

CMSC 471:

Reasoning with Bayesian Belief Network

Chapters 12 & 13

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Overview

- Bayesian Belief Networks (BBNs) can reason with networks of propositions and associated probabilities
- Useful for many AI problems
 - Diagnosis
 - Expert systems
 - Planning
 - Learning

Probabilistic Graphical Models

A graph G that represents a probability distribution over N random variables X_1, \dots, X_N

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Vertices \longleftrightarrow random variables

Edges show dependencies among random variables

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Two main flavors: *directed* graphical models and *undirected* graphical models

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Two main flavors: **directed graphical models** and *undirected* graphical models

Directed Graphical Models

A *directed* (acyclic) graph $G=(V,E)$ that represents a probability distribution over random variables

$$X_1, \dots, X_N$$

Joint probability factorizes into factors of X_i conditioned on the parents of X_i

Directed Graphical Models

A *directed* (acyclic) graph $G=(V,E)$ that represents a probability distribution over random variables

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Benefit: the independence properties are *transparent*

Directed Graphical Models

A *directed* (acyclic) graph $G=(V,E)$ that represents a probability distribution over random variables X_1, \dots, X_N

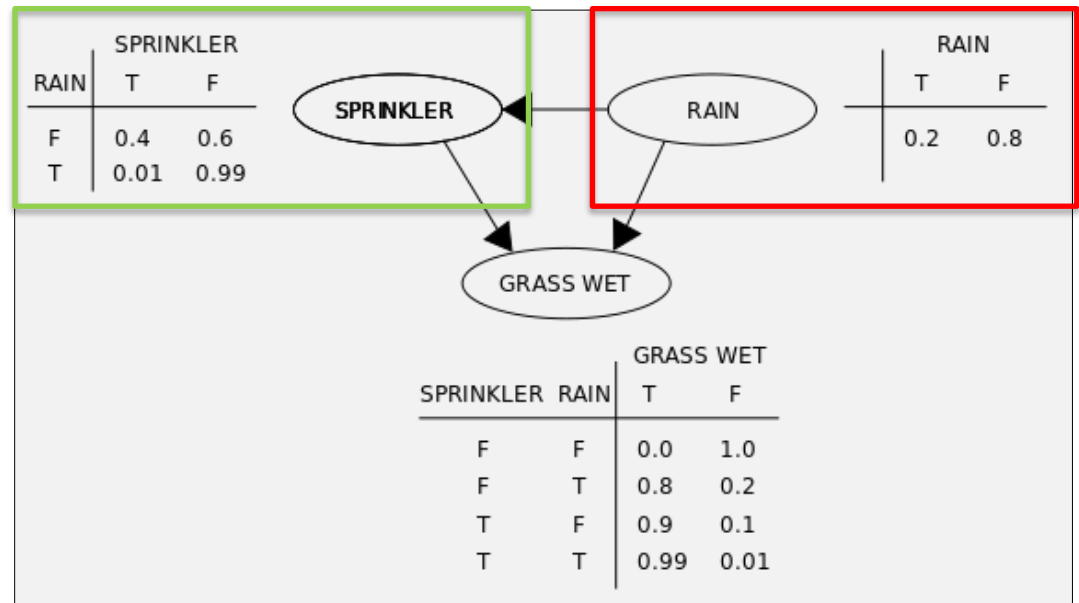
Joint probability factorizes into factors of X_i conditioned on the parents of X_i

A graph/joint distribution that follows this is a **Bayesian network**

BBN Definition

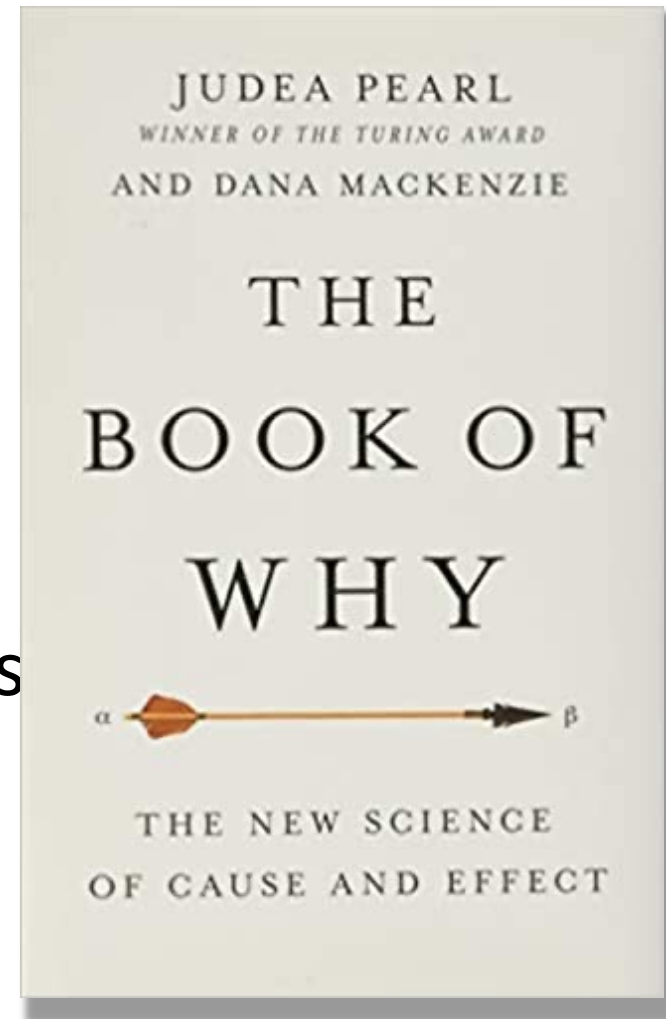
- AKA Bayesian Network, Bayes Net
- A graphical model (as a [DAG](#)) of probabilistic relationships among a set of random variables
- Nodes are variables, links represent direct influence of one variable on another
- Nodes have **prior probabilities** or **conditional probability tables** (CPTs)

[source](#)



History lesson: Judea Pearl

- UCLA CS professor
- Introduced [Bayesian networks](#) in the 1980s
- Pioneer of probabilistic approach to AI reasoning
- First to formalize causal modeling in empirical sciences
- Written many books on the topics, including the popular 2018 [Book of Why](#)



Why? Three (Four) kinds of reasoning

BBNs support three main kinds of reasoning:

- **Predicting** conditions given predispositions
- **Diagnosing** conditions given symptoms (and predisposing)
- **Explaining** a condition by one or more predispositions

To which we can add a fourth:

- **Deciding** on an action based on probabilities of the conditions

Recall Bayes Rule

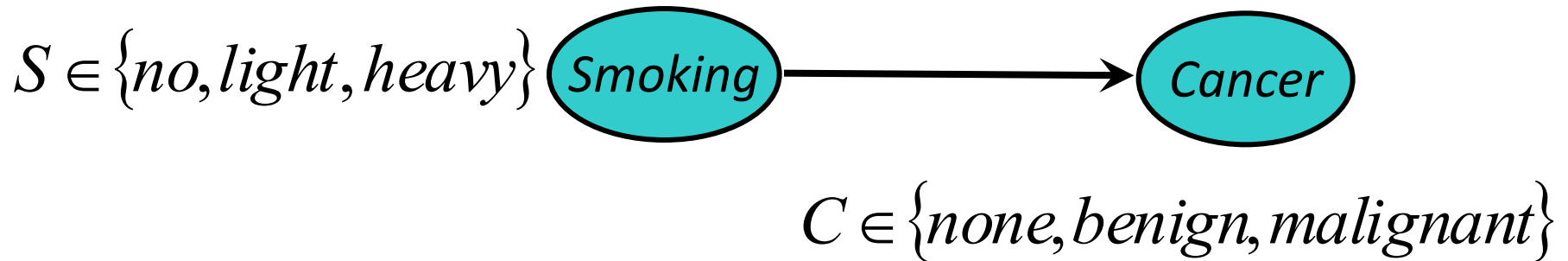
$$P(H, E) = P(H | E)P(E) = P(E | H)P(H)$$

$$P(H | E) = \frac{P(E | H) * P(H)}{P(E)}$$

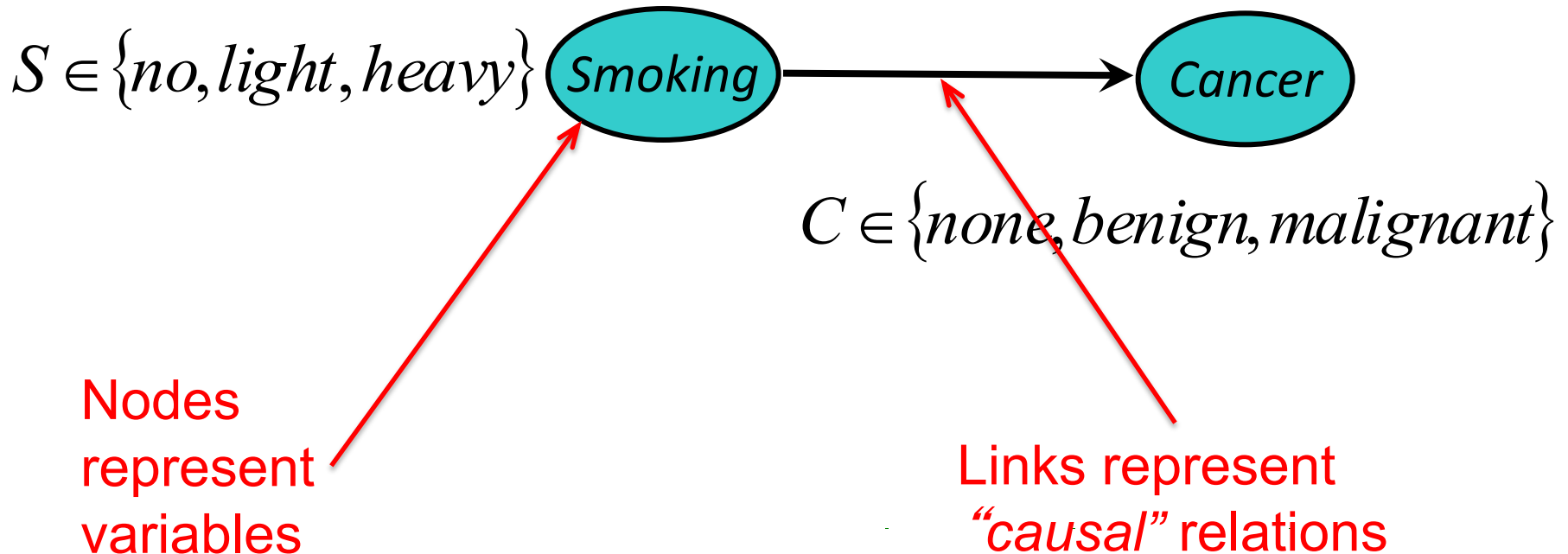
$$P(E | H) = \frac{P(H | E) * P(E)}{P(H)}$$

Note symmetry: we can compute probability of a *hypothesis given its evidence* as well as probability of *evidence given hypothesis*

Simple Bayesian Network



Simple Bayesian Network



Simple Bayesian Network



Prior probability of S

$P(S=no)$	0.80
$P(S=light)$	0.15
$P(S=heavy)$	0.05

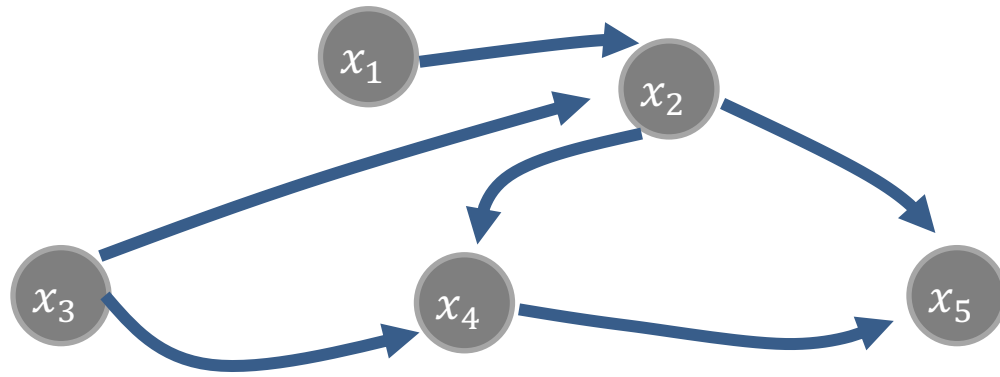
Nodes with no in-links
have **prior
probabilities**

Conditional distribution of S and C

$Smoking=$	no	$light$	$heavy$
$C=none$	0.96	0.88	0.60
$C=benign$	0.03	0.08	0.25
$C=malignant$	0.01	0.04	0.15 ¹⁷

Nodes with in-links
have **joint
probability
distributions**

Bayesian Networks: Directed Acyclic Graphs

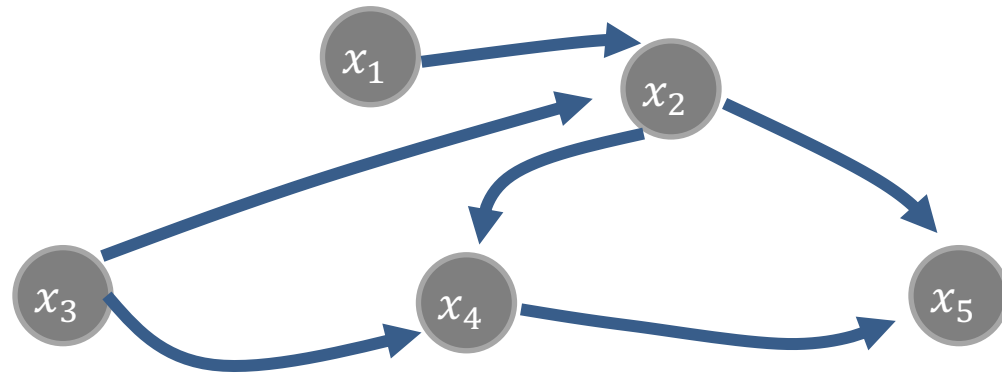


$$p(x_1, x_2, x_3, \dots, x_N) = \prod_i p(x_i \mid \pi(x_i))$$

topological
sort

“parents of”

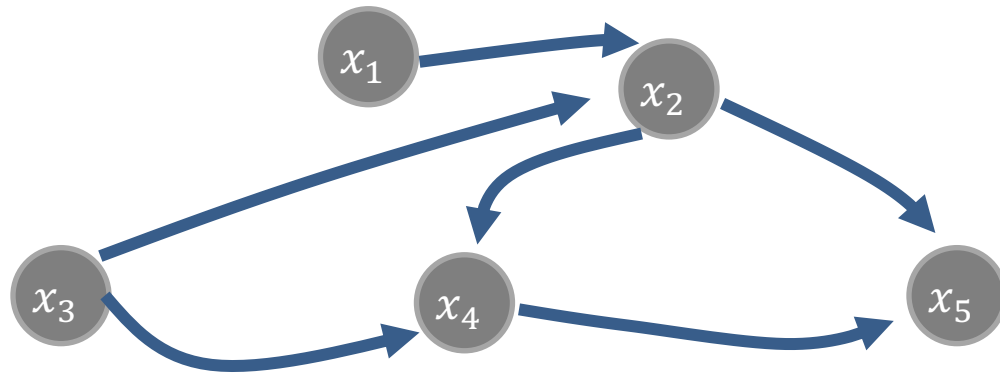
Bayesian Networks: Directed Acyclic Graphs



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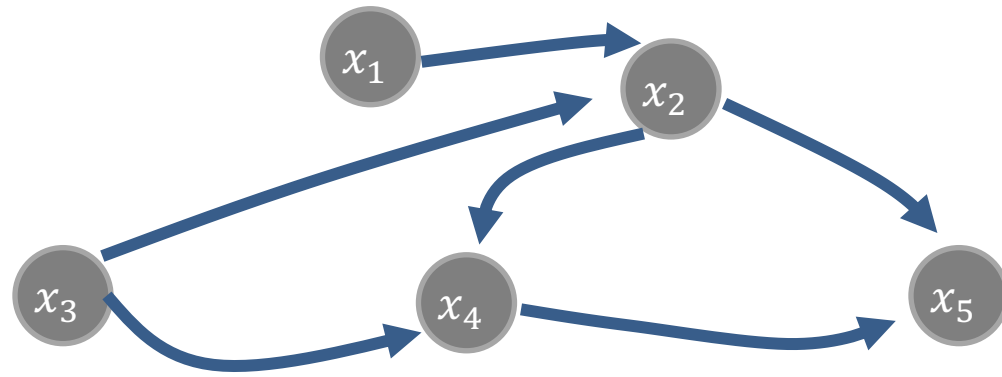
$$p(x_1, x_2, x_3, x_4, x_5) = ???$$

Bayesian Networks: Directed Acyclic Graphs



$$p(x_1, x_2, x_3, x_4, x_5) = \\ p(x_1)p(x_3)p(x_2|x_1, x_3)p(x_4|x_2, x_3)p(x_5|x_2, x_4)$$

Bayesian Networks: Directed Acyclic Graphs

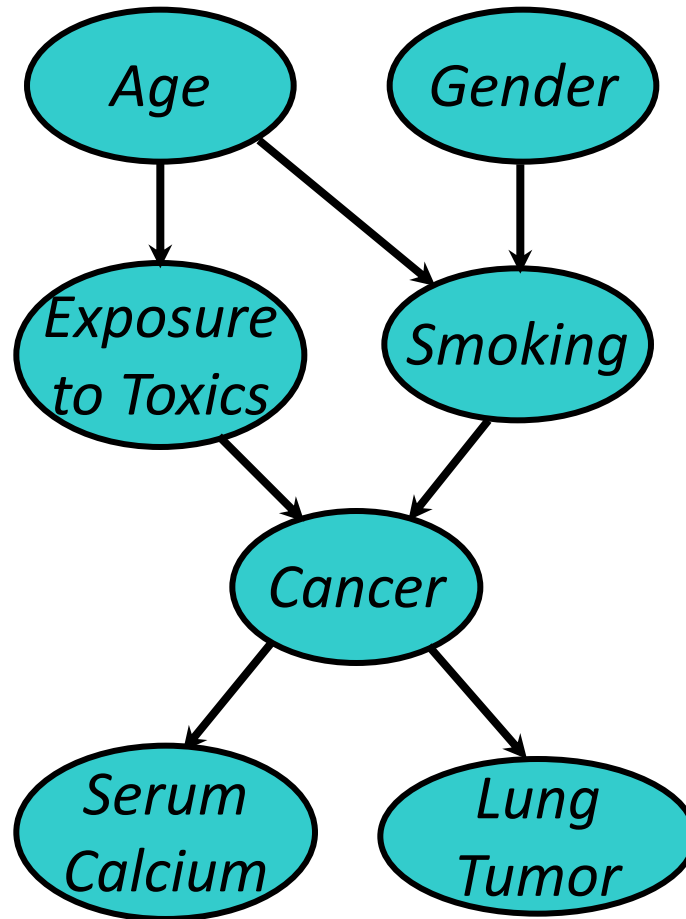


$$p(x_1, x_2, x_3, \dots, x_N) = \prod_i p(x_i \mid \pi(x_i))$$

exact inference in general DAGs is NP-hard

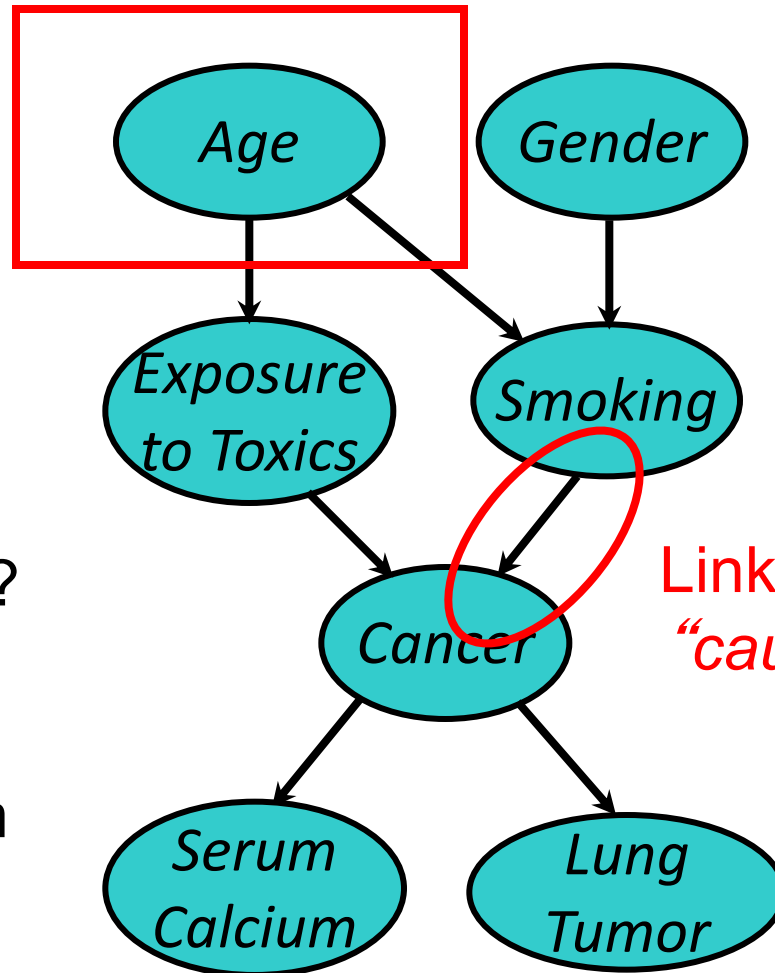
inference in trees can be exact

More Complex Bayesian Network



More Complex Bayesian Network

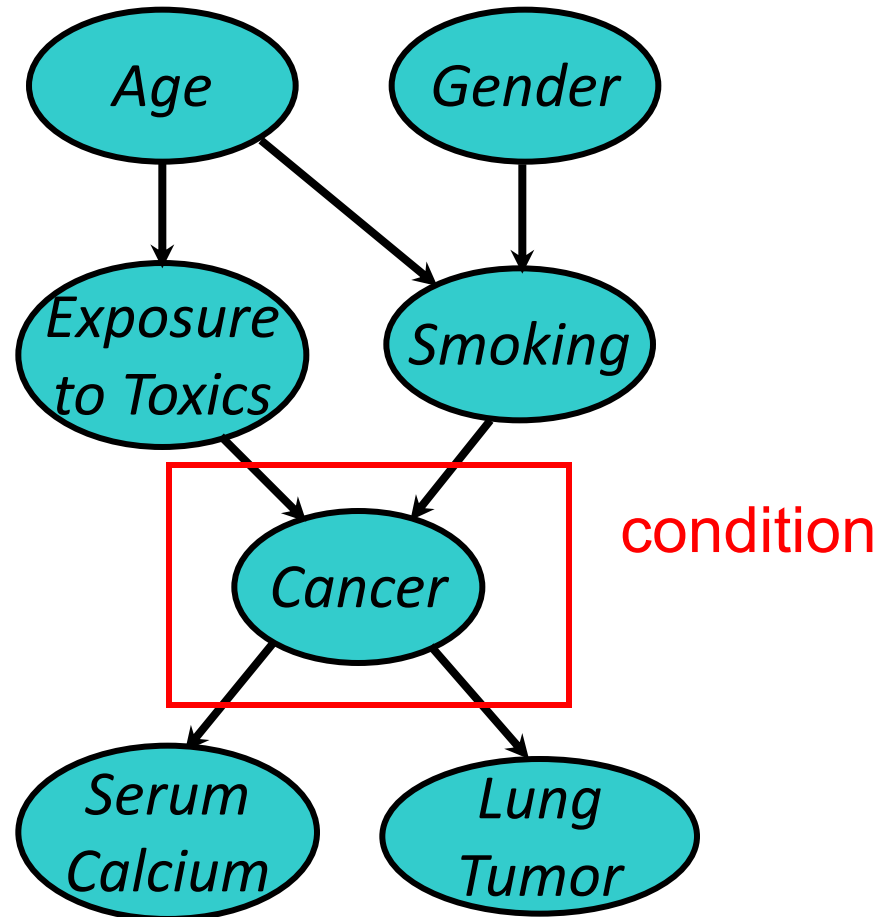
Nodes
represent
variables



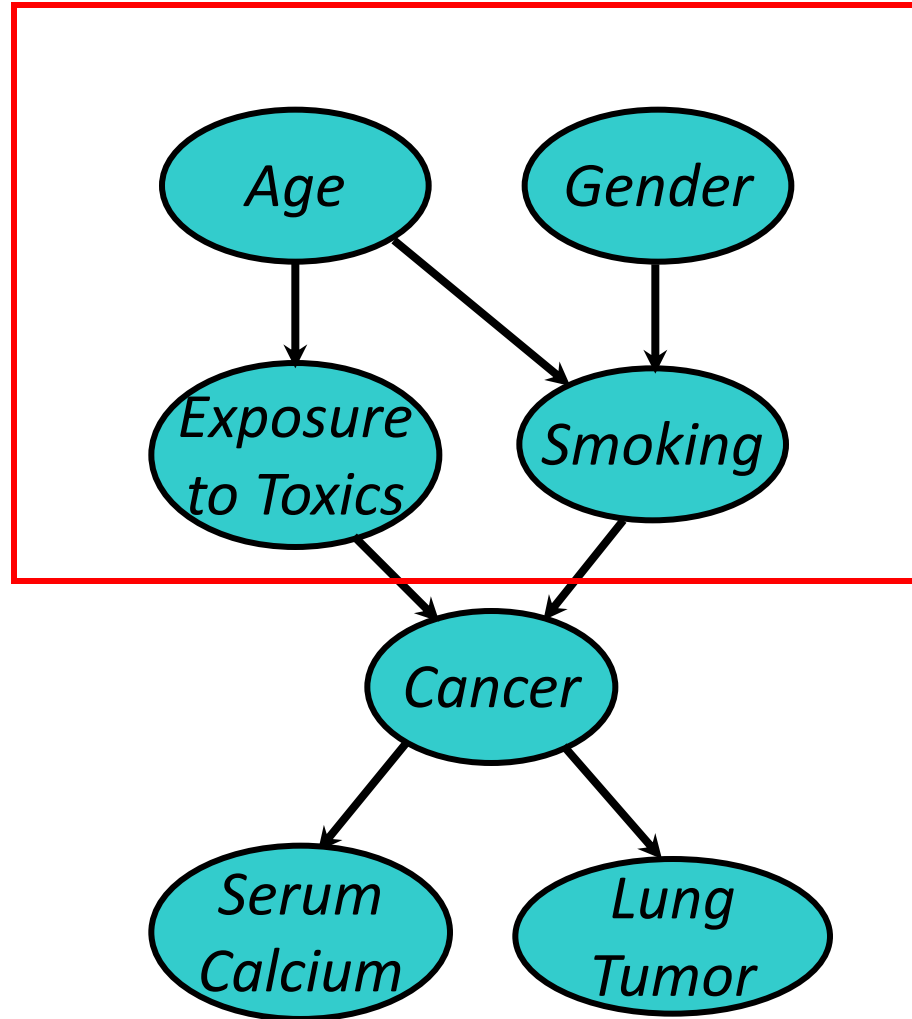
Links represent
“causal” relations

- Does gender cause smoking?
- Influence might be a better term

More Complex Bayesian Network

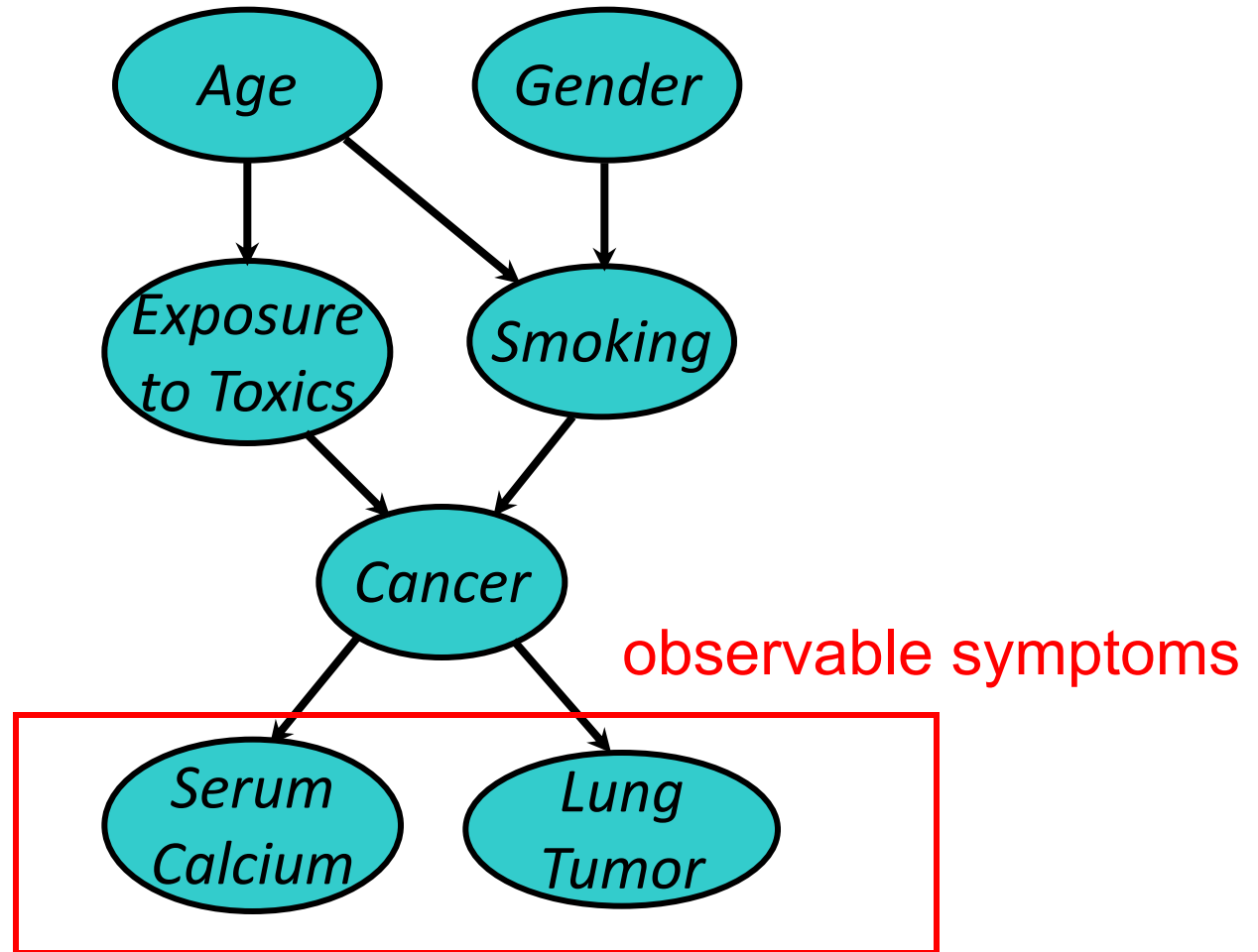


More Complex Bayesian Network



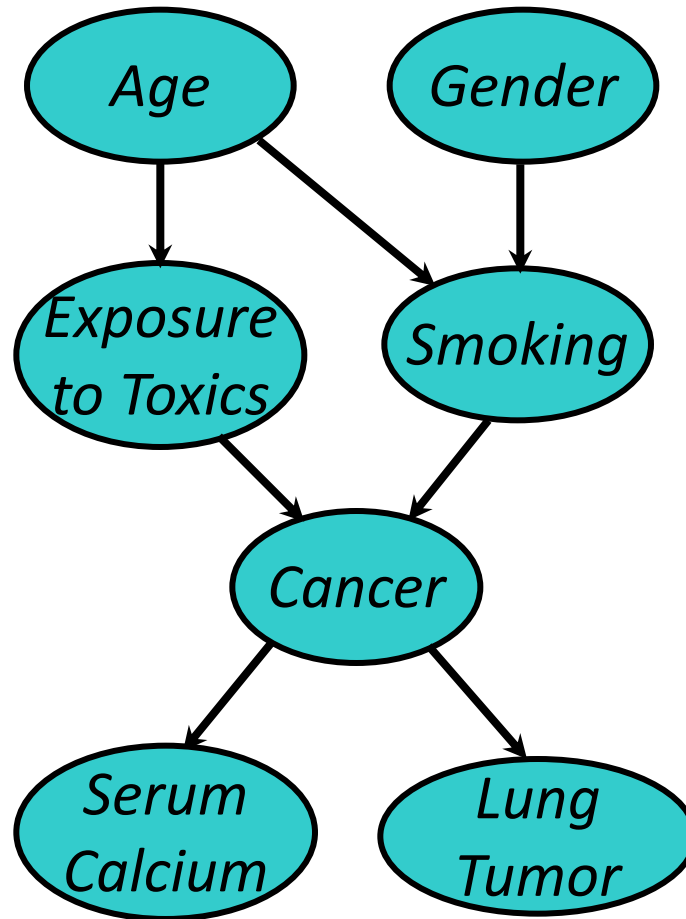
predispositions

More Complex Bayesian Network



More Complex Bayesian Network

Can we predict likelihood of **lung tumor** given values of other 6 variables?



- Model has 7 variables
- Complete joint probability distribution will have 7 dimensions!
- Too much data required ☹
- BBN simplifies: a node has a CPT with data on itself & parents in graph

Independence & Conditional Independence in BBNs

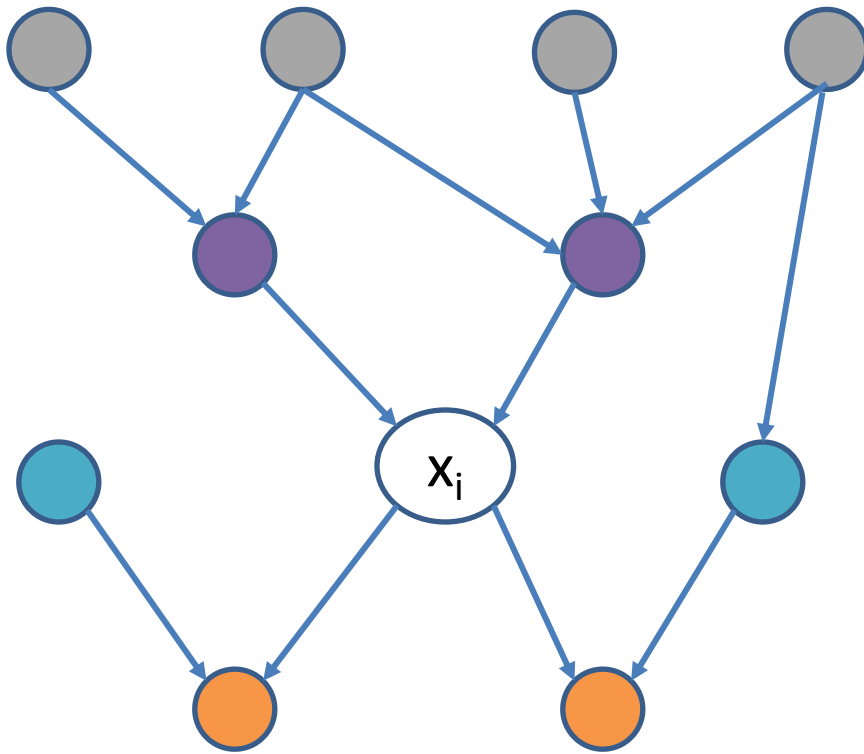
Read these independence relationships right from the graph!

There are two common concepts that can help:

1. Markov blanket
2. D-separation (not covering)

Markov Blanket

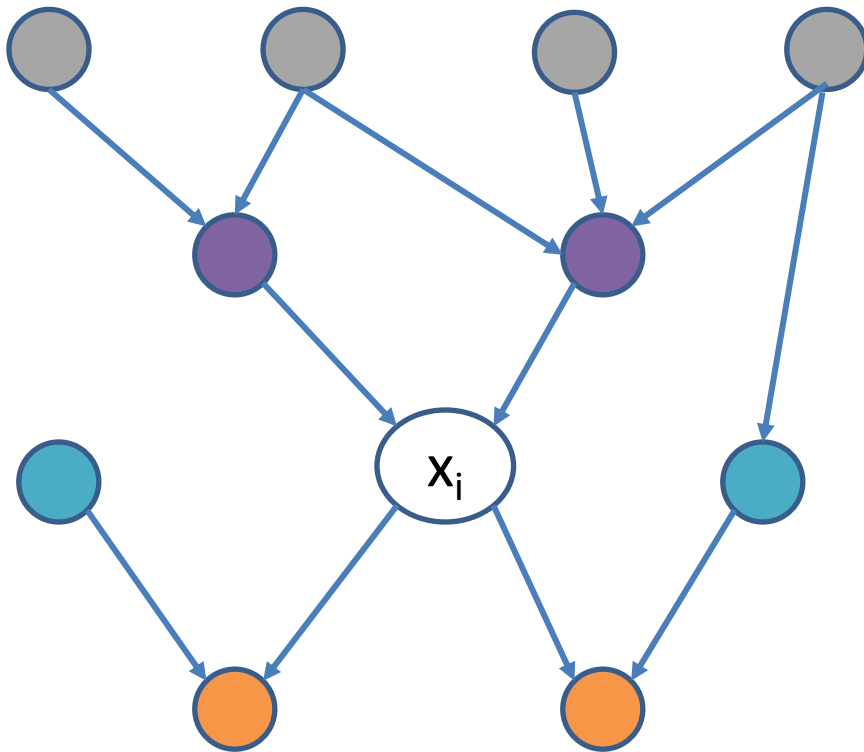
The **Markov Blanket** of a node x_i is the set of nodes needed to form the complete conditional for a variable x_i



Markov blanket of a node x is its **parents**, **children**, and **children's parents**

(in this example, shading does not show observed/latent)

Markov Blanket



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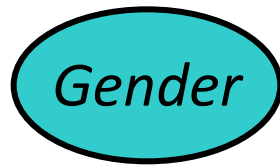
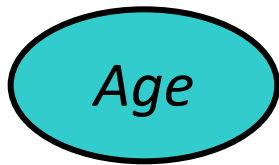
$$p(\text{ } | \text{ })$$

=

$$p(\text{ } | \text{ })$$

Given its Markov blanket, a node is conditionally independent of all other nodes in the BN

Independence



*Age and Gender are independent**.

$$P(A, G) = P(G) * P(A)$$

There is no path
between them in
the graph

$$P(A | G) = P(A)$$

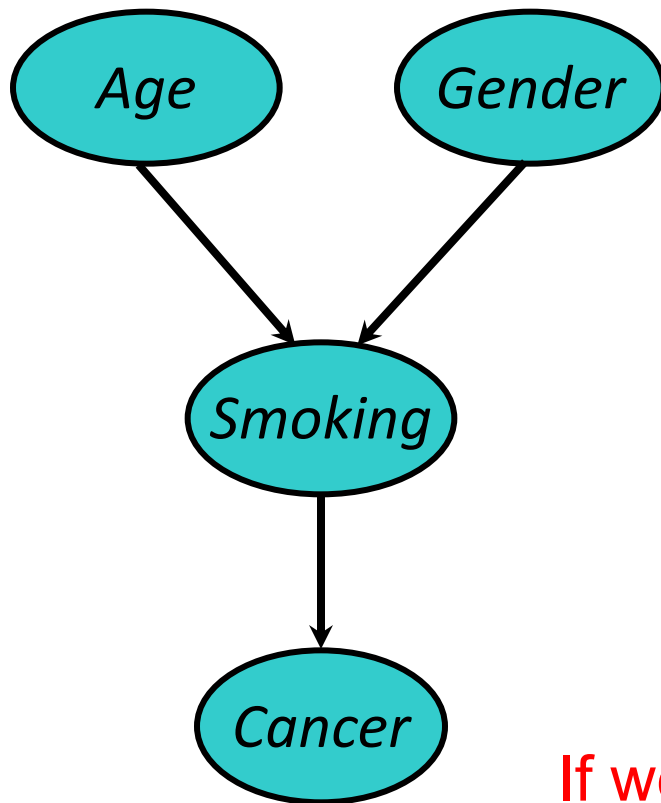
$$P(G | A) = P(G)$$

$$P(A, G) = P(G | A) P(A) = P(G)P(A)$$

$$P(A, G) = P(A | G) P(G) = P(A)P(G)$$

* Not strictly true, but a reasonable approximation³¹

Conditional Independence

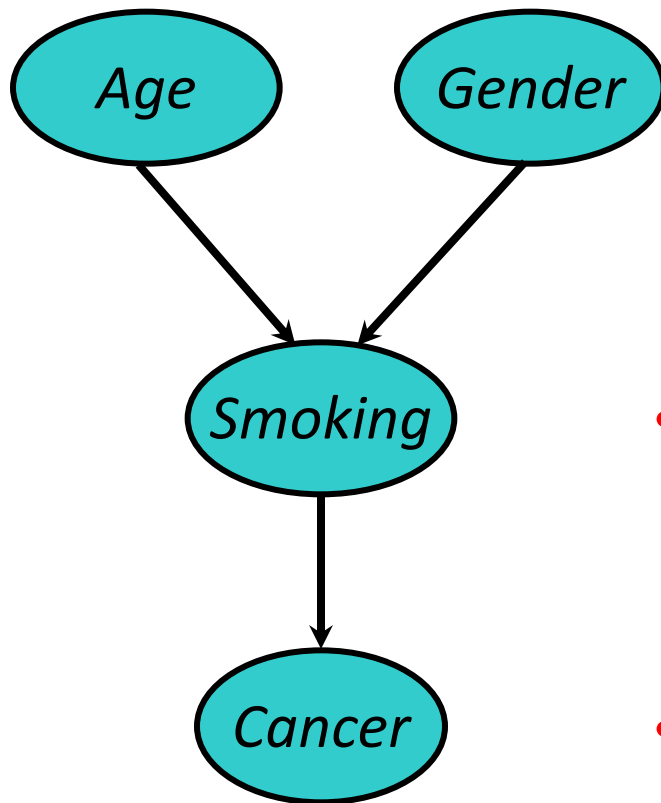


Cancer is independent of Age and Gender given Smoking

$$P(C \mid A, G, S) = P(C \mid S)$$

If we know value of smoking, no need to know values of age or gender

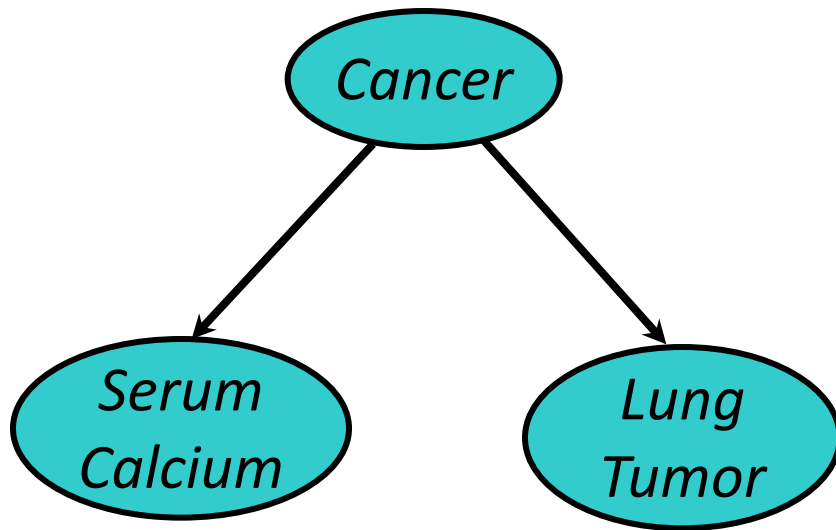
Conditional Independence



Cancer is independent of Age and Gender given Smoking

- Instead of one big CPT with 4 variables, we have two smaller CPTs with 3 and 2 variables
- If all variables binary: 12 models ($2^3 + 2^2$) rather than 16 (2^4)

Conditional Independence: Naïve Bayes



Serum Calcium and Lung Tumor are dependent

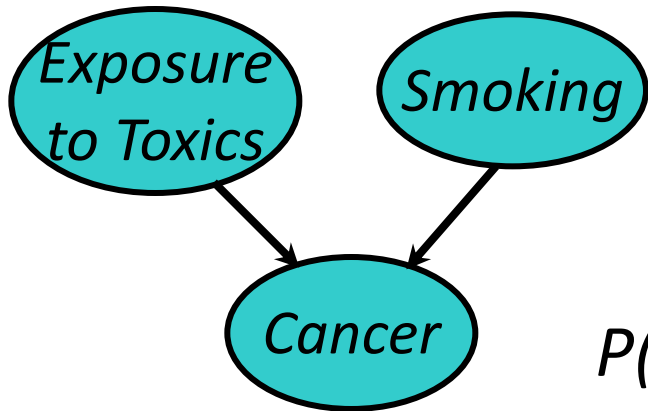
Serum Calcium is independent of Lung Tumor, given Cancer

$$P(L \mid SC, C) = P(L \mid C)$$

$$P(SC \mid L, C) = P(SC \mid C)$$

Naïve Bayes assumption: evidence (e.g., symptoms) independent given disease; easy to combine evidence

Explaining Away



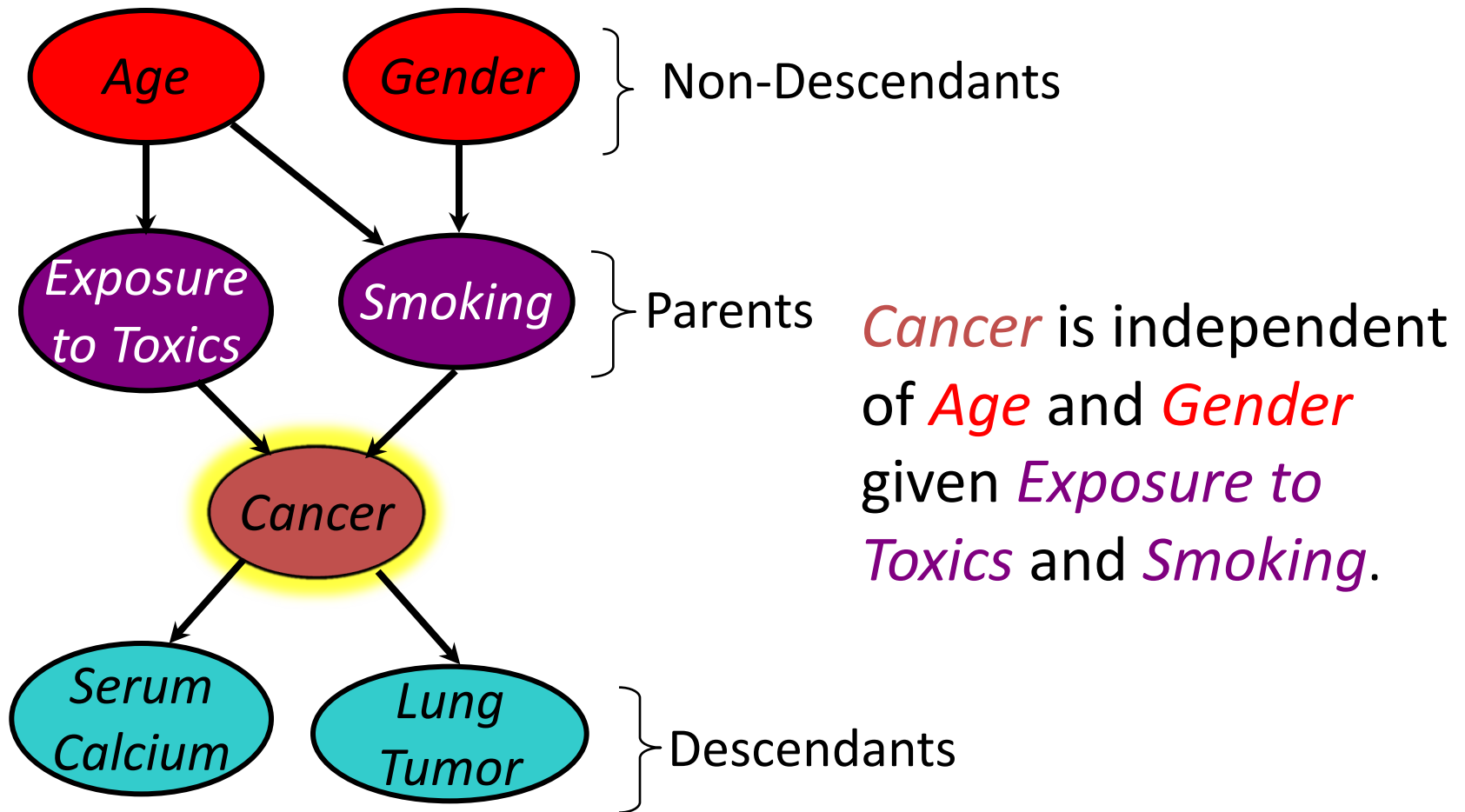
Exposure to Toxics and Smoking are independent

*Exposure to Toxics is **dependent** on Smoking, given Cancer*

$$P(E=\text{heavy} \mid C=\text{malignant}) > P(E=\text{heavy} \mid C=\text{malignant}, S=\text{heavy})$$

- *Explaining away*: reasoning pattern where confirmation of one cause reduces need to invoke alternatives
- Essence of [Occam's Razor](#) (prefer hypothesis with fewest assumptions)
- Relies on independence of causes

Conditional Independence



BBN Construction

The knowledge acquisition process for a BBN involves three steps

KA1: Choosing appropriate variables

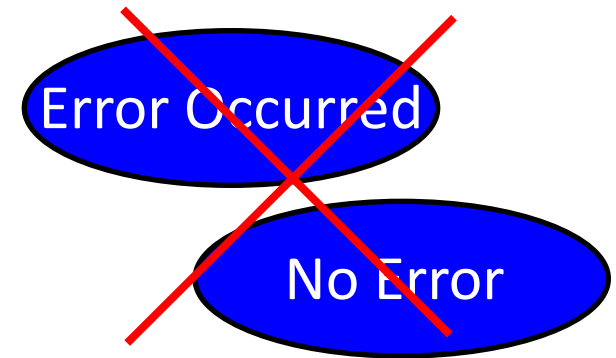
KA2: Deciding on the network structure

KA3: Obtaining data for the conditional probability tables

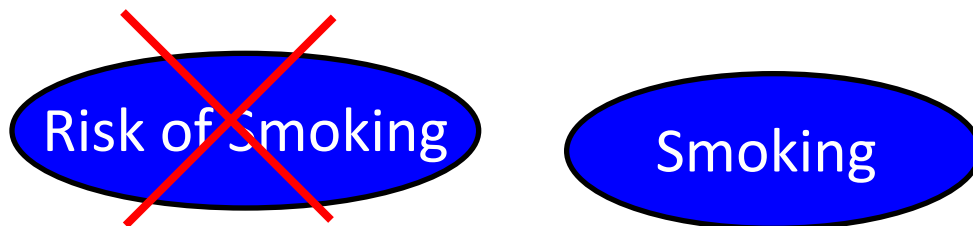
KA1: Choosing variables

- Variable values: integers, reals or enumerations
- Variable should have collectively *exhaustive*, *mutually exclusive* values

$$x_1 \vee x_2 \vee x_3 \vee x_4$$
$$\neg (x_i \wedge x_j) \quad i \neq j$$



- They should be values, not probabilities

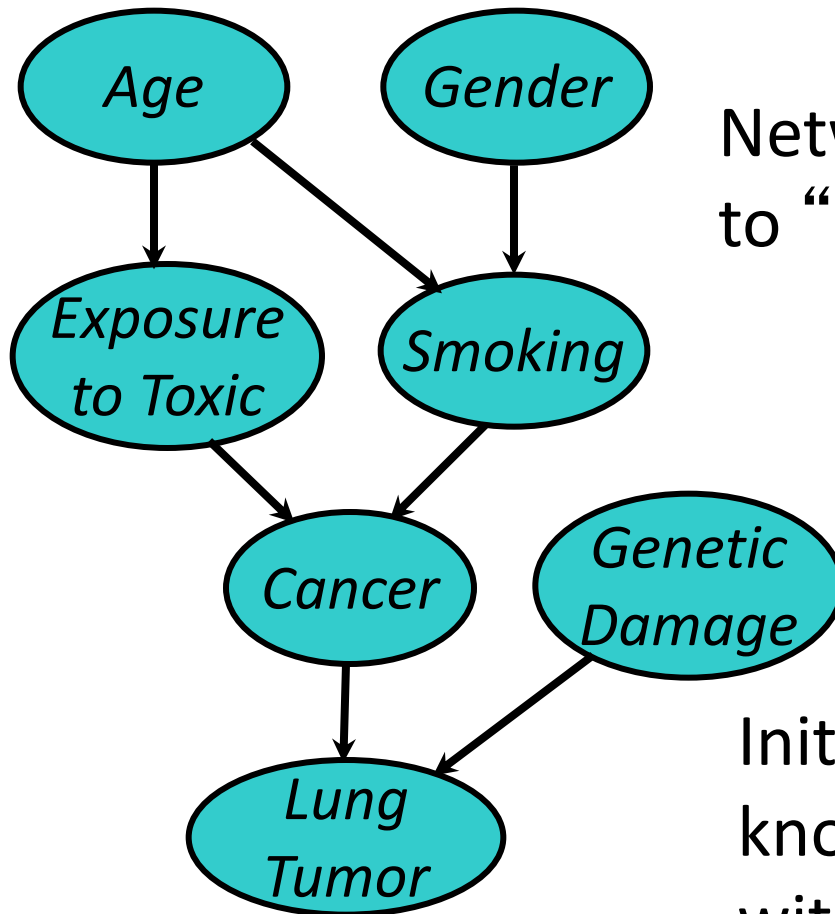


Heuristic: Knowable in Principle

Example of good variables

- Weather: {Sunny, Cloudy, Rain, Snow}
- Gasoline: Cents per gallon {0,1,2...}
- Temperature: { $\geq 100^{\circ}$ F , $< 100^{\circ}$ F }
- User needs help on Excel Charts: {Yes, No}
- User's personality: {dominant, submissive}

KA2: Structuring



Network structure corresponding to “causality” is usually good.

Initially this uses the designer’s knowledge but can be checked with data

KA3: The Numbers

- For each variable we have a table of probability of its value for values of its **parents**
- For variables w/o parents, we have **prior probabilities**

$S \in \{no, light, heavy\}$

$C \in \{none, benign, malignant\}$



smoking priors	
no	0.80
light	0.15
heavy	0.05

	smoking		
cancer	no	light	heavy
none	0.96	0.88	0.60
benign	0.03	0.08	0.25
malignant	0.01	0.04	0.15 ₅₀

Three (Four) kinds of reasoning

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To which we can add a fourth:

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Fundamental Inference & Learning

Question

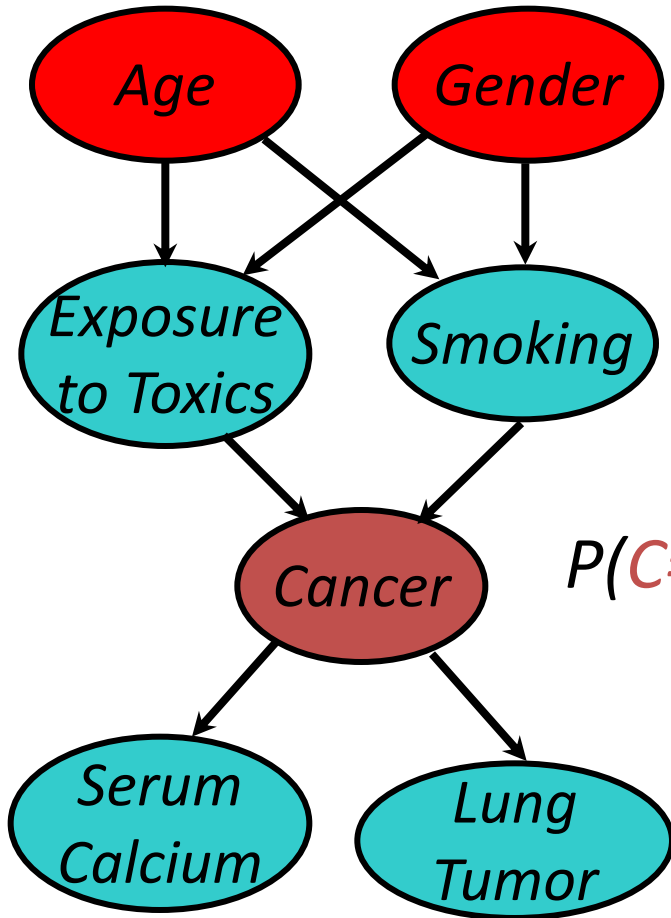
- Compute posterior probability of a node given some other nodes

$$p(Q|x_1, \dots, x_j)$$

- Some techniques
 - MLE (maximum likelihood estimation)/MAP (maximum a posteriori)
 - Variable Elimination
 - (Loopy) Belief Propagation ((Loopy) BP)
 - Monte Carlo
 - Variational methods
 - ...

*Advanced
topics*

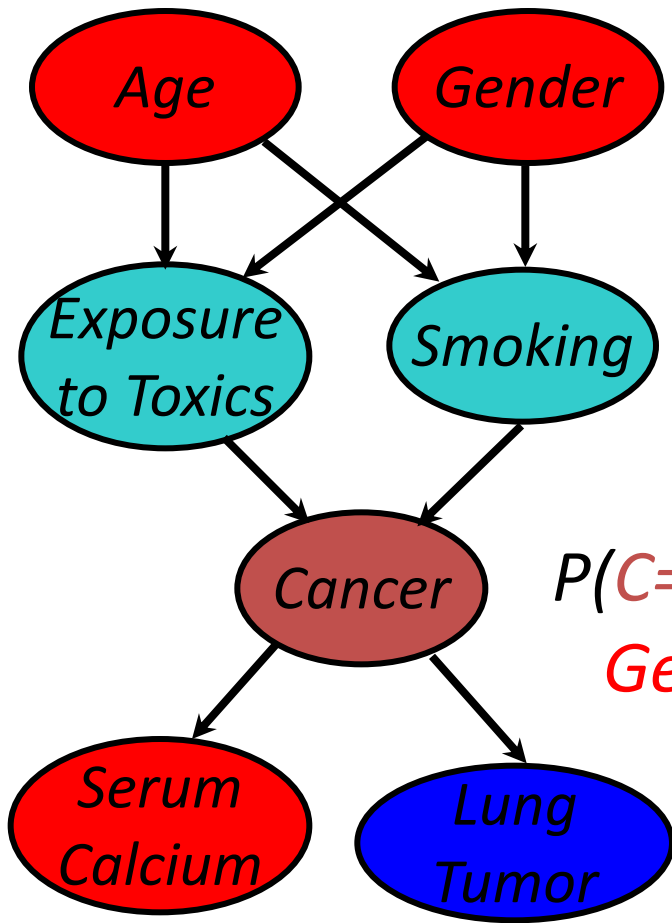
Predictive Inference



How likely are **elderly males** to get **malignant cancer**?

$$P(C=\text{malignant} \mid \text{Age}>60, \text{Gender}=\text{male})$$

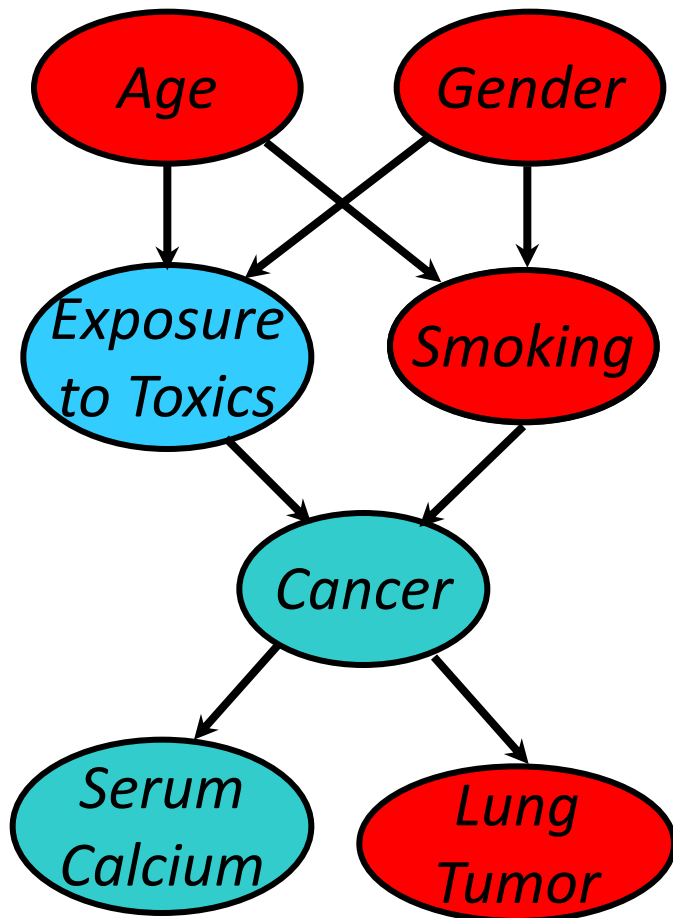
Predictive and diagnostic combined



How likely is an **elderly male** patient with high **Serum Calcium** to have malignant cancer?

$$P(C=\text{malignant} \mid \text{Age} > 60, \text{Gender} = \text{male}, \text{Serum Calcium} = \text{high})$$

Explaining away



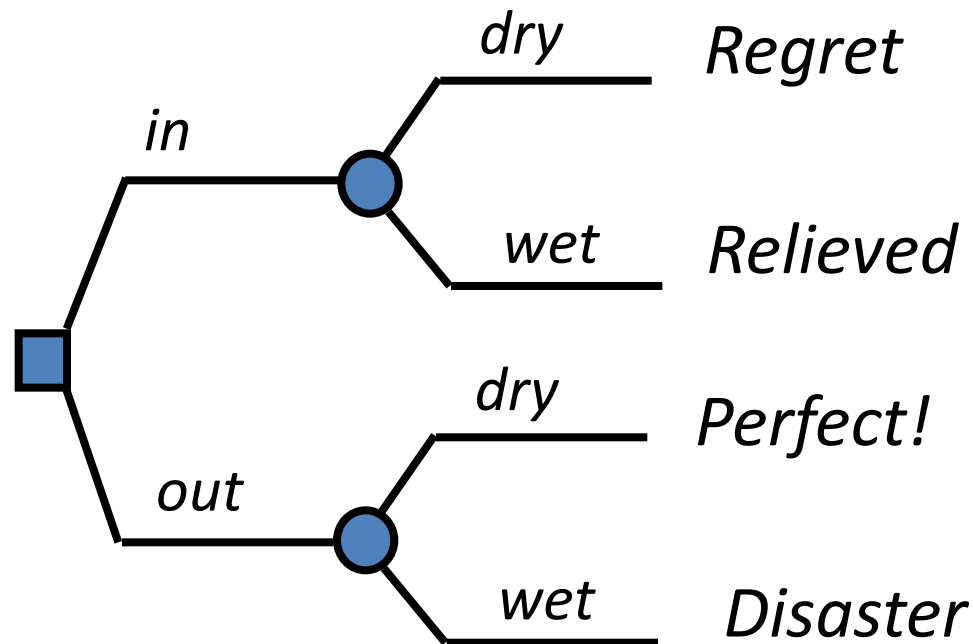
- If we see a **lung tumor**, the probability of **heavy smoking** and of **exposure to toxics** both go up
- If we then observe **heavy smoking**, the probability of **exposure to toxics** goes back down

Decision making

- A decision in a medical domain might be a choice of treatment (e.g., radiation or chemotherapy)
- Decisions should be made to **maximize expected utility**
- View decision making in terms of
 - Beliefs/Uncertainties
 - Alternatives/Decisions
 - Objectives/Utilities

Decision Problem

Should I have my party
inside or outside?



Decision Making with BBNs

- Today's weather forecast might be either sunny, cloudy or rainy
- Should you take an umbrella when you leave?
- Your decision depends only on the forecast
 - The forecast “depends on” the actual weather
- Your satisfaction depends on your decision and the weather
 - Assign a utility to each of four situations: (rain | no rain) x (umbrella, no umbrella)

Decision Making with BBNs

- Extend BBN framework to include two new kinds of nodes: **decision** and **utility**
- **Decision** node computes the expected utility of a decision given its parent(s) (e.g., forecast) and a valuation
- **Utility** node computes utility value given its parents, e.g. a decision and weather
 - Assign utility to each situations: (rain|no rain) x (umbrella, no umbrella)
 - Utility value assigned to each is probably subjective

Fundamental Inference & Learning

Question

- Compute posterior probability of a node given some other nodes

$$p(Q|x_1, \dots, x_j)$$

- Some techniques
 - MLE (maximum likelihood estimation)/MAP (maximum a posteriori) [covered 2nd]
 - Variable Elimination [covered 1st]
 - (Loopy) Belief Propagation ((Loopy) BP)
 - Monte Carlo
 - Variational methods
 - ...

*Advanced
topics*

Variable Elimination

- Inference: Compute posterior probability of a node given some other nodes

$$p(Q|x_1, \dots, x_j)$$

- Variable elimination: An algorithm for exact inference
 - Uses dynamic programming
 - Not necessarily polynomial time!

Variable Elimination (High-level)

Goal: $p(Q | x_1, \dots, x_j)$

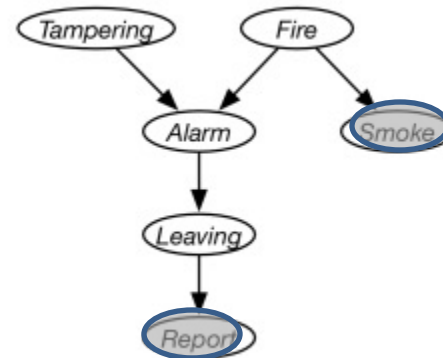
(The word “factor” is used for each CPT.)

1. Pick one of the non-conditioned, MB variables
2. Eliminate this variable by marginalizing (summing) it out from all factors (CPTs) that contain it
3. Go back to 1 until no (MB) variables remain
4. Multiply the remaining factors and normalize.

Variable Elimination: Example

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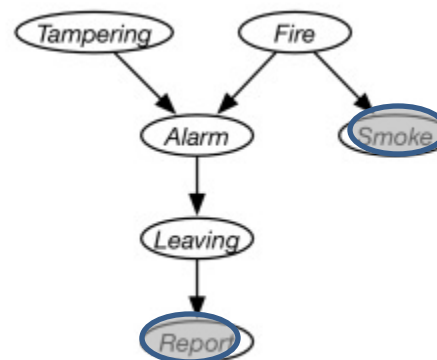


Goal: $P(\text{Tampering} \mid \text{Smoke}=\text{true} \wedge \text{Report}=\text{true})$

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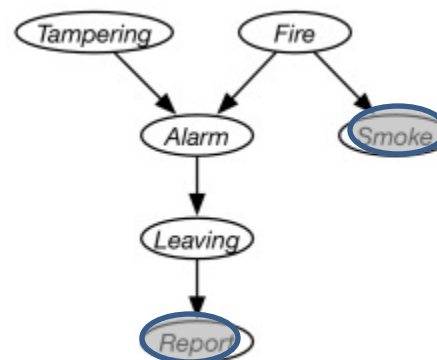
Goal: $P(\text{Tampering} \mid \text{Smoke}=\text{true} \wedge \text{Report}=\text{true})$

Conditional Probability	Factor
$P(\text{Tampering})$	$f_0(\text{Tampering})$
$P(\text{Fire})$	$f_1(\text{Fire})$
$P(\text{Alarm} \mid \text{Tampering}, \text{Fire})$	$f_2(\text{Tampering}, \text{Fire}, \text{Alarm})$
$P(\text{Smoke} = \text{yes} \mid \text{Fire})$	$f_3(\text{Fire})$
$P(\text{Leaving} \mid \text{Alarm})$	$f_4(\text{Alarm}, \text{Leaving})$
$P(\text{Report} = \text{yes} \mid \text{Leaving})$	$f_5(\text{Leaving})$

Variable Elimination: Example

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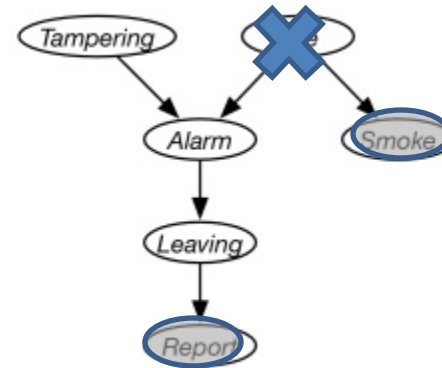
Task: Eliminate Fire

Conditional Probability	Factor
$P(\text{Tampering})$	$f_0(\text{Tampering})$
$P(\text{Fire})$	$f_1(\text{Fire})$
$P(\text{Alarm} \mid \text{Tampering}, \text{Fire})$	$f_2(\text{Tampering}, \text{Fire}, \text{Alarm})$
$P(\text{Smoke} = \text{yes} \mid \text{Fire})$	$f_3(\text{Fire})$
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Variable Elimination: Example

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1. Pick one of the non-conditioned, MB variables
2. Eliminate this variable by marginalizing (summing) it out from **all factors (CPTs) that contain it**
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Goal: $P(\text{Tampering} \mid \text{Smoke}=\text{true} \wedge \text{Report}=\text{true})$

$f_1(\text{Fire})$

$f_2(\text{Tampering}, \text{Fire}, \text{Alarm})$

$f_3(\text{Fire})$



$f_6(\text{Tampering}, \text{Alarm}) =$

$$= \sum_u f_1(\text{Fire} = u) f_2(T, F = u, A) f_3(F = u)$$

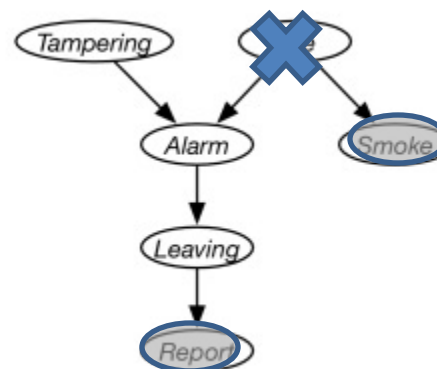
$$= \sum_u p(\text{Fire} = u) p(A \mid T, F = u) p(S = y \mid F = u)$$

Conditional Probability	Factor
$P(\text{Tampering})$	$f_0(\text{Tampering})$
$P(\text{Fire})$	$f_1(\text{Fire})$
$P(\text{Alarm} \mid \text{Tampering}, \text{Fire})$	$f_2(\text{Tampering}, \text{Fire}, \text{Alarm})$
$P(\text{Smoke} = \text{yes} \mid \text{Fire})$	$f_3(\text{Fire})$
$P(\text{Leaving} \mid \text{Alarm})$	$f_4(\text{Alarm}, \text{Leaving})$
$P(\text{Report} = \text{yes} \mid \text{Leaving})$	$f_5(\text{Leaving})$

Variable Elimination: Example

(The word “factor” is used for each CPT.)

1. Pick one of the non-conditioned, MB variables
2. Eliminate this variable by marginalizing (summing) it out from **all factors (CPTs) that contain it**
3. Go back to 1 until no (MB) variables remain
4. Multiply the remaining factors and normalize.



Goal: $P(\text{Tampering} \mid \text{Smoke}=\text{true} \wedge \text{Report}=\text{true})$

$f_6(\text{Tampering}, \text{Alarm}) =$

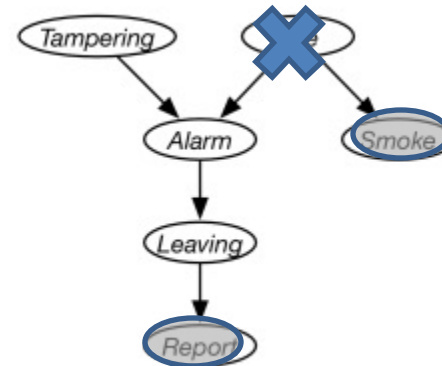
$$\begin{aligned}
 &= \sum_u p(\text{Fire} = u) p(A \mid T, F = u) p(S = y \mid F = u) \\
 &= p(\text{Fire} = y) p(A \mid T, F = y) p(S = y \mid F = y) + \\
 &\quad p(\text{Fire} = n) p(A \mid T, F = n) p(S = y \mid F = n)
 \end{aligned}$$

Conditional Probability	Factor
$P(\text{Tampering})$	$f_0(\text{Tampering})$
$P(\text{Fire})$	$f_1(\text{Fire})$
$P(\text{Alarm} \mid \text{Tampering}, \text{Fire})$	$f_2(\text{Tampering}, \text{Fire}, \text{Alarm})$
$P(\text{Smoke} = \text{yes} \mid \text{Fire})$	$f_3(\text{Fire})$
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Goal: $P(\text{Tampering} \mid \text{Smoke}=\text{true} \wedge \text{Report}=\text{true})$

$f_6(\text{Tampering}, \text{Alarm}) =$

$$= \sum_u p(\text{Fire} = u) p(A \mid T, F = u) p(S = y \mid F = u)$$

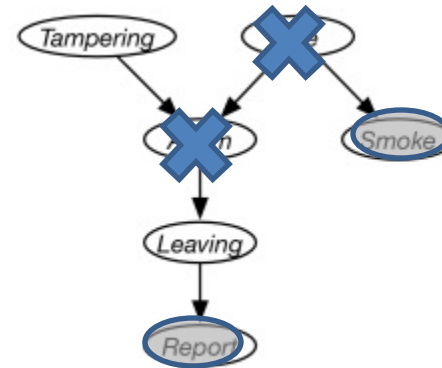
Tamp.	Alarm	f6
Yes	Yes	$p(\text{Fire} = y) p(A = y \mid T = y, F = y) p(S = y \mid F = y) + p(\text{Fire} = n) p(A = y \mid T = y, F = n) p(S = y \mid F = n)$
Yes	No	...
No	No	...
No	Yes	...

Conditional Probability	Factor
$P(\text{Tampering})$	$f_0(\text{Tampering})$
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Goal: $P(\text{Tampering} \mid \text{Smoke}=\text{true} \wedge \text{Report}=\text{true})$

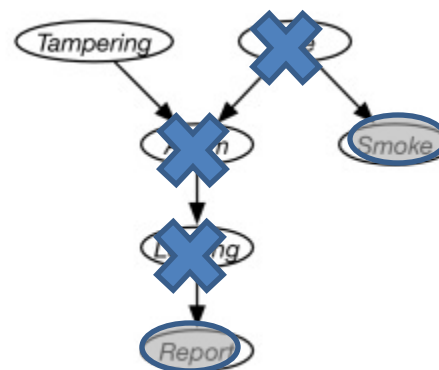
Task: Eliminate Alarm

Conditional Probability	Factor
$P(\text{Tampering})$	$f_0(\text{Tampering})$
$P(\text{Fire})$	$f_1(\text{Fire})$
$P(\text{Alarm} \mid \text{Tampering}, \text{Fire})$	$f_2(\text{Tampering}, \text{Fire}, \text{Alarm})$
$P(\text{Smoke} = \text{yes} \mid \text{Fire})$	$f_3(\text{Fire})$
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Variable Elimination: Example

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Goal: $P(\text{Tampering} \mid \text{Smoke}=\text{true} \wedge \text{Report}=\text{true})$

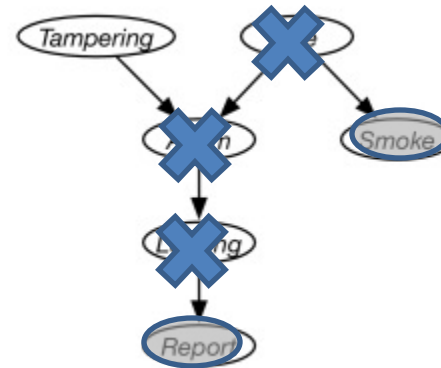
...other computations not shown---see the book...

Conditional Probability	Factor
$P(\text{Tampering})$	$f_0(\text{Tampering})$
$P(\text{Fire})$	$f_1(\text{Fire})$
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4. **Multiply the remaining factors and normalize.**



Goal: $P(\text{Tampering} \mid \text{Smoke}=\text{true} \wedge \text{Report}=\text{true})$

Task: Normalize in order to compute $p(\text{Tampering})$

We'll have a single factor $f_9(\text{Tampering})$:

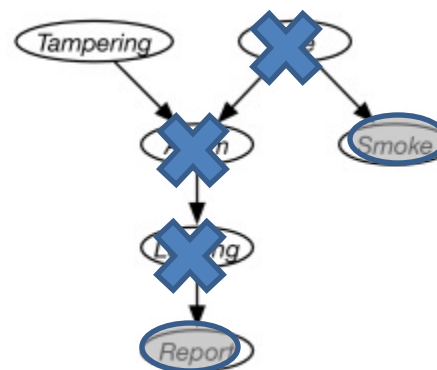
$$p(T = u) = \frac{f_9(T = u)}{\sum_v f_9(T = v)}$$

Conditional Probability	Factor
$P(\text{Tampering})$	$f_0(\text{Tampering})$
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$P(\text{Alarm} \mid \text{Tampering}, \text{Fire})$	$f_2(\text{Tampering}, \text{Fire}, \text{Alarm})$
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Variable Elimination: Example

(The word “factor” is used for each CPT.)

1. Pick one of the non-conditioned, MB variables
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Goal: $P(\text{Tampering} \mid \text{Smoke}=\text{true} \wedge \text{Report}=\text{true})$

Task: Normalize in order to compute $p(\text{Tampering})$

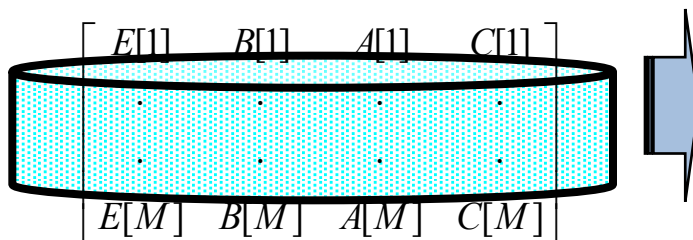
We'll have a single factor $f_9(\text{Tampering})$:

$$p(T = y) = \frac{f_9(T = y)}{f_9(T = y) + f_9(T = n)}$$

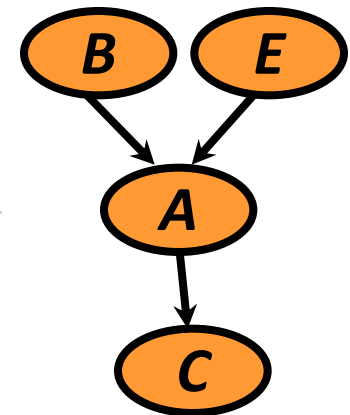
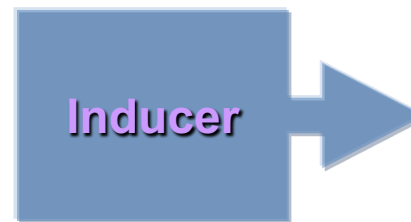
Conditional Probability	Factor
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Learning Bayesian networks

- Given training set $\mathbf{D} = \{\mathbf{x}[1], \dots, \mathbf{x}[M]\}$
- Find graph that best matches \mathbf{D}
 - model selection
 - parameter estimation



Data D



Learning Bayesian Networks

- Describe a BN by specifying its (1) structure and (2) conditional probability tables (CPTs)
- Both can be learned from data, but
 - learning structure much harder than learning parameters
 - learning when some nodes are hidden, or with missing data harder still

- Four cases:

<i>Structure</i>	<i>Observability</i>	<i>Method</i>
Known	Full	Maximum Likelihood Estimation
Known	Partial	EM (or gradient ascent)
Unknown	Full	Search through model space
Unknown	Partial	EM + search through model space

Variations on a theme

- **Known structure, fully observable:** only need to do parameter estimation
- **Unknown structure, fully observable:** do heuristic search through structure space, then parameter estimation
- **Known structure, missing values:** use expectation maximization (EM) to estimate parameters
- **Known structure, hidden variables:** apply adaptive probabilistic network (APN) techniques
- **Unknown structure, hidden variables:** too hard to solve!

Fundamental Inference Question

- Compute posterior probability of a node given some other nodes

$$p(Q|x_1, \dots, x_j)$$

- Some techniques
 - MLE (maximum likelihood estimation)/MAP (maximum a posteriori) [covered 2nd]
 - Variable Elimination [covered 1st]
 - (Loopy) Belief Propagation ((Loopy) BP)
 - Monte Carlo
 - Variational methods
 - ...

*Advanced
topics*

Parameter estimation

- Assume known structure
- Goal: estimate BN parameters θ
 - entries in local probability models, $P(X \mid \text{Parents}(X))$
- A parameterization θ is good if it is likely to generate the observed data:

$$L(\theta : D) = P(D \mid \theta) = \prod_m P(x[m] \mid \theta)$$



i.i.d. samples

- Maximum Likelihood Estimation (MLE) Principle:
Choose θ^* so as to maximize L

Parameter estimation II

- The likelihood **decomposes** according to the structure of the network
 - we get a separate estimation task for each parameter
- The MLE (maximum likelihood estimate) solution for **discrete** data & RV values:
 - for each value x of a node X
 - and each instantiation \mathbf{u} of $Parents(X)$

$$\theta_{x|\mathbf{u}}^* = \frac{N(\mathbf{x}, \mathbf{u})}{N(\mathbf{u})}$$

← sufficient statistics

- Just need to collect the counts for every combination of parents and children observed in the data
- MLE is equivalent to an assumption of a uniform prior over parameter values

Learning:

Maximum Likelihood Estimation (MLE)

Core concept in intro statistics:

- Observe some data \mathcal{X}
- Compute some distribution $g(\mathcal{X})$ to {predict, explain, generate} \mathcal{X}
- Assume g is controlled by parameters ϕ , i.e., $g_{\phi}(\mathcal{X})$
 - Sometimes written $g(\mathcal{X}; \phi)$
- Learning appropriate value(s) of ϕ allows you to **GENERALIZE** about \mathcal{X}

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Central to machine learning:

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Learning Parameters for the Die Model

$$p(w_1, w_2, \dots, w_N) = p(w_1)p(w_2) \cdots p(w_N) = \prod_i p(w_i)$$

maximize (log-) likelihood to learn the probability parameters

Q: Why is maximizing log-likelihood a reasonable thing to do?

Learning Parameters for the Die Model

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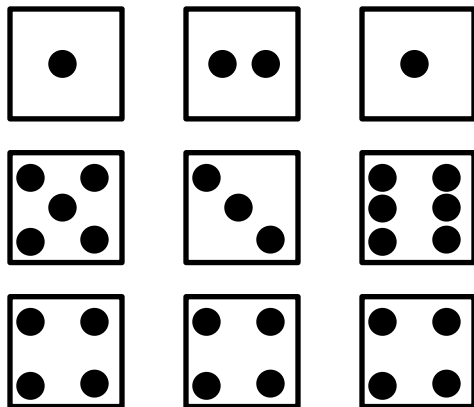
A: Develop a good model for what we observe

Learning Parameters for the Die Model: Maximum Likelihood (Intuition)

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If you observe
these 9 rolls...



...what are “reasonable”
estimates for $p(w)$?

$p(1) = ?$

$p(2) = ?$

$p(3) = ?$

$p(4) = ?$

$p(5) = ?$

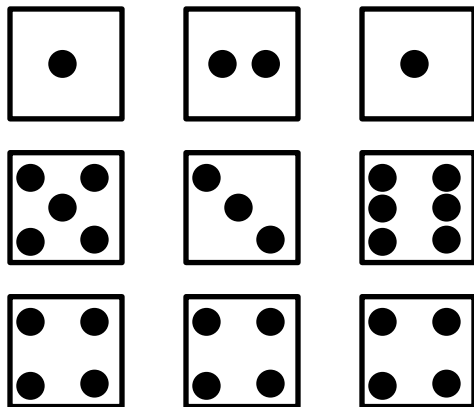
$p(6) = ?$

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If you observe
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...what are “reasonable”
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$$p(1) = 2/9$$

$$p(2) = 1/9$$

$$p(3) = 1/9$$

$$p(4) = 3/9$$

$$p(5) = 1/9$$

$$p(6) = 1/9$$

maximum
likelihood
estimates

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Maximum Likelihood Estimation (MLE)

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- Learning appropriate value(s) of ϕ allows you to **GENERALIZE** about \mathcal{X}

How do we “learn appropriate value(s) of ϕ ?”

Many different options: a common one is **maximum likelihood estimation (MLE)**

- Find values ϕ s.t. $g_\phi(\mathcal{X} = \{x_1, \dots, x_N\})$ is maximized
- Independence assumptions are very useful here!
- Logarithms are also useful!

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Example: How much does it snow?

- $\mathcal{X} = \{x_1, x_2, \dots, x_N\}$ are snowfall values from the previous N storms
- Goal: learn ϕ such that g correctly models, as accurately as possible, the amount of snow likely



Advanced
topic

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$$\max_{\phi} \sum_{i=1}^N \log g_{\phi}(x_i)$$



Advanced
topic

MLE Snowfall Example

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Advanced
topic

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Q: What other assumptions, or decisions, do we need to make?

x_i is positive, real-valued.
What's a **faithful** probability distribution for x_i ?

- Normal? ✗
- Gamma? ✓
- Exponential? ✓
- Bernoulli? ✗
- Poisson? ✗

Advanced
topic

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- Normal? **X**
- Gamma? **✓** $p(X = x) = \frac{x^{k-1} \exp(\frac{-x}{\theta})}{\theta^k \Gamma(k)}$
- Exponential? **✓**
- Bernoulli? **X**
- Poisson? **X**

Advanced
topic

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$$\max_{\phi} \sum_{i=1}^N \log g_{\phi}(x_i)$$

Q: Why is taking logarithms okay?

Q: What other assumptions, or decisions, do we need to make?

x_i is positive, real-valued. What's a **faithful/nice-to-compute-and-good-enough** probability distribution for x_i ?

- Normal? **X** ✓ $\leftarrow p(X = x) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left(\frac{-(x - \mu)^2}{2\sigma^2}\right)$
- Gamma? ✓ ?
- Exponential? ✓ ?
- Bernoulli? **X** **X**
- Poisson? **X** **X**



Advanced
topic

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$$\max_{\phi} \sum_{i=1}^N \log g_{\phi}(x_i)$$

$$x_i \sim \text{Normal}(\mu, \sigma^2)$$

$$\max_{(\mu, \sigma^2)} \sum_{i=1}^N \log \text{Normal}_{\mu, \sigma^2}(x_i) =$$

Advanced
topic

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Advanced
topic

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Q: How do we find μ, σ^2 ?

Advanced
topic

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Q: How do we find μ, σ^2 ?

A: Differentiate and find that

$$\begin{aligned} \hat{\mu} &= \frac{\sum_i x_i}{N} \\ \sigma^2 &= \frac{\sum_i (x_i - \hat{\mu})^2}{N} \end{aligned}$$

Learning:

Maximum Likelihood Estimation (MLE)

Central to machine learning:

- Observe some data $(\mathcal{X}, \mathcal{Y})$
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 - Sometimes written $f(\mathcal{X}; \theta)$
- Parameters are learned to minimize error (loss) ℓ

Advanced topic

Learning:

Maximum Likelihood Estimation (MLE)

Example: Can I sleep in the next time it snows/is school canceled?

- $\mathcal{X} = \{x_1, x_2, \dots, x_N\}$ are snowfall values from the previous N storms
 - $\mathcal{Y} = \{y_1, y_2, \dots, y_N\}$ are closure results from the previous N storms
 - Goal: learn θ such that f correctly predicts, as accurately as possible, if UMBC will close in the next storm:
 - y_{n+1}^* from x_{n+1}
- If we assume the output of f is a *probability distribution* on $\mathcal{Y}|\mathcal{X}$...
 - $f(\mathcal{X}) \rightarrow \{p(\text{yes}|\mathcal{X}), p(\text{no}|\mathcal{X})\}$
 - Then re: θ , {predicting, explaining, generating} \mathcal{Y} means... *what?*

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 - Then re: θ , {predicting, explaining, generating} \mathcal{Y} means... *what?*

Learning:

Maximum Likelihood Estimation (MLE)

Example: Can I sleep in the next time it snows/is school canceled?

- $\mathcal{X} = \{x_1, x_2, \dots, x_N\}$ are snowfall values from the previous N storms
- $\mathcal{Y} = \{y_1, y_2, \dots, y_N\}$ are closure results from the previous N storms
- Goal: learn θ such that f correctly predicts, as accurately as possible, if UMBC will close in the next storm:
 - y_{n+1}^* from x_{n+1}
- If we assume the output of f is a *probability distribution* on $\mathcal{Y}|\mathcal{X}$...
- Then re: θ , {predicting, explaining, generating} \mathcal{Y} means finding a value for θ that maximizes the probability of \mathcal{Y} given \mathcal{X}

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Maximum Likelihood Estimation (MLE)

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- If we assume the output of f is a *probability distribution* on $\mathcal{Y}|\mathcal{X}$...
 - Then re: θ , {predicting, explaining, generating} \mathcal{Y} means finding a value for θ that maximizes the probability of \mathcal{Y} given \mathcal{X} , according to f
 - To model \mathcal{X} : learn a distribution g , on \mathcal{X}

Extended examples of MLE

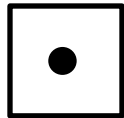
Advanced
topic

Learning Parameters for the Die Model: Maximum Likelihood (Math)

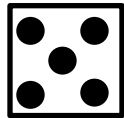
N different
(independent) rolls

$$p(w_1, w_2, \dots, w_N) = p(w_1)p(w_2) \cdots p(w_N) = \prod_i p(w_i)$$

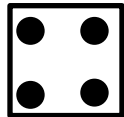
$$w_1 = 1$$



$$w_2 = 5$$



$$w_3 = 4$$



...

Generative Story

for roll $i = 1$ to N :

$$w_i \sim \text{Cat}(\theta)$$

Maximize Log-likelihood

$$\begin{aligned} \mathcal{L}(\theta) &= \sum_i \log p_{\theta}(w_i) \\ &= \sum_i \log \theta_{w_i} \end{aligned}$$

Advanced
topic

Learning Parameters for the Die Model: Maximum Likelihood (Math)

N different
(independent) rolls

$$p(w_1, w_2, \dots, w_N) = p(w_1)p(w_2) \cdots p(w_N) = \prod_i p(w_i)$$

Maximize Log-likelihood (with distribution constraints)

$$\mathcal{L}(\theta) = \sum_i \log \theta_{w_i} \text{ s.t. } \sum_{k=1}^6 \theta_k = 1$$

(we can include the
inequality constraints
 $0 \leq \theta_k$, but it complicates
the problem and, *right
now*, is not needed)

solve using Lagrange multipliers

Advanced
topic

Learning Parameters for the Die Model: Maximum Likelihood (Math)

N different
(independent) rolls

$$p(w_1, w_2, \dots, w_N) = p(w_1)p(w_2) \cdots p(w_N) = \prod_i p(w_i)$$

Maximize Log-likelihood (with distribution constraints)

$$\mathcal{F}(\theta) = \sum_i \log \theta_{w_i} - \lambda \left(\sum_{k=1}^6 \theta_k - 1 \right)$$

(we can include the
inequality constraints
 $0 \leq \theta_k$, but it
complicates the
problem and, *right
now*, is not needed)

$$\frac{\partial \mathcal{F}(\theta)}{\partial \theta_k} = \sum_{i:w_i=k} \frac{1}{\theta_{w_i}} - \lambda \quad \frac{\partial \mathcal{F}(\theta)}{\partial \lambda} = - \sum_{k=1}^6 \theta_k + 1$$

Advanced
topic

Learning Parameters for the Die Model: Maximum Likelihood (Math)

N different
(independent) rolls

$$p(w_1, w_2, \dots, w_N) = p(w_1)p(w_2) \cdots p(w_N) = \prod_i p(w_i)$$

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(we can include the
inequality constraints
 $0 \leq \theta_k$, but it
complicates the
problem and, *right
now*, is not needed)

$$\theta_k = \frac{\sum_{i:w_i=k} 1}{\lambda}$$

$$\text{optimal } \lambda \text{ when } \sum_{k=1}^6 \theta_k = 1$$

Advanced
topic

Learning Parameters for the Die Model: Maximum Likelihood (Math)

N different
(independent) rolls

$$p(w_1, w_2, \dots, w_N) = p(w_1)p(w_2) \cdots p(w_N) = \prod_i p(w_i)$$

Maximize Log-likelihood (with distribution constraints)

$$\mathcal{F}(\theta) = \sum_i \log \theta_{w_i} - \lambda \left(\sum_{k=1}^6 \theta_k - 1 \right)$$

(we can include the
inequality constraints
 $0 \leq \theta_k$, but it
complicates the
problem and, *right
now*, is not needed)

$$\theta_k = \frac{\sum_{i:w_i=k} 1}{\sum_k \sum_{i:w_i=k} 1} = \frac{N_k}{N}$$

optimal λ when $\sum_{k=1}^6 \theta_k = 1$

Example: Conditionally Rolling a Die

$$p(w_1, w_2, \dots, w_N) = p(w_1)p(w_2) \cdots p(w_N) = \prod_i p(w_i)$$



*add **complexity** to better
explain what we see*

$$\begin{aligned} p(\mathbf{z}_1, w_1, \mathbf{z}_2, w_2, \dots, \mathbf{z}_N, w_N) &= p(\mathbf{z}_1)p(w_1|\mathbf{z}_1) \cdots p(\mathbf{z}_N)p(w_N|\mathbf{z}_N) \\ &= \prod_i p(w_i|\mathbf{z}_i) p(\mathbf{z}_i) \end{aligned}$$

Example: Conditionally Rolling a Die

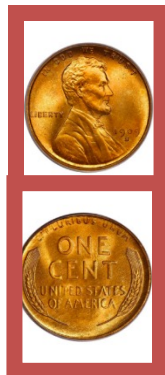
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add *complexity* to better
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$$p(z_1, w_1, z_2, w_2, \dots, z_N, w_N) = p(z_1)p(w_1|z_1) \cdots p(z_N)p(w_N|z_N) \\ = \prod_i p(w_i|z_i) p(z_i)$$

First flip a coin...



$$z_1 = T$$

$$z_2 = H$$

...

Example: Conditionally Rolling a Die

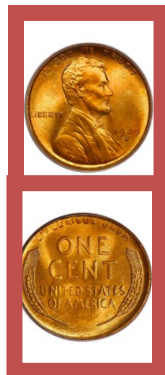
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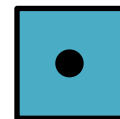
$$p(z_1, w_1, z_2, w_2, \dots, z_N, w_N) = p(z_1)p(w_1|z_1) \cdots p(z_N)p(w_N|z_N) \\ = \prod_i p(w_i|z_i) p(z_i)$$

First flip a coin...



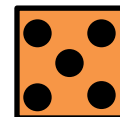
$z_1 = T$

$w_1 = 1$



$z_2 = H$

$w_2 = 5$



...

...then roll a different die
depending on the coin flip

Learning in Conditional Die Roll Model: Maximize (Log-)Likelihood

$$p(w_1, w_2, \dots, w_N) = p(w_1)p(w_2) \cdots p(w_N) = \prod_i p(w_i)$$



*add **complexity** to better
explain what we see*

$$\begin{aligned} p(\mathbf{z}_1, w_1, \mathbf{z}_2, w_2, \dots, \mathbf{z}_N, w_N) &= p(\mathbf{z}_1)p(w_1|\mathbf{z}_1) \cdots p(\mathbf{z}_N)p(w_N|\mathbf{z}_N) \\ &= \prod_i p(w_i|\mathbf{z}_i) p(\mathbf{z}_i) \end{aligned}$$

If you observe the \mathbf{z}_i
values, this is easy!



Advanced
topic

Learning in Conditional Die Roll Model: Maximize (Log-)Likelihood

$$p(\mathbf{z}_1, w_1, \mathbf{z}_2, w_2, \dots, \mathbf{z}_N, w_N) = \prod_i p(w_i | \mathbf{z}_i) p(\mathbf{z}_i)$$

If you observe the \mathbf{z}_i
values, this is easy!

First: Write the Generative Story

λ = distribution over coin (z)

$\gamma^{(H)}$ = distribution for die when coin comes up heads

$\gamma^{(T)}$ = distribution for die when coin comes up tails

for item $i = 1$ to N :

$z_i \sim \text{Bernoulli}(\lambda)$

$w_i \sim \text{Cat}(\gamma^{(z_i)})$

Advanced
topic

Learning in Conditional Die Roll Model: Maximize (Log-)Likelihood

$$p(\mathbf{z}_1, w_1, \mathbf{z}_2, w_2, \dots, \mathbf{z}_N, w_N) = \prod_i p(w_i | \mathbf{z}_i) p(\mathbf{z}_i)$$

If you observe the \mathbf{z}_i values, this is easy!

First: Write the Generative Story

λ = distribution over coin (z)

$\gamma^{(H)}$ = distribution for H die

$\gamma^{(T)}$ = distribution for T die

for item $i = 1$ to N :

$z_i \sim \text{Bernoulli}(\lambda)$

$w_i \sim \text{Cat}(\gamma^{(z_i)})$

Second: Generative Story \rightarrow Objective

$$\mathcal{F}(\theta) = \sum_i^n (\log \lambda_{z_i} + \log \gamma_{w_i}^{(z_i)})$$

– Lagrange multiplier
constraints



Advanced
topic

Learning in Conditional Die Roll Model: Maximize (Log-)Likelihood

$$p(\mathbf{z}_1, w_1, \mathbf{z}_2, w_2, \dots, \mathbf{z}_N, w_N) = \prod_i p(w_i | \mathbf{z}_i) p(\mathbf{z}_i)$$

If you observe the \mathbf{z}_i
values, this is easy!

First: Write the Generative Story

λ = distribution over coin (z)

$\gamma^{(H)}$ = distribution for H die

$\gamma^{(T)}$ = distribution for T die

for item $i = 1$ to N :

$z_i \sim \text{Bernoulli}(\lambda)$

$w_i \sim \text{Cat}(\gamma^{(z_i)})$

Second: Generative Story \rightarrow Objective

$$\mathcal{F}(\theta) = \sum_i^n (\log \lambda_{z_i} + \log \gamma_{w_i}^{(z_i)}) \\ - \eta \left(\sum_{k=1}^2 \lambda_k - 1 \right) - \sum_{k=1}^2 \delta_k \left(\sum_{j=1}^6 \gamma_j^{(k)} - 1 \right)$$

Advanced
topic

Learning in Conditional Die Roll Model: Maximize (Log-)Likelihood

$$p(\mathbf{z}_1, w_1, \mathbf{z}_2, w_2, \dots, \mathbf{z}_N, w_N) = \prod_i p(w_i | \mathbf{z}_i) p(\mathbf{z}_i)$$

If you observe the \mathbf{z}_i
values, this is easy!

But if you don't observe the
 \mathbf{z}_i values, this is not easy!

First: Write the Generative Story

λ = distribution over coin (z)

$\gamma^{(H)}$ = distribution for H die

$\gamma^{(T)}$ = distribution for T die

for item $i = 1$ to N :

$z_i \sim \text{Bernoulli}(\lambda)$

$w_i \sim \text{Cat}(\gamma^{(z_i)})$

Second: Generative Story \rightarrow Objective

$$\mathcal{F}(\theta) = \sum_i^n (\log \lambda_{z_i} + \log \gamma_{w_i}^{(z_i)}) \\ - \eta \left(\sum_{k=1}^2 \lambda_k - 1 \right) - \sum_{k=1}^2 \delta_k \left(\sum_{j=1}^6 \gamma_j^{(k)} - 1 \right)$$

Model selection

Goal: Select the best network structure, given the data

Input:

- Training data
- Scoring function

Output:

- A network that maximizes the score

Structure selection: Scoring

- Bayesian: prior over parameters and structure
 - get balance between model complexity and fit to data as a byproduct

Marginal likelihood

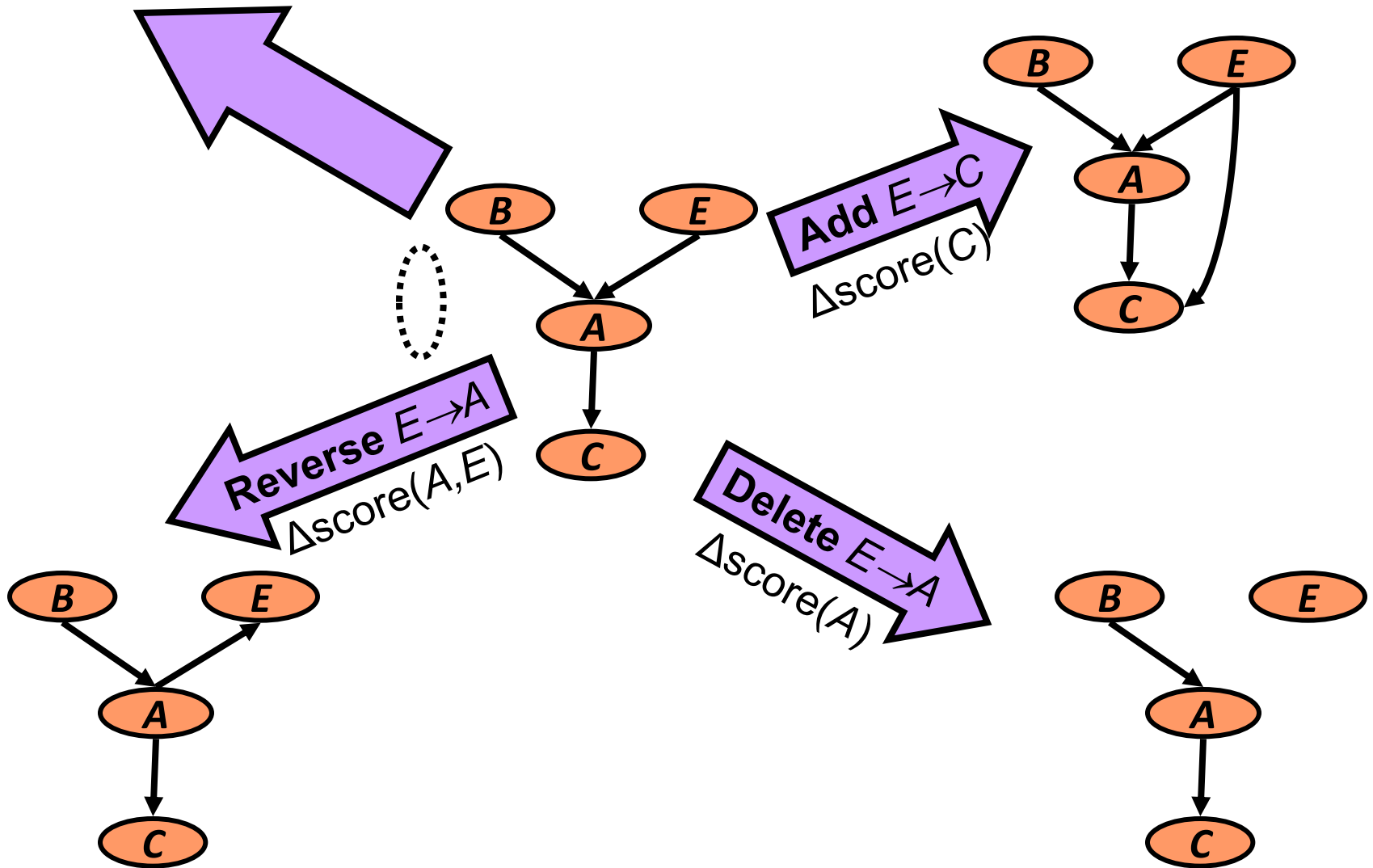
Prior

- $\text{Score}(G:D) = \log P(G|D) \propto \log [P(D|G) P(G)]$
- Marginal likelihood just comes from our parameter estimates
- Prior on structure can be any measure we want; typically a function of the network complexity

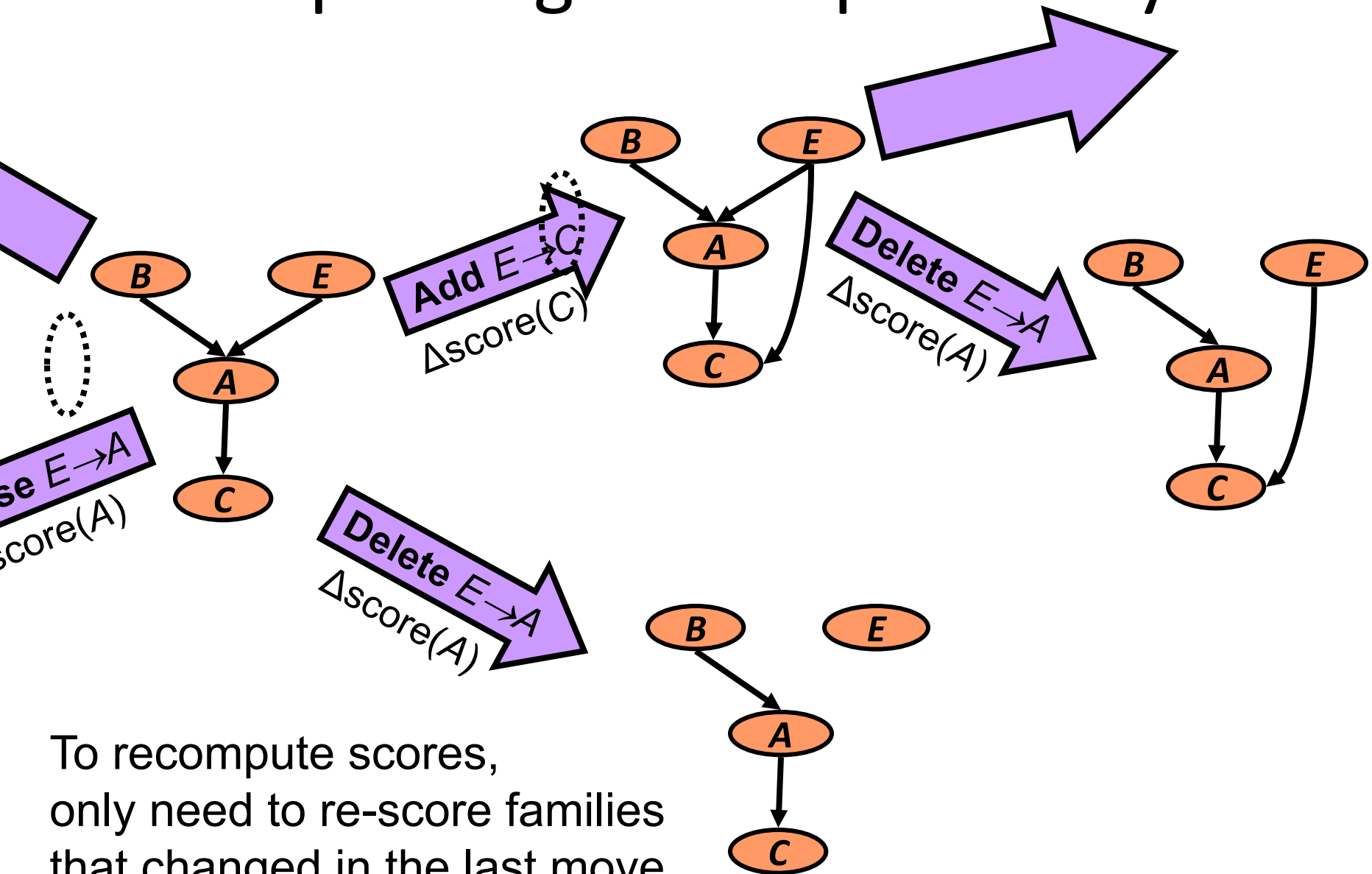
Same key property: Decomposability

$$\text{Score}(\text{structure}) = \sum_i \text{Score}(\text{family of } x_i)$$

Heuristic search

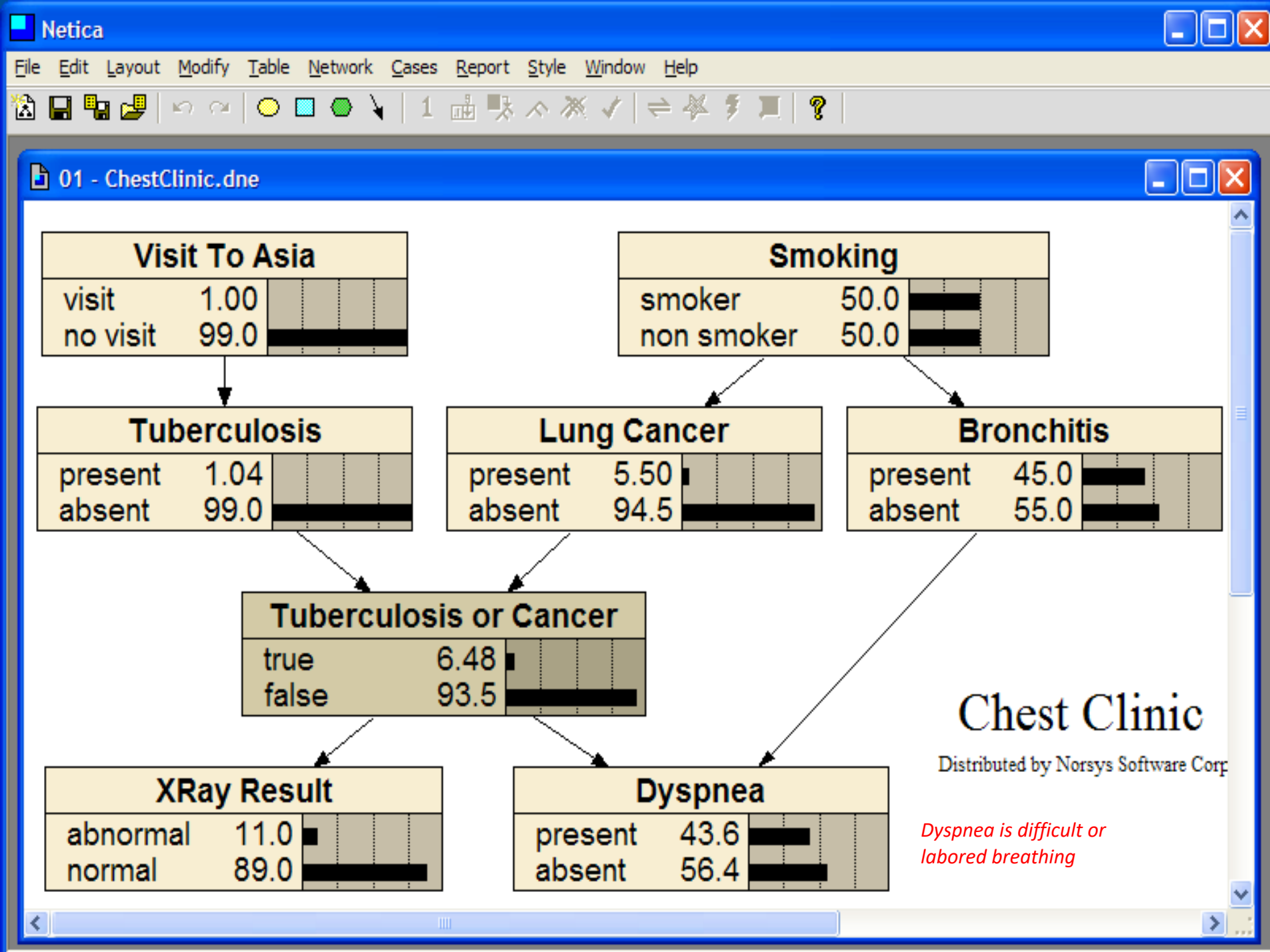


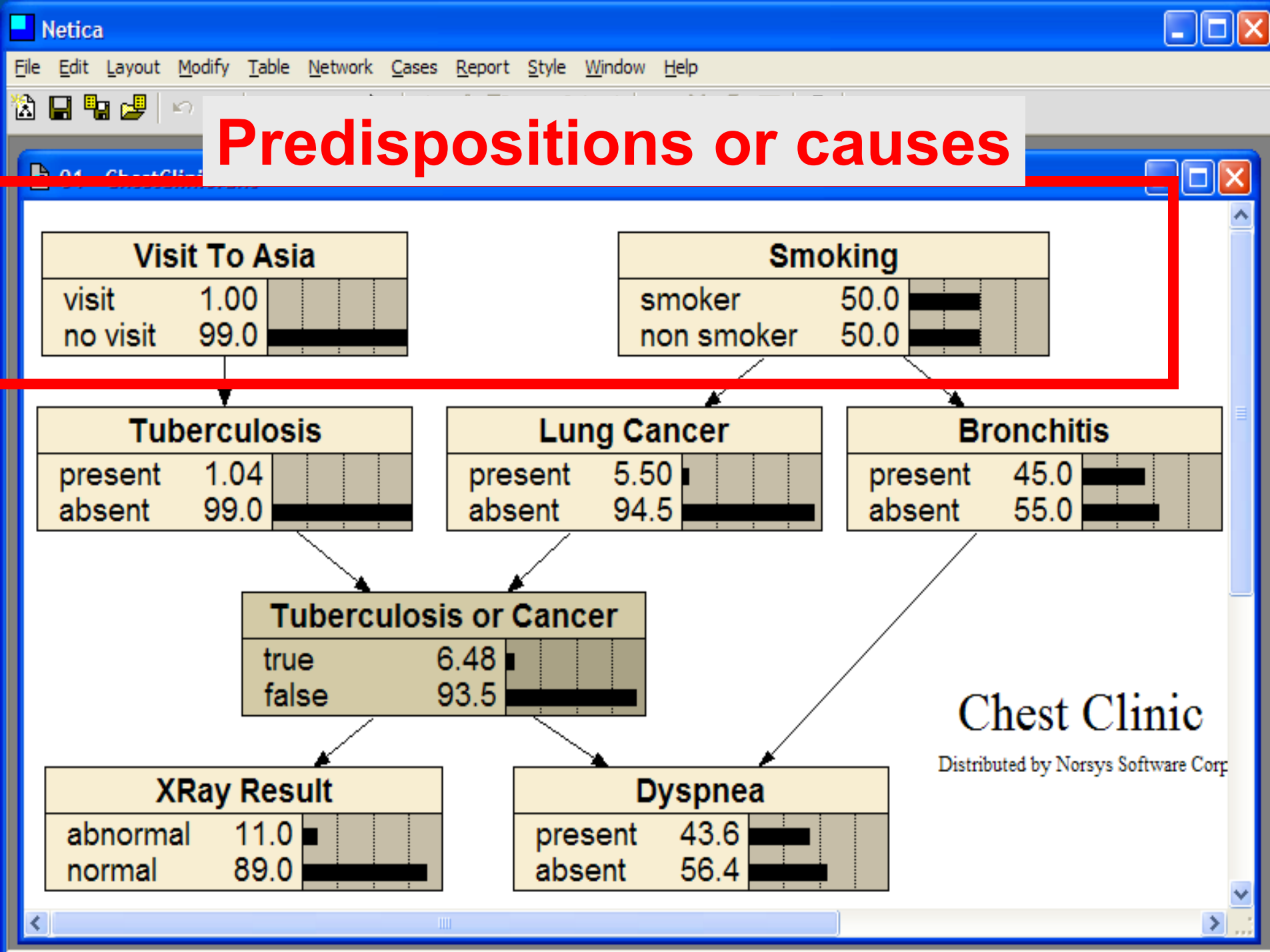
Exploiting decomposability

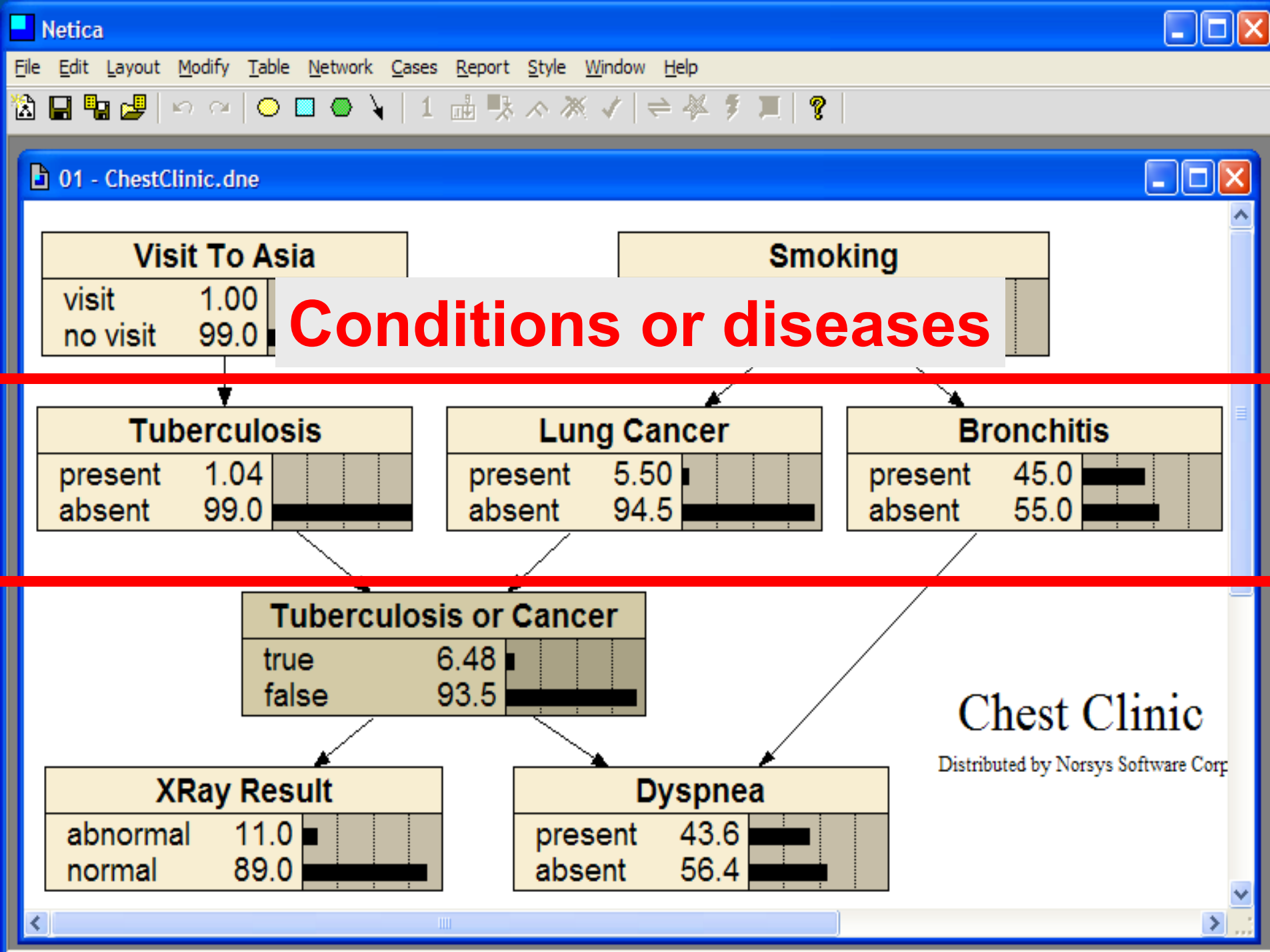


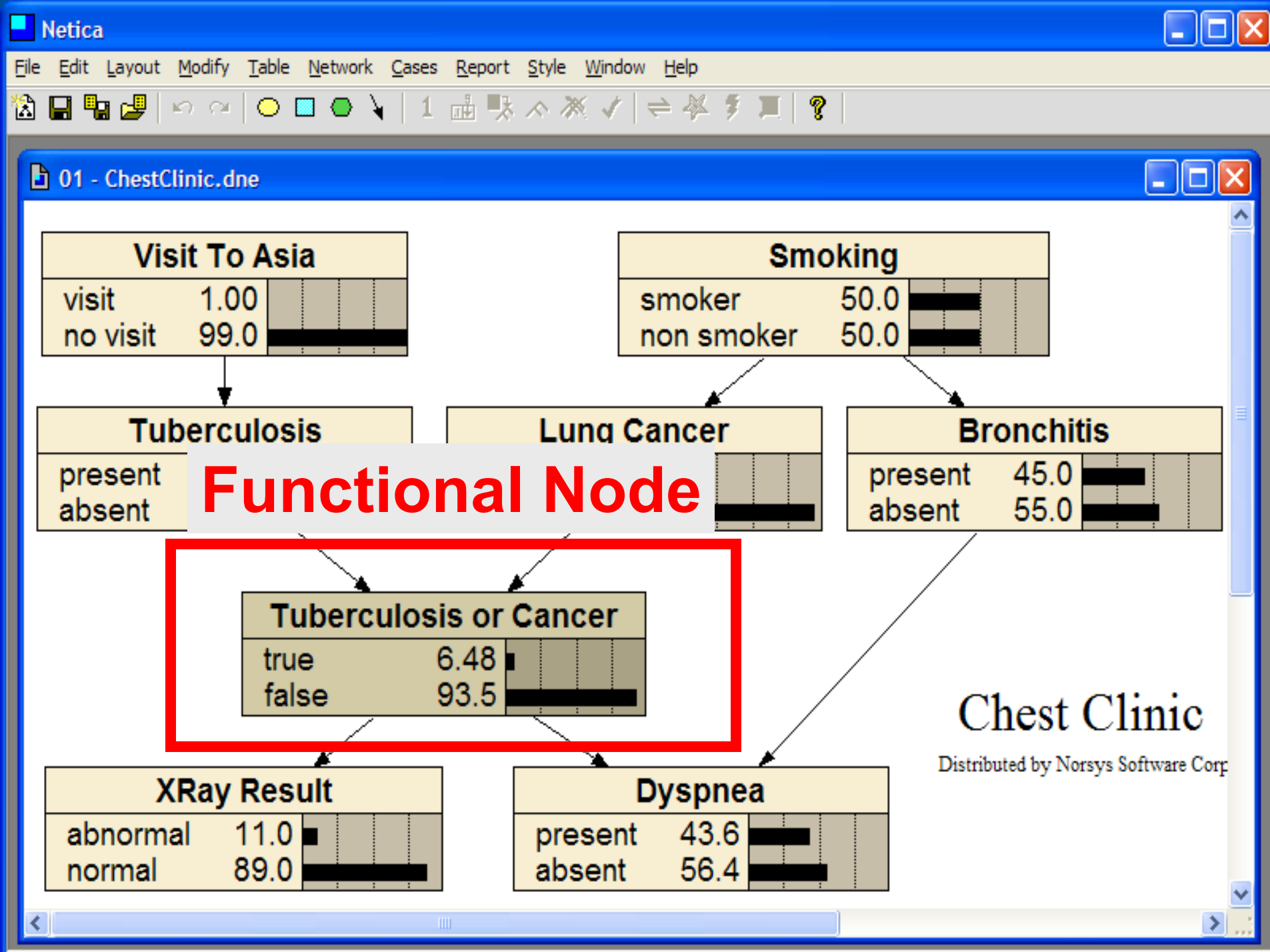
Some software tools

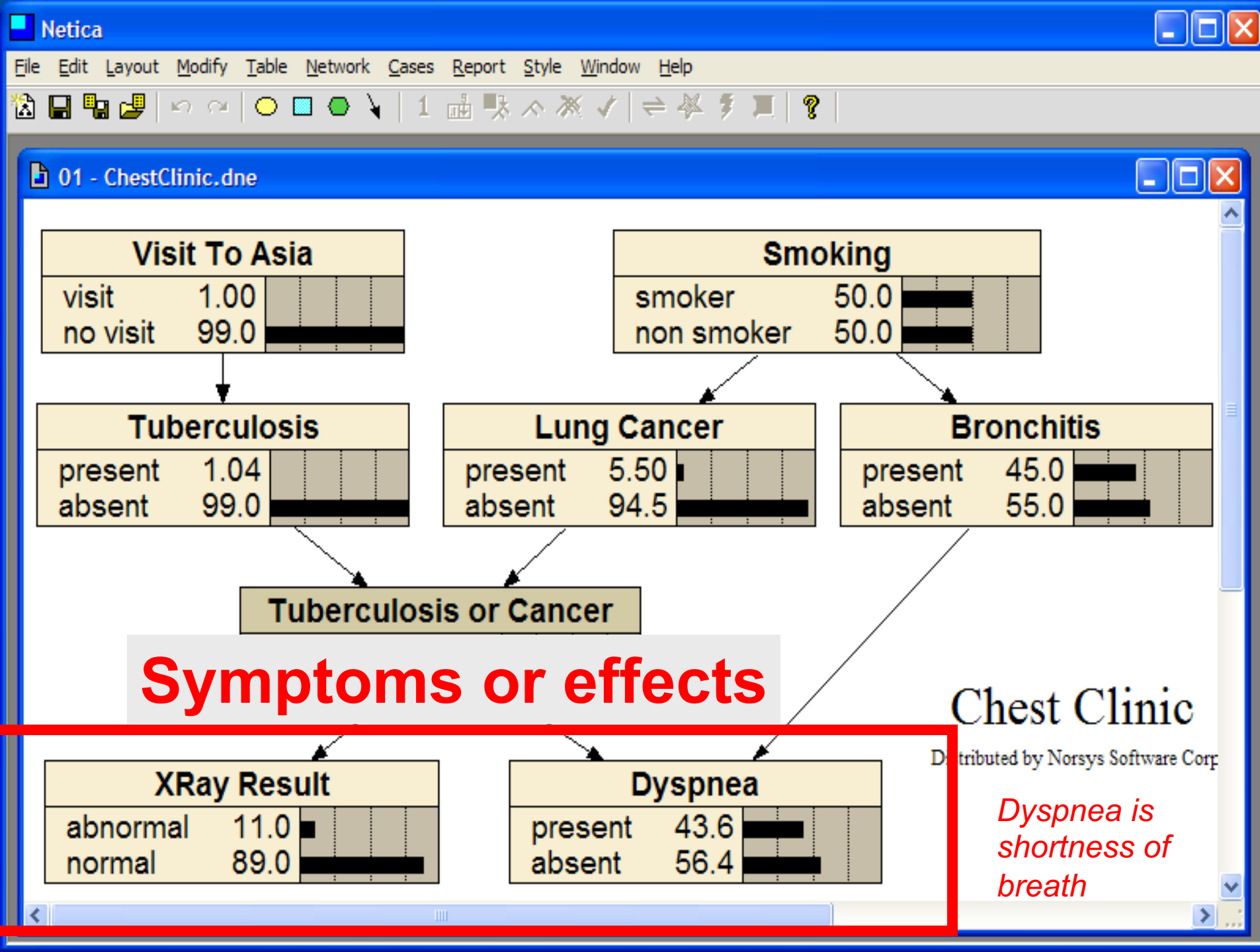
- [Netica](#): Windows app for working with Bayesian belief networks and influence diagrams
 - Commercial product, free for small networks
 - Includes graphical editor, compiler, inference engine, etc.
 - To run in OS X or Linux you need Wine or Crossover
- [Hugin](#): free demo versions for Linux, Mac, and Windows are available
- [BBN.ipynb](#) based on an ALMA notebook



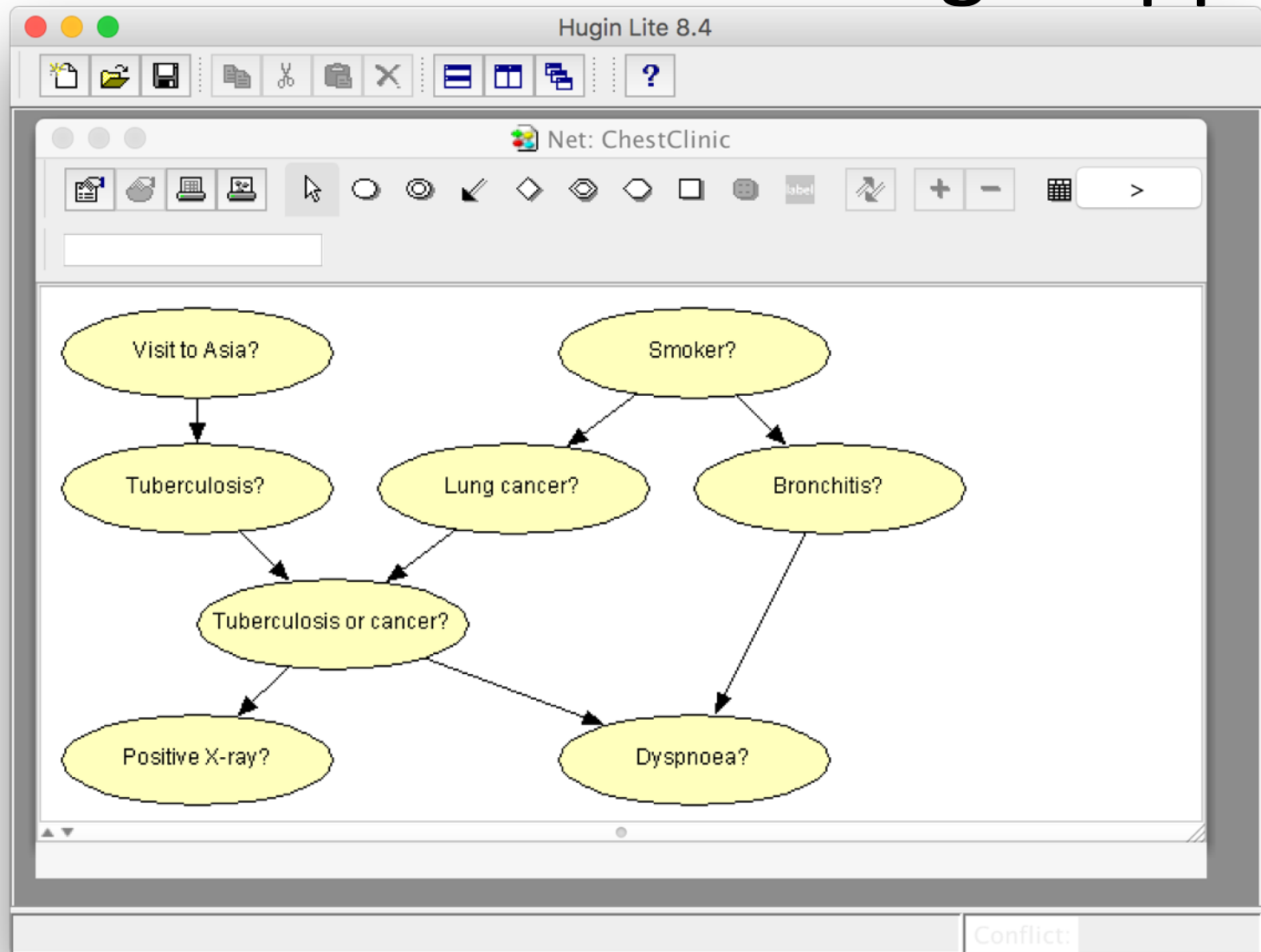








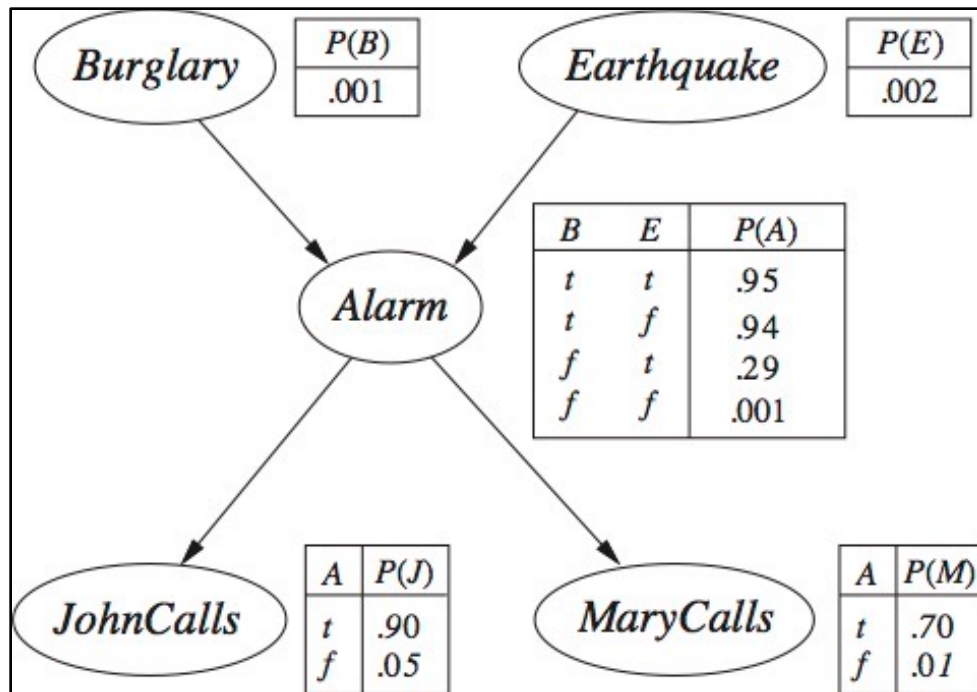
Same BBN model in Hugin app



See the 4-minute [HUGIN Tutorial](#) on YouTube

Python Code




See this [AIMA notebook](#) on colab showing how to construct this BBN Network in Python





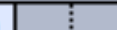
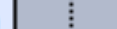
Judea Pearl example

There's a house with a burglar alarm that can be triggered by a burglary or earthquake. If it sounds, one or both neighbors John & Mary, might call the owner to say the alarm is sounding.

03 - Umbrella.dne

Forecast		
Sunny	53.5	
Cloudy	21.5	
Rainy	25.0	

Weather		
No Rain	70.0	
Rain	30.0	

Decide_Umbrella		
Take It	35.0000	
Leave At Home	70.0000	

Satisfaction



Satisfaction Table (in net N3____Umbrella)

Node: Satisfaction

Apply

Okay

Deterministic

Percentages

Reset

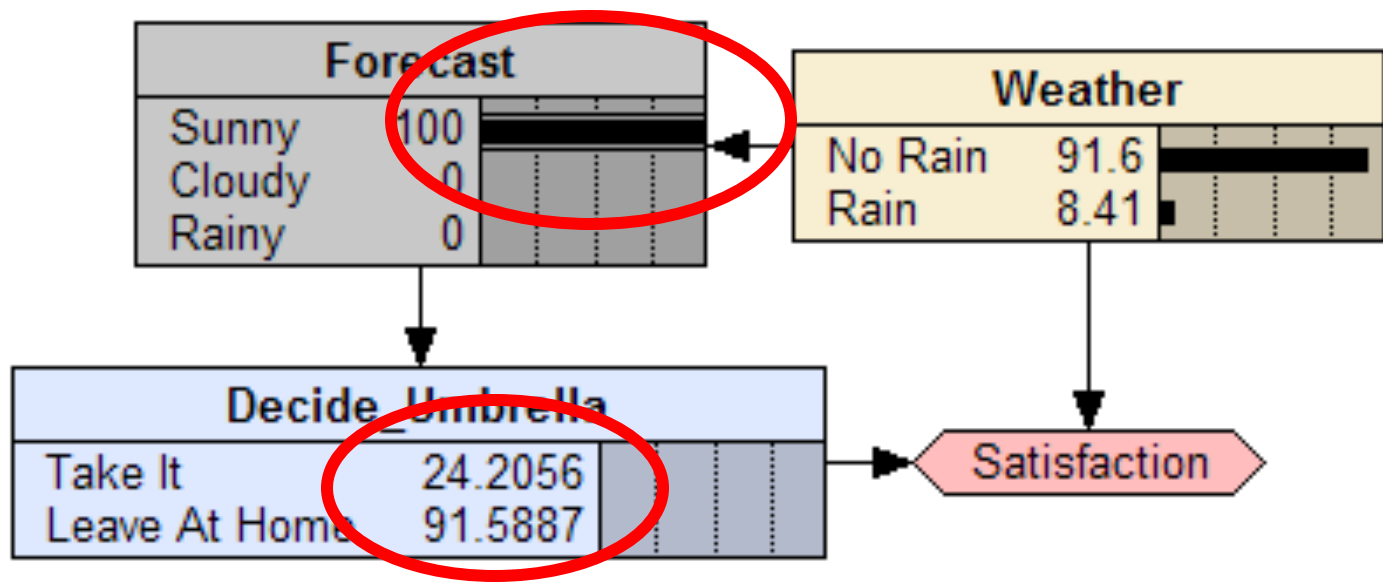
Close

Weather	Decide_Umbrella	Satisfaction
No Rain	Take It	20
No Rain	Leave At Home	100
Rain	Take It	70
Rain	Leave At Home	0

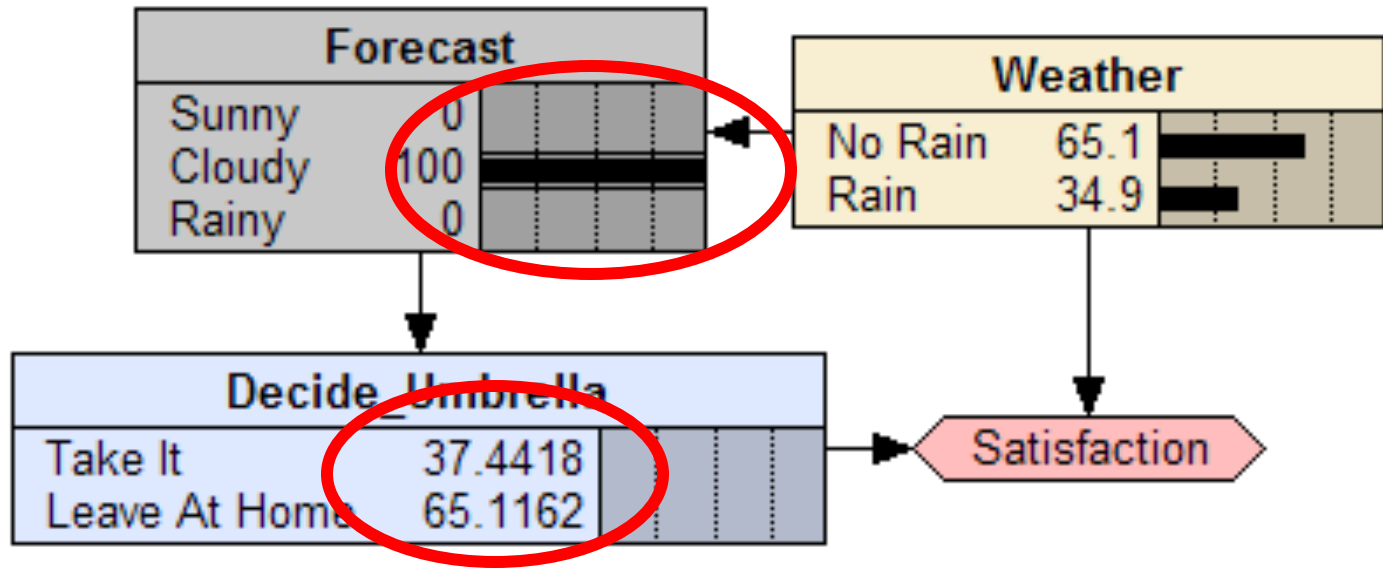
Take

Leave

03 - Umbrella.dne



03 - Umbrella.dne



03 - Umbrella.dne

