

Notation & Matrix Differentiation.

• $S(\theta) = 1 \times 1$ scalar

• $\theta = \begin{bmatrix} \theta_1 \\ \theta_2 \\ \vdots \\ \theta_k \end{bmatrix} \downarrow k \times 1$ vector, $\theta' = [\theta_1 \ \theta_2 \ \dots \ \theta_k] \xrightarrow{\quad}$

$\Rightarrow \frac{\partial S(\theta)}{\partial \theta} \downarrow = \begin{bmatrix} \frac{\partial S(\theta)}{\partial \theta_1} \\ \vdots \\ \frac{\partial S(\theta)}{\partial \theta_k} \end{bmatrix} \quad \begin{matrix} k \times 1 \text{ vector} \\ \text{Gradient} \end{matrix}$

$\Rightarrow \frac{\partial S(\theta)}{\partial \theta'} \xrightarrow{\quad} = \begin{bmatrix} \frac{\partial S(\theta)}{\partial \theta_1} & \dots & \frac{\partial S(\theta)}{\partial \theta_k} \end{bmatrix} \quad \begin{matrix} 1 \times k \text{ vector} \\ \text{Jacobian} \end{matrix}$

$\xrightarrow{\quad}$ For scalar
 $\frac{\partial S(\theta)'}{\partial \theta} = \frac{\partial S(\theta)}{\partial \theta'}$
 \triangle 分母表示形状.

$\Rightarrow \frac{\partial S(\theta)}{\partial \theta \partial \theta'} = \frac{\partial}{\partial \theta} \left(\frac{\partial S(\theta)}{\partial \theta'} \right) = \frac{\partial}{\partial \theta} \begin{bmatrix} \frac{\partial S(\theta)}{\partial \theta_1} & \dots & \frac{\partial S(\theta)}{\partial \theta_k} \end{bmatrix} = \begin{bmatrix} \frac{\partial^2 S(\theta)}{\partial \theta_1 \partial \theta_1} & \dots & \frac{\partial^2 S(\theta)}{\partial \theta_1 \partial \theta_k} \\ \vdots & & \vdots \\ \frac{\partial^2 S(\theta)}{\partial \theta_k \partial \theta_1} & \dots & \frac{\partial^2 S(\theta)}{\partial \theta_k \partial \theta_k} \end{bmatrix}$

$k \times k$ vector
Hessian

• $A(\theta) \downarrow = \begin{bmatrix} A_1(\theta) \\ A_2(\theta) \\ \vdots \\ A_r(\theta) \end{bmatrix} \downarrow r \times 1$ matrix

$\Rightarrow \frac{\partial A(\theta)}{\partial \theta'} \xrightarrow{\quad} = \begin{bmatrix} \frac{\partial A_1(\theta)}{\partial \theta_1} & \dots & \frac{\partial A_1(\theta)}{\partial \theta_k} \\ \vdots & & \vdots \\ \frac{\partial A_r(\theta)}{\partial \theta_1} & \dots & \frac{\partial A_r(\theta)}{\partial \theta_k} \end{bmatrix} \quad \begin{matrix} r \times k \text{ matrix} \\ \text{Jacobian} \end{matrix}$

$\triangle \frac{\partial A(\theta)}{\partial \theta} = \left(\frac{\partial A(\theta)}{\partial \theta'} \right)' \quad \begin{matrix} k \times r \text{ matrix} \\ \text{Jacobian}^T \end{matrix}$

内積

$$\frac{\partial}{\partial \theta} (a^T \theta) = \frac{\partial}{\partial \theta} (a \cdot \theta) = \frac{\partial}{\partial \theta} (\theta \cdot a) = \frac{\partial}{\partial \theta} (\theta^T a) \Rightarrow \frac{\partial}{\partial \theta} (a^T \theta) = \frac{\partial}{\partial \theta} (\theta^T a)$$

$$= \frac{\partial}{\partial \theta} (a_1 \theta_1 + \dots + a_k \theta_k) = a_1 \frac{\partial \theta_1}{\partial \theta} + \dots + a_k \frac{\partial \theta_k}{\partial \theta}$$

$$= a_1 \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix} + \dots + a_k \begin{bmatrix} 0 \\ \vdots \\ 1 \end{bmatrix} = \begin{bmatrix} a_1 \\ \vdots \\ a_k \end{bmatrix} = a$$

1xk r x 1

$$\frac{\partial}{\partial \theta} (a^T F(\theta)) = \frac{\partial}{\partial \theta} (a_1 F_1(\theta) + \dots + a_r F_r(\theta))$$

k x 1

$$= \frac{\partial F_1(\theta)}{\partial \theta} a_1 + \dots + \frac{\partial F_r(\theta)}{\partial \theta} a_r$$

$$= \begin{bmatrix} \frac{\partial F_1(\theta)}{\partial \theta_1} a_1 \\ \vdots \\ \frac{\partial F_1(\theta)}{\partial \theta_k} a_1 \end{bmatrix} + \dots + \begin{bmatrix} \frac{\partial F_r(\theta)}{\partial \theta_1} a_r \\ \vdots \\ \frac{\partial F_r(\theta)}{\partial \theta_k} a_r \end{bmatrix}$$

$$= \begin{bmatrix} \frac{\partial F_1(\theta)}{\partial \theta_1} a_1 + \dots + \frac{\partial F_r(\theta)}{\partial \theta_1} a_r \\ \vdots \\ \frac{\partial F_1(\theta)}{\partial \theta_k} a_1 + \dots + \frac{\partial F_r(\theta)}{\partial \theta_k} a_r \end{bmatrix} = \begin{bmatrix} \frac{\partial F_1(\theta)}{\partial \theta_1} & \dots & \frac{\partial F_r(\theta)}{\partial \theta_1} \\ \vdots & & \vdots \\ \frac{\partial F_1(\theta)}{\partial \theta_k} & \dots & \frac{\partial F_r(\theta)}{\partial \theta_k} \end{bmatrix} \begin{bmatrix} a_1 \\ \vdots \\ a_r \end{bmatrix}$$

But $\frac{\partial F(\theta)}{\partial \theta'} = \text{Jacobian}(F) = \begin{bmatrix} \frac{\partial F_1}{\partial \theta_1} & \dots & \frac{\partial F_1}{\partial \theta_k} \\ \vdots & & \vdots \\ \frac{\partial F_r}{\partial \theta_1} & \dots & \frac{\partial F_r}{\partial \theta_k} \end{bmatrix}$ ← transpose

denote

$$= \left(\frac{\partial F(\theta)}{\partial \theta'} \right)' a = \frac{\partial F(\theta)}{\partial \theta} a$$

\downarrow $\begin{matrix} r \times k \\ k \times r \end{matrix}$ $r \times 1$ $k \times r$ $r \times 1$

$$\frac{\partial}{\partial \theta} \left[\underset{k \times 1}{F(\theta)}' \underset{1 \times r}{G(\theta)} \right] = \frac{\partial}{\partial \theta} \left[F(\theta) \cdot G(\theta) \right]$$

$$= \frac{\partial}{\partial \theta} \left[F_1(\theta) G_1(\theta) + \dots + F_r(\theta) G_r(\theta) \right] = \frac{\partial}{\partial \theta} \sum_{i=1}^r F_i(\theta) G_i(\theta)$$

$$= \begin{bmatrix} \frac{\partial}{\partial \theta_1} \sum F_i(\theta) G_i(\theta) \\ \vdots \\ \frac{\partial}{\partial \theta_k} \sum F_i(\theta) G_i(\theta) \end{bmatrix}$$

$$= \begin{bmatrix} \sum F_i(\theta) \frac{\partial G_i(\theta)}{\partial \theta_1} + G_i(\theta) \frac{\partial F_i(\theta)}{\partial \theta_1} \\ \vdots \\ \sum F_i(\theta) \frac{\partial G_i(\theta)}{\partial \theta_k} + G_i(\theta) \frac{\partial F_i(\theta)}{\partial \theta_k} \end{bmatrix} = \begin{bmatrix} \sum F_i(\theta) \frac{\partial G_i(\theta)}{\partial \theta_1} \\ \vdots \\ \sum F_i(\theta) \frac{\partial G_i(\theta)}{\partial \theta_k} \end{bmatrix} + \begin{bmatrix} \sum G_i(\theta) \frac{\partial F_i(\theta)}{\partial \theta_1} \\ \vdots \\ \sum G_i(\theta) \frac{\partial F_i(\theta)}{\partial \theta_k} \end{bmatrix}$$

$$= \begin{bmatrix} F_1(\theta) \frac{\partial G_1(\theta)}{\partial \theta_1} + F_2(\theta) \frac{\partial G_2(\theta)}{\partial \theta_1} + \dots + F_r(\theta) \frac{\partial G_r(\theta)}{\partial \theta_1} \\ \vdots \\ F_1(\theta) \frac{\partial G_1(\theta)}{\partial \theta_k} + F_2(\theta) \frac{\partial G_2(\theta)}{\partial \theta_k} + \dots + F_r(\theta) \frac{\partial G_r(\theta)}{\partial \theta_k} \end{bmatrix} \leftarrow F \leftrightarrow G$$

$$= \begin{bmatrix} \frac{\partial G_1(\theta)}{\partial \theta_1} & \frac{\partial G_2(\theta)}{\partial \theta_1} & \dots & \frac{\partial G_r(\theta)}{\partial \theta_1} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial G_1(\theta)}{\partial \theta_k} & \frac{\partial G_2(\theta)}{\partial \theta_k} & \dots & \frac{\partial G_r(\theta)}{\partial \theta_k} \end{bmatrix} \begin{bmatrix} F_1(\theta) \\ F_2(\theta) \\ \vdots \\ F_r(\theta) \end{bmatrix} \leftarrow F \leftrightarrow G$$

The Jacobian

$$\frac{\partial G}{\partial \theta} \rightarrow \begin{bmatrix} \frac{\partial G_1}{\partial \theta_1} & \frac{\partial G_1}{\partial \theta_2} & \dots & \frac{\partial G_1}{\partial \theta_k} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial G_r}{\partial \theta_1} & \dots & \dots & \frac{\partial G_r}{\partial \theta_k} \end{bmatrix}$$

Jacobian transpose

$$= \left(\frac{\partial G(\theta)}{\partial \theta} \right)' F(\theta) + \left(\frac{\partial F(\theta)}{\partial \theta} \right)' G(\theta)$$

$$= \underset{k \times r}{\frac{\partial G(\theta)'}{\partial \theta}} \underset{1 \times 1}{F(\theta)} + \underset{k \times r}{\frac{\partial F(\theta)'}{\partial \theta}} \underset{1 \times 1}{G(\theta)}$$