# Lecture Three Supervised Learning: Classification

KMA Solaiman Fall 2023

Adapted From Chris Re' Stanford ML

## Supervised Learning and Classification

- Linear Regression via a Probabilistic Interpretation
- Logistic Regression
- Optimization Method: Newton's Method

We'll learn the maximum likelihood method (a probabilistic interpretation) to generalize from linear regression to more sophisticated models.

- ▶ **Given** a training set  $\{(x^{(i)}, y^{(i)}) \text{ for } i = 1, ..., n\}$  in which  $x^{(i)} \in \mathbb{R}^{d+1}$  and  $y^{(i)} \in \mathbb{R}$ .
- ▶ **Do** find  $\theta \in \mathbb{R}^{d+1}$  s.t.  $\theta = \operatorname{argmin}_{\theta} \sum_{i=1}^{n} (h_{\theta}(x^{(i)}) y^{(i)})^2$  in which  $h_{\theta}(x) = \theta^T x$ .

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Where did this model come from?

One way to view is via a probabilistic interpretation (helpful throughout the course).

We make an assumption (common in statistics) that the data are *generated* according to some model (that may contain random choices). That is,

$$y^{(i)} = \theta^T x^{(i)} + \varepsilon^{(i)}.$$

Here,  $\varepsilon^{(i)}$  is a random variable that captures "noise" that is, unmodeled effects, measurement errors, etc.

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Please keep in mind: this is just a model! As they say, all models are wrong but some models are *useful*. This model has been *shockingly* useful.

## What do we expect of the noise?

What properties should we expect from  $\varepsilon^{(i)}$ 

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- ► The errors for different points are *independent* and *identically* distributed (called, **iid**)

$$\mathbb{E}[\varepsilon^{(i)}\varepsilon^{(j)}] = \mathbb{E}[\varepsilon^{(i)}]\mathbb{E}[\varepsilon^{(j)}] \text{ for } i \neq j.$$

and

$$\mathbb{E}\left[\left(\varepsilon^{(i)}\right)^2\right] = \sigma^2$$

Here  $\sigma^2$  is some measure of *how noisy* the data are.

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Here  $\sigma^2$  is some measure of *how noisy* the data are. Turns out, this effectively defines the *Gaussian or Normal distribution*.

#### Notation for the Gaussian

We write  $z \sim \mathcal{N}(\mu, \sigma^2)$  and read these symbols as z is distributed as a normal with mean  $\mu$  and standard deviation  $\sigma^2$ .

or equivalently the probability density function -

$$P(z) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left\{-\frac{(z-\mu)^2}{2\sigma^2}\right\} \dots (10.1)$$

$$P(\mu-1 \sigma \le X \le \mu+1 \cdot \sigma) \approx 68.27 \%$$

$$P(\mu-2 \sigma \le X \le \mu+2 \cdot \sigma) \approx 95.45 \%$$

$$P(\mu-3 \cdot \sigma \le X \le \mu+3 \cdot \sigma) \approx 99.73 \%$$

$$P(X \le \mu+1 \cdot \sigma) \approx 84.13 \%$$

$$P(X \le \mu+2 \cdot \sigma) \approx 97.72 \%$$

$$P(X \le \mu+3 \cdot \sigma) \approx 99.87 \%$$

#### Notation for Guassians in our Problem

Recall in our model,

$$y^{(i)} = \theta^T x^{(i)} + \varepsilon^{(i)}$$
 in which  $\varepsilon^{(i)} \sim \mathcal{N}(0, \sigma^2)$  ....... (11.1)

or more compactly notation:

$$y^{(i)} | x^{(i)}; \theta \sim \mathcal{N}(\theta^T x, \sigma^2)$$
.....(11.2)

equivalently, Probability distribution over  $y^{(i)}$ , given  $x^{(i)}$  and parameterized by  $\theta$ 

$$P\left(y^{(i)} \mid x^{(i)}; \theta\right) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left\{-\frac{(y^{(i)} - x^{(i)}\theta)^2}{2\sigma^2}\right\} \dots (11.3)$$

- ▶ We **condition** on  $x^{(i)}$ .
- ▶ In contrast,  $\theta$  parameterizes or "picks" a distribution.

We use bar (|) versus semicolon (;) notation above.



# How did we calculate Probability Distribution of $y^{(i)}$ in 11.3?

Using our error term in place of z, we get

$$\frac{1}{\sigma\sqrt{2\pi}}exp\left\{-\frac{\left(\varepsilon^{(i)}-0\right)^2}{2\sigma^2}\right\}$$

Now if we replace this with values from 11.1, we get

$$\frac{1}{\sigma\sqrt{2\pi}}exp\left\{-\frac{\left(y^{(i)}-x^{(i)}\theta\right)^2}{2\sigma^2}\right\}$$

This term gives us the probability distribution over  $y^{(i)}$ , but we must add  $x^{(i)}$  as a given, since we will see it as input, so by fiat we consider this as,  $P(y^{(i)}|x^{(i)};\theta)$  which is not conditioned on  $\theta$ , as it isn't Random Variable

Intuition: among many distributions, pick the one that agrees with the data the most (is most "likely").

$$L(\theta) = p(y|X;\theta) = \prod_{i=1}^{n} p(y^{(i)} \mid x^{(i)};\theta)$$
 iid assumption

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For convenience, we use the *Log Likelihood*  $\ell(\theta) = \log L(\theta)$ .

$$\ell(\theta) = \sum_{i=1}^{n} \log \frac{1}{\sigma \sqrt{2\pi}} - \frac{(x^{(i)}\theta - y^{(i)})^2}{2\sigma^2}$$

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$$\ell(\theta) = \sum_{i=1}^{n} \log \frac{1}{\sigma \sqrt{2\pi}} - \frac{(x^{(i)}\theta - y^{(i)})^2}{2\sigma^2}$$

$$= n \log \frac{1}{\sigma \sqrt{2\pi}} - \frac{1}{2\sigma^2} \sum_{i=1}^{n} (x^{(i)}\theta - y^{(i)})^2 = C(\sigma, n) - \frac{1}{\sigma^2} J(\theta)$$

where  $C(\sigma, n) = n \log \frac{1}{\sigma \sqrt{2\pi}}$ .



So we've shown that finding a  $\theta$  to maximize  $L(\theta)$  is the same as maximizing

$$\ell(\theta) = C(\sigma, n) - \frac{1}{\sigma^2}J(\theta)$$

Or minimizing,  $J(\theta)$  directly (why?)

**Takeaway:** "Under the hood," solving least squares *is* solving a maximum likelihood problem for a particular probabilistic model.

This view shows a path to generalize to new situations!

#### Summary of Least Squares

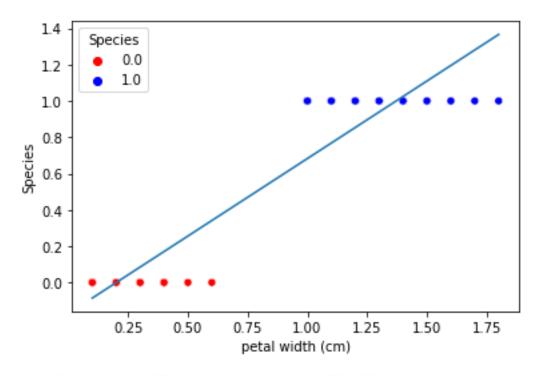
- We introduced the Maximum Likelihood framework–super powerful (next lectures)
- We showed that least squares was actually a version of maximum likelihoods.
- ► We learned some notation that will help us later in the course. . .

#### Classification

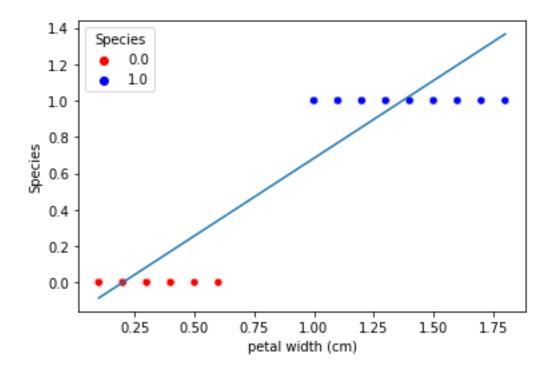
Given a training set  $\{(x^{(i)}, y^{(i)}) \text{ for } i = 1, ..., n\} \text{ let } y^{(i)} \in \{0, 1\}.$  Why not use regression, say least squares? A picture ...

	petal width (cm)	Species
0	0.2	0.0
1	0.2	0.0
2	0.2	0.0
3	0.2	0.0
4	0.2	0.0
95	1.2	1.0
96	1.3	1.0
97	1.3	1.0
98	1.1	1.0
99	1.3	1.0

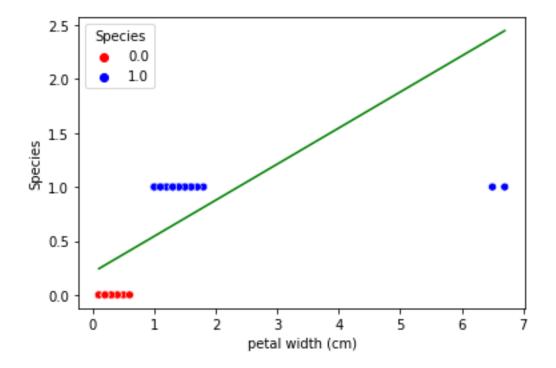
Iris Flower Dataset



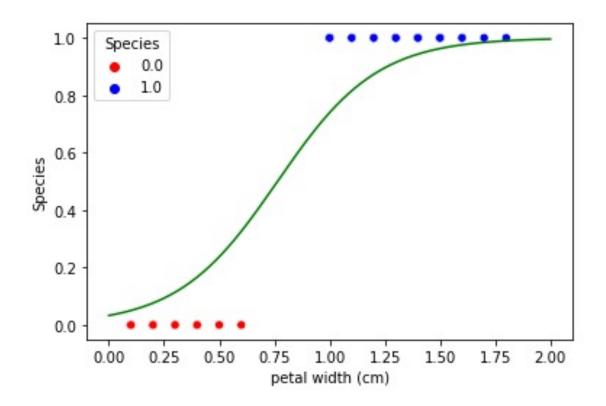
Graph of Iris Dataset with linear regression



Graph of Iris  $\underline{\text{Dataset}}$  with linear regression



Graph of Iris Dataset(with outliers) with linear regression



Graph of Iris Dataset with logistic regression

Given a training set  $\{(x^{(i)}, y^{(i)}) \text{ for } i = 1, ..., n\} \text{ let } y^{(i)} \in \{0, 1\}.$  Want  $h_{\theta}(x) \in [0, 1]$ . Let's pick a smooth function:

$$h_{\theta}(x) = g(\theta^T x)$$

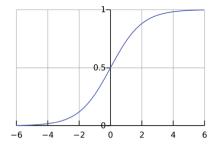
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$$g(z)=\frac{1}{1+e^{-z}}.$$

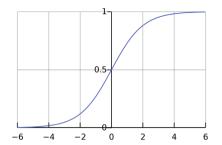


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. SIGMOID



How do we interpret  $h_{\theta}(x)$ ?

$$P(y = 1 \mid x; \theta) = h_{\theta}(x)$$
  
 
$$P(y = 0 \mid x; \theta) = 1 - h_{\theta}(x)$$

Let's write the Likelihood function. Recall:

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How do we go to a cost function from P (y I X;  $\theta$ ) ?

We need to go back to Maximum Likelihood Estimation that we saw before at the beginning of this lecture.

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Then,

$$\begin{split} L(\theta) = & P(y \mid X; \theta) = \prod_{i=1}^{n} p(y^{(i)} \mid x^{(i)}; \theta) \\ = & \prod_{i=1}^{n} h_{\theta}(x^{(i)})^{y^{(i)}} (1 - h_{\theta}(x^{(i)}))^{1 - y^{(i)}} \quad \text{exponents encode "if-then"} \end{split}$$

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Taking logs to compute the log likelihood  $\ell(\theta)$  we have:

$$\ell(\theta) = \log L(\theta) = \sum_{i=1}^{n} y^{(i)} \log h_{\theta}(x^{(i)}) + (1 - y^{(i)}) \log(1 - h_{\theta}(x^{(i)}))$$

#### Now to solve it...

$$\ell(\theta) = \log L(\theta) = \sum_{i=1}^{n} y^{(i)} \log h_{\theta}(x^{(i)}) + (1 - y^{(i)}) \log(1 - h_{\theta}(x^{(i)}))$$

We maximize for  $\theta$  but we already saw how to do this! Just compute derivative, run (S)GD and you're done with it!

**Takeaway:** This is *another* example of the max likelihood method: we setup the likelihood, take logs, and compute derivatives.

#### Time Permitting: There is magic in the derivative. . .

Even more, the batch update can be written in a *remarkably familiar* form:

$$\theta^{(t+1)} = \theta^{(t)} + \sum_{j \in B} (y^{(j)} - h_{\theta}(x^{(j)}))x^{(j)}.$$

We sketch why (you can check!) We drop superscripts to simplify notation and examine a single data point:

$$y \log h_{\theta}(x) + (1 - y) \log(1 - h_{\theta}(x))$$

$$= -y \log(1 + e^{-\theta^{T}x}) + (1 - y)(-\theta^{T}x) - (1 - y) \log(1 + e^{-\theta^{T}x})$$

$$= -\log(1 + e^{-\theta^{T}x}) - (1 - y)(\theta^{T}x)$$

We used  $1 - h_{\theta}(x) = \frac{e^{-\theta^T x}}{1 - e^{-\theta^T x}}$ . We now compute the derivative of this expression wrt  $\theta$  and get:

$$\frac{e^{-\theta^T x}}{1+e^{-\theta^T x}}x-(1-y)x=(y-h_{\theta}(x))x$$

# Perceptron Learning Algorithm

- Modify link function to output either 0 or 1.
- Make g to be a threshold function
- Then use same  $h_{\theta}(x) = g(\theta^T x)$  using this g
- Follow the same update rule for  $\theta$

$$g(z) = \begin{cases} 1 & \text{if } z \ge 0 \\ 0 & \text{if } z < 0 \end{cases}$$

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- ► We used the principle of maximum likelihood (and a probabilistic model) to extend to classification.
- ▶ We developed logistic regression from this principle.
  - Logistic regression is *widely* used today.
- We noticed a familiar pattern: take derivatives of the likelihood, and the derivatives had this (hopefully) intuitive "misprediction form"

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We apply this with  $f(\theta) = \nabla_{\theta} \ell(\theta)$ , the likelihood function

# Newton's Method (Drawn in Class)

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## Newton's Method Summary

Given  $f: \mathbb{R}^d \to \mathbb{R}$  find x s.t. f(x) = 0.

► This is the update rule in 1d

$$x^{(t+1)} = x^{(t)} - \frac{f(x^{(t)})}{f'(x^{(t)})}$$

- ▶ It may converge *very* fast (quadratic local convergence!)
- ► For the likelihood, i.e.,  $f(\theta) = \nabla_{\theta} \ell(\theta)$  we need to generalize to a vector-valued function which has:

$$\theta^{(t+1)} = \theta^{(t)} - \left(H(\theta^{(t)})\right)^{-1} \nabla_{\theta} \ell(\theta^{(t)}).$$

in which  $H_{i,j}(\theta) = \frac{\partial}{\partial \theta_i \partial \theta_i} \ell(\theta)$ .

#### **Optimization Method Summary**

	Compute per Step	Number of Steps
Method		to convergence
SGD	$\theta(d)$	≈ <b>є</b> <sup>-2</sup>
Minibatch SGD		
GD	θ(nd)	≈ <b>є</b> <sup>-1</sup>
Newton	$\Omega(\mathrm{nd}^2)$	≈ log(1/€ )

- In classical stats, d is small (< 100), n is often small, and exact parameters matter
- ▶ In modern ML, d is huge (billions, trillions), n is huge (trillions), and parameters used only for prediction
  - > These are approximate number of computing steps
  - Convergence happens when loss settles to within an error range around the final value.
  - Newton would be very fast, where SGD needs a lot of step, but individual steps are fast, makes up for it
- As a result, (minibatch) SGD is the workhorse of ML.



# Classification Lecture Summary

- ▶ We saw the differences between classification and regression.
- ► We learned about a principle for probabilistic interpretation for linear regression and classification: **Maximum Likelihood**.
  - ▶ We used this to derive logistic regression.
  - ► The Maximum Likelihood principle will be used again next lecture (and in the future)
- We saw Newton's method, which is classically used models (more statistics than ML-it's not used in most modern ML)