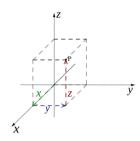
FORMULAIRE D'ANALYSE VECTORIELLE

Coordonnées cartésiennes



$$\overrightarrow{OM} = x\overrightarrow{e_x} + y\overrightarrow{e_y} + z\overrightarrow{e_z}$$

$$d\overrightarrow{OM} = dx\overrightarrow{e_x} + dy\overrightarrow{e_y} + dz\overrightarrow{e_z}$$

$$dS = dx dy$$

$$dV = dx dy dz$$

$$\overrightarrow{grad}U = \frac{\partial U}{\partial x}\overrightarrow{e_x} + \frac{\partial U}{\partial y}\overrightarrow{e_y} + \frac{\partial U}{\partial z}\overrightarrow{e_z}$$

$$div \overrightarrow{V} = \frac{\partial V_x}{\partial x} + \frac{\partial V_y}{\partial y} + \frac{\partial V_z}{\partial z}$$

$$\overrightarrow{rot} \overrightarrow{V} = \left(\frac{\partial V_z}{\partial y} - \frac{\partial V_y}{\partial z}\right) \overrightarrow{e_x}$$

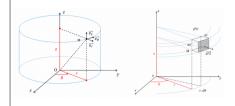
$$+ \left(\frac{\partial V_x}{\partial z} - \frac{\partial V_z}{\partial x}\right) \overrightarrow{e_y}$$

$$+ \left(\frac{\partial V_y}{\partial x} - \frac{\partial V_z}{\partial y}\right) \overrightarrow{e_x}$$

$$\Delta U = \frac{\partial^2 U}{\partial x^2} + \frac{\partial^2 U}{\partial y^2} + \frac{\partial^2 U}{\partial z^2}$$

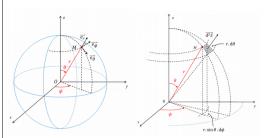
$$\Delta \overrightarrow{V} = \Delta V_x \overrightarrow{e_x} + \Delta V_y \overrightarrow{e_y} + \Delta V_z \overrightarrow{e_z}$$

Coordonnées cylindriques



$$\begin{split} & \overrightarrow{OM} = r \, \overrightarrow{e_r} + z \, \overrightarrow{e_z} \\ & d \, \overrightarrow{OM} = dr \, \overrightarrow{e_r} + r \, d \, \theta \, \overrightarrow{e_\theta} + dz \, \overrightarrow{e_z} \\ & dS = r \, d \, \theta \, dz \\ & dV = r \, dr \, d \, \theta \, dz \\ & \overrightarrow{grad} \, U = \frac{\partial U}{\partial r} \, \overrightarrow{e_r} + \frac{1}{r} \, \frac{\partial U}{\partial \theta} \, \overrightarrow{e_\theta} + \frac{\partial U}{\partial z} \, \overrightarrow{e_z} \\ & \operatorname{div} \, \overrightarrow{V} = \frac{1}{r} \, \frac{\partial (r \, V_r)}{\partial r} + \frac{1}{r} \, \frac{\partial V_\theta}{\partial \theta} + \frac{\partial V_z}{\partial z} \\ & \overrightarrow{rot} \, \overrightarrow{V} = \left(\frac{1}{r} \, \frac{\partial V_z}{\partial \theta} - \frac{\partial V_\theta}{\partial z} \right) \overrightarrow{e_r} \\ & + \left(\frac{\partial (r \, V_\theta)}{\partial r} - \frac{\partial V_z}{\partial r} \right) \overrightarrow{e_\theta} \\ & + \left(\frac{\partial (r \, V_\theta)}{\partial r} - \frac{\partial V_r}{\partial \theta} \right) \overrightarrow{e_z} \\ & \Delta U = \frac{1}{r} \, \frac{\partial}{\partial r} \left(r \, \frac{\partial U}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 U}{\partial \theta^2} + \frac{\partial^2 U}{\partial z^2} \\ & \Delta \overrightarrow{V} = \left[\Delta V_r - \frac{1}{r^2} \left(V_r + 2 \, \frac{\partial V_\theta}{\partial \theta} \right) \right] \overrightarrow{e_\theta} \\ & + \left(\Delta V_\theta - \frac{1}{r^2} \left(V_\theta - 2 \, \frac{\partial V_r}{\partial r} \right) \right) \overrightarrow{e_\theta} \\ & + \Delta V_z \, \overrightarrow{e_r} \end{split}$$

Coordonnées sphériques



$$\begin{split} \overline{OM} &= r \, \overline{e_r} \\ d \, \overline{OM} &= dr \, \overline{e_r} + r \, d \, \theta \, \overline{e_\theta} + r \sin \theta \, d \, \phi \, \overline{e_\phi} \\ dS &= r^2 \sin \theta \, d \, \theta \, d \, \phi \\ dV &= r^2 \, dr \sin \theta \, d \, \theta \, d \, \phi \\ \overline{grad} U &= \frac{\partial U}{\partial r} \, \overline{e_r} + \frac{1}{r} \frac{\partial U}{\partial \theta} \, \overline{e_\theta} + \frac{1}{r \sin \theta} \, \frac{\partial U}{\partial \phi} \, \overline{e_\phi} \\ \operatorname{div} \, \overrightarrow{V} &= \frac{1}{r^2} \frac{\partial \left(r^2 V_r \right)}{\partial r} + \frac{1}{r \sin \theta} \, \frac{\partial \left(\sin \theta V_\theta \right)}{\partial \theta} + \frac{1}{r \sin \theta} \, \frac{\partial V_\phi}{\partial \phi} \\ \overrightarrow{rot} \, \overrightarrow{V} &= \frac{1}{r \sin \theta} \left(\frac{\partial \left(\sin \theta V_\phi \right)}{\partial \theta} - \frac{\partial V_\theta}{\partial \phi} \right) \overrightarrow{e_r} \\ &+ \left(\frac{1}{r \sin \theta} \, \frac{\partial V_r}{\partial \phi} - \frac{\partial \left(r V_\phi \right)}{\partial \theta} \right) \overrightarrow{e_\theta} \\ &+ \frac{1}{r} \left(\frac{\partial \left(r V_\theta \right)}{\partial r} - \frac{\partial V_r}{\partial \theta} \right) \overrightarrow{e_\theta} \\ &+ \frac{1}{r} \left(\frac{\partial \left(r V_\theta \right)}{\partial r} - \frac{\partial V_\theta}{\partial \theta} \right) \overrightarrow{e_\theta} \\ \Delta U &= \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial U}{\partial r} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \, \frac{\partial U}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 U}{\partial \phi} \\ \Delta \overrightarrow{V} &= \left(\Delta V_r - \frac{2 V_r}{r^2} - \frac{2 V_\theta}{r^2} \frac{\cos \theta}{\sin \theta} - \frac{2}{r^2} \frac{\partial V_\theta}{\partial \theta} - \frac{2}{r^2 \sin^2 \theta} \frac{\partial V_\phi}{\partial \phi} \right) \overrightarrow{e_\theta} \\ &+ \left(\Delta V_\theta - \frac{V_\theta}{r^2 \sin^2 \theta} + \frac{2}{r^2} \frac{\partial V_r}{\partial \theta} - \frac{2 \cos \theta}{r^2 \sin^2 \theta} \frac{\partial V_\phi}{\partial \phi} \right) \overrightarrow{e_\theta} \\ &+ \left(\Delta V_\phi - \frac{V_\phi}{r^2 \sin^2 \theta} + \frac{2}{r^2 \sin^2 \theta} \frac{\partial V_r}{\partial \phi} + \frac{2 \cos \theta}{r^2 \sin^2 \theta} \frac{\partial V_\theta}{\partial \phi} \right) \overrightarrow{e_\phi} \end{split}$$

Composition des opérateurs

$$\begin{array}{l} \operatorname{div}\left(\overrightarrow{rot}\,\overrightarrow{V}\right) = 0 \\ \overrightarrow{rot}\left(\overrightarrow{rot}\,\overrightarrow{V}\right) = \overrightarrow{grad}\left(\operatorname{div}\overrightarrow{V}\right) - \Delta\,\overrightarrow{V} \\ \operatorname{div}\left(\overrightarrow{grad}\,U\right) = \Delta\,U \\ \overrightarrow{rot}\left(\overrightarrow{grad}\,U\right) = \overrightarrow{0} \end{array}$$

Produits scalaires et vectoriels :

$$\vec{A} \cdot \vec{B} = |\vec{A}| \cdot |\vec{B}| \cdot \cos \theta \quad \text{et} \quad \vec{A} \cdot \vec{B} = x_A \cdot x_B + y_A \cdot y_B + z_A \cdot z_B \\ |\vec{C}| = |\vec{A} \wedge \vec{B}| = |\vec{A}| \cdot |\vec{B}| \cdot \sin \theta \quad \text{et} \quad \vec{A} \wedge \vec{B} = (y_A \cdot z_B - y_B \cdot z_A) \vec{u_x} + (z_A \cdot x_B - z_B \cdot x_A) \vec{u_y} + (x_A \cdot y_B - x_B \cdot y_A) \vec{u_z}$$

Constantes:

permittivité diélectrique du vide : ϵ_0 =8,854·10⁻¹² A^2 ·s⁴·kg⁻¹·m⁻³ perméabilité magnétique du vide : μ_0 =4 π ·10⁻⁷ kg·m·A⁻²·s⁻²

vitesse de la lumière : $c \approx 3.10^8 \,\mathrm{m \cdot s}^{-1}$ masse de l'électron : $m_e = 9,109 \cdot 10^{-31} \,\mathrm{kg}$ charge de élémentaire : $e = 1,6 \cdot 10^{-19} \,\mathrm{C}$