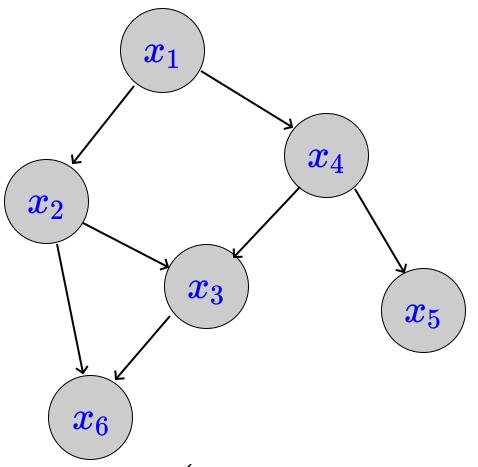
50.007 Machine Learning

Lu, Wei

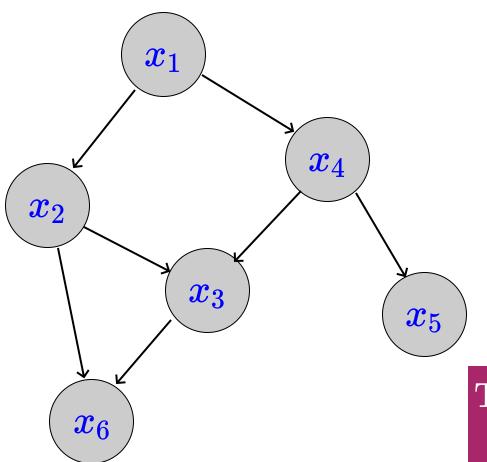


Bayesian Networks (II)



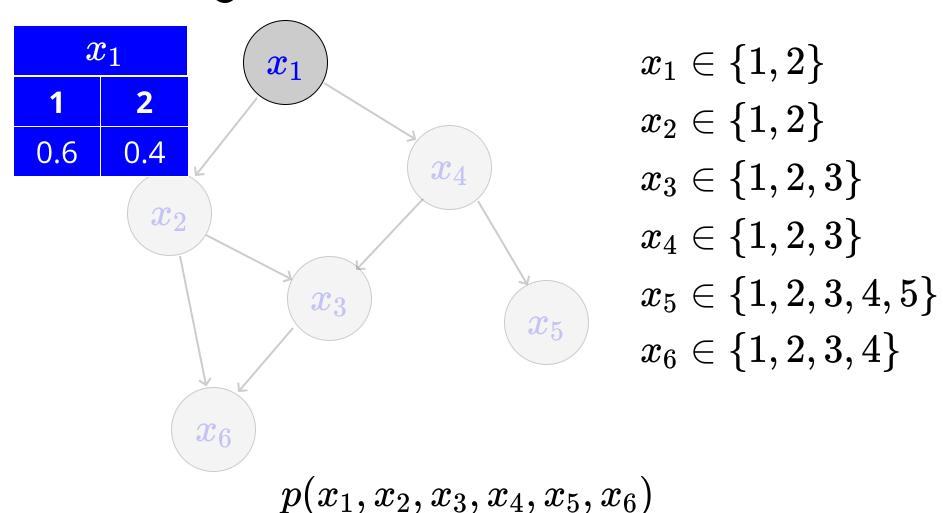
$$p(x_1, x_2, x_3, x_4, x_5, x_6)$$

 $=p(x_1)p(x_2|x_1)p(x_4|x_1)p(x_3|x_2,x_4)p(x_6|x_2,x_3)p(x_5|x_4)$

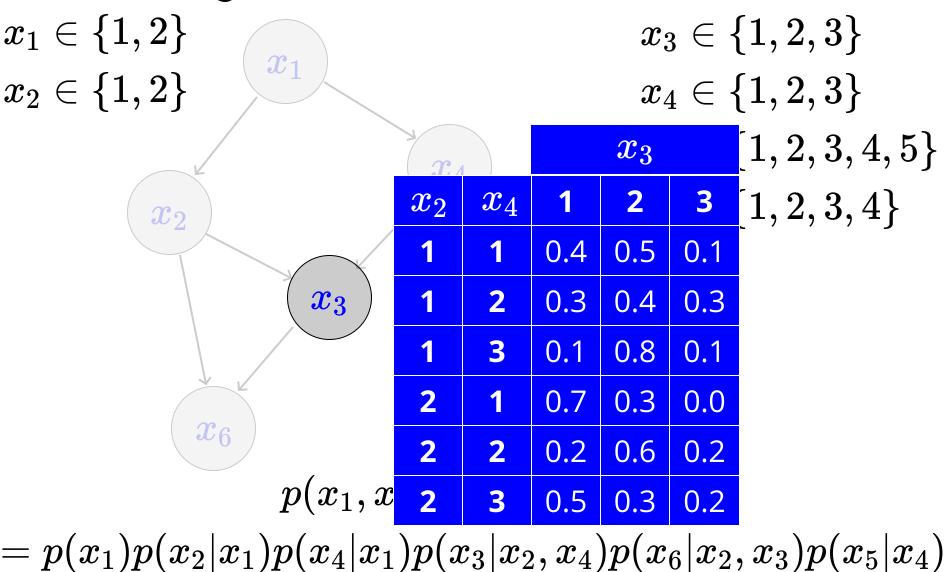


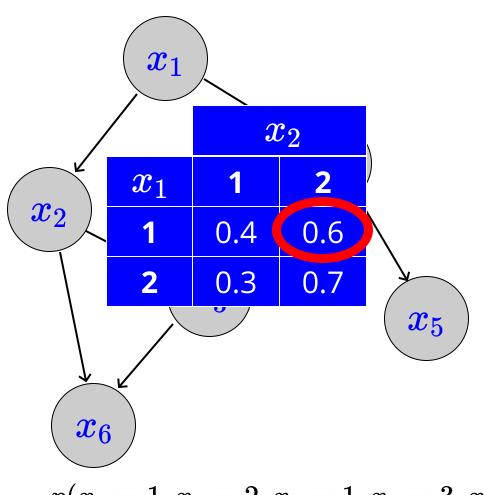
The set of parent nodes for x_i .

$$p(x_1,\ldots,x_d) = \prod_{i=1}^d p(x_i|\mathbf{x}_{pa_i})$$



 $=p(x_1)p(x_2|x_1)p(x_4|x_1)p(x_3|x_2,x_4)p(x_6|x_2,x_3)p(x_5|x_4)$





$$egin{align} p(x_1=1,x_2=2,x_3=1,x_4=3,x_5=5,x_6=2) \ = p(x_1=1) imes p(x_2=2|x_1=1) imes p(x_4=3|x_1=1) \ \end{array}$$

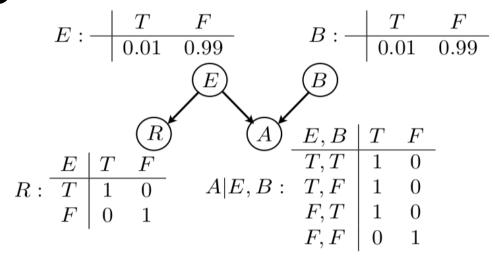
 $imes p(x_3=1|x_2=2,x_4=3) imes p(x_6=2|x_2=2,x_3=1) imes p(x_5=5|x_4=3)$

$$\begin{array}{ll} P(B=b,A=T) \\ = & \sum_{e \in \{T,F\}} \sum_{r \in \{T,F\}} P(E=e) P(B=b) P(A=T|E=e,B=b) P(R=r|E=e) \\ = & \sum_{e \in \{T,F\}} P(E=e) P(B=b) P(A=T|E=e,B=b) \sum_{r \in \{T,F\}} P(R=r|E=e) \\ = & \sum_{e \in \{T,F\}} P(E=e) P(B=b) P(A=T|E=e,B=b) \\ = & P(B=b) \sum_{e \in \{T,F\}} P(E=e) P(A=T|E=e,B=b) \end{array}$$

$$P(B=T|A=T) = rac{P(B=T,A=T)}{\sum_{b\in IT} P(B=b,A=T)} = 0.5025\dots$$

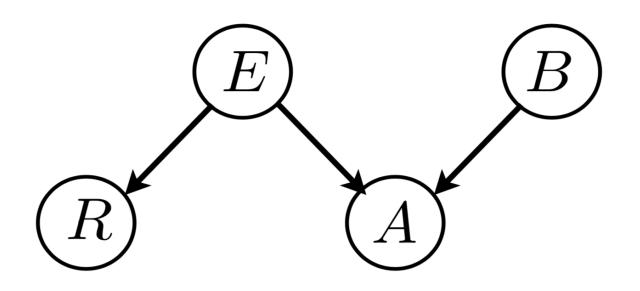
$$\begin{array}{ll} P(B=b,A=T,E=T) \\ = & \sum_{r \in \{T,F\}} P(E=T) P(B=b) P(A=T|E=e,B=b) P(R=r|E=T) \\ = & P(E=T) P(B=b) P(A=T|E=T,B=b) \sum_{r \in \{T,F\}} P(R=r|E=T) \\ = & P(E=T) P(B=b) P(A=T|E=T,B=b) \end{array}$$

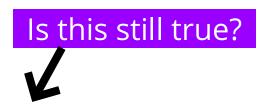
$$P(B=T|A=T,E=T) = rac{P(B=T,A=T,E=T)}{\sum_{b \in \{T,F\}} P(B=b,A=T,E=T)} = 0.01$$



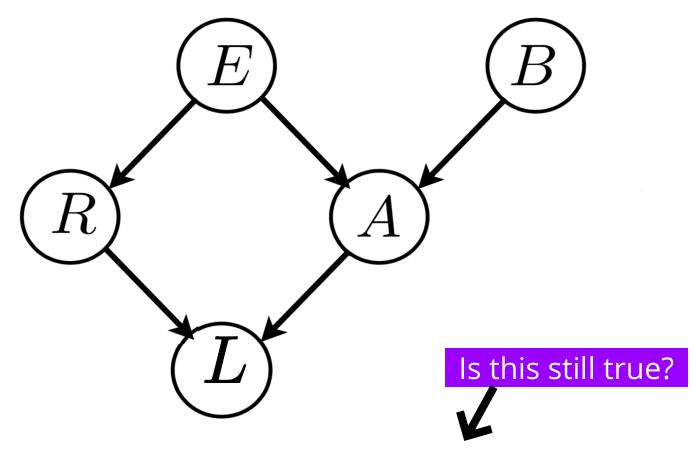
$$\begin{array}{ll} P(B=b,A=T,E=T) \\ = & \sum_{r \in \{T,F\}} P(E=T) P(B=b) P(A=T|E=e,B=b) P(R=r|E=T) \\ = & P(E=T) P(B=b) P(A=T|E=T,B=b) \sum_{r \in \{T,F\}} P(R=r|E=T) \\ = & P(E=T) P(B=b) P(A=T|E=T,B=b) \end{array}$$

E and B are not conditionally independent given A

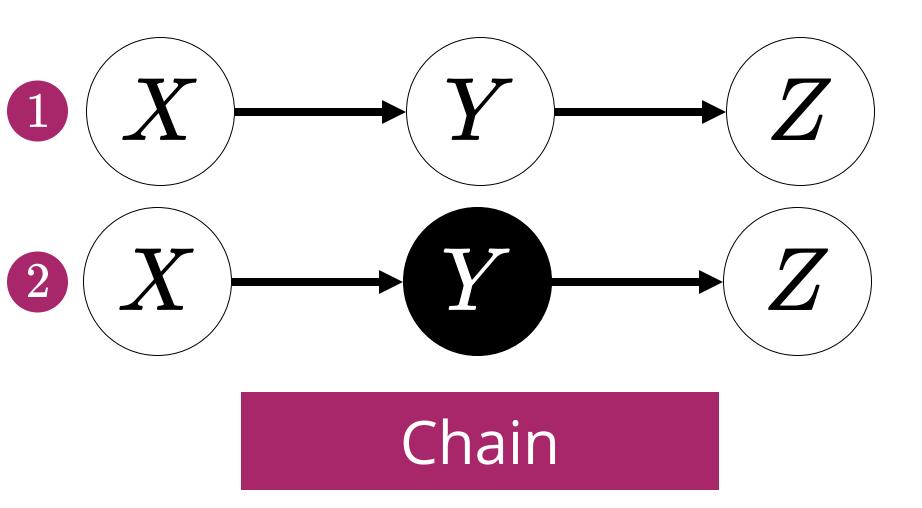




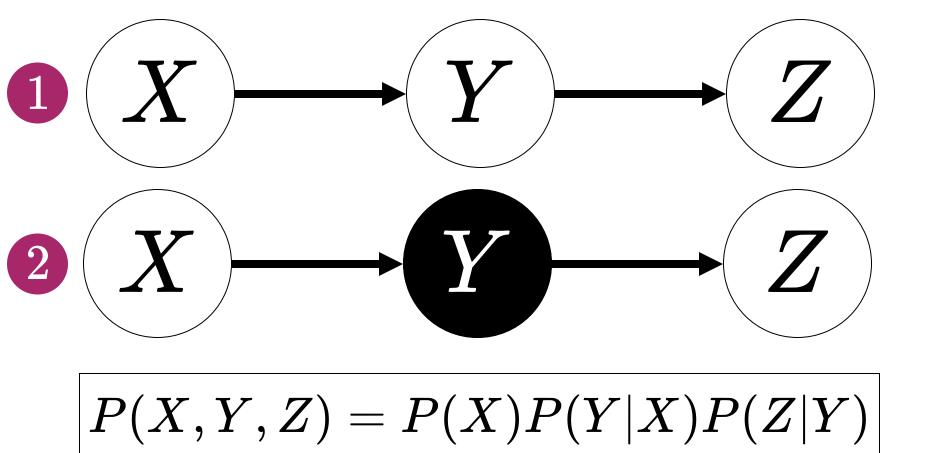
E and B are not conditionally independent given A

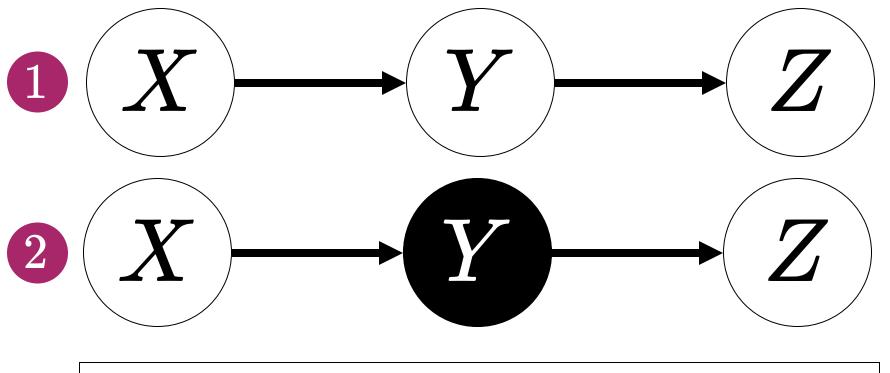


E and B are not conditionally independent given A



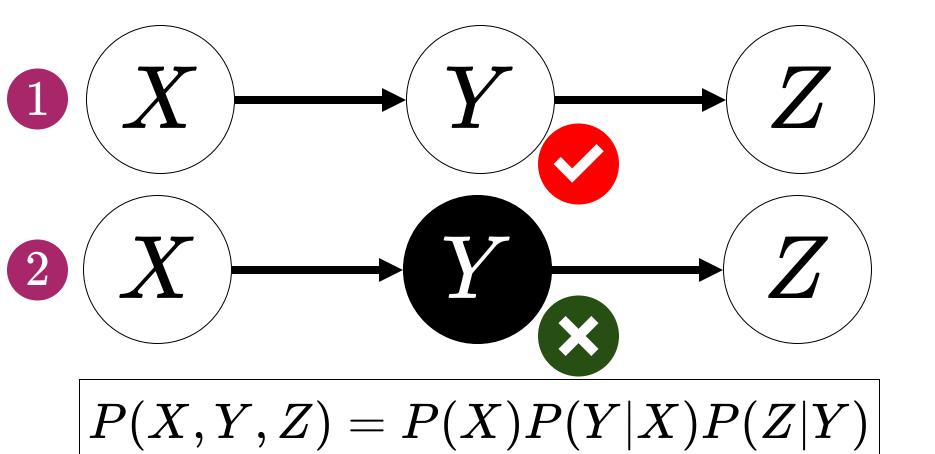
In which case X and Z are independent?



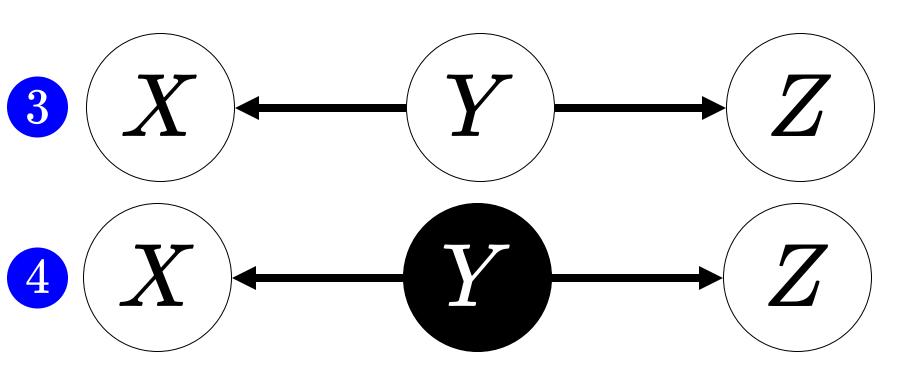


$$P(X,Y,Z) = P(X)P(Y|X)P(Z|Y)$$

$$P(Z|X,Y) = rac{P(X,Y,Z)}{P(X,Y)} = rac{P(X)P(Y|X)P(Z|Y)}{P(X)P(Y|X)} = P(Z|Y)$$

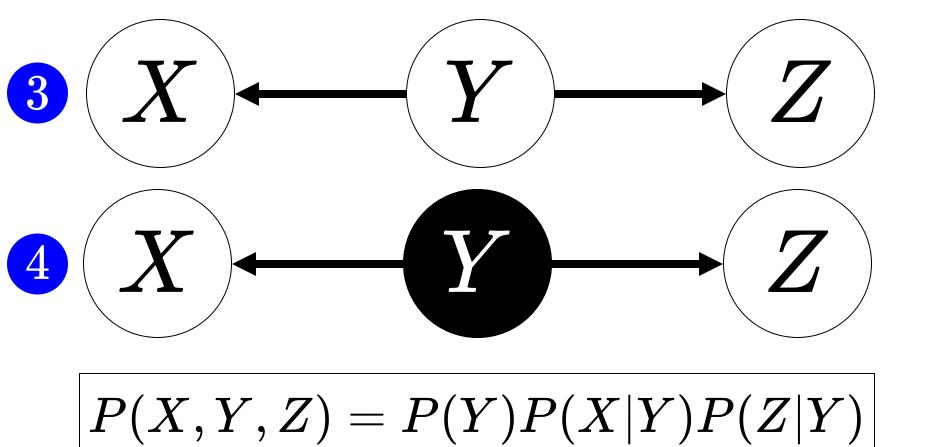


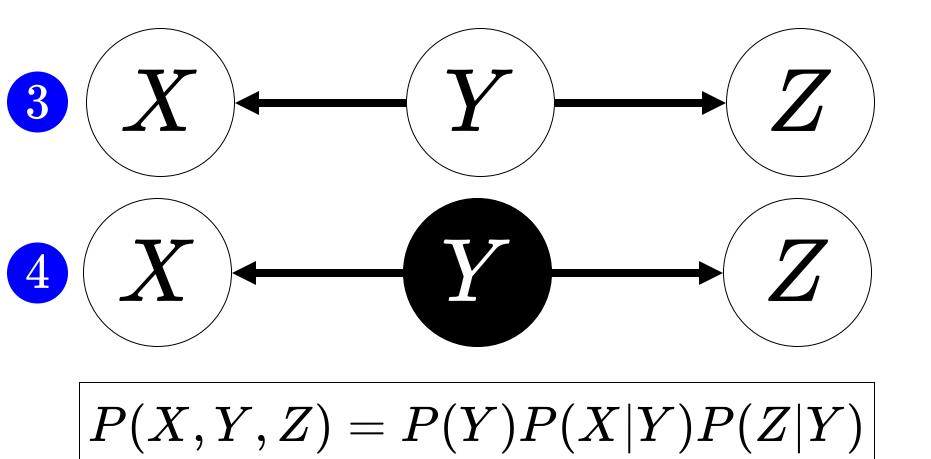
$$P(Z|X,Y)=rac{P(X,Y,Z)}{P(X,Y)}=rac{P(X)P(Y|X)P(Z|Y)}{P(X)P(Y|X)}=P(Z|Y)$$



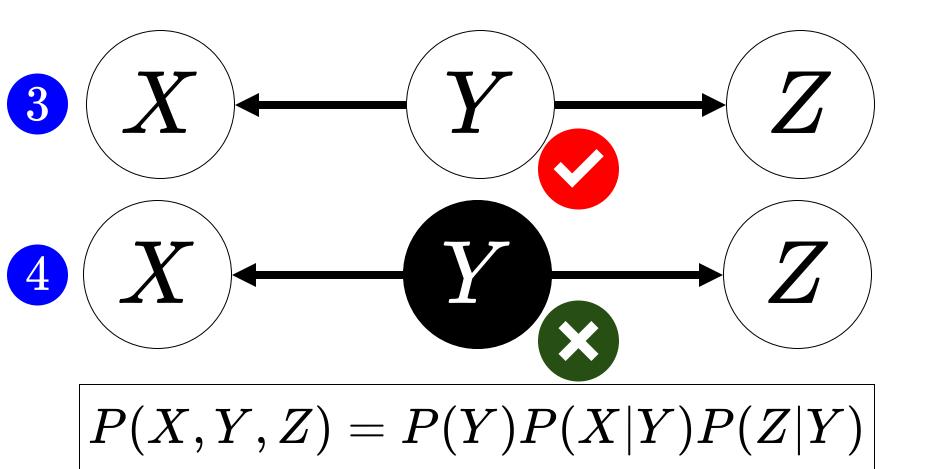
Common Cause

In which case X and Z are independent?

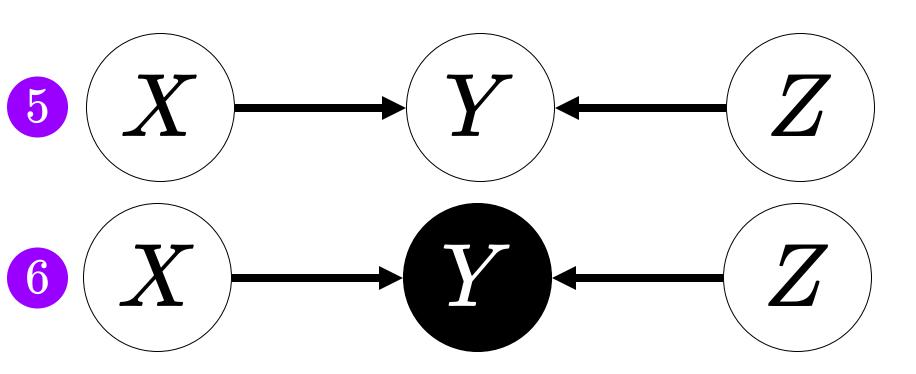




$$P(Z|X,Y) = rac{P(X,Y,Z)}{P(X,Y)} = rac{P(Y)P(X|Y)P(Z|Y)}{P(Y)P(X|Y)} = P(Z|Y)$$

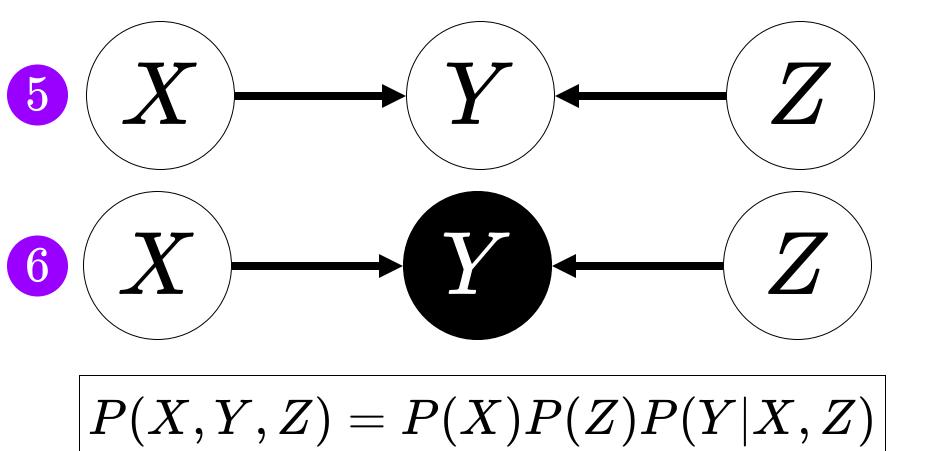


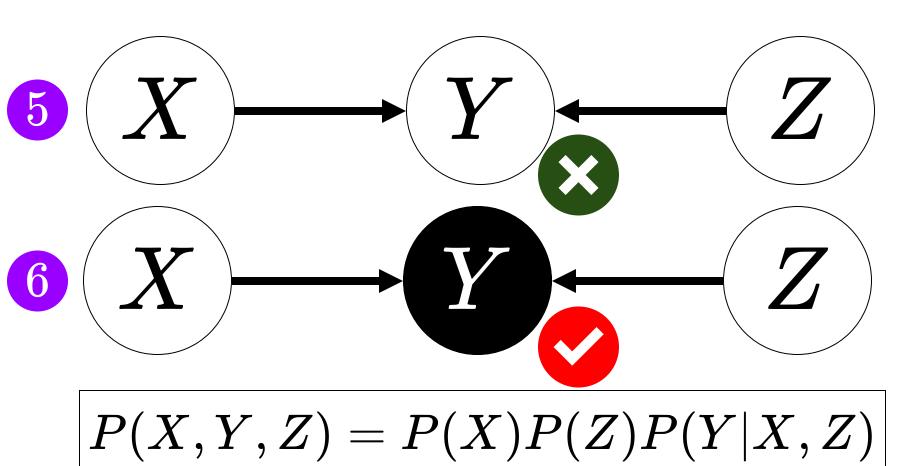
$$P(Z|X,Y) = rac{P(X,Y,Z)}{P(X,Y)} = rac{P(Y)P(X|Y)P(Z|Y)}{P(Y)P(X|Y)} = P(Z|Y)$$



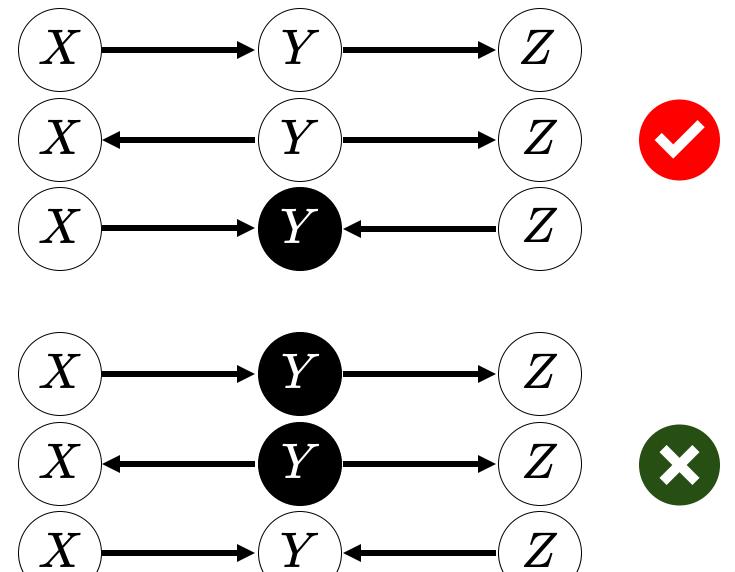
Explaining Away

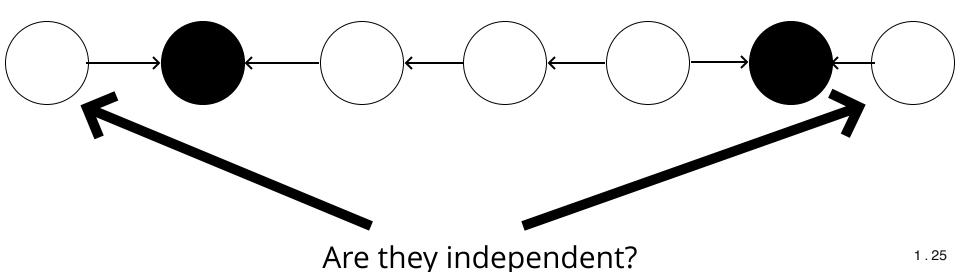
In which case X and Z are independent?



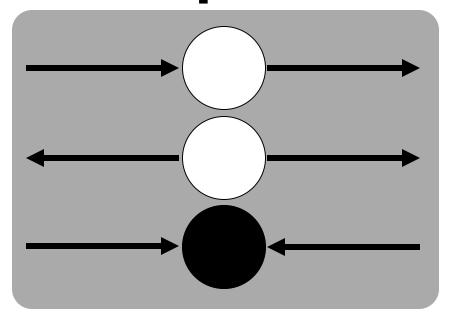


$$P(X,Z) = \sum_{Y} P(X)P(Z)P(Y|X,Z) = P(X)P(Z)\sum_{Y} P(Y|X,Z) = P(X)P(Z)$$

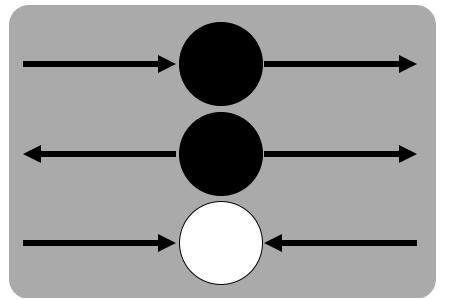




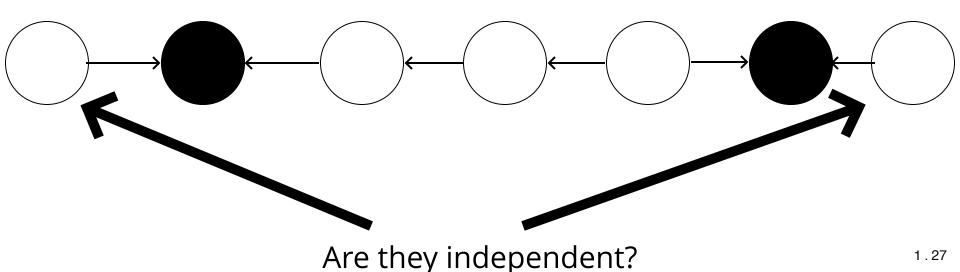
1.25





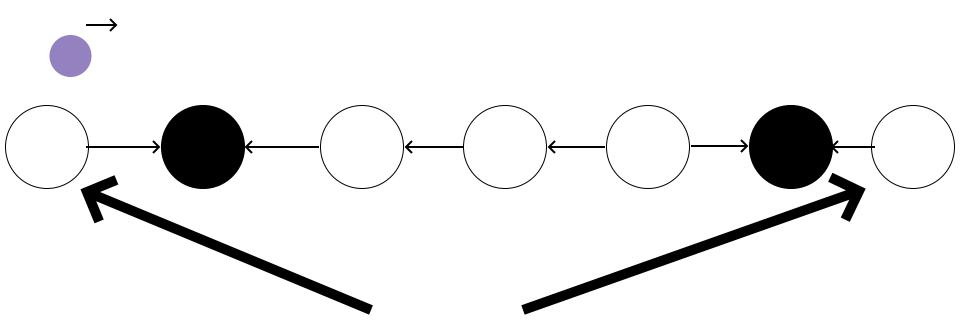


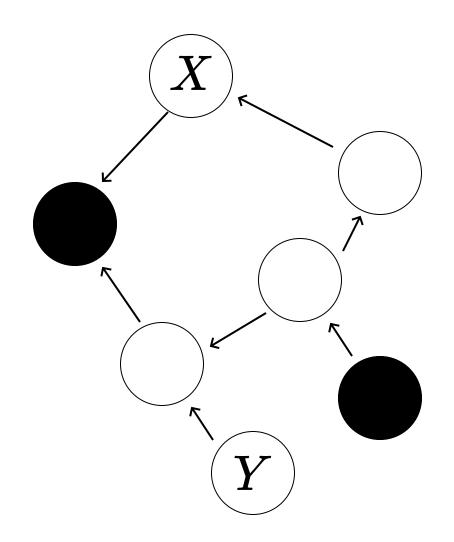


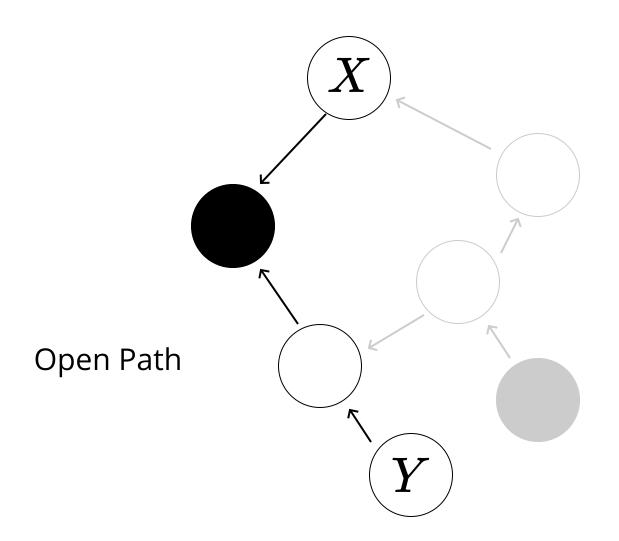


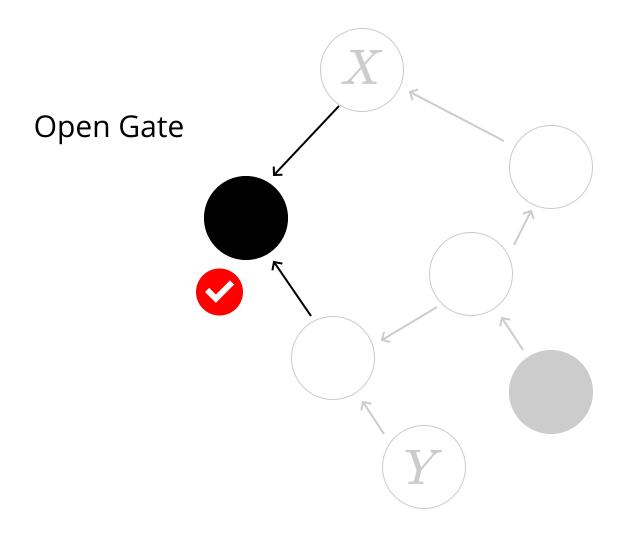
1.27

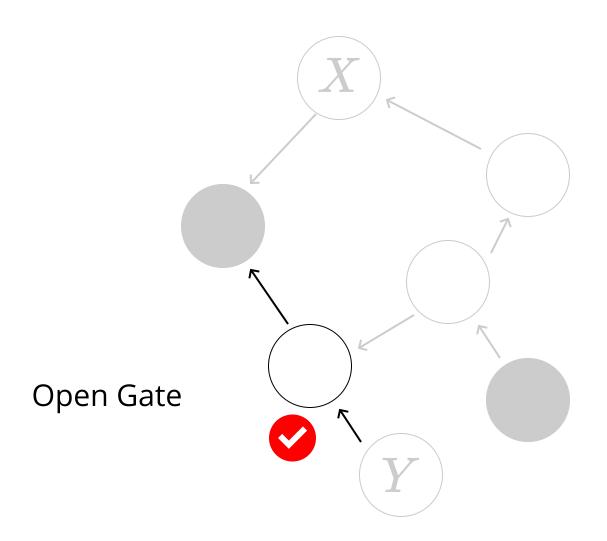
Can the ball reach the other node from one node (passing through various gates along the path)? If there is such a path where all gates are open, then they are not independent. Otherwise they are independent.

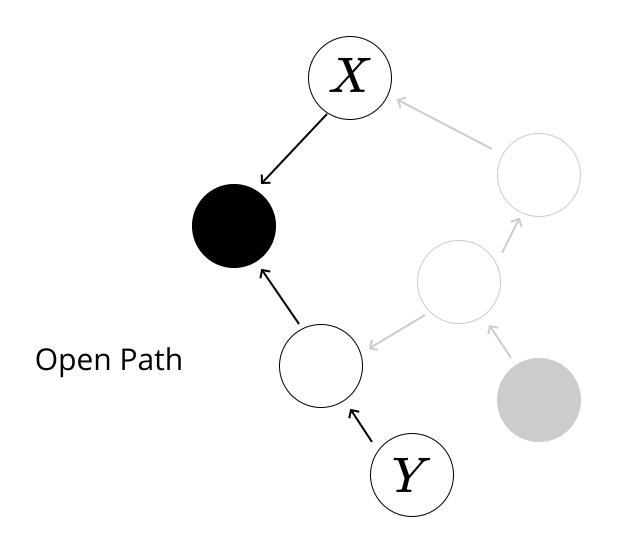


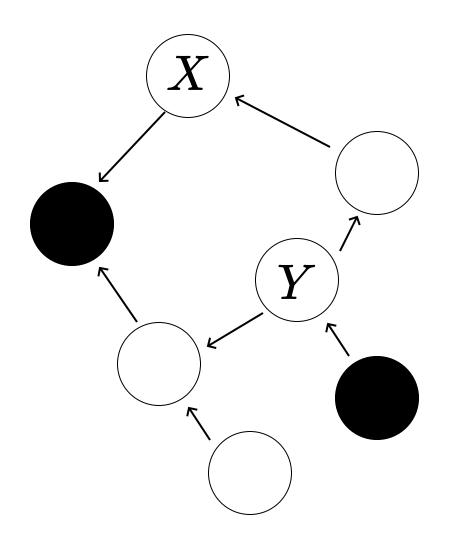


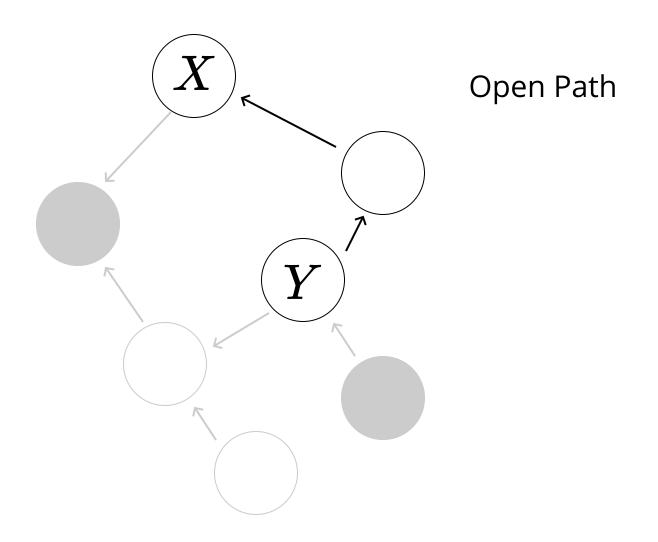


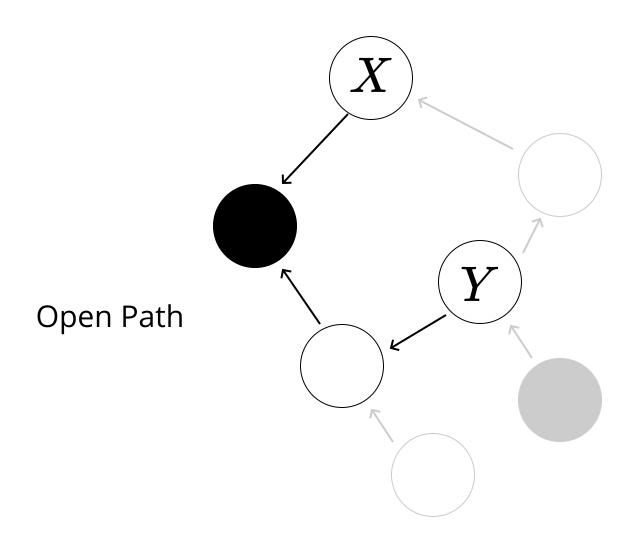


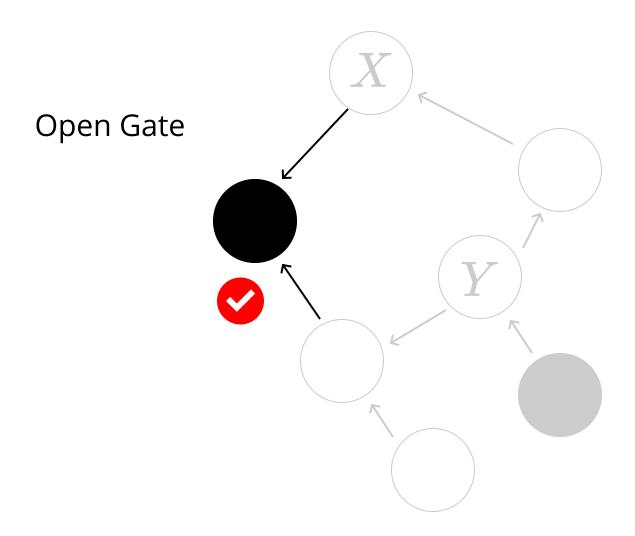


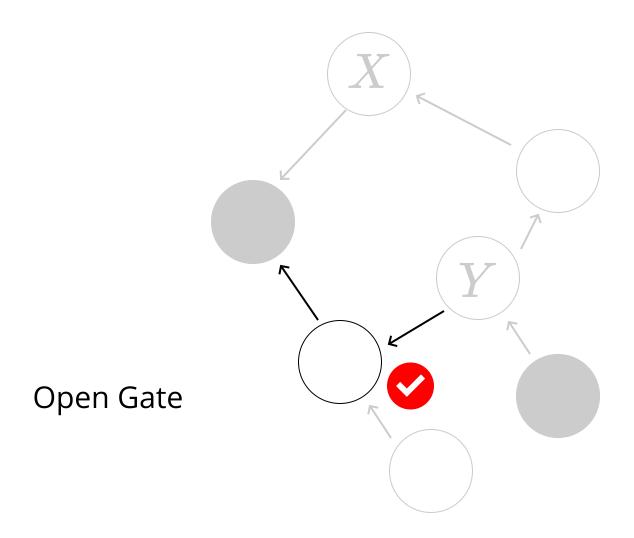


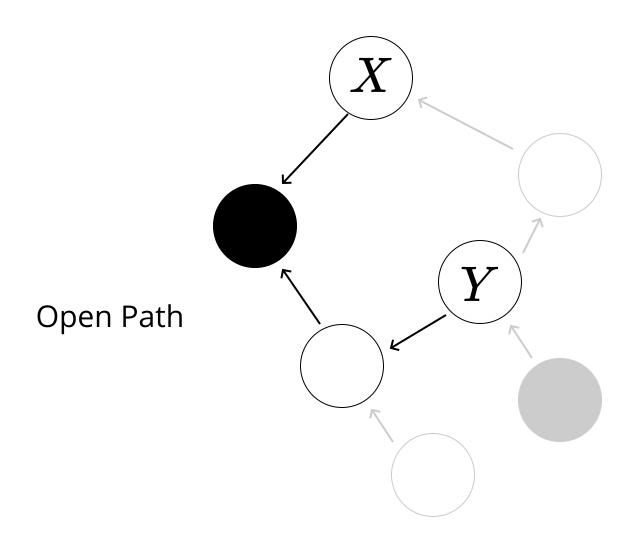


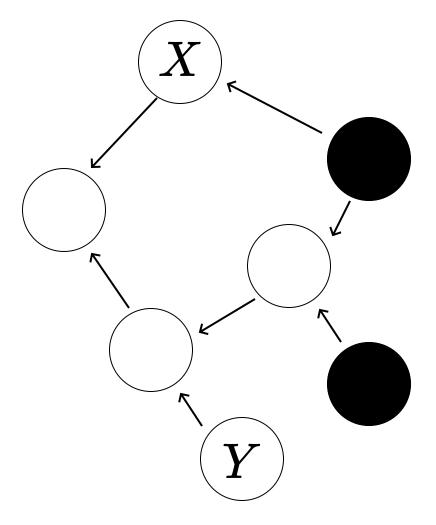


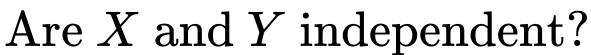


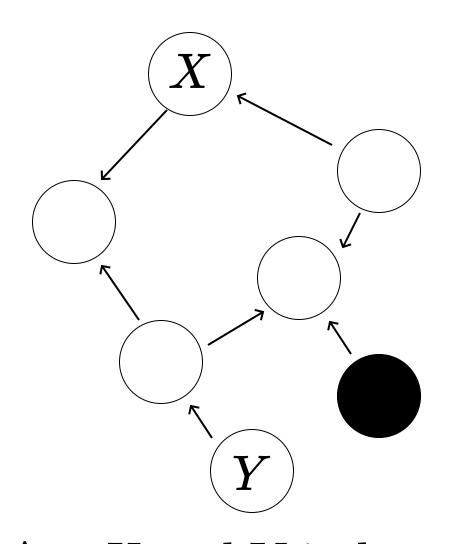




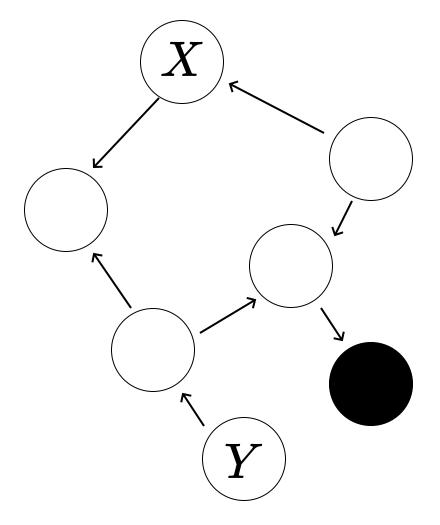


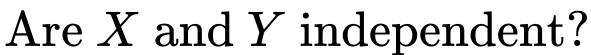


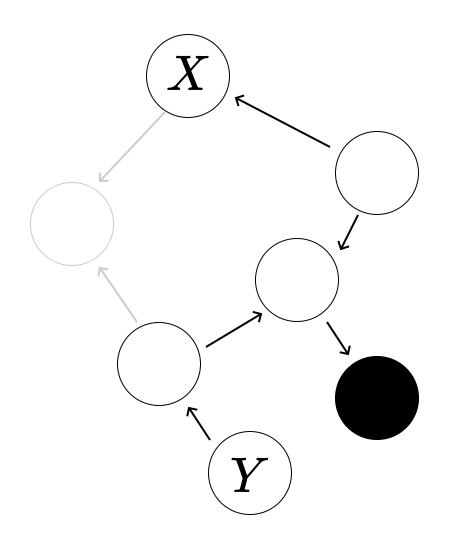


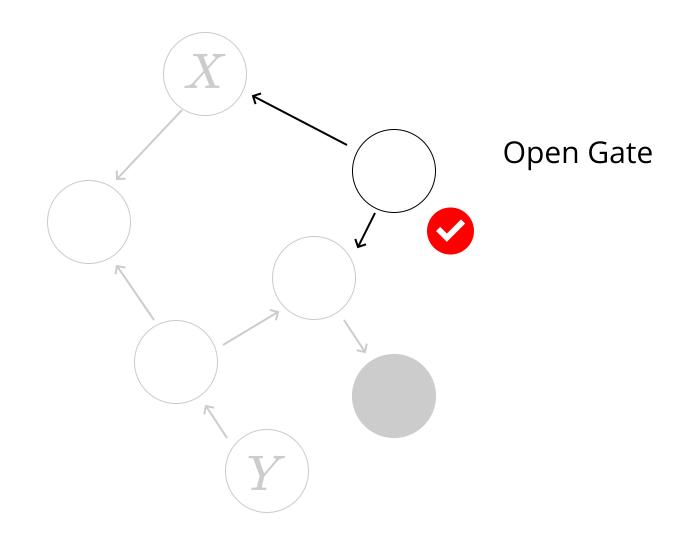


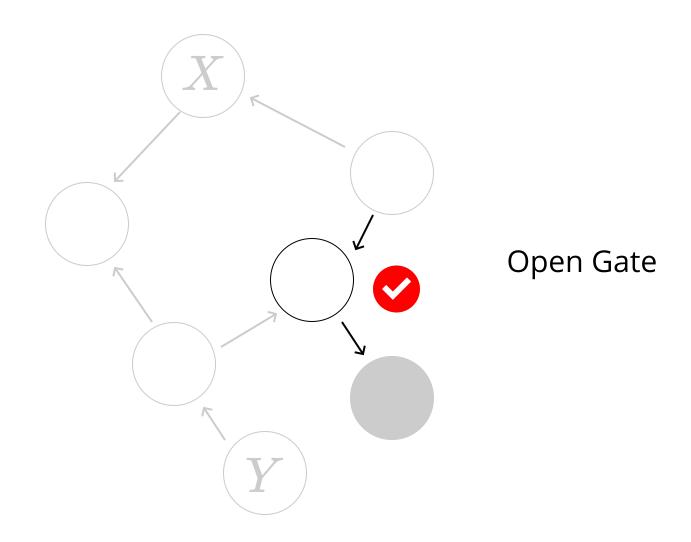


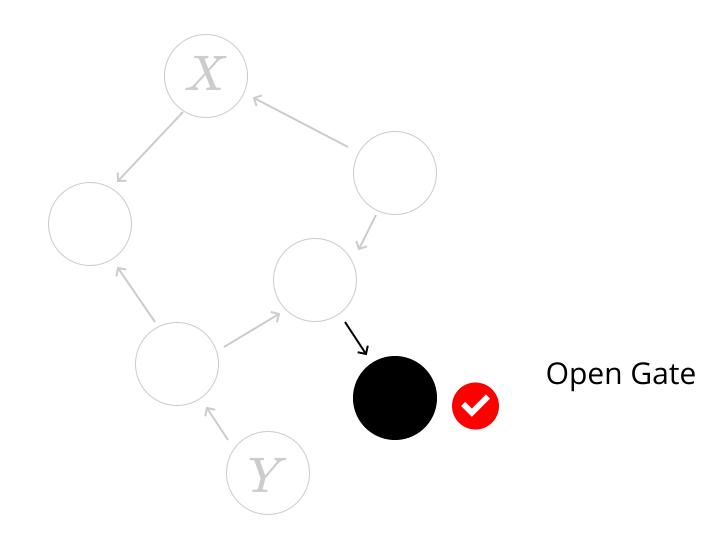


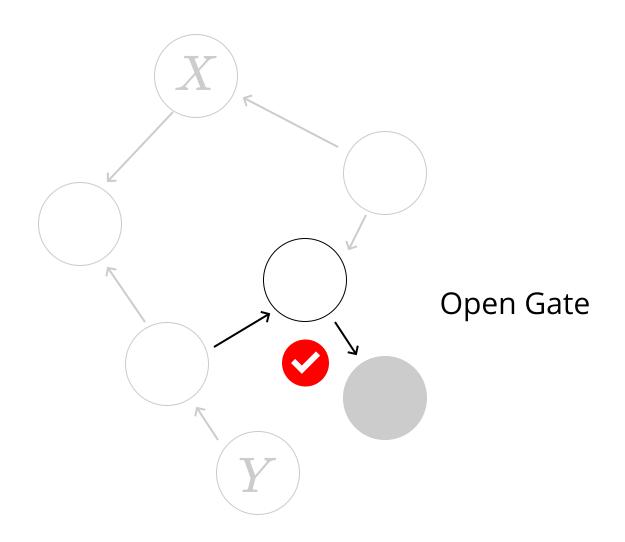


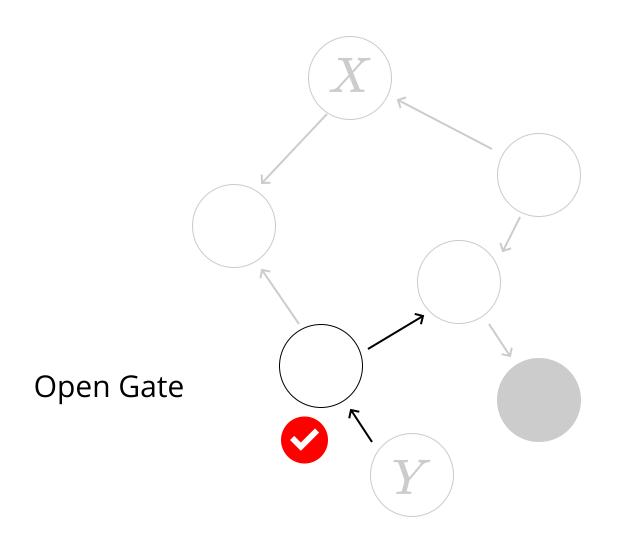


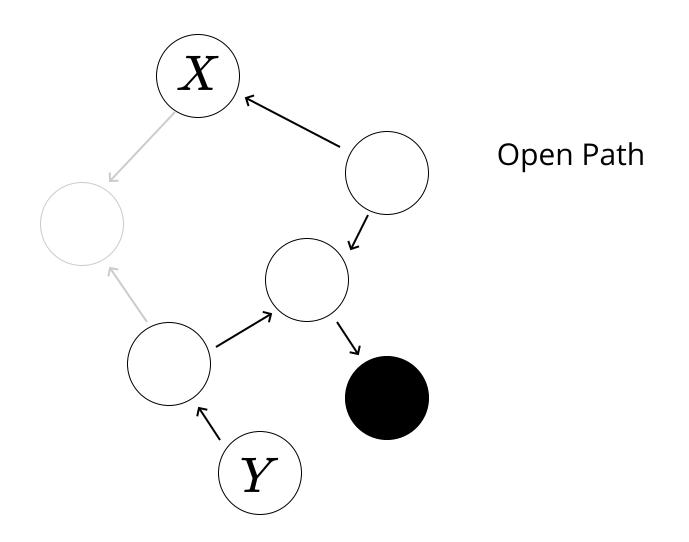




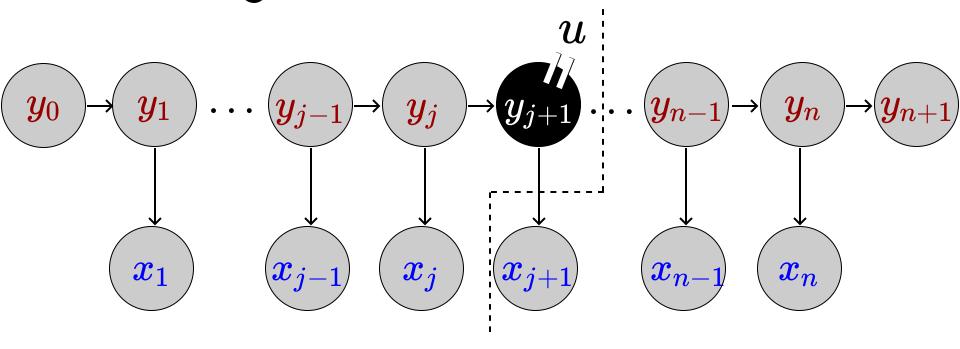






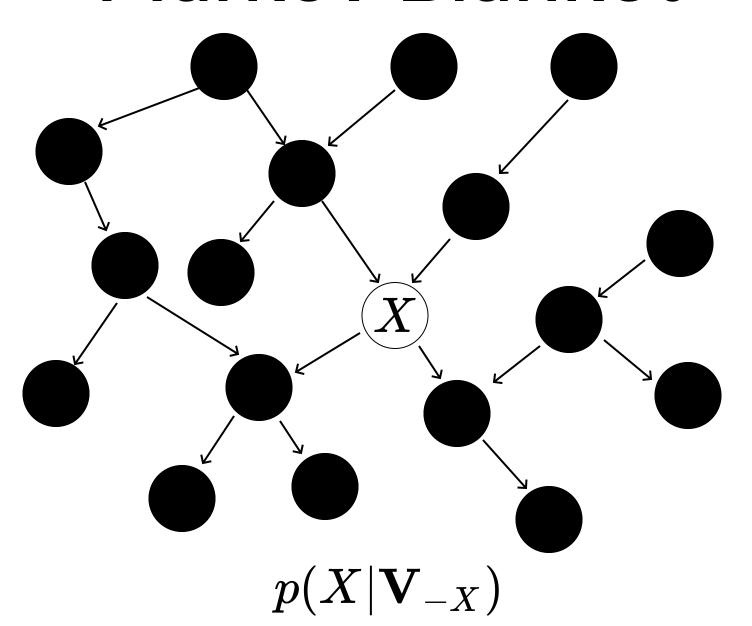


Bayes Net - HMM

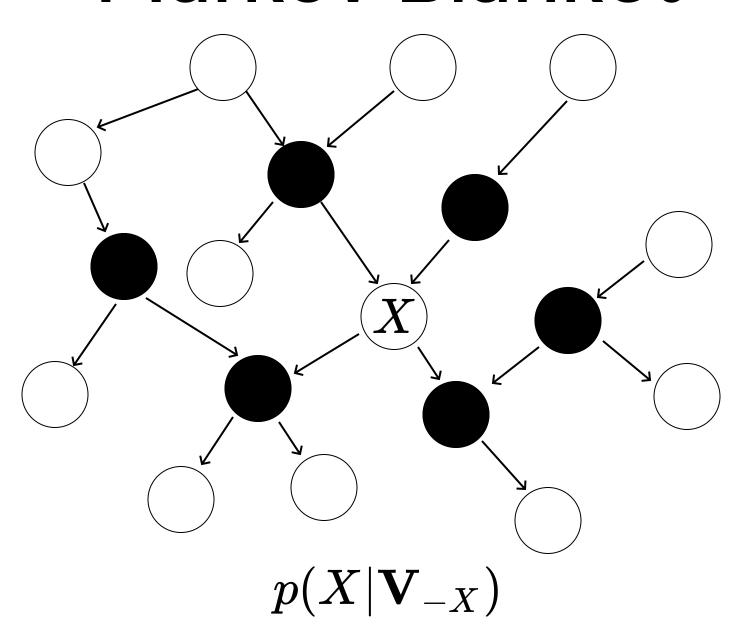


Given $y_{j+1} = u$, now we can see the two portions of the network are independent of each other.

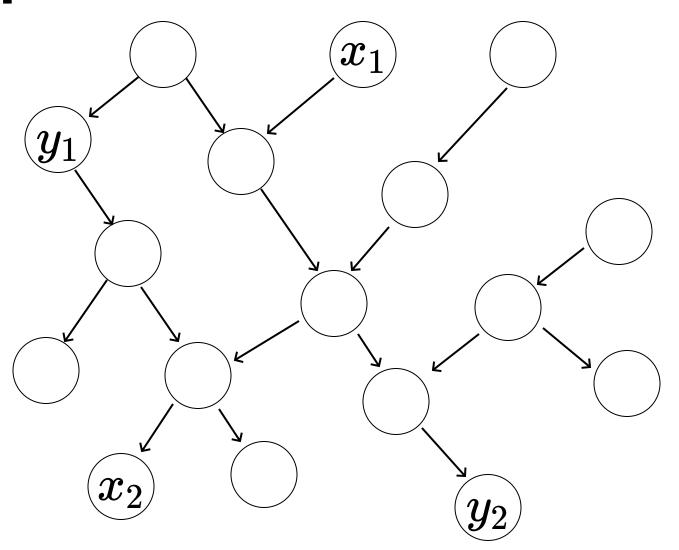
Markov Blanket



Markov Blanket

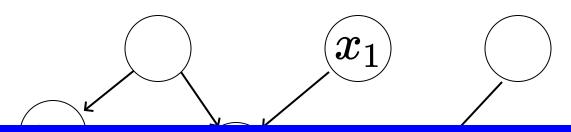


Approximate Inference



$$p(y_1 = 1, y_2 = 2 | x_1 = 1, x_2 = 3) = ?$$

Approximate Inference

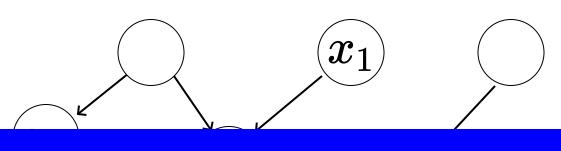


What if we have a large collection of samples:

X1	X2	 Y1	Y2	•••
1	3	1	1	
1	3	1	2	
1	3	2	2	
1	3	2	2	
	(x_2)		(y_2)	

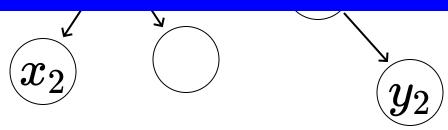
$$p(y_1 = 1, y_2 = 2 | x_1 = 1, x_2 = 3) = ?$$

Approximate Inference



We need a way to generate samples from:

$$p(\mathbf{y}|\mathbf{x})$$
 all other evidence variables (what's given)



$$p(y_1 = 1, y_2 = 2 | x_1 = 1, x_2 = 3) = ?$$

tional

Gibbs Sampling

- 1. Randomly initialize $\mathbf{y}^{(0)} = \langle y_1^{(0)}, y_2^{(0)}, \dots, y_n^{(0)} \rangle$
- 2. For t = 1, ..., T do
 - $y_k^{(t)} \sim P(y_k|y_1^{(t)},\dots,y_{k-1}^{(t)},y_{k+1}^{(t-1)},y_{k+2}^{(t-1)},\dots,y_n^{(t-1)},\mathbf{x})$
 - (b) Collect the t-th sample as $\langle y_1^{(t)}, y_2^{(t)}, \dots, y_n^{(t)} \rangle$
- 3. Return the collection of samples



These samples are from $p(\mathbf{y}|\mathbf{x})$

kional

Gibbs Sampling

- 1. Randomly initialize $\mathbf{y}^{(0)} = \langle y_1^{(0)} \rangle$ conditional probability
- 2. For t = 1, ..., T do
 - (a) For $k = 1, \ldots, n$ do

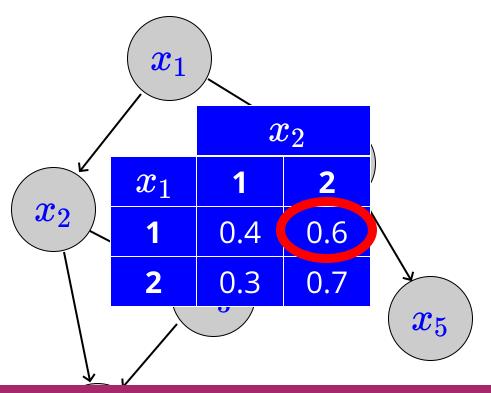
$$y_k^{(t)} \sim P(y_k|y_1^{(t)}, \dots, y_{k-1}^{(t)}, y_{k+1}^{(t-1)}, y_{k+2}^{(t-1)}, \dots, y_n^{(t-1)}, \mathbf{x})$$

with Markov blanket

- (b) Collect the t-th sample as $\langle y_1^{(t)}, y_2^{(t)}, \dots, y_n^{(t)} \rangle$
- 3. Return the collection of samples

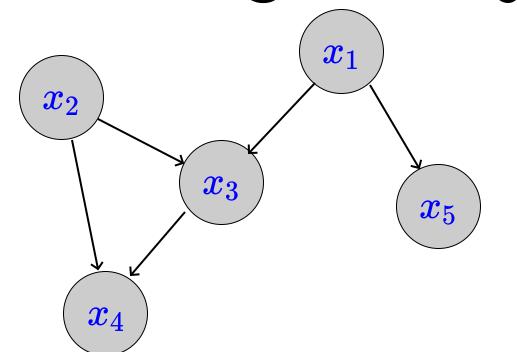


You may use then to perform approximate inference



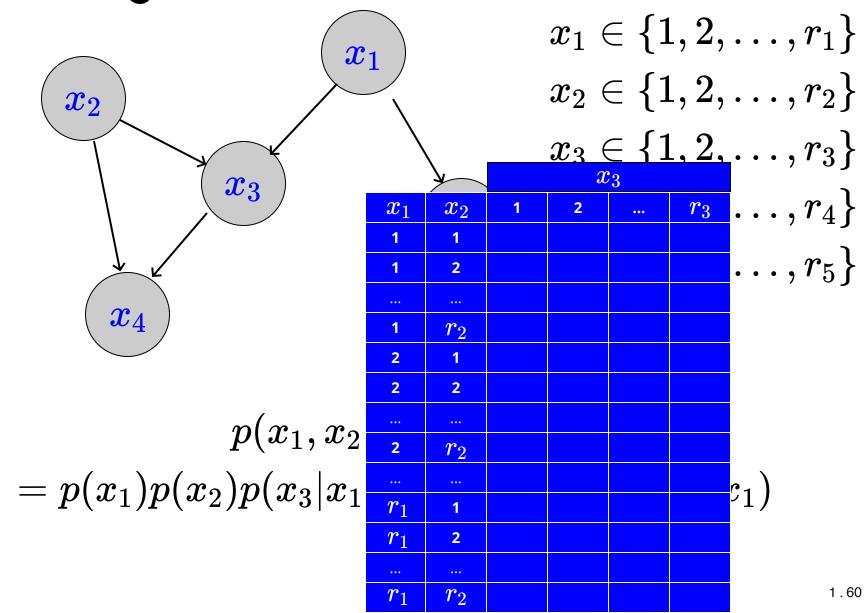
How do we learn such probability values?

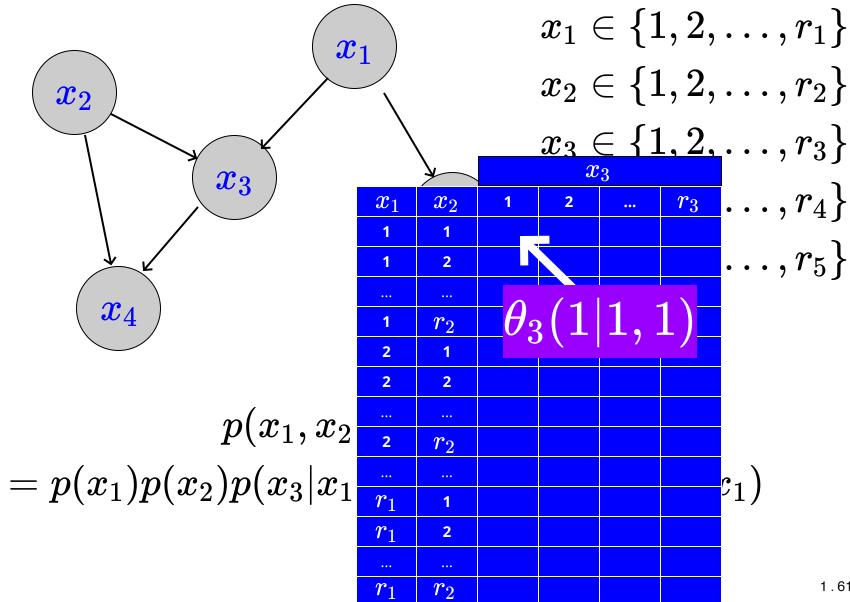
$$egin{align} p(x_1=1,x_2=2,x_3=1,x_4=3,x_5=5,x_6=2)\ &=p(x_1=1) imes p(x_2=2|x_1=1) imes p(x_4=3|x_1=1)\ & imes p(x_3=1|x_2=2,x_4=3) imes p(x_6=2|x_2=2,x_3=1) imes p(x_5=5|x_4=3) \end{aligned}$$

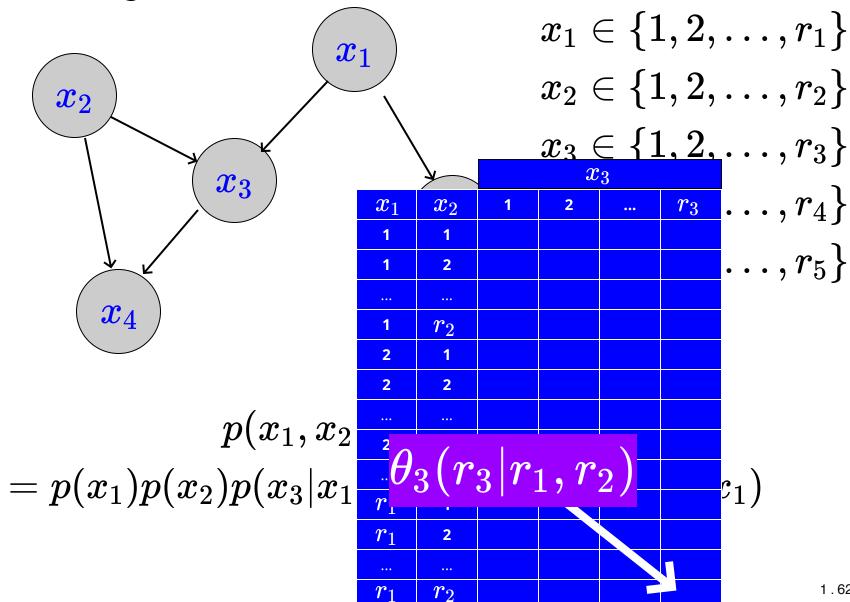


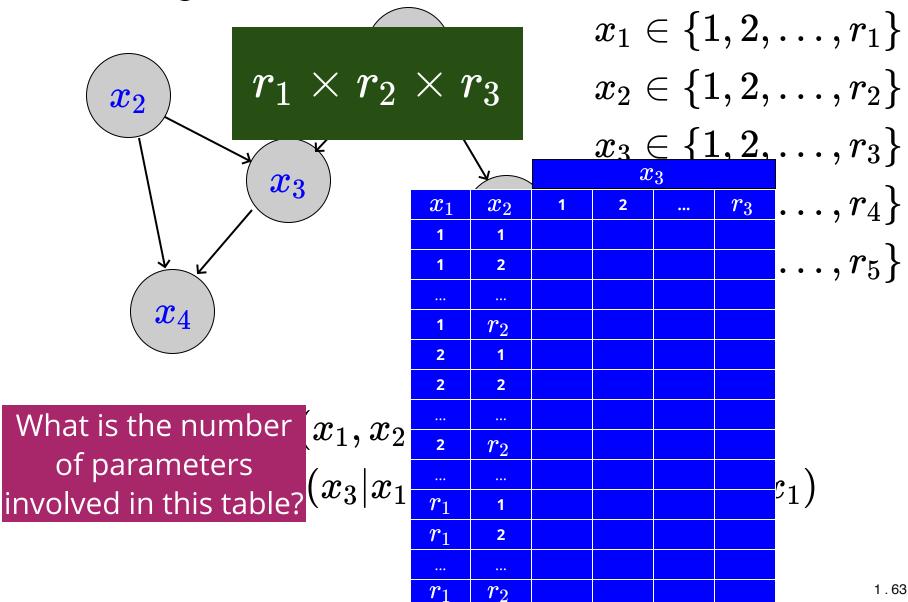
$$egin{aligned} x_1 &\in \{1,2,\ldots,r_1\} \ x_2 &\in \{1,2,\ldots,r_2\} \ x_3 &\in \{1,2,\ldots,r_3\} \ x_4 &\in \{1,2,\ldots,r_4\} \ x_5 &\in \{1,2,\ldots,r_5\} \end{aligned}$$

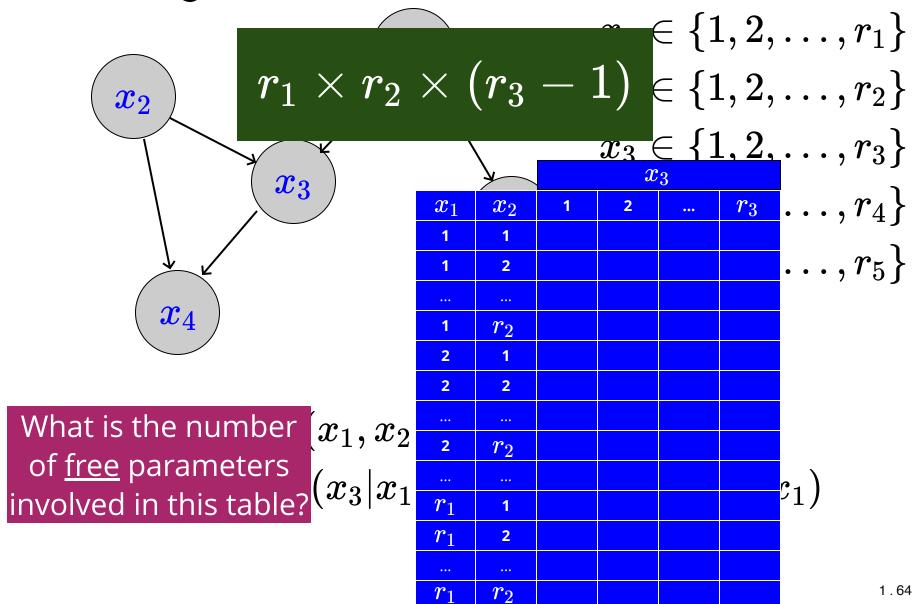
$$egin{aligned} p(x_1,x_2,x_3,x_4,x_5) \ &= p(x_1)p(x_2)p(x_3|x_1,x_2)p(x_4|x_2,x_3)p(x_5|x_1) \end{aligned}$$

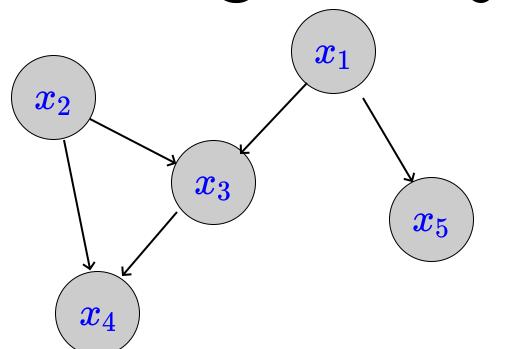










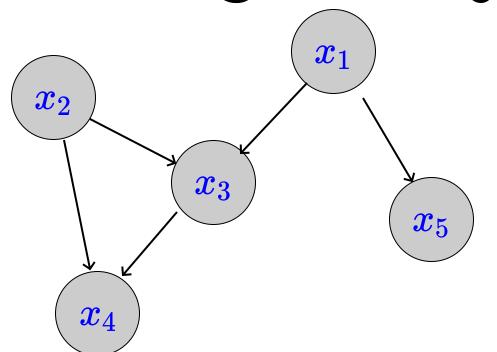


\mathbf{X}_1	\mathbf{X}_2	\mathbf{X}_3	\mathbf{X}_4	\mathbf{X}_5
1	1	2	2	2
1	2	1	1	2
2	2	2	1	2
2	2	1	2	1
2	1	2	2	1
1	1	2	1	2
1	2	1	1	1
2	2	2	1	2
1	1	1	1	2

$$p(x_1, x_2, x_3, x_4, x_5)$$

$$=p(x_1)p(x_2)p(x_3|x_1,x_2)p(x_4|x_2,x_3)p(x_5|x_1)$$

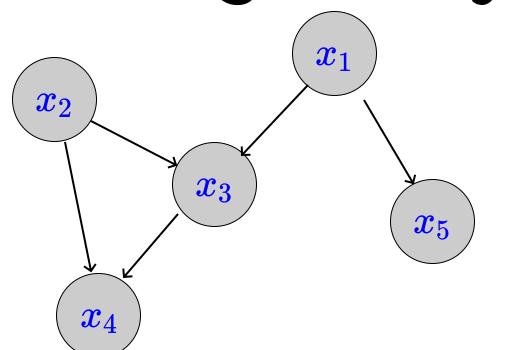
How do we learn the values for each of these model parameters?



\mathbf{X}_1	\mathbf{X}_2	\mathbf{X}_3	\mathbf{X}_4	\mathbf{X}_5
1	1	2	2	2
1	2	1	1	2
2	2	2	1	2
2	2	1	2	1
2	1	2	2	1
1	1	2	1	2
1	2	1	1	1
2	2	2	1	2
1	1	1	1	2

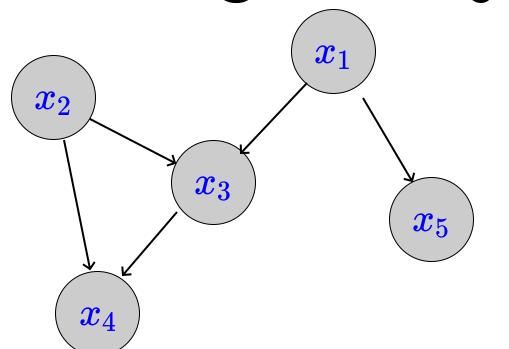
$$l(D; heta; G) = \sum_{t=1}^m \log \left[\prod_{i=1}^d heta_i(x_i^{(t)} | \mathbf{x}_{pa_i}^{(t)})
ight]$$

This is what we would like to maximize!



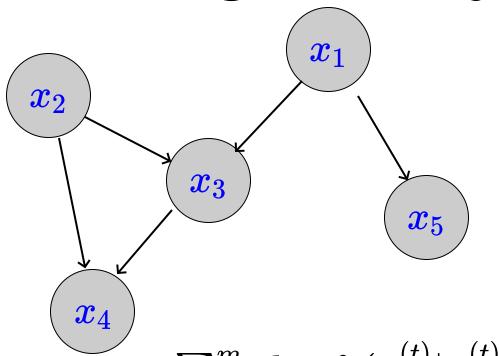
\mathbf{X}_1	\mathbf{X}_2	\mathbf{X}_3	\mathbf{X}_4	\mathbf{X}_5
1	1	2	2	2
1	2	1	1	2
2	2	2	1	2
2	2	1	2	1
2	1	2	2	1
1	1	2	1	2
1	2	1	1	1
2	2	2	1	2
1	1	1	1	2

$$egin{aligned} l(D; heta;G) &= \sum_{t=1}^m \log\left[\prod_{i=1}^d heta_i(x_i^{(t)}|\mathbf{x}_{pa_i}^{(t)})
ight] \ &= \sum_{t=1}^m \sum_{i=1}^d \log heta_i(x_i^{(t)}|\mathbf{x}_{pa_i}^{(t)}) \end{aligned}$$



\mathbf{X}_1	\mathbf{X}_2	\mathbf{X}_3	\mathbf{X}_4	\mathbf{X}_5
1	1	2	2	2
1	2	1	1	2
2	2	2	1	2
2	2	1	2	1
2	1	2	2	1
1	1	2	1	2
1	2	1	1	1
2	2	2	1	2
1	1	1	1	2

$$egin{aligned} l(D; heta;G) &= \sum_{t=1}^m \log\left[\prod_{i=1}^d heta_i(x_i^{(t)}|\mathbf{x}_{pa_i}^{(t)})
ight] \ &= \sum_{t=1}^m \sum_{i=1}^d \log heta_i(x_i^{(t)}|\mathbf{x}_{pa_i}^{(t)}) \ &= \sum_{i=1}^d \left[\sum_{t=1}^m \log heta_i(x_i^{(t)}|\mathbf{x}_{pa_i}^{(t)})
ight] \end{aligned}$$



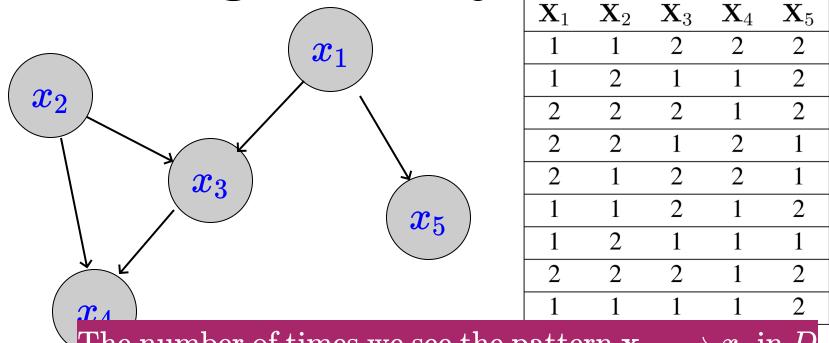
\mathbf{X}_1	\mathbf{X}_2	\mathbf{X}_3	\mathbf{X}_4	\mathbf{X}_5
1	1	2	2	2
1	2	1	1	2
2	2	2	1	2
2	2	1	2	1
2	1	2	2	1
1	1	2	1	2
1	2	1	1	1
2	2	2	1	2
1	1	1	1	2

$$\sum_{t=1}^m \log heta_i(x_i^{(t)}|\mathbf{x}_{pa_i}^{(t)})$$

$$=\sum_{x_i,\mathbf{x}_{pa_i}} ext{Count}ig((x_i,\mathbf{x}_{pa_i}) ext{ in } Dig) \log heta_i(x_i|\mathbf{x}_{pa_i})$$



 $egin{aligned} ext{The number of observations in data I} \ ext{for which } X_i = x_i, \mathbf{X}_{pa_i} = \mathbf{x}_{pa_i} \end{aligned}$



The number of times we see the pattern $\mathbf{x}_{pa_i} o x_i$ in D

$$\hat{ heta}_i(x_i|\mathbf{x}_{pa_i}) = rac{ ext{Count}ig((x_i,\mathbf{x}_{pa_i}) ext{ in }Dig)}{ ext{Count}ig((\mathbf{x}_{pa_i}) ext{ in }Dig)}, x_i \in \{1,\dots,r_1\}$$