

POLI 273: Causal Inference
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Lecture 02 | Some Background

Announcements

- ▶ Syllabus is on. All the readings are on now.
- ▶ PS 01 is also on. Make sure you have access to Canvas and to Gradescope.
- ▶ And let me know if you do not!
- ▶ GitHub page: <https://github.com/umbertomig/POLI273>

Background

Background

- ▶ This is going to be very repetitive for you now.
- ▶ But it is important to build a solid foundation. And as Leo and I were talking in the previous lecture, repetitive is not necessarily bad.
 - ▶ Ok, maybe boring...
- ▶ This background part: Probability Theory, Distributions, and Random Samples
- ▶ Mostly based on [Aronow and Miller \(2019\)](#)
 - ▶ A great book that we have free access here at the UCSD!

Probability Theory

- ▶ Important to establish some basic understanding of our research fundamentals.
- ▶ Helps us to formalize the quantities of interest and their uncertainty in precise terms.
- ▶ **Probability:** “Random generative process that selects an outcome among multiple possible outcomes.”

Fundamentals of Probability Theory

1. (Definition) **Sample space:** Denoted by Ω . Containing individual outcomes, denoted as $\omega \in \Omega$.
 - ▶ Polity IV scores: $\Omega = [-10, 10]$
 - ▶ Income: $\Omega = \mathbb{R}^+$
 - ▶ GDP growth: $\Omega = \mathbb{R}$ (but not really...)
 - ▶ Deaths in a civil conflict: $\Omega = \mathbb{N} \cup 0$
 - ▶ And so on.
 - ▶ One simple case, a coin toss: $\Omega = \{H, T\}$.

Fundamentals of Probability Theory

2. (Definition) **Event space**: Subsets of Ω (that form a σ -Algebra: [check this](#)). The set of the subsets (S) have to satisfy the following properties:
- ▶ $S \neq \emptyset$
 - ▶ If $A \in S$, then $A^C \in S$
 - ▶ For a countable sequence $A_1, A_2, \dots \in S$, then $\bigcup A_i \in S$
 - ▶ For a coin toss, let us consider $S = 2^\Omega$.

Fundamentals of Probability Theory

- ▶ A set with these two properties is called a **measurable set**.
- ▶ And this pretty much means that we can **measure** stuff in this set.
- ▶ We are going to use a special function to measure stuff. Something called a *probability measure*.

Fundamentals of Probability Theory

3. (Definition) **Probability Measure:** A function $\mathbb{P} : S \rightarrow [0, 1]$, that we are going to call *probability measure*. \mathbb{P} has to satisfy three axioms (Kolmogorov):
- ▶ $\forall A \in S, \mathbb{P}(A) \in [0, 1]$.
 - ▶ $\mathbb{P}(\Omega) = 1$.
 - ▶ Let the sequence $A_1, A_2, \dots \in S$, such that $A_i \cap A_j = \emptyset \forall i \neq j$. Then, $\mathbb{P}(\bigcup A_i) = \sum \mathbb{P}(A_i)$
 - ▶ For a coin toss, let us consider $\mathbb{P}(A) = \frac{1}{2}|A|$.
 - ▶ Lots of consequences can be reached from these simple things: e.g., $\mathbb{P}(\emptyset)$ or $\mathbb{P}(A^c) = 1 - \mathbb{P}(A)$, etc.

Fundamentals of Probability Theory

- ▶ We rarely talk about one event. In science, we talk about *how one event is related to another*.
- ▶ (Definition) **Joint Probability:** For $A, B \in S$, the joint probability of A and B is $\mathbb{P}(A \cap B)$
- ▶ (Theorem) **Addition Rule:** For $A, B \in S$

$$\mathbb{P}(A \cup B) = \mathbb{P}(A) + \mathbb{P}(B) - \mathbb{P}(A \cap B)$$

- (Definition) **Conditional Probability** For $A, B \in \mathcal{S}$, the joint probability of A and B is

$$\mathbb{P}(A|B) = \frac{\mathbb{P}(A \cap B)}{\mathbb{P}(B)}$$

- (Theorem) **Multiplicative Law**: For $A, B \in \mathcal{S}$, with $\mathbb{P}(B) > 0$,

$$\mathbb{P}(A|B)\mathbb{P}(B) = \mathbb{P}(A \cap B)$$

- (Theorem) **Bayes Rule**: For $A, B \in \mathcal{S}$, with $\mathbb{P}(A) > 0$ and $\mathbb{P}(B) > 0$,

$$\mathbb{P}(A|B) = \frac{\mathbb{P}(B|A)\mathbb{P}(A)}{\mathbb{P}(B)}$$

Independence

- ▶ (Definition) **Independence of Events:** Events $A, B \in \mathcal{S}$ are *independent* if $\mathbb{P}(A \cap B) = \mathbb{P}(A)\mathbb{P}(B)$
- ▶ (Theorem) **Conditional Probability and Independence:** For $A, B \in \mathcal{S}$, with $\mathbb{P}(B) > 0$, A and B are independent if, and only if, $\mathbb{P}(A|B) = \mathbb{P}(A)$.

Random Variable

- ▶ (Definition) **Random Variable:** A *random variable* is a function $X : \Omega \rightarrow \mathbb{R}$ such that, $\forall r \in \mathbb{R}$,
 $\{\omega \in \Omega : X(\omega) \leq r\} \in \mathcal{S}$
- ▶ A random variable maps each state of the world ($\omega \in \Omega$) to a real number.
 - ▶ Example: the event $\{X = 1\}$ means
 $\{\omega \in \Omega : X(\omega) = 1\}$
- ▶ The book differentiates the prob of sets (prob spaces) and probs of random variables and random operators.
 - ▶ I will loosely keep using \mathbb{P} for both, but you should understand that this is *poetic license* (see discussions on pages 16-18).

Discrete Random Variables

- ▶ (Definition) **Discrete Random Variable:** A *random variable* X is discrete if its range is a countable set.
- ▶ (Definition) **Probability Mass Function:** For a discrete random variable X , the *PMF* of X is $f(x) = \mathbb{P}[X = x]$, $\forall x \in \mathbb{R}$
 - ▶ If you look carefully, you will now understand why the book uses \mathbb{P} and Pr !
- ▶ (Facts) **Properties of Probability Mass Functions:** For a discrete variable X , with *PMF* f :
 1. $\forall x \in \mathbb{R}, f(x) \geq 0$
 2. $\sum_{x \in X(\Omega)} f(x) = 1$
 3. If $D \subseteq \mathbb{R}$, and $A = \{X \in D\}$, then
$$\mathbb{P}(A) = \mathbb{P}(X \in D) = \sum_{x \in X(A)} f(x)$$

Discrete Random Variables

- ▶ (Definition) **Cumulative Distribution Function:** For a random variable X , the *CDF* of X is $F(x) = \mathbb{P}[X \leq x]$, $\forall x \in \mathbb{R}$
 - ▶ More general way to look at things than look at *PMFs*
- ▶ (Facts) **Properties of CDFs:** For a random variable X , with *CDF* F :
 - ▶ $\lim_{x \rightarrow -\infty} F(x) = 0$
 - ▶ $\lim_{x \rightarrow \infty} F(x) = 1$
 - ▶ $\forall x \in \mathbb{R}, 1 - F(x) = \mathbb{P}[x > x]$

Continuous Random Variables

- ▶ (Definition) **Continuous Random Variables and CDFs:**
A random variable X is continuous if \exists a function $F : \mathbb{R} \rightarrow [0, 1]$ such that the *CDF* of X is $F(x) = \mathbb{P}[X \leq x] = \int_{-\infty}^x f(u)du, \forall x \in \mathbb{R}$.
- ▶ (Definition) **Probability Density Function:** For a continuous random variable X with *CDF* $F(x)$, the *PDF* is defined as $f(x) = \left. \frac{dF(u)}{du} \right|_{u=x}, \forall x \in \mathbb{R}$.

Continuous Random Variables

- (Facts) **Properties of Continuous Random Variables:** For a continuous random variable X with *CDF* $F(x)$ and *PDF* $f(x)$:

1. $\forall x \in \mathbb{R}, f(x) \geq 0$

2. $\int_{-\infty}^{\infty} f(x) dx = 1$

3. $\forall x \in \mathbb{R}, \mathbb{P}[X = x] = 0$

4. $\forall x \in \mathbb{R},$

$$\mathbb{P}[X > x] = \mathbb{P}[X \geq x] = 1 - F(x) = \int_x^{\infty} f(u) du$$

5. $\forall a, b \in \mathbb{R}, \text{ with } a \leq b, \mathbb{P}[a \leq X \leq b] = F(b) - F(a)$

Support

- ▶ (Definition) **Support of a Random Variable:** For a random variable X with *PMF/PDF* f , the *support* of X is $\text{Supp} = \{x \in \mathbb{R} : f(x) > 0\}$
 - ▶ Sounds out of nowhere, but it is actually very important for Conditional Expectations!

Bivariate Relationships

- ▶ Most of what matters for us is about more than just one Random Variable.
- ▶ The same way we care about different sets of events, we care even more about bivariate relations
 - ▶ Or how to Random Variables relate to each other.
- ▶ Luckily, we can extend the primitives we formulated so far to account for bivariate relationships.

Bivariate Relationships

- ▶ (Definition) **Equality of Random Variables:** Let X and Y random variables. $X = Y$ if, $\forall \omega \text{ in } \Omega, X(\omega) = Y(\omega)$.
- ▶ (Theorem) **Equality of Functions of Random Variables:** Let X a random variable and f and g functions of X . Then $f(X) = g(X) \iff \forall x \in X(\Omega), f(x) = g(x)$.

Discrete Bivariate Relationships

- ▶ (Definition) **Joint Probability Mass Function:** For discrete random variables X and Y , the joint *PMF* of X and Y is $f(x, y) = \mathbb{P}[X = x, Y = y]$.
- ▶ (Definition) **Joint Cumulative Distribution Function:** For discrete random variables X and Y , the joint *CDF* of X and Y is $F(x, y) = \mathbb{P}[X \leq x, Y \leq y]$.

Discrete Bivariate Relationships

- ▶ (Fact) **Multiplicative Law for Probability Mass Functions:** For discrete random variables X and Y with joint *PMF* f . Then, $\forall x \in \mathbb{R}$ and $\forall y \in \text{Supp}[Y]$,
 $f_{X|Y}(x|y)f_Y(y) = f(x, y)$.
- ▶ Joint distributions are essential for Causal Inference, and data analysis in general.
- ▶ Now, let's look at the continuous case.

Continuous Bivariate Relationships

- (Definition) **Jointly Continuous Random Variables:** Two random variables X and Y are jointly continuous if there exists a function $f : \mathbb{R}^2 \rightarrow [0, 1]$ such that the joint *CDF* of X and Y is

$$F(x, y) = \mathbb{P}[X \leq x, Y \leq y] = \int_{-\infty}^x \int_{-\infty}^y f(u, v) dv du$$

- (Definition) **Joint Probability Distribution Function:** For two jointly continuous random variables X and Y , with joint *CDF* F , the joint *PDF* is

$$f(x, y) = \left. \frac{\partial^2 F(u, v)}{\partial u \partial v} \right|_{u=x, v=y}$$

Continuous Bivariate Relationships

- (Fact) **Marginal Probability Distribution Function:** For two jointly continuous random variables X and Y , with joint *PDF* f , the *marginal PDF* of Y is

$$f_Y(y) = \int_{-\infty}^{\infty} f(x, y) dx$$

- (Definition) **Conditional Probability Distribution Function:** For two jointly continuous random variables X and Y , with joint *PDF* f , the *conditional PDF* of Y is

$$f_{Y|X}(y|x) = \frac{f(x, y)}{f_X(x)}$$

- (Fact) **Multiplicative Law of Probability Distribution Functions:** For two jointly continuous random variables X and Y , with joint *PDF* f . Then, $\forall x \in \mathbb{R}$ and

Independence

- (Definition) **Independence of Random Variables:** Let X and Y two random variables with joint *PDF/PMF* f . We say X and Y are independent if, for all $x, y \in \mathbb{R}$,

$$f(x, y) = f_X(x)f_Y(y)$$

And we write $X \perp\!\!\!\perp Y$ to denote that the random variables X and Y are independent.

Independence

► (Facts) **Implications of Independence:** Let X and Y two random variables with joint *PDF/PMF* f . The following statements are equivalent:

1. $X \perp\!\!\!\perp Y$
2. $\forall x, y \in \mathbb{R}, f(x, y) = f_X(x)f_Y(y)$
3. $\forall x \in \mathbb{R} \text{ and } y \in \text{Supp}[Y], f_{X|Y}(x|y) = f_X(x)$
4. $\forall D, E \subseteq \mathbb{R}$, the events $\{X \in D\}$ and $\{Y \in E\}$ are independent.
5. For all functions g of X and h of Y $g(X) \perp\!\!\!\perp h(Y)$.

Multivariate Generalizations

- ▶ (Definition) **Random Vectors:** A random vector is a function $X : \Omega \rightarrow \mathbb{R}^K$ such that, $\forall \omega \in \Omega$,
 $\mathbf{X}(\omega) = \left(X_1(\omega), \dots, X_K(\omega) \right)$. And where X_i is a random variable.
- ▶ (Definition) **Joint Cumulative Density Function:** For a random vector \mathbf{X} , evaluated at \mathbf{x} , is denoted $F(\mathbf{x}) = \mathbb{P}[\mathbf{X} \leq \mathbf{x}]$.
- ▶ And from here, the extensions are evident:
 - ▶ For continuous random vectors, we use multiple integrals (*CDFs*) or partial derivatives (*PDFs*)
 - ▶ For discrete random vectors, we use multiple sums (*CDFs*).
 - ▶ For the conditional *PDFs/PMFs*, we marginalize on the variables by summing up across their support.

Summarizing Distributions

Summarizing Distributions

- ▶ Statistics would not be very useful if we did not find ways to summarize the objects we work with.
- ▶ (Definition) **Expected Value:** For a random variable X with bounded variation:
 1. If X is discrete, then $\mathbb{E}[X] = \sum_x xf(x)$
 - ▶ If X is continuous, then $\mathbb{E}[X] = \int_{-\infty}^{\infty} xf(x)$
- ▶ (Fact) **Expectation of a Function:** For a random variable X with *PMF/PDF* f and a function g (still assuming bounded variation):
 1. If X is discrete, then $\mathbb{E}[g(X)] = \sum_x g(x)f(x)$
 - ▶ If X is continuous, then $\mathbb{E}[g(X)] = \int_{-\infty}^{\infty} g(x)f(x)$

Summarizing Distributions

- (Definition) **Raw Moment:** For a random variable X , the j -th *raw moment* is defined as:

$$\mu'_j = \mathbb{E}[X^j]$$

- (Definition) **Central Moment:** For a random variable X , the j -th *central moment* is defined as:

$$\mu_j = \mathbb{E} [(X - \mathbb{E}[X])^j]$$

Summarizing Distributions

- (Definition) **Variance:** For a random variable X , the variance is defined as the *second central moment* of X :

$$\mathbb{V}[X] = \mathbb{E} [(X - \mathbb{E}[X])^2]$$

- (Definition) **Standard Deviation:** For a random variable X , the variance is defined as $\sigma[X] = \sqrt{\mathbb{V}[X]}$
- (Theorem) **Alternative formula for the Variance:** For a random variable X , the variance is defined as the *second central moment* of X :

$$\mathbb{V}[X] = \mathbb{E}[X^2] - [\mathbb{E}[X]]^2$$

Summarizing Distributions

- (Definition) **Normal Distribution:** A continuous random variable X follows a normal distribution (denoted by $X \sim N(\mu, \sigma^2)$) if:

$$f(x) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

- (Facts) **Mean and Standard Deviation of a Normal Distribution:** Let $X \sim N(\mu, \sigma^2)$. Then, $\mathbb{E}[X] = \mu$ and $\sigma[X] = \sigma$

Summarizing Distributions

- (Facts) **Algebra of Normal Distributions:** Let $X \sim N(\mu_X, \sigma_X^2)$, $Y \sim N(\mu_Y, \sigma_Y^2)$, and $a, b \in \mathbb{R}$, $a \neq 0$. Then:
 1. If $W = aX + b$, then $W \sim N(a\mu_X + b, a^2\sigma_X^2)$
 2. If $X \perp Y$, and $Z = X + Y$, then
$$Z \sim N(\mu_X + \mu_Y, \sigma_X^2 + \sigma_Y^2)$$
- This proof should be straightforward.

Summarizing Distributions

- ▶ And one of the most important objects: suppose we want to say how well a random variable X approximates a given value $c \in \mathbb{R}$.
- ▶ The most common metric we use for this purpose is the *Mean Squared Error*.
- ▶ (Definition) **Mean Squared Error:** The *MSE* of a random variable X about c is equal to: $\mathbb{E}[(X - c)^2]$.

Summarizing Distributions

- (Theorem) **Alternative formulation for the Mean Squared Error:** The *MSE* of a random variable about c is equal to:

$$\mathbb{E}[(X - c)^2] = \mathbb{V}[X] + (\mathbb{E}[X] - c)^2$$

- (Theorem) **Mean Squared Error Minimization:** The value c that minimizes the *MSE* of a random variable X about c is $c = \mathbb{E}[X]$.

Questions?

See you in the next class