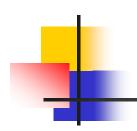


數位IC設計

Case Study



Case - Filter (1/8)

FIR
$$y(n) = \sum_{m=0}^{M} h_m x(n-m)$$
 Filter tap=4

$$y(0) = h_0 x(0) + h_1 x(-1) + h_2 x(-2) + h_3 x(-3)$$

$$y(1) = h_0 x(1) + h_1 x(0) + h_2 x(-1) + h_3 x(-2)$$

$$y(2) = h_0 x(2) + h_1 x(1) + h_2 x(0) + h_3 x(-1)$$

$$y(3) = h_0 x(3) + h_1 x(2) + h_2 x(1) + h_3 x(0)$$

$$y(4) = h_0 x(4) + h_1 x(3) + h_2 x(2) + h_3 x(1)$$

IIR
$$y(n) - \sum_{m=1}^{M} k_m y(n-m) = \sum_{m=0}^{M} h_m x(n-m)$$

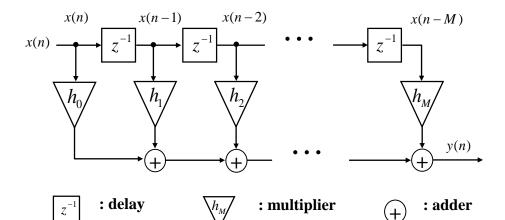
$$y(0) - [k_1y(-1) + k_2y(-2) + k_3y(-3)] = h_0x(0) + h_1x(-1) + h_2x(-2)h_3x(-3)$$

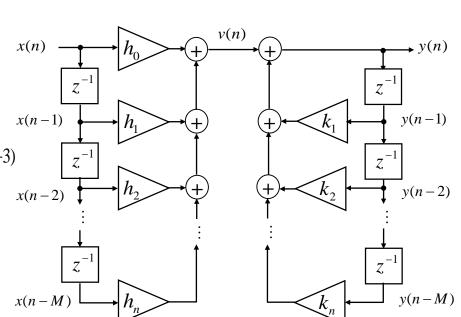
$$y(1) - [k_1y(0) + k_2y(-1) + k_3y(-2)] = h_0x(1) + h_1x(0) + h_2x(-1)h_3x(-2)$$

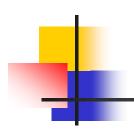
$$y(2) - [k_1y(1) + k_2y(0) + k_3y(-1)] = h_0x(2) + h_1x(1) + h_2x(0)h_3x(-1)$$

$$y(3) - [k_1y(2) + k_2y(1) + k_3y(0)] = h_0x(3) + h_1x(2) + h_2x(1)h_3x(0)$$

$$y(4) - [k_1y(3) + k_2y(2) + k_3y(1)] = h_0x(4) + h_1x(3) + h_2x(2)h_3x(1)$$

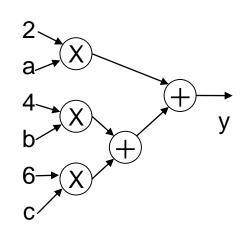






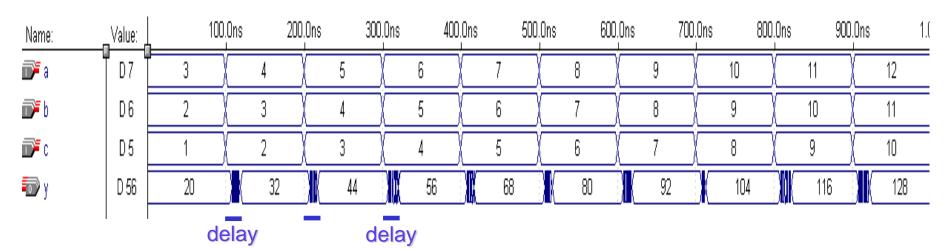
Case - Filter (2/8)

tap=3 h_0 =2; h_1 =4, h_2 =6; module fir1(a, b, c, y); input [7:0] a, b, c; output [11:0] y; assign y = a*2+b*4+c*6; endmodule



module fir2(a, b, c, y); input [7:0] a, b, c; output [11:0] y; reg [11:0] y; always @(a or b or c) y = a*2+b*4+c*6; endmodule

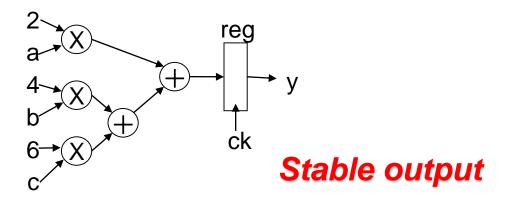
Output: 20, 32, 44, 56, 68, 80, 92, 104,





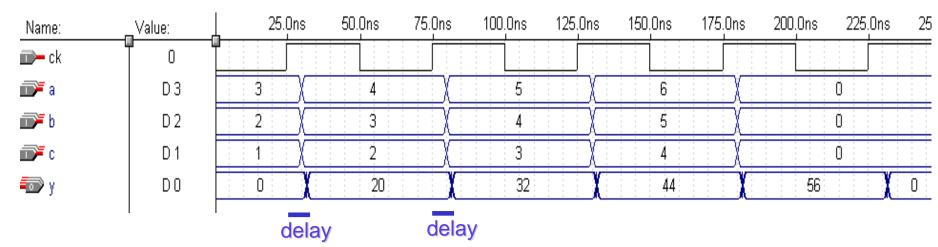
Case - Filter (3/8)

```
module fir3(a, b, c, y, ck);
input [7:0] a, b, c;
input ck;
output [11:0] y;
reg [11:0] y;
always @(posedge ck)
y = a*2+b*4+c*6;
endmodule
```



Three inputs (a, b, c) must be entered concurrently (more pins, higher cost).

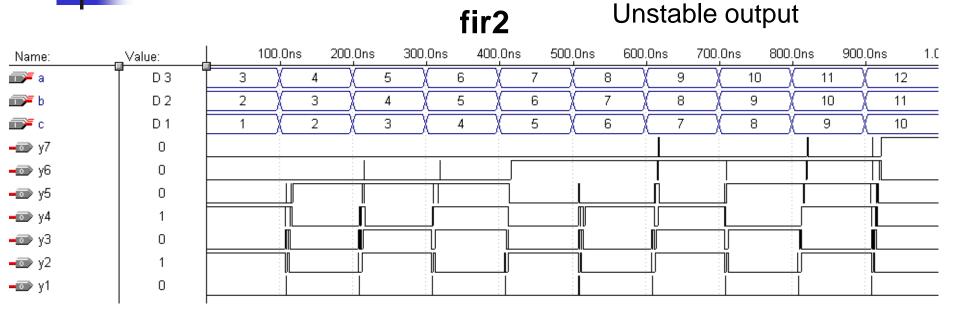
Output: 20, 32, 44, 56, 68, 80, 92, 104,

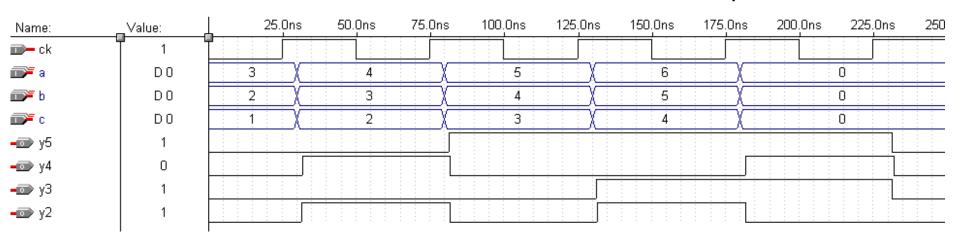


The stable output is generated at the positive edge of clock.



Case - Filter (4/8)





fir3

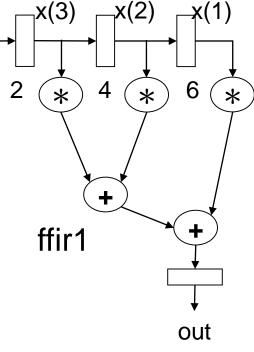
Stable output

Case - Filter (5/8)

```
module register(in, out, ck);
input [11:0] in;
input ck;
output [11:0] out;
reg [11:0] out;
always @(posedge ck)
out=in;
endmodule
`include "register.v"
module ffir1(in, out, ck);
input [11:0] in;
input ck;
output [11:0] out;
wire [11:0] x4, x3, x2, x1;
register r1(in, x3, ck);
register r2(x3, x2, ck);
register r3(x2, x1, ck);
register r4(x4, out, ck)
assign x4=x1*6+x2*4+x3*2;
endmodule
```

```
module ffir1_a(in, out, ck);
                              in
input
                    ck:
input [11:0] in;
output [11:0] out;
     [11:0] out;
reg
reg [11:0] x4, x3, x2, x1;
always @(posedge ck)
begin
         x3 \le in;
         x2 <= x3:
         x1 <= x2;
         out <= (x3*2+x2*4)+x1*6;
end
```

endmodule



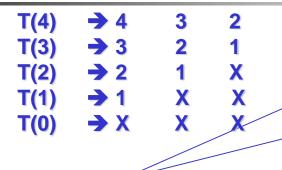
One input (in) is entered every clock cycle (more suitable for memory access and pins' cost)

T(n+1) → 4

T(n)

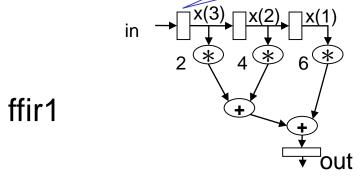


Case - Filter (6/8)

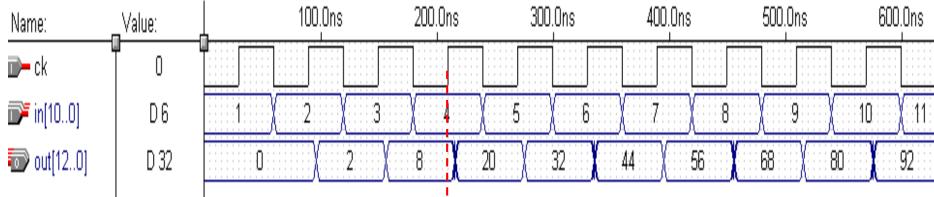


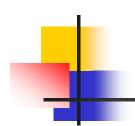
To work well, every input must be ready before the positive edge of every clock

'Correct results start here (4th clock), why?



Output: 20, 32, 44, 56, 68, 80, 92, 104,





Case - Filter (7/8)

in

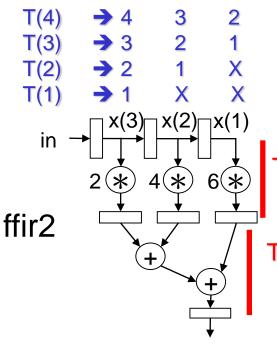
```
register r1(in, x3, ck); register r2(x3, x2, ck); register r3(x2, x1, ck); assign t3=x3*2; assign t2=x2*4; assign t1=x1*6; register r4(t3, y3, ck); register r5(t2, y2, ck); register r6(t1, y1, ck); assign x4=y1+y2+y3; register r7(x4, out, ck); endmodule
```

Datapath Pipelining

```
module ffir2_a(in, out, ck);
input
          ck:
input [11:0] in;
output [11:0] out;
reg [11:0] out;
reg [11:0] x3, x2, x1;
reg [11:0] y3, y2, y1;
always @(posedge ck)
begin
         x3<=in:
         x2 <= x3:
         x1 <= x2;
         y3 <= x3*2;
         y2 <= x2*4;
         y1 <= x1*6;
         out<=(y3+y2)+y1;
end
endmodule
```



Case - Filter (8/8)



Delay for ★ is about 7.3 ns

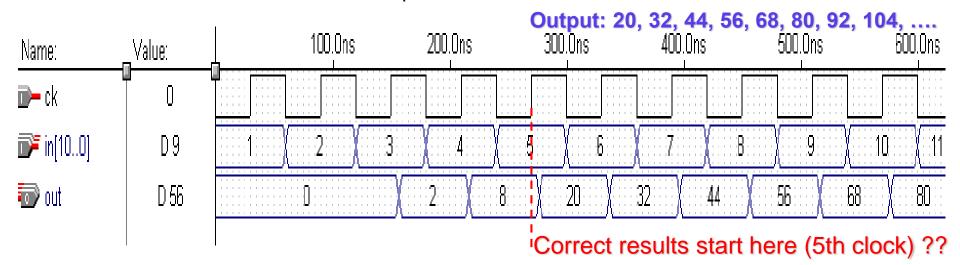
Delay for register assign is about 6.1 ns

Delay for + is about 2.6 ns

Total delay=7.3+6.1=13.4 ns (+ little wire delay)

Total delay=2.6*2+6.1=11.3 ns

Critical path=13.4 ns => clock rate less than 1/(13.4*10⁻⁹) ~= 74.6 MHz





Case - Systolic Array (1/5)

Systolic Array (FIR)

$$y(0) = h_0 x(0) + h_1 x(-1) + h_2 x(-2) + h_3 x(-3)$$

$$y(1) = h_0 x(1) + h_1 x(0) + h_2 x(-1) + h_3 x(-2)$$

$$y(2) = h_0 x(2) + h_1 x(1) + h_2 x(0) + h_3 x(-1)$$

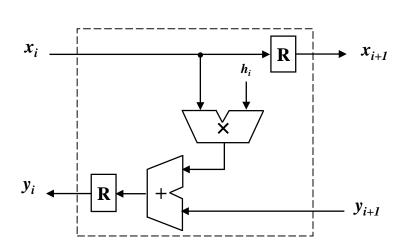
$$y(3) = h_0 x(3) + h_1 x(2) + h_2 x(1) + h_3 x(0)$$

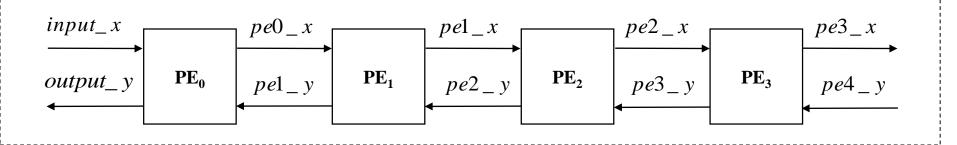
$$y(4) = h_0 x(4) + h_1 x(3) + h_2 x(2) + h_3 x(1)$$

+: adder ×: multiplier

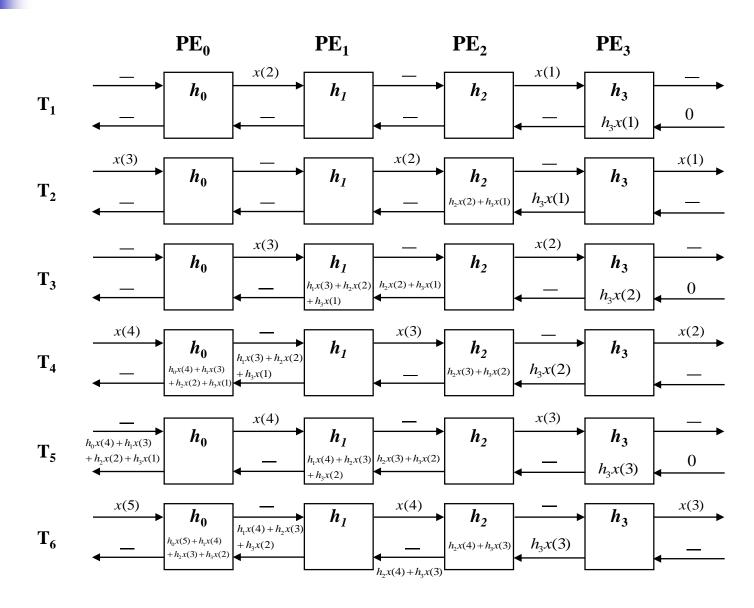
R: register h_i : coefficient

Processing Element





Case - Systolic Array (2/5)



Case - Systolic Array (3/5)

	input_x	<i>pe</i> 0_ <i>x</i>	pel_x	pe2_x	pe3_x	<i>pe</i> 4_ <i>y</i>	pe3_y	pe2_y	<i>pe</i> 1_ <i>y</i>	output_y
T_1	1	<i>x</i> (2)	1	<i>x</i> (1)	l	l	ı			
T_2	<i>x</i> (3)	ı	<i>x</i> (2)	ı	<i>x</i> (1)	0	$h_3x(1)$			
T_3	ı	<i>x</i> (3)	ı	<i>x</i> (2)	ı	1	1	$h_2 x(2) + h_3 x(1)$		
T_4	<i>x</i> (4)	1	<i>x</i> (3)	I	<i>x</i> (2)	0	$h_3x(2)$		$h_1 x(3) + h_2 x(2) + h_3 x(1)$	
T_5		<i>x</i> (4)	I	<i>x</i> (3)	I	ı	1	$h_2 x(3) + h_3 x(2)$	_	$h_0 x(4) + h_1 x(3) + h_2 x(2) + h_3 x(1)$
T_6	<i>x</i> (5)	1	<i>x</i> (4)		<i>x</i> (3)	0	$h_3x(3)$		$h_1 x(4) + h_2 x(3) + h_3 x(2)$	
T_7	_	<i>x</i> (5)	_	<i>x</i> (4)	_	_	_	$h_2 x(4) + h_3 x(3)$		$h_0 x(5) + h_1 x(4) + h_2 x(3) + h_3 x(2)$



Case - Systolic Array (4/5)

```
Design_1
module pe(clk, reset, coeff, in x, in y, out x, out y);
parameter size = 8;
input clk, reset;
input [size-1:0]
                       in x, coeff;
input [size+size-1:0] in_y;
output [size-1:0]
                       out x:
output [size+size-1:0] out_y;
wire [size+size-1:0] mult_out, add_out;
reg_8 r1(clk, reset, in_x, out_x);
reg_16 r2(clk, reset, add_out, out_y);
assign mult_out = in_x * coeff;
assign add out = mult out + in y;
endmodule
                          in_x
```

```
out_y R out_x
```

```
module pe(clk, reset, coeff, in_x, in_y,
out x, out y);
parameter size = 8;
input
              clk, reset;
        [size-1:0]
input
                       in x, coeff;
        [size+size-1:0] in v;
input
output [size-1:0]
                       out x;
output [size+size-1:0] out_y;
        [size+size-1:0] out y;
reg
        [size-1:0]
reg
                       out x;
always@(posedge clk)
begin
 if(reset) begin
   out x = 0;
   out y = 0;
   end
 else begin
   out_y = in_y + (in_x * coeff);
   out x = in x;
   end
end
endmodule
```



endmodule

Case - Systolic Array (5/5)

```
//**** main ****************
module systolic(clk, reset, input_x, output_y);
parameter size = 8;
input clk, reset;
input [size-1:0]
                     input_x;
output [size+size-1:0] output_y;
wire
      [size-1:0]
                 pe0_x, pe1_x, pe2_x, pe3_x;
      [size+size-1:0] pe1_y, pe2_y, pe3_y;
wire
     [size-1:0]
                   h0 = 8'h01;
wire
      [size-1:0]
                   h1 = 8'h01;
wire
     [size-1:0]
                   h2 = 8'h01:
wire
     [size-1:0]
                   h3 = 8'h01;
wire
     [size+size-1:0] pe4_y = 16'h0000;
pe pe_0(clk, reset, h0, input_x, pe1_y, pe0_x,
output_y);
pe pe_1(clk, reset, h1, pe0_x, pe2_y, pe1_x, pe1_y);
pe pe_2(clk, reset, h2, pe1_x, pe3_y, pe2_x, pe2_y);
pe pe 3(clk, reset, h3, pe2 x, pe4 y, pe3 x, pe3 y);
```

```
//**** register 8bits ******
module reg_8(clk,reset,in,out);
parameter size_in = 8;
input
            clk,reset;
            [size_in-1:0] in;
input
output
            [size_in-1:0] out;
            [size in-1:0] out;
reg
always @(posedge clk)
begin
  if(reset)
    out=0;
  else
    out=in;
 end
endmodule
```

```
//**** register 16bits ******
module reg_16(clk,reset,in,out);
parameter size_in = 16;
input
            clk,reset;
input
            [size_in-1:0] in;
output
            [size_in-1:0] out;
            [size in-1:0] out;
reg
always @(posedge clk)
begin
 if(reset)
   out=0;
 else
   out=in;
end
endmodule
```

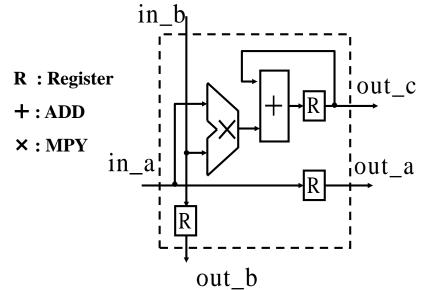


Case-Matrix Multiplication (1/2)

Matrix Multiplication

$$\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \begin{bmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{bmatrix} = \begin{bmatrix} c_{11} & c_{12} \\ c_{21} & c_{22} \end{bmatrix}$$

$$c=c+(a*b)$$



```
`include "reg_8.v"

`include "reg_16.v"
```

```
module PE(clk,reset,in_a,in_b,out_a,out_b,out_c);
parameter data_size=8;
input reset,clk;
input [data_size-1:0] in_a,in_b;
output [data_size-1:0] out_a,out_b;
output [2*data_size-1:0] out_c;
wire [2*data_size-1:0] out_c,ADD_out,out_MPY;
wire [data_size-1:0] out_a,out_b;
```

```
assign out_MPY=in_a*in_b;
assign ADD_out=out_MPY+out_c;
reg_16 reg_16_0(clk,reset,ADD_out,out_c);
reg_8 reg_delay_8_0(clk,reset,in_a,out_a);
reg_8 reg_delay_8_1(clk,reset,in_b,out_b);
endmodule
```



Case-Matrix Multiplication (2/2)

```
module PE_H(reset,clk,in_a,in_b,out_a,out_b,out_c);
parameter data_size=8;
input reset,clk;
input [data_size-1:0] in_a,in_b;
output [2*data_size:0] out_c;
output [data_size-1:0] out_a,out_b;
reg [2*data_size:0] out_c;
reg [data_size-1:0] out_a,out_b;
```

```
begin
   if(reset)
   begin
   out a=0;
   out b=0;
   out c=0;
  end
 else
  begin
   out_c=out_c+in_a*in_b;
  out a=in a;
   out_b=in_b;
 end
end
endmodule
```

always @(posedge clk)

```
in_b

out_c

in_a

out_a
```

The rest of circuit can be designed easily....