ArduCopter.pde

```
 1  void setup()
 2  {
 3      cliSerial = hal.console;
 4
 5      // Load the default values of variables listed in var_info
            [] s
 6      AP_Param::setup_sketch_defaults();
 7
 8      init_ardupilot();
 9
10      // initialise the main loop scheduler 分配一块新空间
            _last_run用于存储任务列表，用memset()将其内容全设为零
11      scheduler.init(&scheduler_tasks[0], sizeof(scheduler_tasks)
            /sizeof(scheduler_tasks[0]));
12  }
```