# CMSC 478 KMA Solaiman

# Supervised Learning: Linear Regression, Learning Algorithm and Gradient Descent

# Supervised Learning and Linear Regression

- Definitions
- Linear Regression
  - > Learning Algorithm
  - Cost / Loss Function
  - ➤ Gradient Descent
- Batch and Stochastic Gradient

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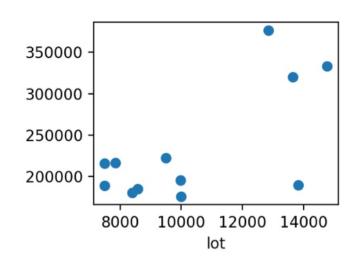
- ightharpoonup If  ${\cal Y}$  is continuous, then called a *regression problem*.
- $\blacktriangleright$  If  $\mathcal{Y}$  is discrete, then called a *classification problem*.



Our first example: Regression using Housing Data.

# Example Data (Housing Prices from Ames Dataset from Kaggle)

	SalePrice	Lot.Area
4	189900	13830
5	195500	9978
9	189000	7500
10	175900	10000
12	180400	8402
22	216000	7500
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55	216500	7851
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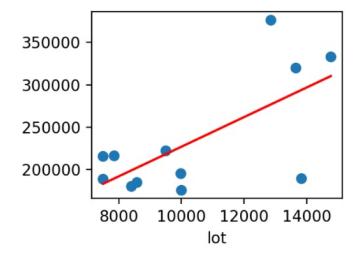
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Notice the prediction is defined by the parameters  $\theta_0$  and  $\theta_1$ . This is a huge reduction in the space of functions!

# Simple Line Fit

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# Slightly More Interesting Data

We add *features* (bedrooms and lot size) to incorporate more information about houses.

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$$h(x) = \theta_0 + \theta_1 x_1 + \theta_2 x_2 + \theta_3 x_3.$$

With the convention that  $x_0 = 1$  we can write:

$$h(x) = \sum_{j=0}^{3} \theta_j x_j$$

#### **Vector Notation for Prediction**

	size	bedrooms	lot size		Price
$\chi^{(1)}$	2104	4	45k	$y^{(1)}$	400
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We write the vectors as (important notation)

$$\theta = \begin{pmatrix} \theta_0 \\ \theta_1 \\ \theta_2 \\ \theta_3 \end{pmatrix} \text{ and } x^{(1)} = \begin{pmatrix} x_0^{(1)} \\ x_1^{(1)} \\ x_2^{(1)} \\ x_3^{(1)} \end{pmatrix} = \begin{pmatrix} 1 \\ 2104 \\ 4 \\ 45 \end{pmatrix} \text{ and } y^{(1)} = 400$$

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We call  $\theta$  (or w) **parameters**,  $x^{(i)}$  is the input or the **features**, and the output or **target** is  $y^{(i)}$ . To be clear,

(x, y) is a training example and  $(x^{(i)}, y^{(i)})$  is the  $i^{th}$  example.

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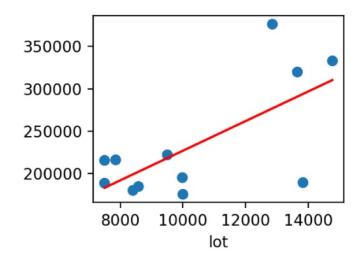
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We have n examples (i.e.,  $i=1,\ldots,n$ ). There are d features so  $x^{(i)}$  and  $\theta$  are d+1 dimensional (since  $x_0=1$ ).

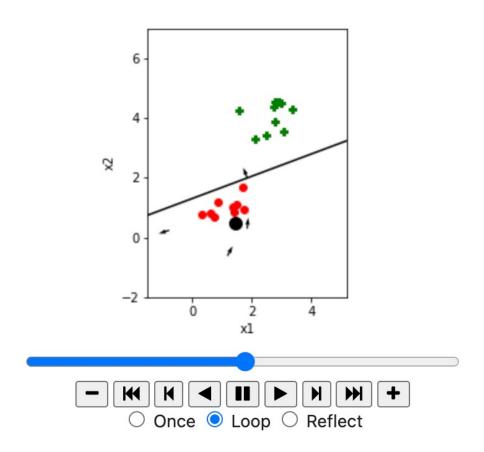
# Visual version of linear regression



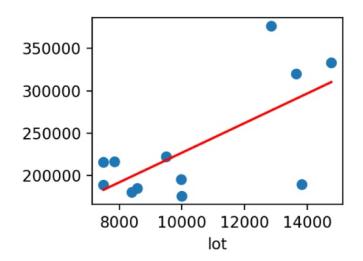
Let  $h_{\theta}(x) = \sum_{j=0}^{d} \theta_{j} x_{j}$  want to choose  $\theta$  so that  $h_{\theta}(x) \approx y$ .

# Fitting a good line

Animation



# Visual version of linear regression: Learning



Let  $h_{\theta}(x) = \sum_{j=0}^{d} \theta_{j} x_{j}$  want to choose  $\theta$  so that  $h_{\theta}(x) \approx y$ . One popular idea called **least squares** 

$$J(\theta) = \frac{1}{2} \sum_{i=1}^{n} \left( h_{\theta}(x^{(i)}) - y^{(i)} \right)^{2}.$$

Choose

$$\theta = \underset{\theta}{\operatorname{argmin}} J(\theta).$$

# Linear Regression Summary

- ▶ We saw our first hypothesis class *affine* or *linear* functions.
- We refreshed ourselves on notation and introduced terminology like parameters, features, etc.
- We saw this paradigm that a "good" hypothesis is some how one that is close to the data (objective function J).

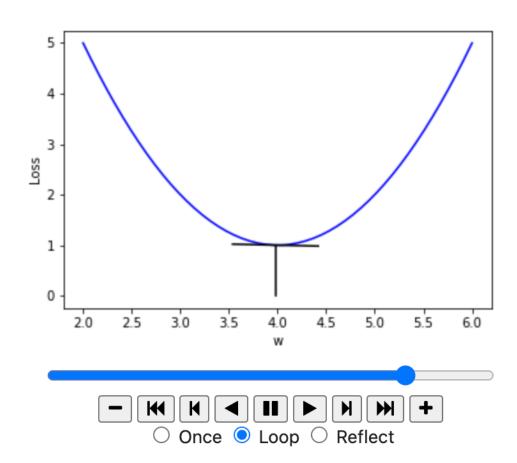
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- Next, we'll see how to solve these equations.

Solving the least squares optimization problem.

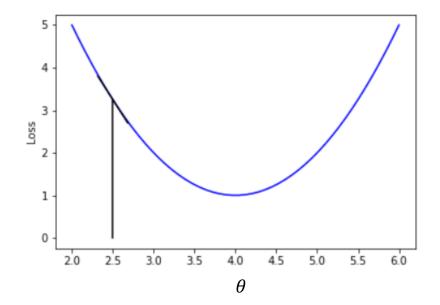
# Gradient Descent

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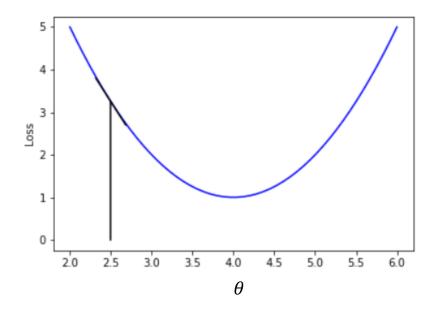
#### **Gradient Descent**

- $\mathcal{J}(\theta) = (\theta 4)^2 + 1$
- Find the weight (value of  $\theta$ ) that minimizes the loss  $\mathcal J$
- $\mathcal{J}'(\theta) = ?$
- $\theta = 2.5$
- given the current value of w, adjusting  $\theta$  by an amount that has the negative of the sign of  $\mathcal{J}'(\theta)$  leads to a smaller value of  $\mathcal{J}$ .



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$$\theta = \theta - \alpha * \mathcal{J}'(\theta)$$

#### Gradient Descent

$$\theta^{(0)} = 0$$

$$\theta_j^{(t+1)} = \theta_j^{(t)} - \alpha \frac{\partial}{\partial \theta_j} J(\theta^{(t)}) \qquad \text{for } j = 0, \dots, d.$$

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Note that  $\alpha$  is called the **learning rate** or **step size**.

Let's compute the derivatives...

$$\frac{\partial}{\partial \theta_j} J(\theta^{(t)}) = \sum_{i=1}^n \frac{1}{2} \frac{\partial}{\partial \theta_j} \left( h_{\theta}(x^{(i)}) - y^{(i)} \right)^2$$
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For our *particular*  $h_{\theta}$  we have:

$$h_{\theta}(x) = \theta_0 x_0 + \theta_1 x_1 + \dots + \theta_d x_d$$
 so  $\frac{\partial}{\partial \theta_j} h_{\theta}(x) = x_j$ 



Thus, our update rule for component j can be written:

$$\theta_j^{(t+1)} = \theta_j^{(t)} - \alpha \sum_{i=1}^n \left( h_{\theta}(x^{(i)}) - y^{(i)} \right) x_j^{(i)}.$$

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We write this in *vector notation* for j = 0, ..., d as:

$$\theta^{(t+1)} = \theta^{(t)} - \alpha \sum_{i=1}^{n} \left( h_{\theta}(x^{(i)}) - y^{(i)} \right) x^{(i)}.$$

Saves us a lot of writing! And easier to understand . . . eventually.

# Linear Classification: Mushroom and Goats

	color	width	height	label
0	-0.311688	0.358501	0.936567	edible
1	-0.472327	0.817906	0.468387	poisonous

```
	exttt{sign}(w_c * 	exttt{color} + w_w * 	exttt{width} + w_h * 	exttt{height}) 	exttt{sign}(0*-0.472327+1*0.817906-1*0.468387) = 	exttt{sign}(0.349519) = +1 	exttt{sign}(0*-0.311688+1*0.358501-1*0.936567) = 	exttt{sign}(-0.578066) = -1
```

Linear Classification

# Loss Function for Classification: 0-1 Loss

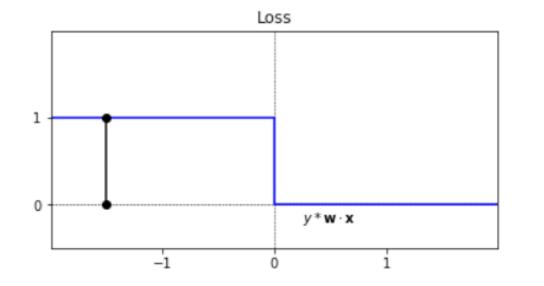
$L_{0-1}$	$egin{array}{l} \hat{y} \ = \ -1 \end{array}$	$\hat{y} = 1$
y = -1	0	1
y = 1	1	0

### Loss Function for Classification: 0-1 Loss

$$L_{0-1}(y,\mathbf{w}\cdot\mathbf{x}) = egin{cases} 0 & ext{if } y*\mathbf{w}\cdot\mathbf{x} > 0 \ 1 & ext{otherwise} \end{cases}$$

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#### Batch Versus Stochastic Minibatch: Motivation

Consider our update rule:

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A single update, our rule examines all n data points.

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  - E.g., we try to "predict" every word on the web.
- ► Idea Sample a few points (maybe even just one!) to approximate the gradient called Stochastic Gradient (SGD).
  - SGD is the workhorse of modern ML, e.g., pytorch and tensorflow.

#### Stochastic Minibatch

- ▶ We randomly select a **batch** of  $B \subseteq \{1, ..., n\}$  where |B| < n.
- We approximate the gradient using just those B points as follows (vs. gradient descent)

$$\frac{1}{|B|} \sum_{j \in B} \left( h_{\theta}(x^{(j)}) - y^{(j)} \right) x^{(j)} \text{ v.s. } \frac{1}{n} \sum_{j=1}^{n} \left( h_{\theta}(x^{(j)}) - y^{(j)} \right) x^{(j)}.$$

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So our update rule for SGD is:

All minibatches are used for each iteration, or epoch and then start the next one

$$\theta^{(t+1)} = \theta^{(t)} - \alpha_B \sum_{j \in B} \left( h_{\theta}(x^{(j)}) - y^{(j)} \right) x^{(j)}.$$

▶ NB: scaling of |B| versus n is "hidden" inside choice of  $\alpha_B$ .



#### Stochastic Minibatch vs. Gradient Descent

Recall our rule B points as follows:

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- ▶ If  $|B| = \{1, ..., n\}$  (the whole set), then they coincide.
- Smaller B implies a lower quality approximation of the gradient (higher variance).
- Nevertheless, it may actually converge faster! (Case where the dataset has many copies of the same point—extreme, but lots of redundancy)

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- ► Smaller *B* implies a lower quality approximation of the gradient (higher variance).
- Nevertheless, it may actually converge faster! (Case where the dataset has many copies of the same point—extreme, but lots of redundancy)
- ▶ In practice, choose B proportional to what works well on modern parallel hardware (GPUs).

## Summary of this Subsection of Optimization

- Our goal was to optimize a loss function to find a good predictor.
- We learned about gradient descent and the workhorse algorithm for ML, Stochastic Gradient Descent (SGD).
- ▶ We touched on the tradeoffs of choosing the right batch size.

## Summary from Today

- ► We saw a lot of notation
- We learned about linear regression: the model, how to solve, and more.
- ▶ We learned the workhorse algorithm for ML called **SGD**.
- Next time: Classification!