Syntaks og semantik

Lektion 12

15 april 2008

Abstrakt syntaks Environment & store Udtryk Variabel-erklæringer Kommandoer Scoperegler Statisk binding

Blokke

- Scoperegler
- Statisk binding

Abstrakt syntaks for **Bip**Environment-store-modellen
Aritmetiske og boolske udtryk
Variabel-erklæringer
Kommandoer minus procedurekald

Abstrakt syntaks Environment & store Udtryk Variabel-erklæringer Kommandoer Scoperegler Statisk binding

Bip = **Bims** + blokke og parameterløse procedurer:

Kom: $S ::= x := a \mid \text{skip} \mid S_1; S_2 \mid \text{if } b \text{ then } S_1 \text{ else}$ $\mid \text{while } b \text{ do } S$ $\mid \text{begin } D_V \ D_P \ S \text{ end} \mid \text{call } p$ **ErkV:** $D_V ::= \text{var } x := a; D_V \mid \varepsilon$

 lokale erklæringer af variable (ErkV) og procedurer (ErkP) i en blok **ErkP**: $D_P := \operatorname{proc} p \text{ is } S; D_P \mid \varepsilon$

- variable initialiseres ved erklæring
- semantikken af procedurekald afhænger af scope-regler
- bogen beskæftiger sig både med dynamisk og statisk scope
- vi lægger mest vægt på statisk scope her

Abstrakt syntaks Environment & store Udtryk Variabel-erklæringer Kommandoer Scoperegler Statisk binding

- brug for ny tilstandsmodel for at kunne erklære variable
- før: Tilstande = Var $ightharpoonup \mathbb{Z}$
- nu: Var ightharpoonup Loc $ightharpoonup \mathbb{Z}$
- Loc: lokationer; lager-adresser
- \Rightarrow en tilstand (*env_V*, *sto*) beskrives ved:
- env_V variabel-environment
- hvilken adresse er en given variabel bundet til?
- Env $V = Var \cup \{next\} \rightarrow Loc$
- next peger til næste frie lokation
- for os: Loc $= \mathbb{Z}$
- opdatering:

$$env_V[x \mapsto \ell](x') = egin{cases} env_V(x') & ext{hvis } x'
eq x \\ \ell & ext{hvis } x' = x \end{cases}$$

sto store

- Store = Loc $\rightarrow \mathbb{Z}$ • opdatering: $sto[\ell \mapsto \nu](\ell') = \begin{cases} sto(\ell') & \text{hvis } \ell' \neq \ell \\ \nu & \text{hvis } \ell' = \frac{\ell}{\ell_{l/18}} \end{cases}$

$$\begin{array}{ll} [\mathsf{plus}_{\mathsf{bss}}] & \frac{\mathsf{env}_{V}, \mathsf{sto} \vdash \mathsf{a}_{1} \to_{\mathsf{a}} \mathsf{v}_{1} \quad \mathsf{env}_{V}, \mathsf{sto} \vdash \mathsf{a}_{2} \to_{\mathsf{a}} \mathsf{v}_{2}}{\mathsf{env}_{V}, \mathsf{sto} \vdash \mathsf{a}_{1} + \mathsf{a}_{2} \to_{\mathsf{a}} \mathsf{v}} \\ & \mathsf{env}_{V}, \mathsf{sto} \vdash \mathsf{a}_{1} + \mathsf{a}_{2} \to_{\mathsf{a}} \mathsf{v} \end{array}$$

$$[\mathsf{minus}_\mathsf{bss}] \quad \frac{\mathsf{env}_V, \mathsf{sto} \vdash \mathsf{a}_1 \to_\mathsf{a} \mathsf{v}_1 \quad \mathsf{env}_V, \mathsf{sto} \vdash \mathsf{a}_2 \to_\mathsf{a} \mathsf{v}_2}{\mathsf{env}_V, \mathsf{sto} \vdash \mathsf{a}_1 - \mathsf{a}_2 \to_\mathsf{a} \mathsf{v}} \quad \mathsf{hvor} \ \mathsf{v} = \mathsf{v}_1 - \mathsf{v}_2 + \mathsf{v}_3 + \mathsf{v}_4 +$$

[mult_{bss}]
$$\frac{env_V, sto \vdash a_1 \rightarrow_a v_1 \quad env_V, sto \vdash a_2 \rightarrow_a v_2}{env_V, sto \vdash a_1 * a_2 \rightarrow_a v}$$

$$[\mathsf{parent}_{\mathsf{bss}}] \quad \frac{\mathsf{env}_{\mathsf{V}}, \mathsf{sto} \vdash \mathsf{a}_1 \, \to_{\mathsf{a}} \, \mathsf{v}_1}{\mathsf{env}_{\mathsf{V}}, \mathsf{sto} \vdash (\mathsf{a}_1) \, \to_{\mathsf{a}} \, \mathsf{v}_1}$$

hvor
$$v = v_1 \cdot v_2$$

[num_{bss}]
$$env_V$$
, $sto \vdash n \rightarrow_a v$

hvis
$$\mathcal{N}[\![n]\!]=
u$$

$$env_V$$
, $sto \vdash x \rightarrow_a v$

[var_{bss}]

hvis
$$sto(env_V(x)) = v$$

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Environment & store Udtryk Variabel-erklæringer Kommandoer Scoperegler Statisk binding

Abstrakt syntaks

ErkV:
$$D_V ::= \text{var } x := a; D_V \mid \varepsilon$$

- erklæringer modificerer env_V (pga. nye variable) og sto (pga. nye værdier til nye variable)
- ⇒ transitionssystem:
- konfigurationer

$$\Gamma_{DV} = \text{ErkV} \times \text{Env}_V \times \text{Store} \cup \text{Env}_V \times \text{Store}$$

- slutkonfigurationer $T_{DV} = \mathbf{Env}_V \times \mathbf{Store}$
- dvs. konfigurationer (D_V , env $_V$, sto) og (env $_V$, sto)

[var-erkl_{bss}]

$$\frac{\langle D_V, \textit{env}_V[x \mapsto \ell][\mathsf{next} \mapsto \mathsf{new}(\ell)], \textit{sto}[\ell \mapsto v] \rangle \to_{DV} \langle \textit{env}_V, \textit{sto}' \rangle}{\langle \forall \texttt{ar} \ x := a; D_V, \textit{env}_V, \textit{sto} \rangle \to_{DV} \langle \textit{env}_V, \textit{sto}' \rangle} \\ \mathsf{hvor} \ \textit{env}_V, \textit{sto} \vdash a \to_a v \ \mathsf{og} \ \ell = \textit{env}_V(\mathsf{next})$$

[tom-var-erkl_{bss}]
$$\langle \varepsilon, \textit{env}_V, \textit{sto} \rangle \rightarrow_{\textit{DV}} \langle \textit{env}_V, \textit{sto} \rangle$$

- big-step: variabelerklæringer sker i ét hug
- new : Loc \rightarrow Loc giver næste lokation; new $(\ell) = \ell + 1$

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 også procedure-environment env_P ∈ Env_P, til at holde styr på procedurer Abstrakt syntaks Environment & store Udtryk Variabel-erklæringer Kommandoer

Scoperegler

Statisk binding

- med tilhørende big-step-semantik for procedure-erklæringer $(\Gamma_{DP}, \rightarrow_{DP}, T_{DP})$
- men det snakker vi om senere

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- dvs. procedure-environment env_P, variabel-environment env_V og store sto
- men kommandoer kan ikke ændre env_V og env_P!
- \Rightarrow transitioner på formen env_V , $env_P \vdash \langle S, sto \rangle \rightarrow sto'$
- dvs. konfigurationer Kom x Store ∪ Store
- og slutkonfigurationer Store

Abstrakt syntaks Environment & store Udtryk Variabel-erklæringer Kommandoer Scoperegler Statisk binding

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$$[\mathsf{ass}_\mathsf{bss}] \qquad \textit{env}_V, \textit{env}_P \vdash \langle x := a, \textit{sto} \rangle \to \textit{sto}[\ell \mapsto \nu] \\ \mathsf{hvor} \; \textit{env}_V, \textit{sto} \vdash a \to_a \nu \; \mathsf{og} \; \textit{env}_V(x) = \ell \\ [\mathsf{skip}_\mathsf{bss}] \qquad \textit{env}_V, \textit{env}_P \vdash \langle \texttt{skip}, \textit{sto} \rangle \to \textit{sto}$$

$$[\mathsf{comp}_\mathsf{bss}] \quad \frac{\mathsf{env}_{V}, \mathsf{env}_{P} \vdash \langle S_1, \mathsf{sto} \rangle \to \mathsf{sto}'}{\mathsf{env}_{V}, \mathsf{env}_{P} \vdash \langle S_2, \mathsf{sto}'' \rangle \to \mathsf{sto}'} \\ = \frac{\mathsf{env}_{V}, \mathsf{env}_{P} \vdash \langle S_1; S_2, \mathsf{sto} \rangle \to \mathsf{sto}'}{\mathsf{env}_{V}, \mathsf{env}_{P} \vdash \langle S_1; S_2, \mathsf{sto} \rangle \to \mathsf{sto}'}$$

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$$[\text{while-sand}_{\text{bss}}] \quad \frac{\textit{env}_{V}, \textit{env}_{P} \vdash \langle S, \textit{sto} \rangle \rightarrow \textit{sto}'}{\textit{env}_{V}, \textit{env}_{P} \vdash \langle \texttt{while} \ b \ \texttt{do} \ S, \textit{sto}' \rangle \rightarrow \textit{sto}'}{\textit{env}_{V}, \textit{env}_{P} \vdash \langle \texttt{while} \ b \ \texttt{do} \ S, \textit{sto} \rangle \rightarrow \textit{sto}'} \\ \text{hvis} \quad \textit{env}_{V}, \textit{sto} \vdash b \rightarrow_{b} \textit{tt}}$$

$$[\text{while-falsk}_{\text{bss}}] \quad \textit{env}_{\textit{V}}, \textit{env}_{\textit{P}} \vdash \langle \text{while } b \text{ do } S, \textit{sto} \rangle \rightarrow \textit{sto} \\ \quad \text{hvis } \textit{env}_{\textit{V}}, \textit{sto} \vdash b \rightarrow_b \textit{ff} \\$$

$$\begin{array}{c} \langle D_{V}, env_{V}, sto \rangle \rightarrow_{DV} \langle env_{V}, sto'' \rangle \\ env_{V} \vdash \langle D_{P}, env_{P} \rangle \rightarrow_{DP} env_{P} \\ env_{V}, env_{P} \vdash \langle S, sto'' \rangle \rightarrow sto' \\ env_{V}, env_{P} \vdash \langle begin \ D_{V} \ D_{P} \ S \ end, sto \rangle \rightarrow sto' \end{array}$$

[blok_{bss}]

Abstrakt syntaks Environment & store Udtryk Variabel-erklæringer Kommandoer **Scoperegler** Statisk binding

- ullet dynamisk binding af variable og procedurer: y=10
- statisk binding af variable og procedurer: y = 9 (hint: det er et andet x !)
- også muligt: statisk binding af variable og dynamisk binding af procedurer, og omvendt

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statisk binding af variable og procedurer: ved procedure*kald* skal anvendes det variabel- og procedure-environment der fandtes ved *erklæringen*

Abstrakt syntaks Environment & store Udtryk Variabel-erklæringer Kommandoer Scoperegler Statisk binding

⇒ procedurer skal huske env_V og env_P

 \Rightarrow Env_P = Pnavne \rightarrow Kom \times Env_V \times Env_P

(Pnavne : procedurenavne)

ullet dvs. **Env** $_P$ består af partielle afbildninger $p\mapsto \langle S, \mathit{env}_V, \mathit{env}_P
angle$

S: procedure"kroppen"

• env_V , env_P : variabel- og procedure-environment da p blev erklæret

en rekursiv definition!

big-step-semantik:

tilstande ErkP × Env_P ∪ Env_P

sluttilstande Env_P

transitioner → DP

Abstrakt syntaks Environment & store Udtryk Variabel-erklæringer Kommandoer Scoperegler Statisk binding

$$\frac{\textit{env}_{V} \vdash \langle D_{P}, \textit{env}_{P}[p \mapsto (S, \textit{env}_{V}, \textit{env}_{P})] \rangle \rightarrow_{\textit{DP}} \textit{env}_{P}}{\textit{env}_{V} \vdash \langle \texttt{proc} \textit{p} \texttt{is} \textit{S}; \textit{D}_{P}, \textit{env}_{P} \rangle \rightarrow_{\textit{DP}} \textit{env}_{P}}$$

$$[\mathsf{proc\text{-}tom}_{\mathsf{bss}}] \quad \textit{env}_{\mathit{V}} \vdash \langle \varepsilon, \textit{env}_{\mathit{P}} \rangle \rightarrow_{\mathit{DP}} \textit{env}_{\mathit{P}}$$

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Procedurer med parametre



Værdiparametre

Rekursion

Værdiparametre

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Referenceparametre

Kom: $S ::= x := a \mid \text{skip} \mid S_1; S_2 \mid \text{if } b \text{ then } S_1 \text{ else } S_2$ while b do Sbegin D_V D_P S end | call ho(y)

At udvide **Bip** med procedurer med én referenceparameter:

ErkV: $D_V ::= \text{var } x := a; D_V \mid \varepsilon$

ErkP: $D_P ::= \operatorname{proc} \rho(\operatorname{var} x) \text{ is } S; D_P \mid \varepsilon$

- referenceparametre: den formelle parameter x er en reference til adressen på den aktuelle parameter y
- (klares ved pointers i c)
- Eksempel: begin

 \Rightarrow y = 4

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Referenceparametre Rekursion

Værdiparametre

procedure-environment:

$$\mathsf{Env}_{\mathcal{P}} = \mathsf{Pnavne} o \mathsf{Kom} imes \mathsf{Var} imes \mathsf{Env}_{\mathcal{V}} imes \mathsf{Env}_{\mathcal{P}}$$

- skal huske navnet på den formelle parameter
- at erklære procedurer:

$$[\operatorname{proc}_{\operatorname{bss}}] \quad \frac{\operatorname{\textit{env}}_V \vdash \langle D_P, \operatorname{\textit{env}}_P[p \mapsto (S, x, \operatorname{\textit{env}}_V, \operatorname{\textit{env}}_P)] \rangle \rightarrow_{DP} \operatorname{\textit{env}}_P}{\operatorname{\textit{env}}_V \vdash \langle \operatorname{proc} p(\operatorname{var} x) \text{ is } S; D_P, \operatorname{\textit{env}}_P \rangle \rightarrow_{DP} \operatorname{\textit{env}}_P}$$

[proc-tom_{bss}] $env_V \vdash \langle \varepsilon, env_P \rangle \rightarrow_{DP} env_P$

at kalde procedurer:

Værdiparametre

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 $env_V[x \mapsto \ell][\mathsf{next} \mapsto \ell'], env_P \vdash \langle S, sto \rangle \to sto'$

Rekursion

$$env_{V}, env_{P} \vdash \langle ext{call } p(y), sto
angle
ightarrow sto'$$
 hvor $env_{P}(p) = (S, x, env_{V}, env_{P}),$

 $\ell = env_V(y) \text{ og } \ell' = env_V(\text{next})$

[call-ref_{bss}]

Problem: dén regel tillader ikke rekursive procedurekald

fordi env_p er procedure-environmentet fra før p blev erklæret

Løsning: ny regel

(kan også klares ved at modificere [proc_{bss}] i stedet (hvordan?))

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At udvide **Bip** med procedurer med én værdiparameter:

Kom: $S ::= x := a \mid \text{skip} \mid S_1; S_2 \mid \text{if } b \text{ then } S_1 \text{ else } S_2 \mid \text{while } b \text{ do } S \mid \text{begin } D_V \mid D_P \mid S \mid \text{end} \mid \text{call } p(a)$

ErkV: $D_V ::= \text{var } x := a; D_V \mid \varepsilon$

ErkP: $D_P ::= \operatorname{proc} p(\operatorname{var} x) \text{ is } S; D_P \mid \varepsilon$

- værdiparametre: den formelle parameter x bliver til en lokal variabel i proceduren, med startværdi = værdien af den aktuelle parameter
- Eksempel: begin

en

⇒ y = 3

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Værdiparametre

• procedure-erklæringer (uændret):

 $[\operatorname{proc}_{\operatorname{bss}}] \quad \frac{\operatorname{\textit{env}}_V \vdash \langle D_P, \operatorname{\textit{env}}_P[p \mapsto (S, x, \operatorname{\textit{env}}_V, \operatorname{\textit{env}}_P)] \rangle \rightarrow_{DP} \operatorname{\textit{env}}_P}{\operatorname{\textit{env}}_V \vdash \langle \operatorname{proc} p (\operatorname{var} x) \text{ is } S; D_P, \operatorname{\textit{env}}_P \rangle \rightarrow_{DP} \operatorname{\textit{env}}_P}$

 $[\mathsf{proc}\text{-}\mathsf{tom}_{\mathsf{bss}}] \quad \mathit{env}_{\mathit{V}} \vdash \langle \varepsilon, \mathit{env}_{\mathit{P}} \rangle \rightarrow_{\mathit{DP}} \mathit{env}_{\mathit{P}}$

procedurekald:

$$[\text{call-val}_{bss}] \begin{tabular}{l} & env_V[x\mapsto\ell][\text{next}\mapsto \text{new}(\ell)], env_P\\ & \vdash \langle S, sto[\ell\mapsto\nu] \rangle \to sto\\ & env_V, env_P \vdash \langle \texttt{call} \ p(a), sto \rangle \to sto\\ & \text{hvor } env_P(p) = (S, x, env_V, env_P),\\ & env_V, sto \vdash a \to_a v \text{ og } \ell = env_V(\text{next}) \end{tabular}$$

$$[\text{call-val-rec}_{\text{bss}}] = \frac{env_{\nu}[x \mapsto \ell][\text{next} \mapsto \text{new}(\ell)],}{env_{\rho}[p \mapsto (S, x, env_{\nu}, env_{\rho})]}$$

$$+ \langle S, sto[\ell \mapsto \nu] \rangle \to sto'$$

$$+ \langle \text{call} p(a), sto \rangle \to sto'$$

$$+ \langle \text{nv}_{\nu} \mapsto \text{nv}_{\nu}(p) = (S, x, env_{\nu}, env_{\rho}),$$

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