Lecture Three Supervised Learning: Classification

KMA Solaiman Fall 2023

Adapted From Chris Re' Stanford ML

Supervised Learning and Classification

- Linear Regression via a Probabilistic Interpretation
- Logistic Regression
- Optimization Method: Newton's Method

We'll learn the maximum likelihood method (a probabilistic interpretation) to generalize from linear regression to more sophisticated models.

- ▶ **Given** a training set $\{(x^{(i)}, y^{(i)}) \text{ for } i = 1, ..., n\}$ in which $x^{(i)} \in \mathbb{R}^{d+1}$ and $y^{(i)} \in \mathbb{R}$.
- ▶ **Do** find $\theta \in \mathbb{R}^{d+1}$ s.t. $\theta = \operatorname{argmin}_{\theta} \sum_{i=1}^{n} (h_{\theta}(x^{(i)}) y^{(i)})^2$ in which $h_{\theta}(x) = \theta^T x$.

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Where did this model come from?

One way to view is via a probabilistic interpretation (helpful throughout the course).

We make an assumption (common in statistics) that the data are generated according to some model (that may contain random choices). That is,

$$y^{(i)} = \theta^T x^{(i)} + \varepsilon^{(i)}.$$

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Please keep in mind: this is just a model! As they say, all models are wrong but some models are *useful*. This model has been *shockingly* useful.

What do we expect of the noise?

What properties should we expect from $\varepsilon^{(i)}$

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- ► The errors for different points are *independent* and *identically* distributed (called, **iid**)

$$\mathbb{E}[\varepsilon^{(i)}\varepsilon^{(j)}] = \mathbb{E}[\varepsilon^{(i)}]\mathbb{E}[\varepsilon^{(j)}] \text{ for } i \neq j.$$

and

$$\mathbb{E}\left[\left(\varepsilon^{(i)}\right)^2\right] = \sigma^2$$

Here σ^2 is some measure of *how noisy* the data are.

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Here σ^2 is some measure of how noisy the data are. Turns out, this effectively defines the Gaussian or Normal distribution.

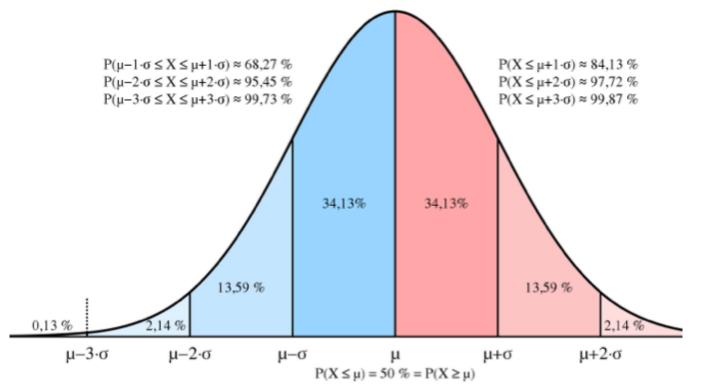


Notation for the Gaussian

We write $z \sim \mathcal{N}(\mu, \sigma^2)$ and read these symbols as z is distributed as a normal with mean μ and standard deviation σ^2 .

or equivalently the probability density function -

$$P(z) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left\{-\frac{(z-\mu)^2}{2\sigma^2}\right\} \dots (10.1)$$



Notation for Guassians in our Problem

Recall in our model,

$$y^{(i)} = \theta^T x^{(i)} + \varepsilon^{(i)}$$
 in which $\varepsilon^{(i)} \sim \mathcal{N}(0, \sigma^2)$ (11.1)

or more compactly notation:

equivalently, Probability distribution over $y^{(i)}$, given $x^{(i)}$ and parameterized by θ

$$P\left(y^{(i)} \mid x^{(i)}; \theta\right) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left\{-\frac{(y^{(i)} - x^{(i)}\theta)^2}{2\sigma^2}\right\} \dots (11.3)$$

- We **condition** on $x^{(i)}$.
- \blacktriangleright In contrast, θ parameterizes or "picks" a distribution.

We use bar (|) versus semicolon (;) notation above.



How did we calculate Probability Distribution of $y^{(i)}$ in 11.3?

Using our *error term* in place of
$$z$$
, we get
$$\frac{1}{\sigma\sqrt{2\pi}}exp\left\{-\frac{\left(\varepsilon^{(i)}-0\right)^2}{2\sigma^2}\right\}$$
 Now if we replace this with values from 11.1, we get
$$\frac{1}{\sigma\sqrt{2\pi}}exp\left\{-\frac{\left(y^{(i)}-x^{(i)}\theta\right)^2}{2\sigma^2}\right\}$$

This term gives us the probability distribution over $y^{(i)}$, but we must add $x^{(i)}$ as a given, since we will see it as input, so by fiat we consider this as, $P(y^{(i)}|x^{(i)};\theta)$ which is not conditioned on θ , as it isn't Random Variable

Intuition: among many distributions, pick the one that agrees with the data the most (is most "likely").

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For convenience, we use the Log Likelihood $\ell(\theta) = \log L(\theta)$.

$$\ell(\theta) = \sum_{i=1}^{n} \log \frac{1}{\sigma \sqrt{2\pi}} - \frac{(x^{(i)}\theta - y^{(i)})^2}{2\sigma^2}$$

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$$= n \log \frac{1}{\sigma \sqrt{2\pi}} - \frac{1}{2\sigma^2} \sum_{i=1}^{n} (x^{(i)}\theta - y^{(i)})^2 = C(\sigma, n) - \frac{1}{\sigma^2} J(\theta)$$

where $C(\sigma, n) = n \log \frac{1}{\sigma \sqrt{2\pi}}$.



So we've shown that finding a θ to maximize $L(\theta)$ is the same as maximizing

$$\ell(\theta) = C(\sigma, n) - \frac{1}{\sigma^2}J(\theta)$$

Or minimizing, $J(\theta)$ directly (why?)

Takeaway: "Under the hood," solving least squares *is* solving a maximum likelihood problem for a particular probabilistic model.

This view shows a path to generalize to new situations!

Summary of Least Squares

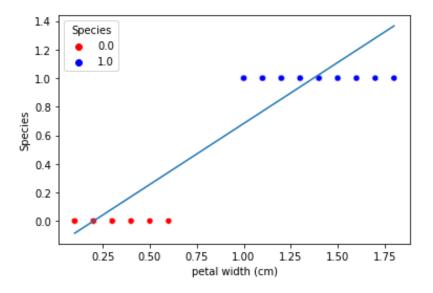
- We introduced the Maximum Likelihood framework—super powerful (next lectures)
- We showed that least squares was actually a version of maximum likelihoods.
- We learned some notation that will help us later in the course...

Classification

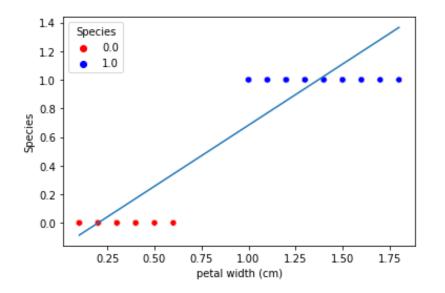
Given a training set $\{(x^{(i)}, y^{(i)}) \text{ for } i = 1, ..., n\} \text{ let } y^{(i)} \in \{0, 1\}.$ Why not use regression, say least squares? A picture ...

	petal width (cm)	Species
0	0.2	0.0
1	0.2	0.0
2	0.2	0.0
3	0.2	0.0
4	0.2	0.0
95	1.2	1.0
96	1.3	1.0
97	1.3	1.0
98	1.1	1.0
99	1.3	1.0

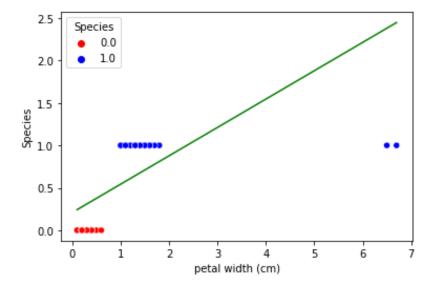
Iris Flower Dataset



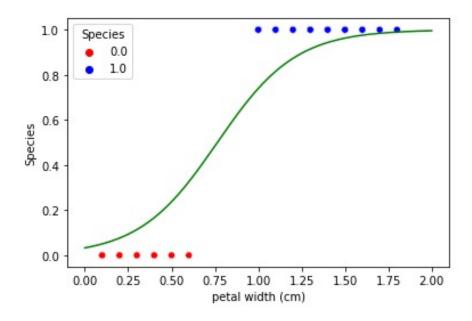
Graph of Iris Dataset with linear regression



Graph of Iris Dataset with linear regression



Graph of Iris Dataset(with outliers) with linear regression



Graph of Iris Dataset with logistic regression

Given a training set $\{(x^{(i)}, y^{(i)}) \text{ for } i = 1, ..., n\}$ let $y^{(i)} \in \{0, 1\}$. Want $h_{\theta}(x) \in [0, 1]$. Let's pick a smooth function:

$$h_{\theta}(x) = g(\theta^T x)$$

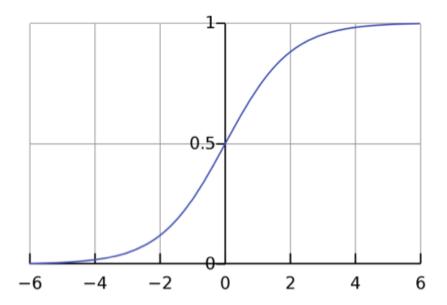
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$$g(z)=\frac{1}{1+e^{-z}}.$$

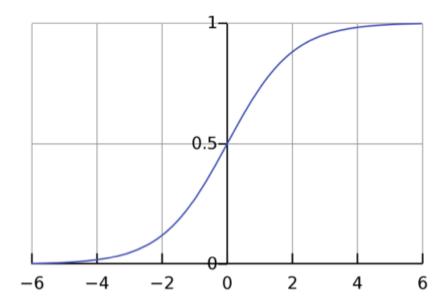


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. SIGMOID



How do we interpret $h_{\theta}(x)$?

$$P(y = 1 \mid x; \theta) = h_{\theta}(x)$$

$$P(y = 0 \mid x; \theta) = 1 - h_{\theta}(x)$$

Let's write the Likelihood function. Recall:

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How do we go to a cost function from P (y | X; θ) ?

We need to go back to Maximum Likelihood Estimation that we saw before at the beginning of this lecture.

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Taking logs to compute the log likelihood $\ell(\theta)$ we have:

$$\ell(\theta) = \log L(\theta) = \sum_{i=1}^{n} y^{(i)} \log h_{\theta}(x^{(i)}) + (1 - y^{(i)}) \log(1 - h_{\theta}(x^{(i)}))$$



Now to solve it...

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We maximize for θ but we already saw how to do this! Just compute derivative, run (S)GD and you're done with it!

Takeaway: This is *another* example of the max likelihood method: we setup the likelihood, take logs, and compute derivatives.

Time Permitting: There is magic in the derivative...

Even more, the batch update can be written in a *remarkably* familiar form:

$$\theta^{(t+1)} = \theta^{(t)} + \sum_{j \in B} (y^{(j)} - h_{\theta}(x^{(j)})) x^{(j)}.$$

We sketch why (you can check!) We drop superscripts to simplify notation and examine a single data point:

$$y \log h_{\theta}(x) + (1 - y) \log(1 - h_{\theta}(x))$$

= $-y \log(1 + e^{-\theta^T x}) + (1 - y)(-\theta^T x) - (1 - y) \log(1 + e^{-\theta^T x})$
= $-\log(1 + e^{-\theta^T x}) - (1 - y)(\theta^T x)$

We used $1 - h_{\theta}(x) = \frac{e^{-\theta' x}}{1 - e^{-\theta T_x}}$. We now compute the derivative of this expression wrt θ and get:

$$\frac{e^{-\theta^T x}}{1 + e^{-\theta^T x}} x - (1 - y) x = (y - h_{\theta}(x)) x$$



Perceptron Learning Algorithm

- Modify link function to output either 0 or 1.
- Make g to be a threshold function
- Then use same $h_{\theta}(x) = g(\theta^T x)$ using this g
- Follow the same update rule for θ

$$g(z) = \begin{cases} 1 & \text{if } z \ge 0 \\ 0 & \text{if } z < 0 \end{cases}$$

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- We used the principle of maximum likelihood (and a probabilistic model) to extend to classification.
- We developed logistic regression from this principle.
 - Logistic regression is widely used today.
- We noticed a familiar pattern: take derivatives of the likelihood, and the derivatives had this (hopefully) intuitive "misprediction form"

Newton's Method

Given $f: \mathbb{R}^d \to \mathbb{R}$ find x s.t. f(x) = 0.

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We apply this with $f(\theta) = \nabla_{\theta} \ell(\theta)$, the likelihood function

Newton's Method (Drawn in Class)

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Newton's Method Summary

Given $f: \mathbb{R}^d \to \mathbb{R}$ find x s.t. f(x) = 0.

► This is the update rule in 1d

$$x^{(t+1)} = x^{(t)} - \frac{f(x^{(t)})}{f'(x^{(t)})}$$

- It may converge very fast (quadratic local convergence!)
- ► For the likelihood, i.e., $f(\theta) = \nabla_{\theta} \ell(\theta)$ we need to generalize to a vector-valued function which has:

$$\theta^{(t+1)} = \theta^{(t)} - \left(H(\theta^{(t)})\right)^{-1} \nabla_{\theta} \ell(\theta^{(t)}).$$

in which $H_{i,j}(\theta) = \frac{\partial}{\partial \theta_i \partial \theta_j} \ell(\theta)$.



Optimization Method Summary

	Compute per Step	Number of Steps
Method		to convergence
SGD	$\theta(d)$	≈ є ⁻²
Minibatch SGD		
GD	θ(nd)	≈ ε ⁻¹
Newton	$\Omega(\mathrm{nd}^2)$	≈ log(1/€)

- In classical stats, d is small (< 100), n is often small, and exact parameters matter
- In modern ML, d is huge (billions, trillions), n is huge (trillions), and parameters used only for prediction
 - ➤ These are approximate number of computing steps
 - ➤ Convergence happens when loss settles to within an error range around the final value.
 - ➤ Newton would be very fast, where SGD needs a lot of step, but individual steps are fast, makes up for it
- ► As a result, (minibatch) SGD is the workhorse of ML.



Classification Lecture Summary

- We saw the differences between classification and regression.
- ► We learned about a principle for probabilistic interpretation for linear regression and classification: **Maximum Likelihood**.
 - We used this to derive logistic regression.
 - ► The Maximum Likelihood principle will be used again next lecture (and in the future)
- We saw Newton's method, which is classically used models (more statistics than ML-it's not used in most modern ML)