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Real UNNS "echo" form

A Concrete, Applied Example

A concrete, applied example that shows how one can do what's usually done with complex numbers entirely in real UNNS "echo" form. It's done in two staples side-by-side:

- 1. a (damped) harmonic oscillator (physics), and
- 2. a single Fourier mode / phasor (signal processing),

both as real 2×2 rotation-dilation recursions (echo cycles), no ii required.

1) Harmonic oscillator via UNNS echo (no complex)

1.1 Undamped SHO

Continuous equation:

$$x''(t) + \omega^2 x(t) = 0$$
, $x(0) = x_0$, $x'(0) = v_0$.

 $x''(t)+\omega 2x(t)=0, x(0)=x0, x'(0)=v0.$

Classically you'd write $x(t) = A\cos(\omega t) + B\sin(\omega t)x(t) = A\cos(\omega t) + B\sin(\omega t)$ or use $e^{i\omega t}$ eiωt. In UNNS, we keep it real and step by a fixed time h > 0 h>0 using the exact flow:

Define the state
$$s(t) = \begin{bmatrix} x(t) \\ v(t)/\omega \end{bmatrix} s(t) = [x(t)v(t)/\omega]$$
. Over step hh ,

$$s(t+h) = R(\theta) s(t), \qquad R(\theta) = \begin{bmatrix} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{bmatrix}, \quad \theta = \omega h.$$

 $s(t+h)=R(\theta)s(t),R(\theta)=[\cos\theta-\sin\theta\sin\theta\cos\theta],\theta=\omega h.$

This matrix is the quarter-turn echo engine (a planar rotation). No complex algebra, same physics.

Discrete UNNS recursion (exact):

$$\left[\begin{array}{c} x_{n+1} \\ v_{n+1}/\omega \end{array}\right] = \left[\begin{array}{cc} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{array}\right] \left[\begin{array}{c} x_n \\ v_n/\omega \end{array}\right], \qquad \theta = \omega h.$$

 $[xn+1vn+1/\omega]=[\cos\theta-\sin\theta\sin\theta\cos\theta][xnvn/\omega],\theta=\omega h.$

- Energy is preserved: $x_n^2 + (v_n/\omega)^2 \text{xn}^2 + (\text{vn}/\omega)^2 \text{ is constant (pure rotation)}$.
- This is exactly what $e^{i\omega t}$ ei ωt does, but as a **real rotation**.

1.2 Damped SHO

$$x'' + 2\zeta\omega x' + \omega^2 x = 0, \qquad 0 < \zeta < 1.$$

 $x''+2\zeta\omega x'+\omega 2x=0,0<\zeta<1.$

Exact step over *h*h:

$$s_{n+1} = \rho R(\theta_d) s_n$$
, $\rho = e^{-\zeta \omega h}$, $\theta_d = \omega \sqrt{1 - \zeta^2} h$.

$$sn+1=\rho R(\theta d)sn, \rho=e-\zeta \omega h, \theta d=\omega 1-\zeta 2$$

So it's a **rotation–dilation**: same rotation, multiplied by $\rho < 1\rho < 1$. Still all-real.

- Amplitude decays like $ho^n=e^{-\zeta\omega nh}$ hon=e- $\zeta\omega$ nh.
- Phase advances by $\theta_d \theta d$ each step.

This is exactly the complex solution $e^{(-\zeta\omega \pm i\omega_d)t}e(-\zeta\omega\pm i\omega d)t$, but as a real echo.

Tiny pseudocode (language-agnostic)

```
given x0, v0, \omega, \zeta (damping \in[0,1)), step h, steps N \theta = \omega*sqrt(max(1-\zeta*\zeta, 0))*h \rho = exp(-\zeta*\omega*h)
      = cos(\theta); s = sin(\theta)
U = v0/\omega # scaled velocity
for n = 1..N:

X_new = p*( c*X + s*U)
U_new = p*(-s*X + c*U)
X, U = X_new, U_new
# physical velocity v = w*U
```

Why this matters: all computations are real; you can run this on hardware that doesn't want complex arithmetic. Same fidelity.

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2) Single Fourier mode / "phasor" without ii

Suppose a discrete signal has a pure tone with angular step $\theta\theta$. Classically: $e^{in\theta}$ ein θ . In UNNS/real arithmetic, use the **second-order real recursion** (Chebyshev form):

$$y_{n+1} = 2\cos\theta \, y_n - y_{n-1},$$

 $yn+1=2\cos\theta yn-yn-1$,

with, say, $y_0 = 1$, $y_1 = \cos\theta$ y0=1,y1=cos θ . Then $y_n = \cos(n\theta)$ yn=cos(n θ), and the quadrature $q_n = \sin(n\theta)$ qn=sin(n θ) is tracked by the companion rotation:

$$\left[\begin{array}{c} y_{n+1} \\ q_{n+1} \end{array}\right] = \left[\begin{array}{cc} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{array}\right] \left[\begin{array}{c} y_n \\ q_n \end{array}\right].$$

 $[yn+1qn+1] = [\cos\theta - \sin\theta \sin\theta \cos\theta][ynqn].$

Again: pure rotation in R^2 R2. No CC needed.

Under damping / windowing (e.g., exponential window), just multiply by $\rho < 1 \rho <$

$$\left[\begin{array}{c} \mathcal{Y}_{n+1} \\ q_{n+1} \end{array}\right] = \rho \left[\begin{array}{cc} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{array}\right] \left[\begin{array}{c} \mathcal{Y}_{n} \\ q_{n} \end{array}\right].$$

 $[yn+1qn+1]=\rho[\cos\theta-\sin\theta\sin\theta\cos\theta][ynqn]$

Where this is immediately useful

- Education: demystify complex numbers show "imaginary" as real rotation.
- Embedded / GPU computing: keep pipelines real; avoid complex datatypes.
- Signal processing: phasors and Fourier modes as real recursions (helps on constrained hardware).
- Physics sims: oscillators, wave packets, AC circuits, normal modes all via rotation—dilation.

Bonus: "UNNS repair/normalization" hook

If your data are noisy or quantized, insert a UNNS operator after each step:

- Collapse/threshold: zero out tiny components (noise floor).
- Inlaying: snap (y,q)(y,q) to a target lattice (e.g., Gaussian/Eisenstein) for numerical robustness.
- **Damping:** apply $\rho\rho$ to control energy/entropy.

These keep the real recursion stable while preserving the dominant resonance (frequency).