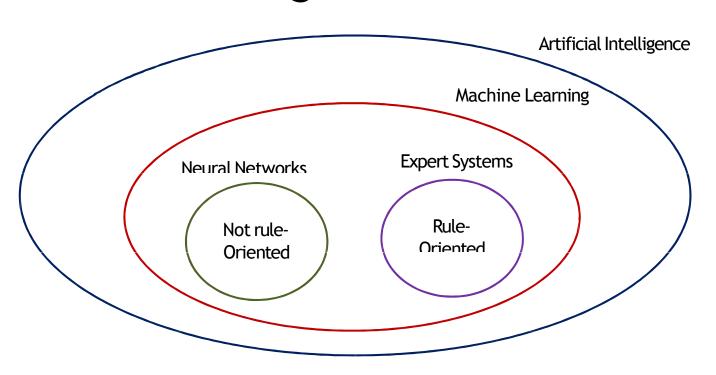
# **Neural Networks**

# Artificial Neural Networks (ANN) Big Picture





#### What are ANNs

- "...a computing system made up of a number of simple, highly interconnected processing elements, which process information by their dynamic state response to external inputs.

  M. Caudill 1989
- Computational model based on the structure and functions of biological Neural Networks
- They are considered nonlinear statistical data modeling tools where the complexrelationships between inputs and outputs are modeled or patterns are found

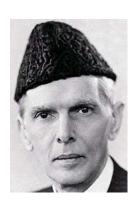


### **Biological Inspiration**



### Biological neural networks

- About 10<sup>11</sup> neurons in human brain
- About 10<sup>14~15</sup> interconnections
- Pulse-transmission frequency million times slower than electronic circuits
- Face recognition
  - hundred million second by human
     Network of artificial neuron operation
     speed only a few million second



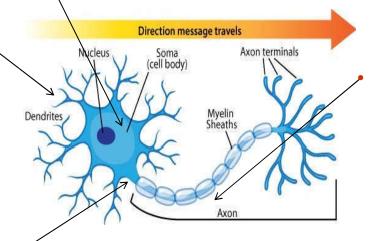




### Biological Neuron

cell body: computes a nonlinear function of its inputs

dendrites:
 nerve fibres
 carrying
 electrical
 signals to the
 cell



axon: single long fibre that carries the electrical signal from the cell body to other neurons

synapse: the point of contact between the axon of one cell and the dendrite of another, regulating a chemical connection whosestrength affects the input to the cell.



### **Biological Neuron**

- A variety of different neurons exist (motor neuron, on-center off-surround visual cells...), with different branching structures
- The connections of the network and the strengths of the individual synapses establish the function of the network.



### **Brief History of ANN**



### **Brief History of ANN**

- McCulloch and Pitts (1943) designed the first neural network
- Hebb (1949) who developed the first learning rule. If two neurons were active at the same time then the strength between them should be increased.
- Rosenblatt (1958) introduced the concept of a perceptron which performed pattern recognition.
- Widrow and Hoff (1960) introduced the concept of the ADALINE (ADAptive Linear Element). The training rule was based on the idea of Least-Mean-Squares learning rule which minimizing the error between the computed output and the desired output.
- Minsky and Papert (1969) stated that the perceptron was limited in its ability to recognize features that were separated by linear boundaries. "Neural Net Winter"
- Kohonen and Anderson independently developed neural networks that acted like memories.
- Webros(1974) developed the concept of back propagation of an error to train the weights of the neural network.
- McCelland and Rumelhart (1986) published the paper on back propagation algorithm. "Rebirth of neural networks".
- Today they are everywhere a decision can be made.

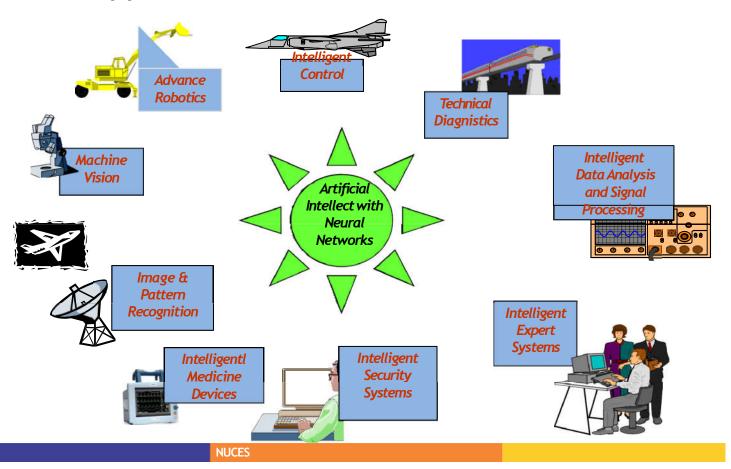
Source: G5AIAI - Introduction to Artificial Intelligence Graham Kendall:



## **Applications of ANN**



#### Applications of Artificial Neural Networks





#### Applications of Artificial Neural Networks

- Aerospace: aircraft autopilots, flight path simulations, aircraft control systems, autopilot enhancements, aircraft component simulations
- Banking: credit application evaluators
- Defense: guidance and control, target detection and tracking, object discrimination, sonar, radar and image signal processing including data compression, feature extraction and noise suppression, signal/image identification
- Financial: real estate appraisal, loan advisor, mortgage screening, stock market analysis, stock trading advisory systems
- Manufacturing: process control, process and machine diagnosis, visual quality inspection systems, computer chip quality analysis

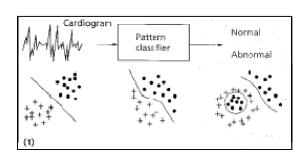


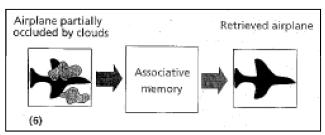
#### Applications of Artificial Neural Networks

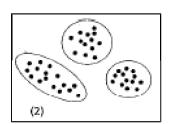
- Medical: cancer cell detection and analysis, EEG and ECG analysis, disease pathway analysis
- Communications: adaptive echo cancellation, image and data compression, speech synthesis, signal filtering
- Robotics: Trajectory control, manipulator controllers, vision systems
- Pattern Recognition: character recognition, speech recognition, voice recognition, facial recognition

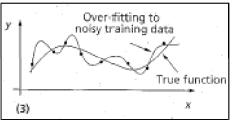


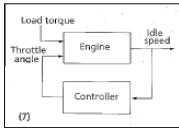
#### **Challenging Problems**

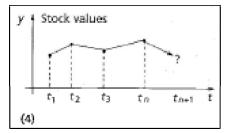


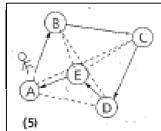












- (1) Pattern classification
- (2) Clustering/categorization
- (3) Function approximation
- (4) Prediction/forecasting
- (5) Optimization (TSP problem)
- (6) Retrieval by content
- (7) Control

### Neural Net vs. Von Neumann Computer

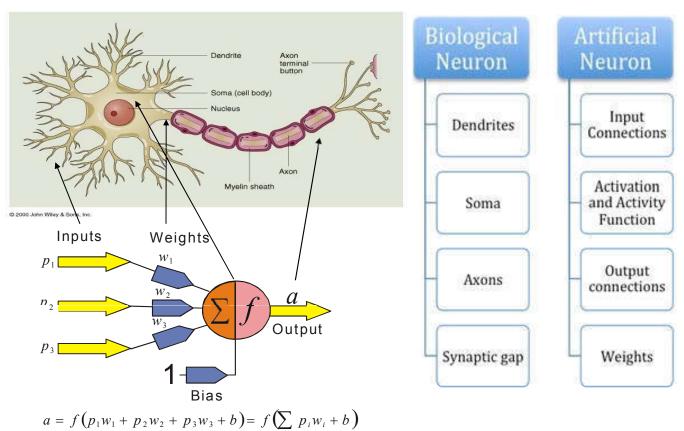
Neural Net	Von Neumann
Non-algorithmic	<u>Algorithmic</u>
<u>Trained</u>	Programmed with instructions
Memory and processing elements the same	Memory and processing separate
Pursue multiple hypotheses	Pursue one hypothesis at a time
Fault tolerant	Non fault tolerant
Non-logical operation	Highly logical operation
Adaptation or <u>learning</u>	Algorithmic parameterization modification only
Seeks answer by finding minima in solution space	Seeks answer by following logical tree structure



#### **Artificial Neuron**



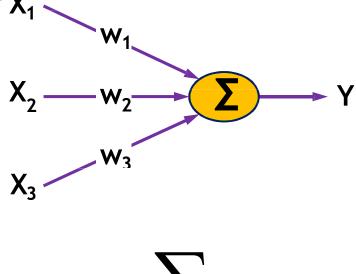
### **Artificial Neuron Model**





#### **Artificial Neuron**

Artificial Neuron is the X<sub>1</sub> basic information processing unit of the X<sub>2</sub> Neural Networks (NN).
 It is a non linear, parameterized function with restricted output range.



$$y = \sum_{i} x_{i} w_{i}$$



### Adding bias

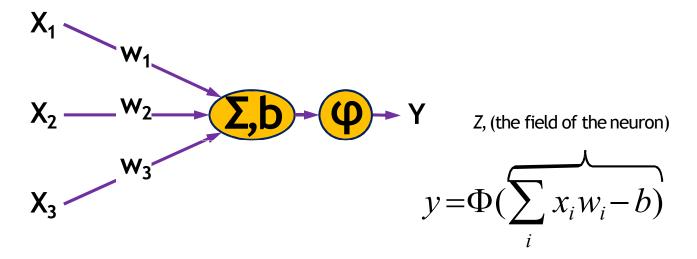
•Bias is like another weight. Its included by adding a component  $x_0$ =1 to the input vector X.

- Bias is of two types
  - Positive bias: increase the net input
  - Negative bias: decrease the net input

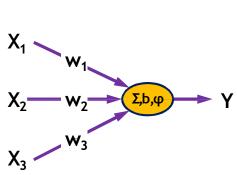


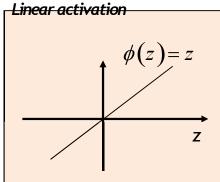
### Adding an "activation" function

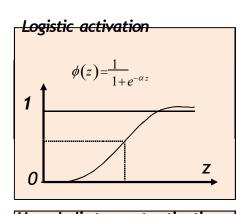
- •Used to calculate the output response of a neuron.
- •Sum of the weighted input signal is applied with an activation to obtain the response.
- Activation functions can be linear or non linear



#### Common activation functions







# Many types of activations functions are used:

linear: a = f(n) = n

Threshold:  $a = \{1 \text{ if } n \ge 0 \text{ (hardlimiting)} \\ 0 \text{ if } n < 0$ 

sigmoid:  $a = 1/(1+e^{-n})$ 

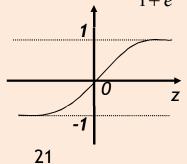
#### Threshold activation

1 \_\_\_\_\_

\_\_\_\_\_ Z

#### Hyperbolic tangent activation

 $\varphi(u) = tanh(\gamma u) = \frac{1 - e^{-2\gamma u}}{1 + e^{-2\gamma u}}$ 





#### **Artificial Neural Networks**



#### **Artificial Neural Networks**

- Artificial Neural Network (ANN): is a machine learning approach that models human brain and consists of a number of artificial neurons that are linked together according to a specific network architecture.
- Neuron in ANNs tend to have fewer connections than biological neurons. each neuron in ANN receives a number of inputs.
- An activation function is applied to these inputs which results in activation level of neuron (output value of the neuron).
- Knowledge about the learning task is given in the form of examples called training examples.

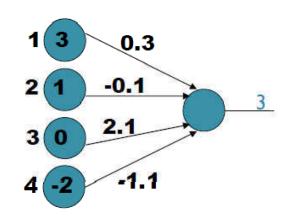


### Computing with Neural Units

- Incoming signals to a unit are presented as inputs.
- How do we generate outputs?
- One idea: <u>Summed</u> WeightedInputs.
- Input: (3, 1, 0, -2)
- Processing

$$3(0.3) + 1(-0.1) + 0(2.1) + -2(-1.1)$$

- = 0.9 + (-0.1) + 0 + 2.2
- Output: 3





#### **Activation Functions**

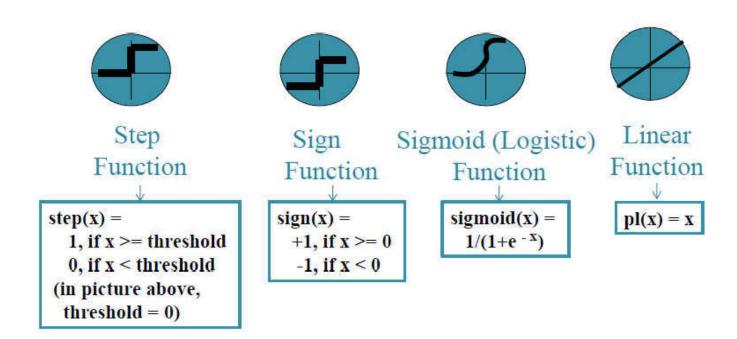
- Usually, do not just use weighted sum directly.
- Apply some function to theweighted sum before it is used (e.g., as output).
- © Call this the activation function.

$$f(x) = \begin{cases} 1 & \text{if } x \ge \theta \\ 0 & \text{if } x < \theta \end{cases} \quad \theta \text{ Is called the threshold}$$

Step function

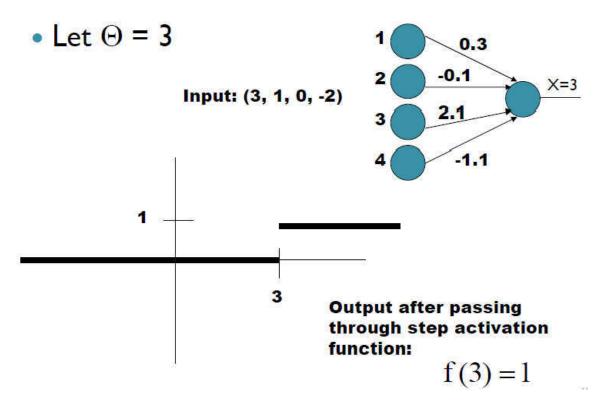


#### **Activation Functions**

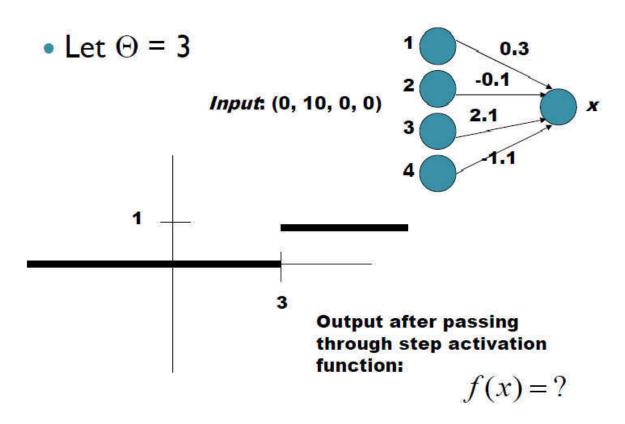


The choice of activation function determines the Neuron Model.

### Example (1): Step Function



### Example (2): Another Step Function

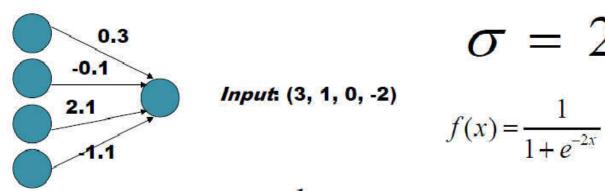


## Example (3): Sigmoid Function

- The math of some neural nets requires that the activation function be continuously differentiable.
  - •A sigmoidal function often used to approximate the step function.

$$f(x) = \frac{1}{1 + e^{-\sigma x}} \qquad \sigma_{\text{parameter}}^{\text{Is the steepness}}$$

### Example (3): Sigmoid Function



$$f(3) = \frac{1}{1 + e^{-2x}} = .998$$

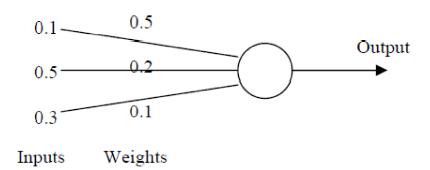
Input: (0, 10, 0, 0)

network output?



### Example

• Calculate the output from the neuron below assuming a threshold of 0.5:



Sum = 
$$(0.1 \times 0.5) + (0.5 \times 0.2) + (0.3 \times 0.1) = 0.05 + 0.1 + 0.03 = 0.18$$
  
Since 0.18 is less than the threshold, the Output = 0

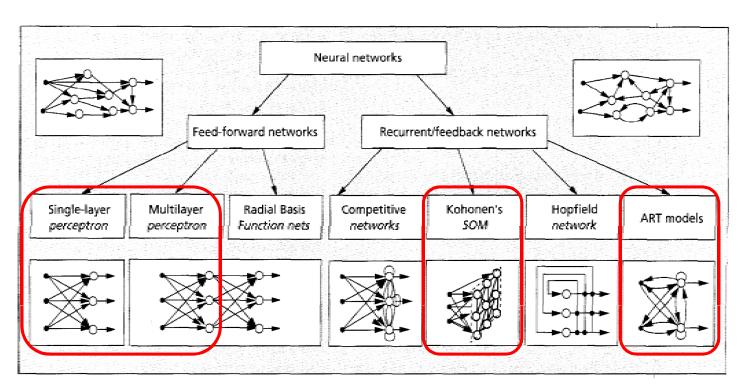
Repeat the above calculation assuming that the neuron has a sigmoid output function: Sum is still 0.18, but now Output =  $\frac{1}{1 + e^{-0.18}} = 0.545$ 



#### **Network Architectures**



### Network architectures



A taxonomy of feed-forward and recurrent/feedback network architectures.

NUCE:



#### **Network Architecture**

- The Architecture of a neural network is linked with the learning algorithm used to train.
- There are different classes of network architecture:
- Single-Layer Neural Networks.
- Multi-Layer Neural Networks.
  - The number of layers and neurons depend on the specific task.

### Single Layer Neural Network

- Single-laver feedforward network is the simplest form of a layered network.
- There are two layers:
  - Input Layer
  - Output Layer (Computation Nodes)
- It is *feedforward*, means the information flow from input to output and not *viceversa*.
- Input layer of source nodes are not counted because no computation is performed.

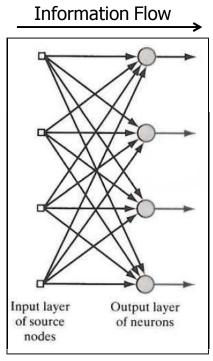


Figure 2.1 Feedforwad network with a single layer of neurons.



### Multilayer Neural Network

- Multilayer feedforward networks has one or more hidden layers.
- Multilayer NN overcome the limitation of Single-Layer NN, they can handle nonlinearly separable learning tasks.
- By adding hidden layers, the network is enabled to extract higher-order statistics from its input.
- In this structure, the computation nodes are called hidden neurons or hidden units.
- The example architecture in Figure 2.2 is referred to as a 10-4-2 network:
  - 10 source nodes
  - 4 hidden neurons
  - 2 output neurons
- Fully Connected VS Partially Connected

#### **Information Flow**

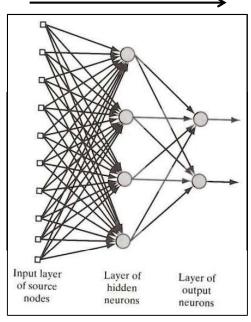


Figure 2.2 Fully connected feedforward network with one hidden layer and one output layer.



#### Recurrent Network

- Recurrent neural network is different from feedforward neural network because it has at least one feedback loop.
- The presence of feedback loop has a profound impact on the learning capability of the network and its performance.
- The feedback loops involve the use of particular branches composed of unittime delay elements (denoted by z-1)
- Structure at Figure 2.3:
  - No self-feedback loops in the network
  - No hidden neurons

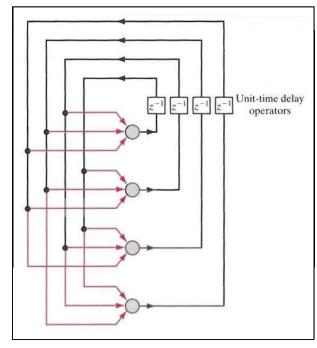


Figure 2.3 Recurrent network with no selffeedback loops and no hidden neurons.



#### Recurrent Network

- Structure at Figure 2.4:
  - Contains self-feedback loops in the network
  - Contains hidden neurons
- The feedback connections originate from the hidden neurons as well as from the

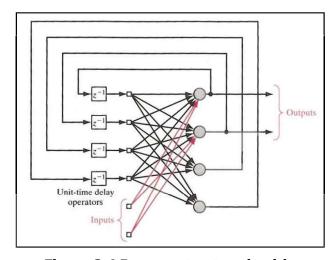
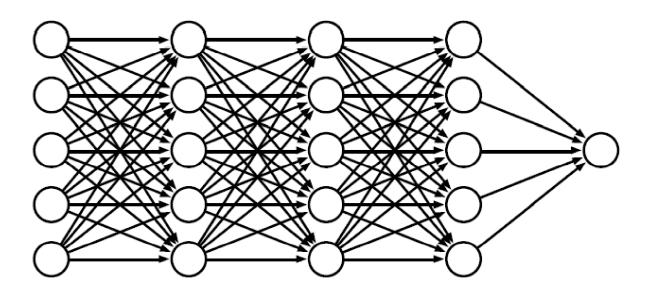


Figure 2.4 Recurrent network with hidden neurons.



# Deep Learning

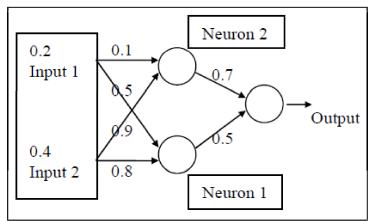
More layers = deep learning





### Example of multilayer ANN

 Calculate the output from this network assuming a Sigmoid Squashing Function.



Input to neuron 1 = 
$$(0.2 \times 0.5) + (0.4 \times 0.8) = 0.42$$
. Output =  $\frac{1}{1 + e^{-0.42}} = 0.603$   
Input to neuron 2 =  $(0.2 \times 0.1) + (0.4 \times 0.9) = 0.38$ . Output =  $\frac{1}{1 + e^{-0.38}} = 0.594$   
Input to final neuron =  $(0.594 \times 0.7) + (0.603 \times 0.5) = 0.717$ .

Final Output = 
$$\frac{1}{1 + e^{-0.717}} = 0.672$$