# Parallel and Distributed Computing CS3006

Lecture 3

Flynn's Taxonomy

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# Agenda

- A Quick Review
- Flynn's Taxonomy
  - SISD
  - MISD
  - SIMD
  - MIMD
- Physical Organization of Parallel Platforms
  - PRAM
- Routing techniques and Costs

## Quick Review to the Previous Lecture

#### Amdahl's Law of Parallel Speedup

Purpose, derivation, and examples

#### Karp-Flatt Metric

Finding sequential fraction in the given parallel setup

#### Types of Parallelism

- Data-parallelism
  - Same operation on different data elements
- Functional-parallelism
  - Different independent tasks with different operations on different data elements can be parallelized
- Pipelining
  - Overlapping the instructions in a single instruction cycle to achieve parallelism

## Quick Review to the Previous Lecture

#### Multiprocessor

- Centralized multiprocessor
- Distributed multiprocessor
- Shared address space(NUMA) vs Shared memory(UMA)

## Multicomputer

- Asymmetrical
- Symmetrical

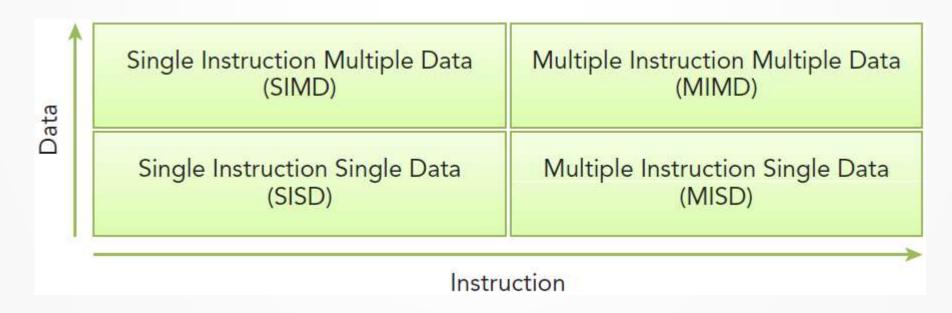
#### Cluster vs Network of Workstations

#### Assigned Reading

- Cache Coherence and snooping
- Branch prediction and issues while pipelining the problem

# Flynn's Taxonomy

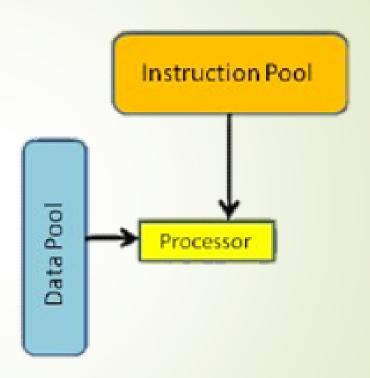
- Widely used architectural classification scheme
- Classifies architectures into four types
- The classification is based on how data and instructions flow through the cores.



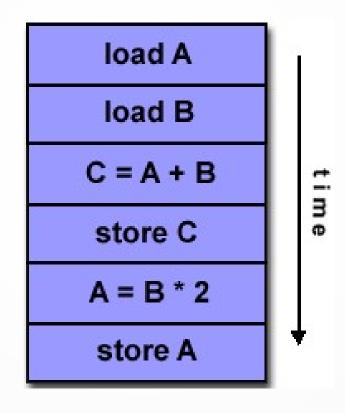
# Flynn's Taxonomy

#### SISD (Single Instruction Single Data)

- Refers to traditional computer: a serial architecture
- This architecture includes single core computers
- Single instruction stream is in execution at a given time
- Similarly, only one data stream is active at any time



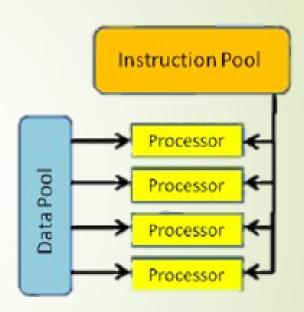
# Example of SISD:



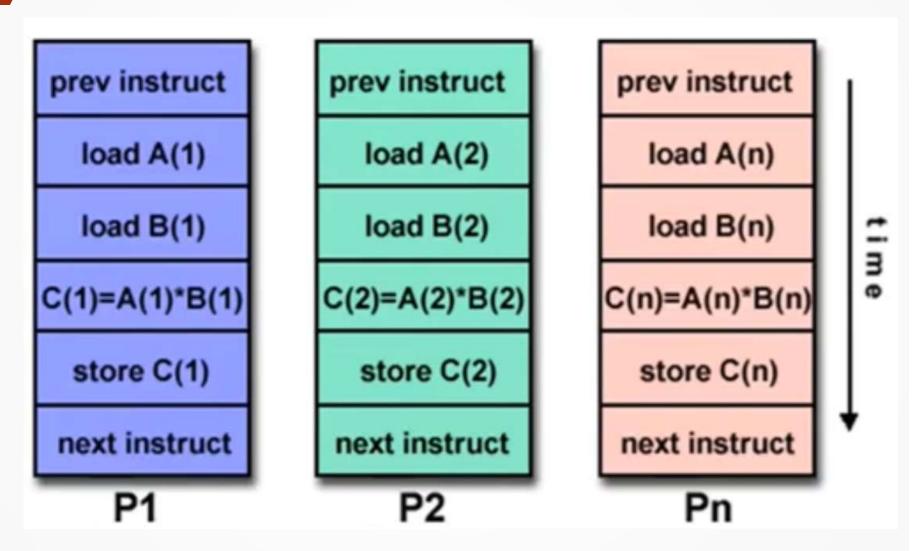
# Flynn's Taxonomy

#### SIMD (Single Instruction Multiple Data)

- Refers to parallel architecture with multiple cores
- All the cores execute the same instruction stream at any time but, data stream is different for the each.
- Well-suited for the scientific operations requiring large matrix-vector operations
- Vector computers (Cray vector processing machine) and Intel coprocessing unit 'MMX' fall under this category.
- Used with array operations, image processing and graphics



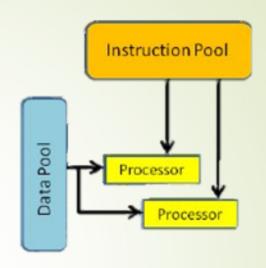
# Example of SIMD:

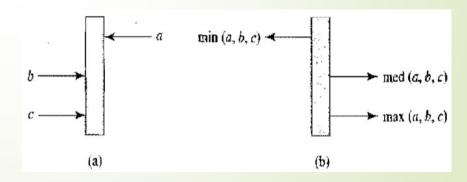


# Flynn's Taxonomy

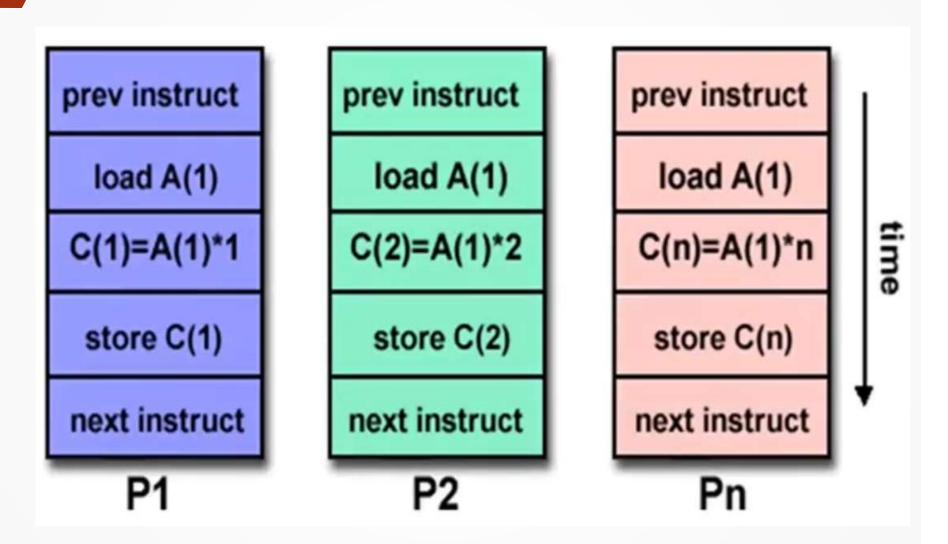
#### MISD (Multiple Instructions Single Data)

- Multiple instruction stream and single data stream
  - A pipeline of multiple independently executing functional units
  - Each operating on a single stream of data and forwarding results from one to the next
- Rarely used in practice
- E.g., Systolic arrays: network of primitive processing elements that pump data.





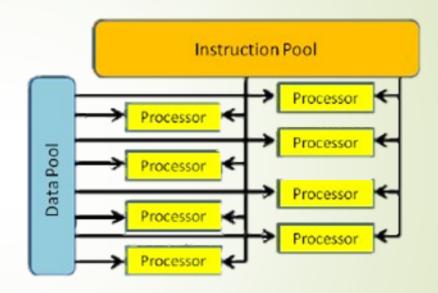
# Example of MISD:



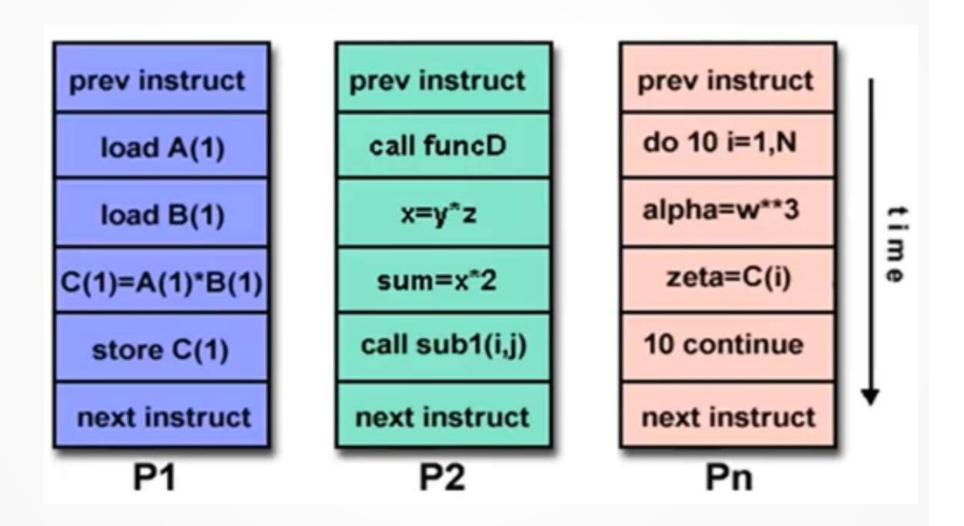
# Flynn's Taxonomy

# MIMD (Multiple Instructions Multiple Data)

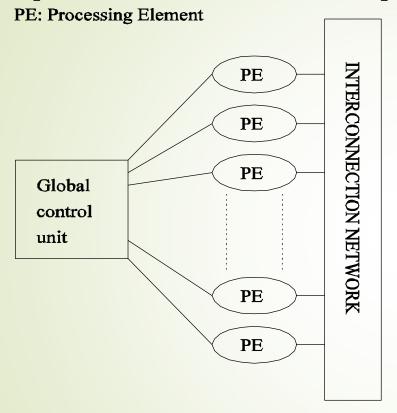
- Multiple instruction streams and multiple data streams
- Different CPUs can simultaneously execute different instruction streams manipulating different data
- Most of the modern parallel architectures fall under this category e.g., Multiprocessor and multicomputer architectures
- Many MIMD architectures include SIMD executions by default.

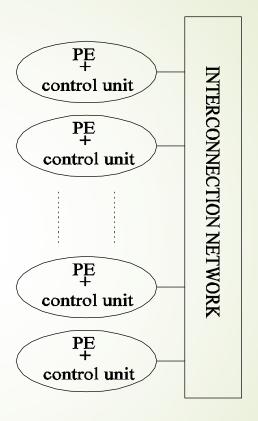


# **Example of MIMD:**



## Flynn's Taxonomy





(a) (b)

A typical SIMD architecture (a) and a typical MIMD architecture (b).

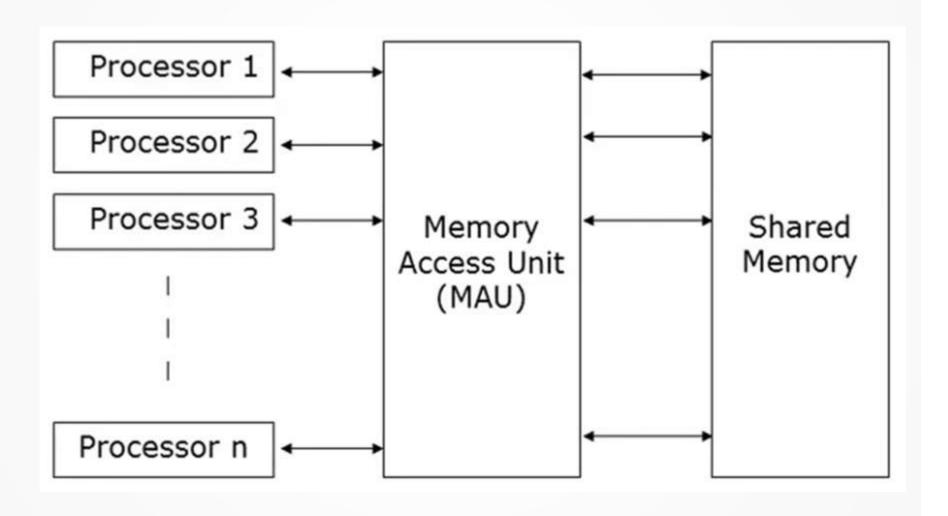
# **SIMD-MIMD** Comparison

- SIMD computers require less hardware than MIMD computers (single control unit).
- However, since SIMD processors are specially designed, they tend to be expensive and have long design cycles.
- Not all applications are naturally suited to SIMD processors.
- In contrast, platforms supporting the SPMD (Same Program Multiple Data) paradigm can be built from inexpensive off-the-shelf components with relatively little effort in a short amount of time.
  - The Term SPMD is close variant of MIMD

# Physical Organization of Parallel Platforms

- An extension to ideal sequential model: random access machine (RAM)
- PRAMs consist of p processors
- A global memory
  - Unbounded size
  - Uniformly accessible to all processors with same address space
- Processors share a common clock but may execute different instructions in each cycle.
- Based on simultaneous memory access mechanisms, PRAM can further be classified.

# Graphical representation of PRAM:



- PRAMs can be divided into four subclasses.
- 1. Exclusive-read, exclusive-write (EREW) PRAM
  - No two processors can perform read/write operations concurrently
  - Weakest PRAM model, provides minimum memory access concurrency
- 2. Concurrent-read, exclusive-write (CREW) PRAM
  - All processors can read concurrently but can't write at same time
  - Multiple write accesses to a memory location are serialized
- 3. Exclusive-read, concurrent-write (ERCW) PRAM
  - No two processors can perform read operations concurrently, but can write
- 4. Concurrent-read, concurrent-write (CRCW) PRAM

- Concurrent reads do not create any semantic inconsistencies
- But, What about concurrent write?
- Need of an arbitration(mediation) mechanism to resolve concurrent write access

- Mostly used arbitration protocols: -
  - Common: write only if all values that the processors are attempting to write are identical
  - Arbitrary: write the data from a randomly selected processor and ignore the rest.
  - Priority: follow a predetermined priority order. Processor with highest priority succeeds and the rest fail.
  - Sum: Write the sum of the data items in all the write requests. The sum-based write conflict resolution model can be extended for any of the associative operators, that is defined for data being written .

#### Physical Complexity of an Ideal Parallel Computer

- Processors and memories are connected via switches.
- Since these switches must operate in O(1) time at the level of words, for a system of p processors and m words, the switch complexity is O(mp).
- Clearly, for meaningful values of p and m, a true PRAM is not realizable.

# Communication Costs in Parallel Machines Parallel and Distributed Computing (CS3006) - Spring 2024

# Communication Costs in Parallel Machines

- Along with idling (doing nothing) and contention (conflict e.g., resource allocation), communication is a major overhead in parallel programs.
- The communication cost is usually dependent on a number of features including the following:
  - Programming model for communication
  - Network topology
  - Data handling and routing
  - Associated network protocols
- Usually, distributed systems suffer from major communication overheads.

- The total time to transfer a message over a network comprises of the following:
  - **Startup time (t<sub>s</sub>):** Time spent at sending and receiving nodes (preparing the message[adding headers, trailers, and parity information], executing the routing algorithm, establishing interface between node and router, etc.).
  - Per-hop time  $(t_h)$ : This time is a function of number of hops (steps) and includes factors such as switch latencies, network delays, etc.
    - Also known as **node latency**.
  - **Per-word transfer time (t\_w):** This time includes all overheads that are determined by the length of the message. This includes bandwidth of links, and buffering overheads, etc.

#### Store-and-Forward Routing

- A message traversing multiple hops is completely received at an intermediate hop before being forwarded to the next hop.
- The total communication cost for a message of size m words to traverse I communication links is

$$t_{comm} = t_s + (mt_w + t_h)l.$$

In most platforms,  $t_h$  is small and the above expression can be approximated by  $t_{comm} = t_s + mlt_w$ .

#### **Packet Routing**

- Store-and-forward makes poor use of communication resources.
- Packet routing breaks messages into packets and pipelines them through the network.
- Since packets may take different paths, each packet must carry routing information, error checking, sequencing, and other related header information.
- The total communication time for packet routing is approximated by:  $t_{comm} = t_s + t_h l + t_w m$ .
- lacktriangle Here factor  $m{t}_{w}$  also accounts for overheads in packet headers.

#### **Cut-Through Routing**

- Takes the concept of packet routing to an extreme by further dividing messages into basic units called flits or flow control digits.
- Since flits are typically small, the header information must be minimized.
- This is done by forcing all flits to take the same path, in sequence.
- A tracer message first programs all intermediate routers. All flits then take the same route.
- Error checks are performed on the entire message, as opposed to flits.
- No sequence numbers are needed.

#### **Cut-Through Routing**

The total communication time for cut-through routing is approximated by:

$$t_{comm} = t_s + t_h l + t_w m.$$

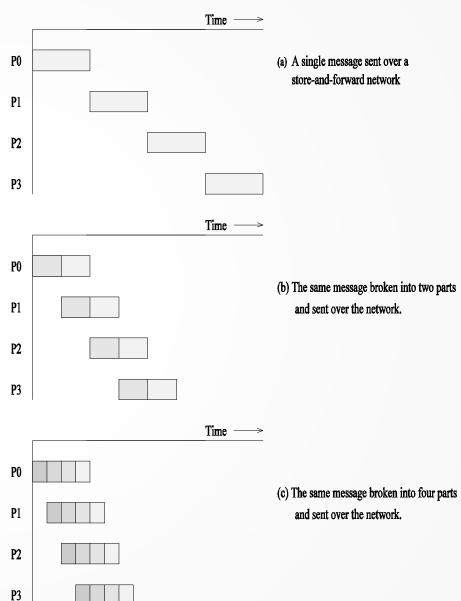
This is identical to packet routing, however,  $t_w$  is typically much smaller.

# Message Passing Costs in Parallel

Computers

(a) through a store-and-forward communication network;

b) and (c) extending the concept to cut-through routing.



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## Simplified Cost Model for Communicating Messages

The cost of communicating a message between two nodes I hops away using cut-through routing is given by

$$t_{comm} = t_s + lt_h + t_w m.$$

- In this expression,  $t_h$  is typically smaller than  $t_s$  and  $t_w$ . For this reason, the second term in the RHS does not show, particularly, when m is large.
- For these reasons, we can approximate the cost of message transfer by

$$t_{comm} = t_s + t_w m$$
.

## Simplified Cost Model for Communicating Messages

- It is important to note that the original expression for communication time is valid for only uncongested networks.
- Different communication patterns congest different networks to varying extents.
- It is important to understand and account for this in the communication time accordingly.

# Questions



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## References

- 1. Flynn, M., "Some Computer Organizations and Their Effectiveness," IEEE Transactions on Computers, Vol. C-21, No. 9, September 1972.
- 2. Kumar, V., Grama, A., Gupta, A., & Karypis, G. (1994). *Introduction to parallel computing* (Vol. 110). Redwood City, CA: Benjamin/Cummings.
- 3. Quinn, M. J. Parallel Programming in C with MPI and OpenMP,(2003).