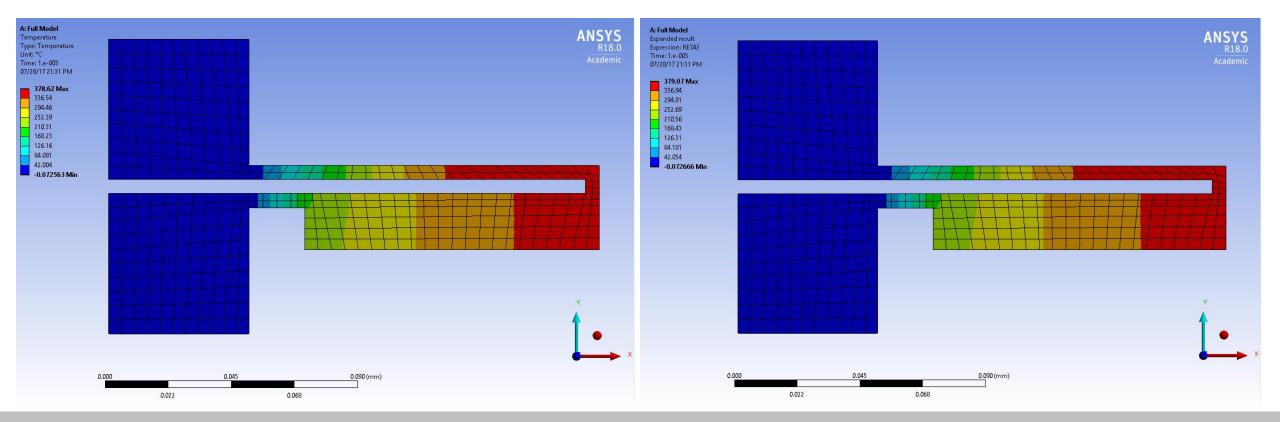


Fig.10: Full Model Results

Fig.10: Reduced Model-Expanded Results

# Result Comparison

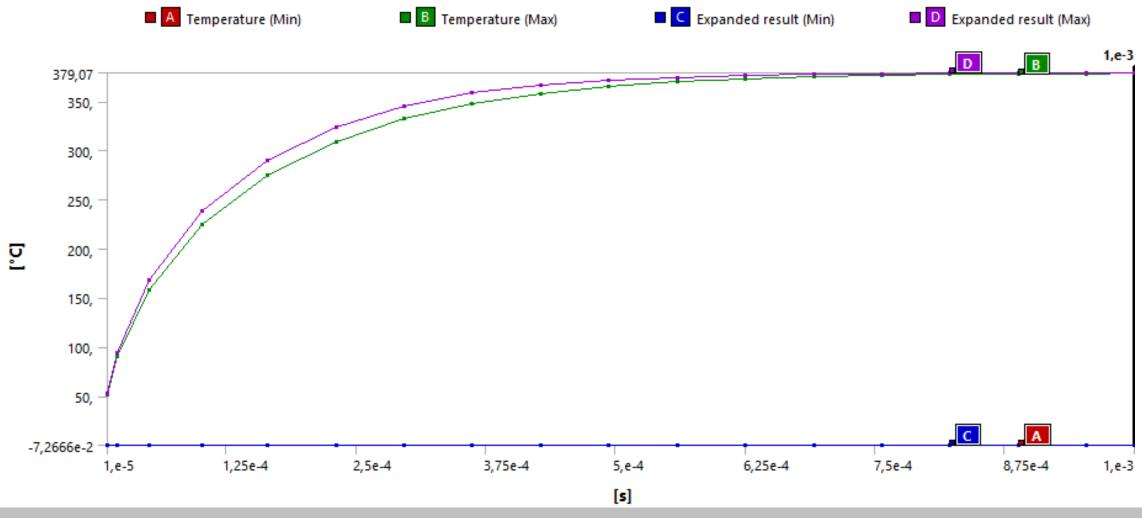


Fig.10: Comparing Expanded Results

#### Conclusion

- The results from both appear to follow same Temperature distribution and values.
- This means that the Reduced model can also be used in place of the Full model, thus reducing the computation effort.
- Maximum actuator temperature increases quickly to 300°C using PI controller optimization.

#### Reference

[1] E.S. Kolesar, P.B. Allen, J.T. Howard and J.M. Wilken, J. Vac. Sci. Technol. A, 17 (1999) 2257-2263.

[2] Kaur, Sandeep, Sukhdeep Kaur, and Subhash Poonia. "APPLICATION OF THERMAL ACTUATOR". International Journal of Advanced Research in Computer and Communication Engineering 2.10 (2013): 3. Print.