Space-efficient alignment



How should we think about "optimal" alignment?

O(nm) time is a problem, but as I've said, we **strongly believe** we can't to much better (in the worst case).

Can we do better in practice?

Doing better in practice

Can we do better in practice?

What about when we know that the edit distance is small (say e << mn)? What about when we only care about edit distances < some threshold?

Yes!

JOURNAL ARTICLE

Optimal gap-affine alignment in O(s) space $\frac{\partial}{\partial s}$

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O(ns) time and O(s) space where s is the score of the optimal alignment!

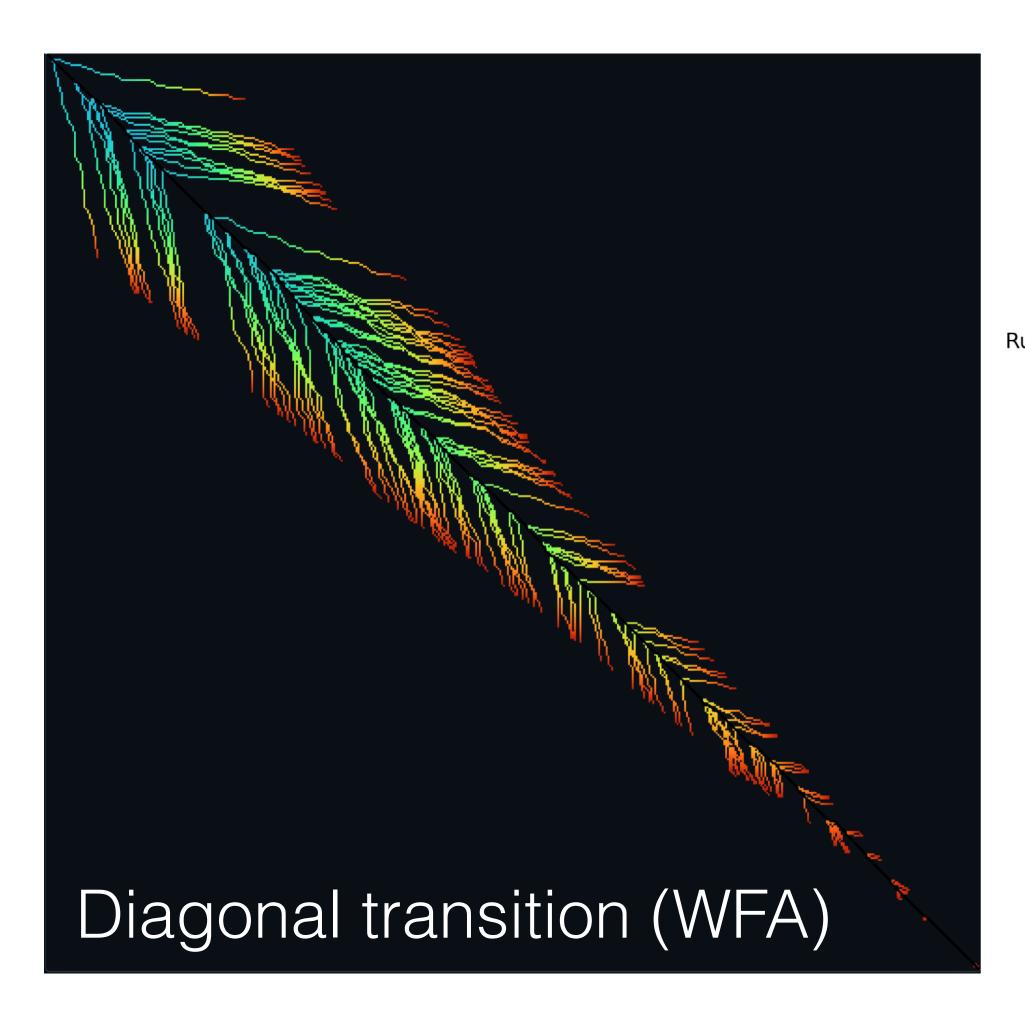


than BiWFA (for long seqs)

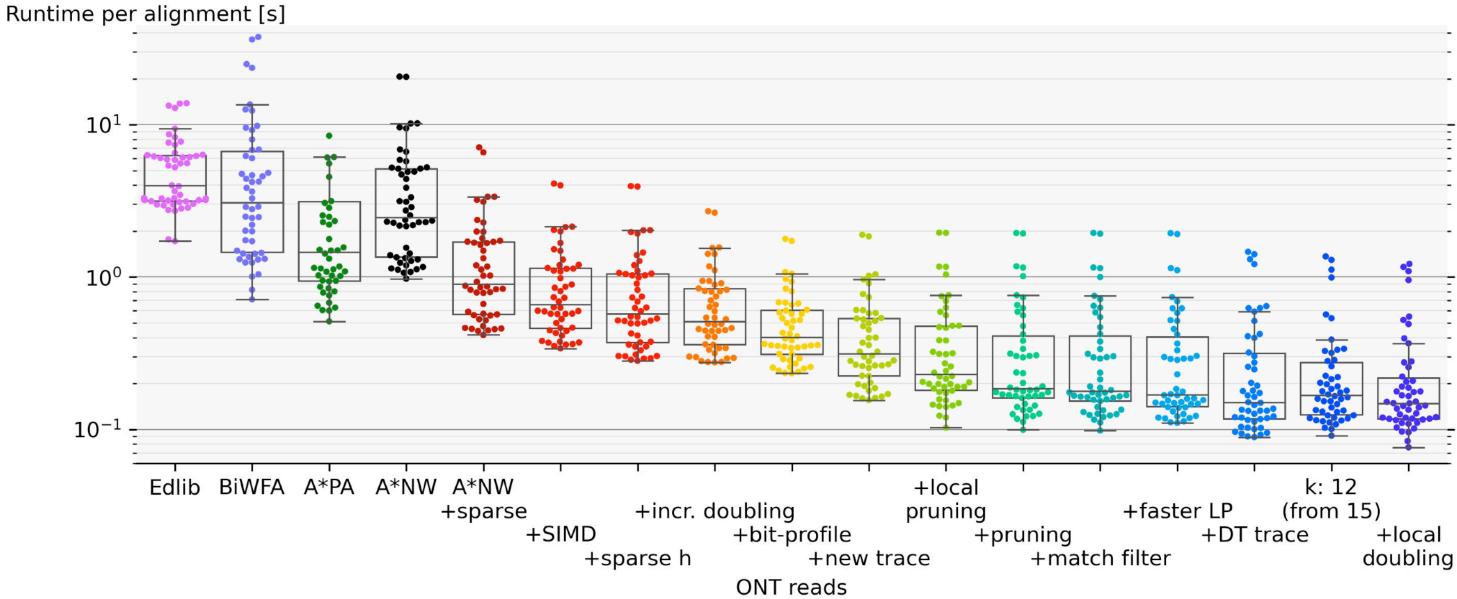
Doing better in practice

Beautiful motivation:

https://github.com/RagnarGrootKoerkamp/astar-pairwise-aligner



Improvements to A*PA since initial publication!



Let's explore how you'd design a space-efficient method

There are many ways to achieve results like those above. To be efficient in both time and space simultaneously requires several clever maneuvers. Let's focus on space.

Can we do better in terms of space?

It turns out we can — at the same asymptotic time complexity!

Combining dynamic programming with the divide-and-conquer algorithm design technique.

Hirshberg's algorithm

Consider our DP matrix:

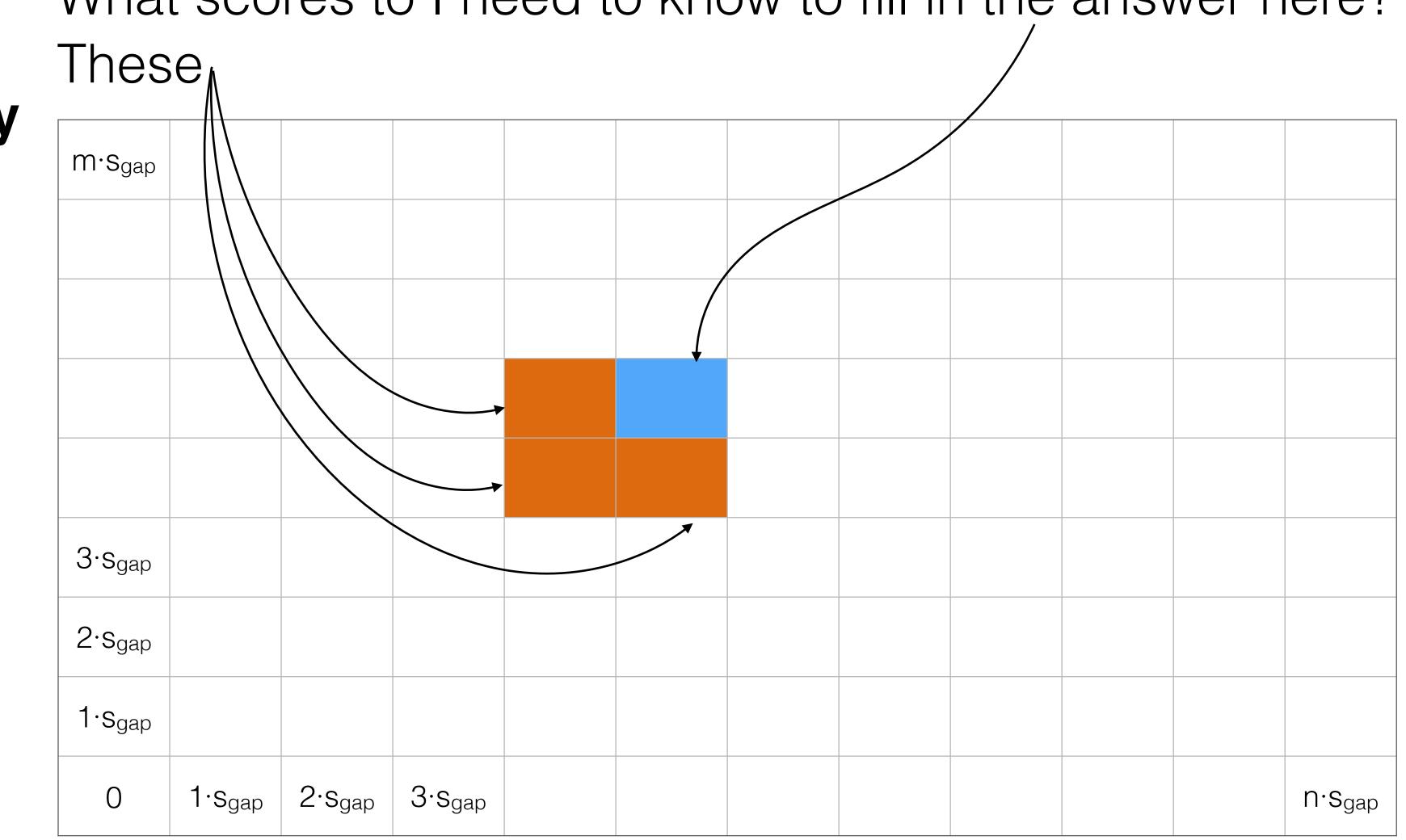
У

m·s _{gap}							
3·s _{gap}							
2·s _{gap}							
1·s _{gap}							
0	1·s _{gap}	2·s _{gap}	3·s _{gap}				n·s _{gap}

What scores to I need to know to fill in the answer here?

3·sgap 2·s_{gap} 1.Sgap 1·sgap 2·sgap 3·sgap n·s_{gap}

What scores to I need to know to fill in the answer here?



If we fill rows left - right, and bottom to top, to fill in row i, we *only* need scores from row i-1.

y

m·s _{gap}							
3·s _{gap}							
2·s _{gap}							
1·s _{gap}							
0	1·s _{gap}	2·s _{gap}	3·s _{gap}				n·s _{gap}

Columns also work; if we go left - right, and bottom to top, to fill in column i, we only need scores from col i-1.

y

m·s _{gap}							
3·s _{gap}							
2·s _{gap}							
1·s _{gap}							
0	1·s _{gap}	2·s _{gap}	3·s _{gap}				n·s _{gap}

If we fill rows left - right, and bottom to top, to fill in row i, we *only* need scores from row i-1.

Thus, we can compute the optimal *score*, keeping at most 2 rows / columns in memory at once.

Each row / column is *linear* in the length of one of the strings, and so we can compute the optimal *score*, in *linear space*.

How can we compute the optimal alignment?

This method won't work for computing the optimal alignment; we need *all* rows to be able to follow the backtracking arrows.

How can we find the optimal *alignment* in linear space?

Hirschberg's algorithm provides a solution.

Consider, again, the meaning of the DP matrix What is contained in the highlighted row?

У

m·s _{gap}							
3·s _{gap}							
2·s _{gap}							
1·S _{gap}							
0	1·s _{gap}	2·s _{gap}	3·s _{gap}				n·s _{gap}

Consider, again, the meaning of the DP matrix score of *every* prefix of **x** against *all* of **y** in this row

m·s_{gap} 3.sgap 2·sgap 1·sgap 2·sgap 3·sgap n·s_{gap}

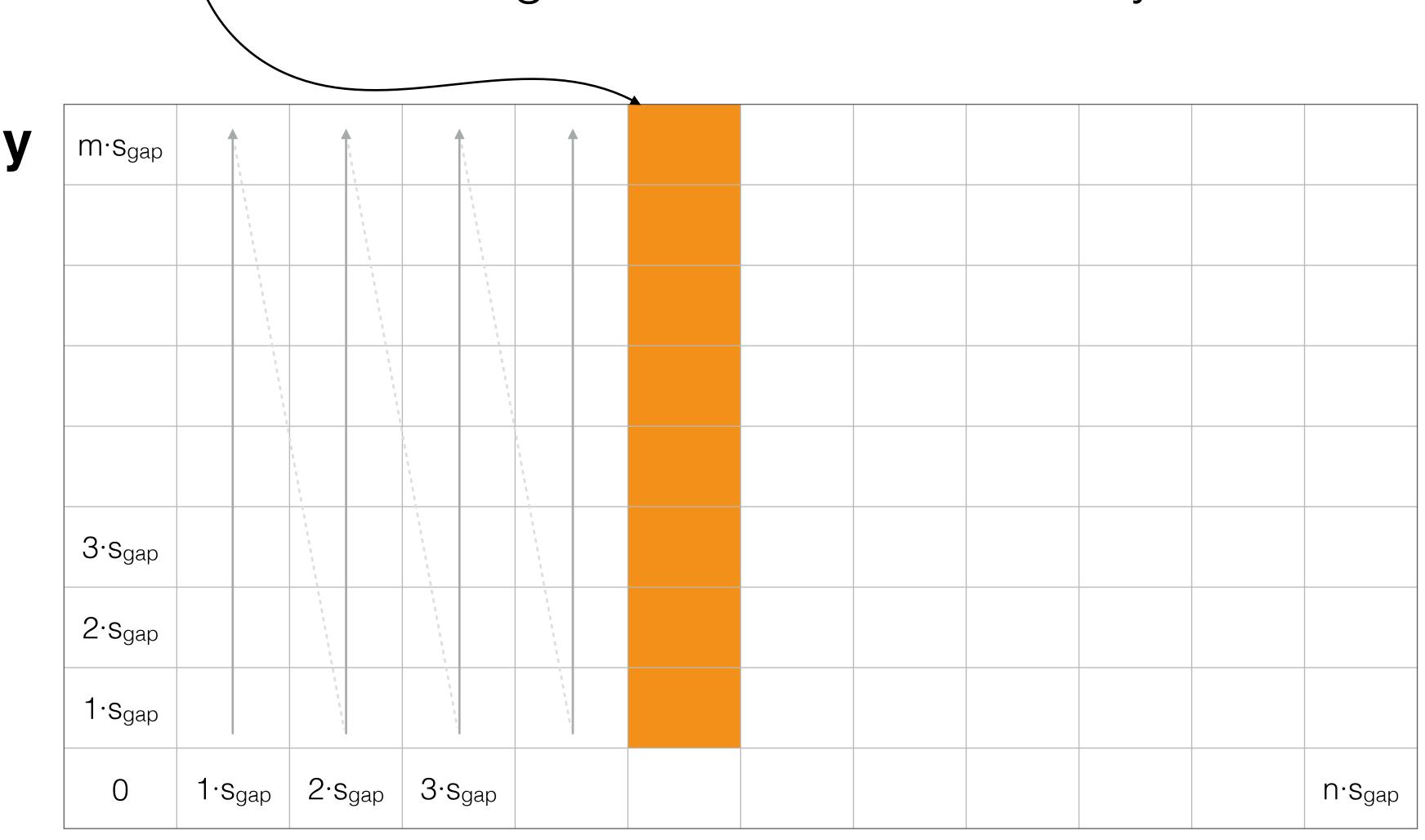
Consider, again, the meaning of the DP matrix What is contained in the highlighted column?

m·s_{gap} 3.sgap 2·sgap 1·sgap 2·sgap 3·sgap n·s_{gap}

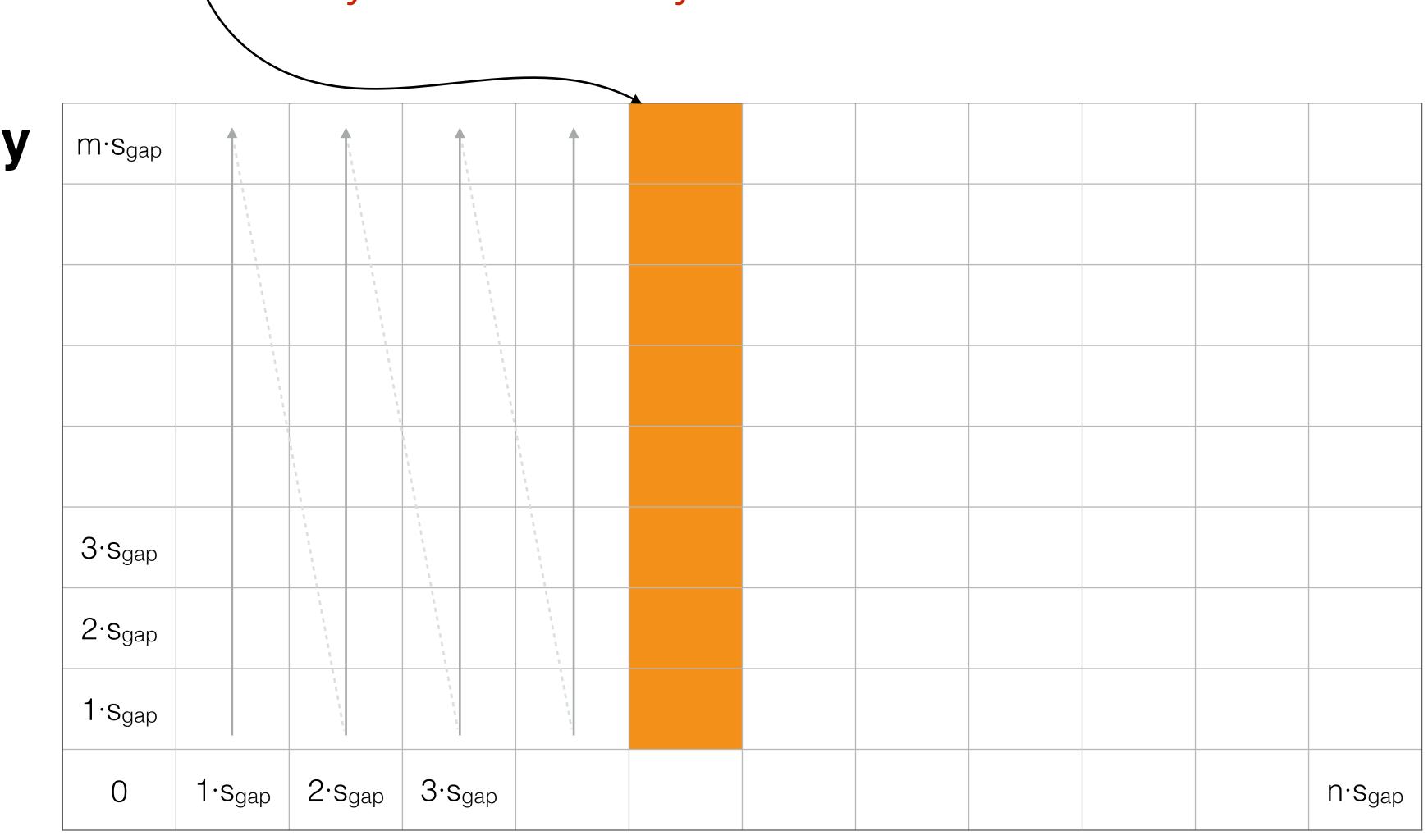
Consider, again, the meaning of the DP matrix score of *every* prefix of **y** against *all* of **x** in this column

m·s_{gap} 3.sgap 2·sgap 1·sgap 2·sgap 3·sgap n·s_{gap}

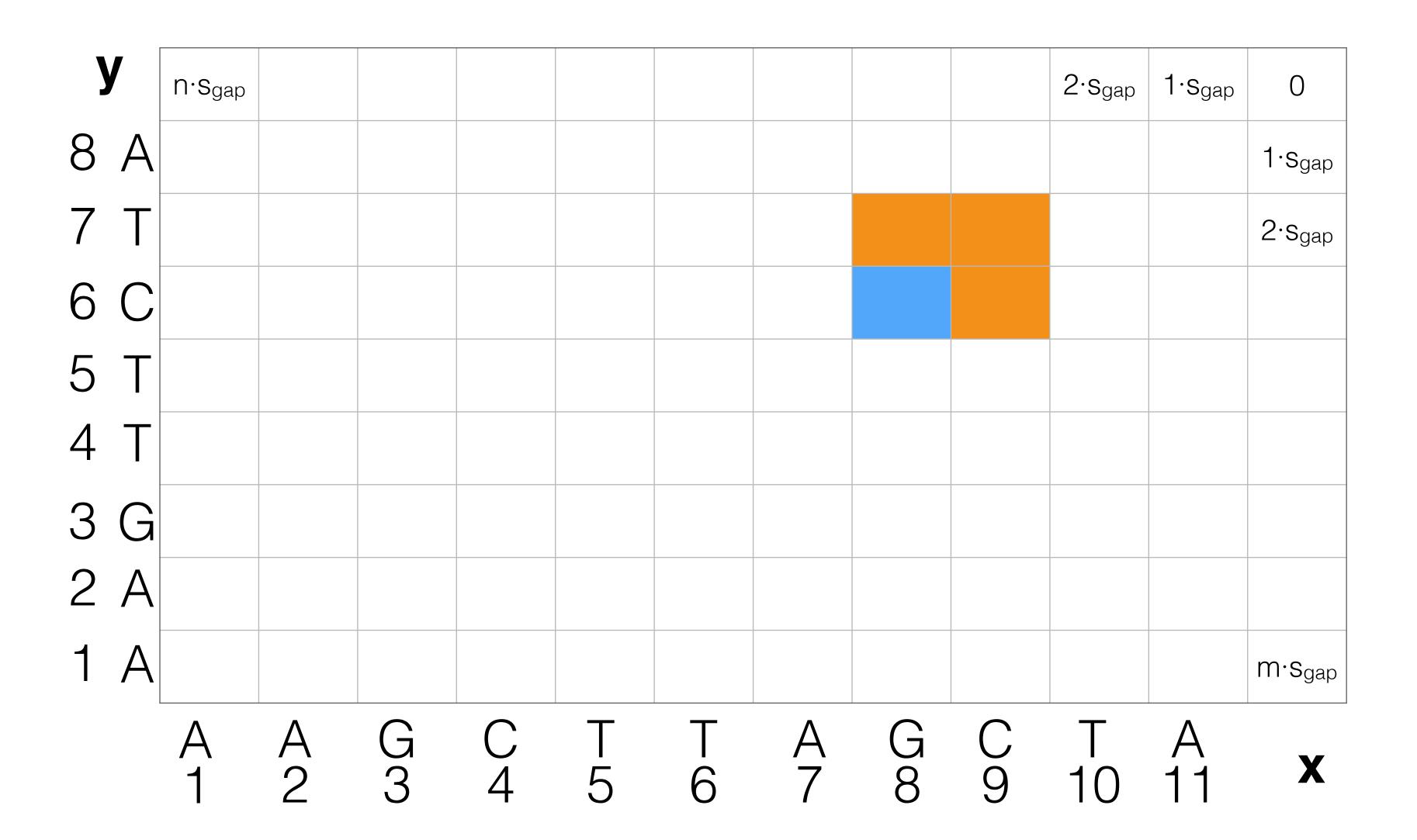
score of *every* prefix of **y** against ith prefix of **x** in the ith column. How do we get these values efficiently?



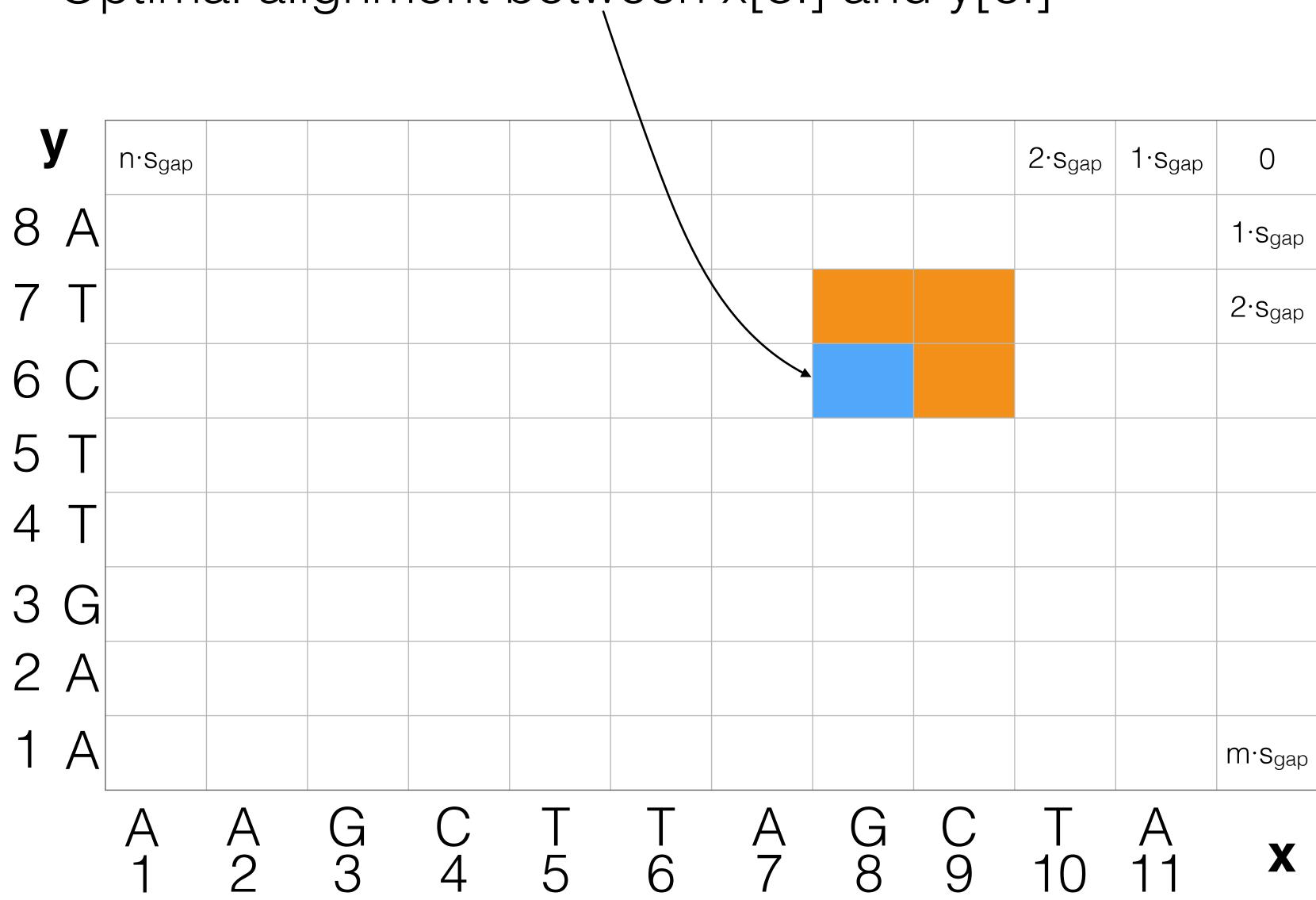
score of *every* prefix of **y** against ith prefix of **x** in the ith column. Easy if we fill in by columns instead of rows.



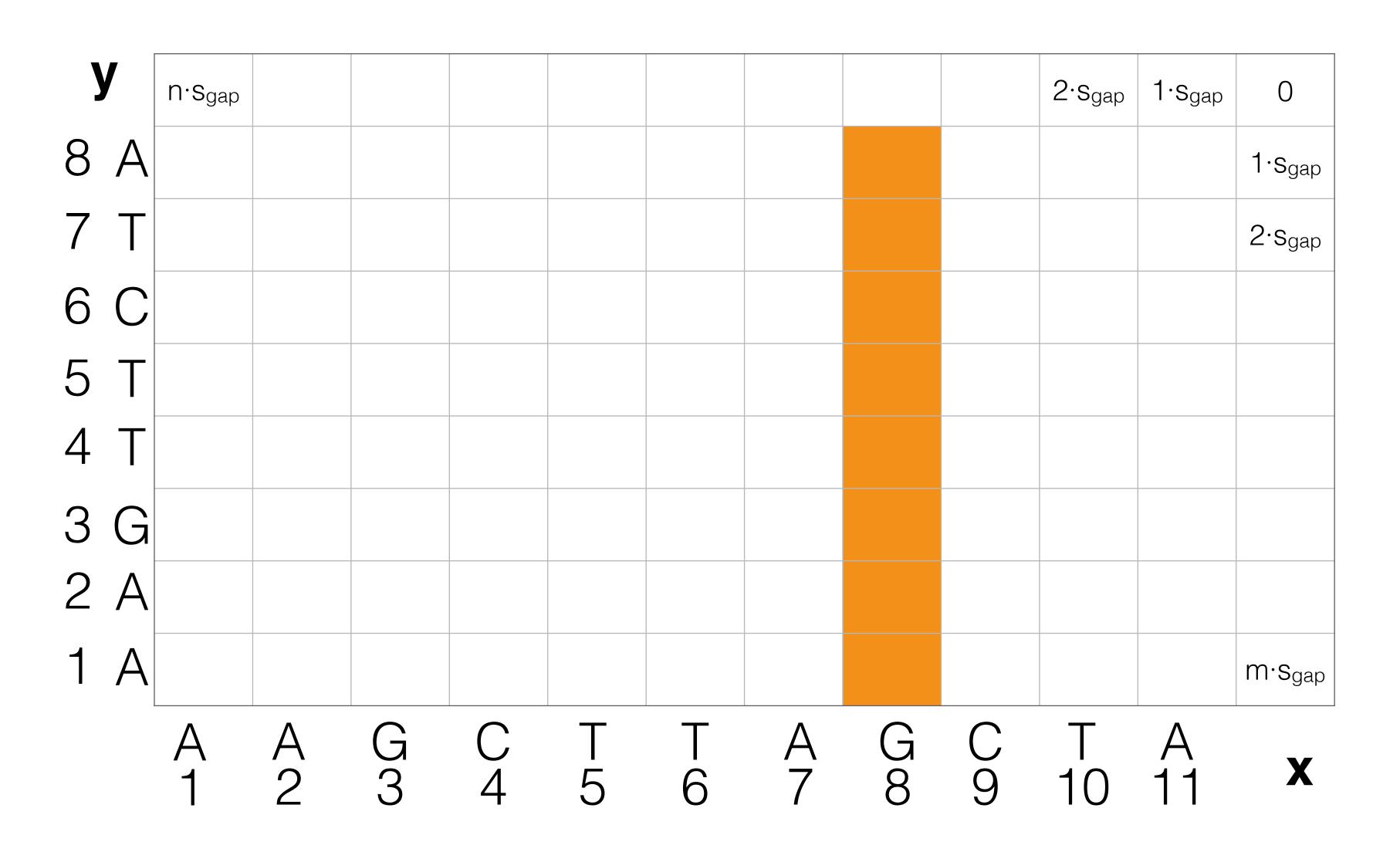
Consider filling in the DP matrix from the *opposite* direction (top right to bottom left)



Optimal alignment between x[8:] and y[6:]



This lets us compute optimal score between a *suffix* of **x** with *all suffixes* of **y**



Prefixes (forward):

$$OPT[i, j] = \max \begin{cases} score(x_i, y_j) + OPT'[i - 1, j - 1] \\ gap + OPT[i, j - 1] \\ gap + OPT[i - 1, j] \end{cases}$$

Suffixes (backward):

OPT'
$$[i, j] = \max \begin{cases} \text{score}(x_{i+1}, y_{j+1}) + \text{OPT'}[i+1, j+1] \\ \text{gap} + \text{OPT'}[i, j+1] \\ \text{gap} + \text{OPT'}[i+1, j] \end{cases}$$

This lets us build up optimal alignments for increasing length suffixes of ${\bf x}$ and ${\bf y}$

Prefixes (forward):

$$\begin{aligned} &\operatorname{OPT}\left[i,j\right] = \max \begin{cases} \operatorname{score}\left(x_{i},y_{j}\right) + \operatorname{OPT'}\left[i-1,j-1\right] \\ &\operatorname{gap} + \operatorname{OPT}\left[i,j-1\right] \\ &\operatorname{gap} + \operatorname{OPT}\left[i-1,j\right] \end{cases} \\ &\operatorname{Suffixes}\left(\operatorname{backward}\right): \\ &\operatorname{OPT'}\left[i,j\right] = \max \begin{cases} \operatorname{score}\left(x_{i+1},y_{j+1}\right) + \operatorname{OPT'}\left[i+1,j+1\right] \\ &\operatorname{gap} + \operatorname{OPT'}\left[i,j+1\right] \\ &\operatorname{gap} + \operatorname{OPT'}\left[i+1,j\right] \end{cases} \end{aligned}$$

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note: thé slight change in indexing here. It will make writing our solution easier.

How does this help us compute the optimal alignment in linear space?

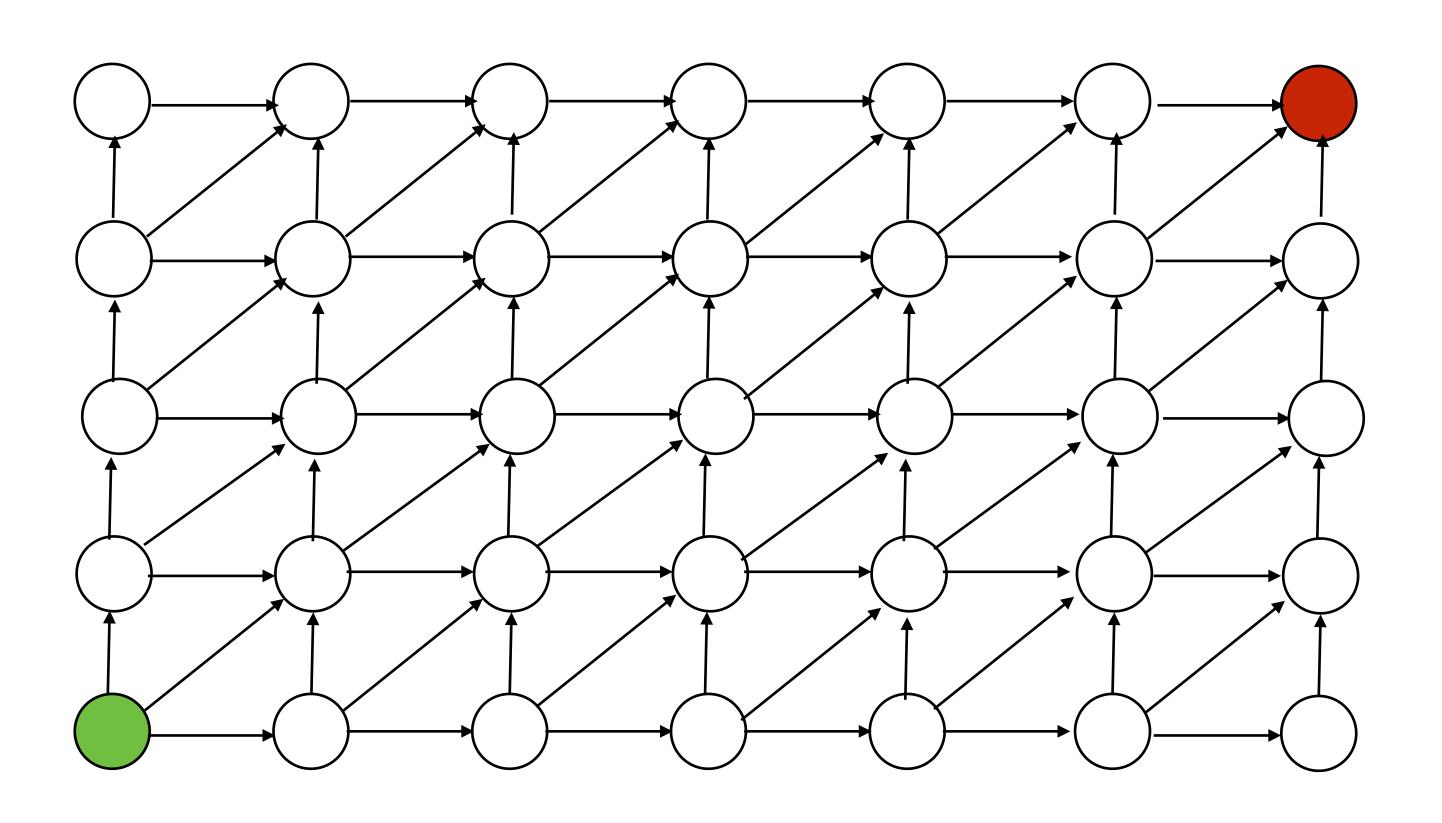
Algorithmic idea: Combine both dynamic programs using divide-and-conquer

Divide-and-conquer splits a problem into smaller subproblems and combines the results (much like DP).

Examples: MergeSort & Karatsuba multiplication

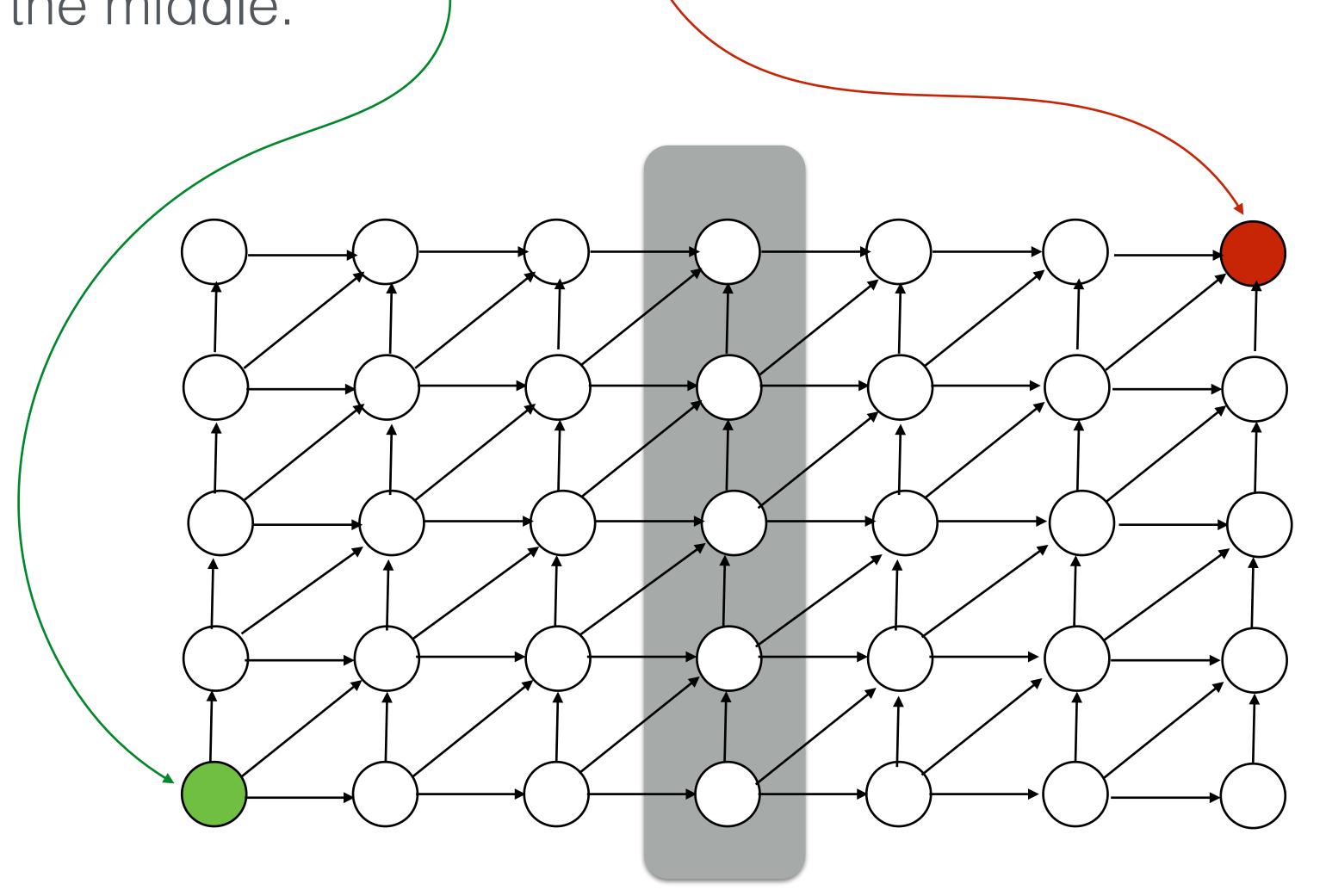
Think about this in "graph" land

What do we know about the structure of the optimal path in our "edit-DAG"?

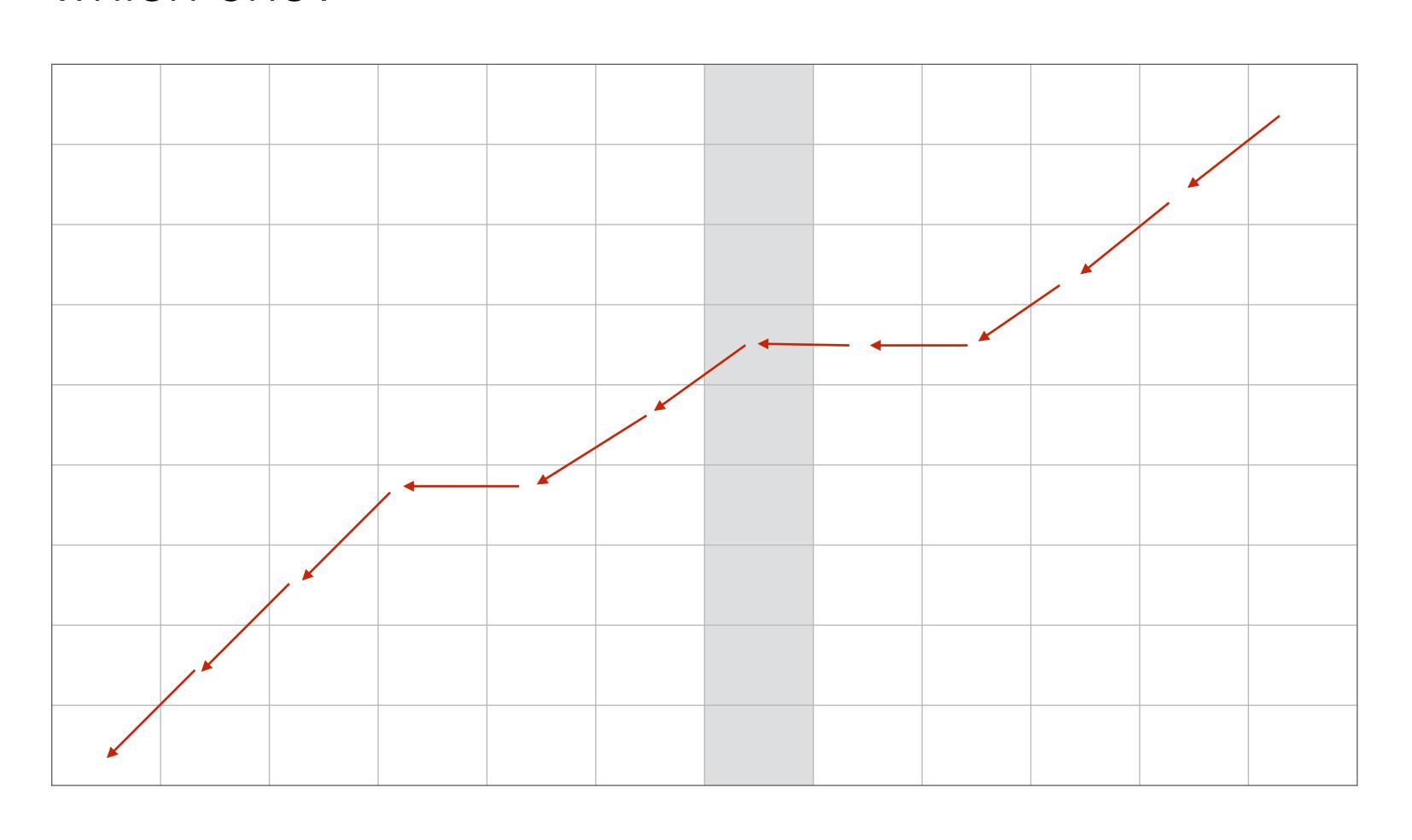


Think about this in "graph" land

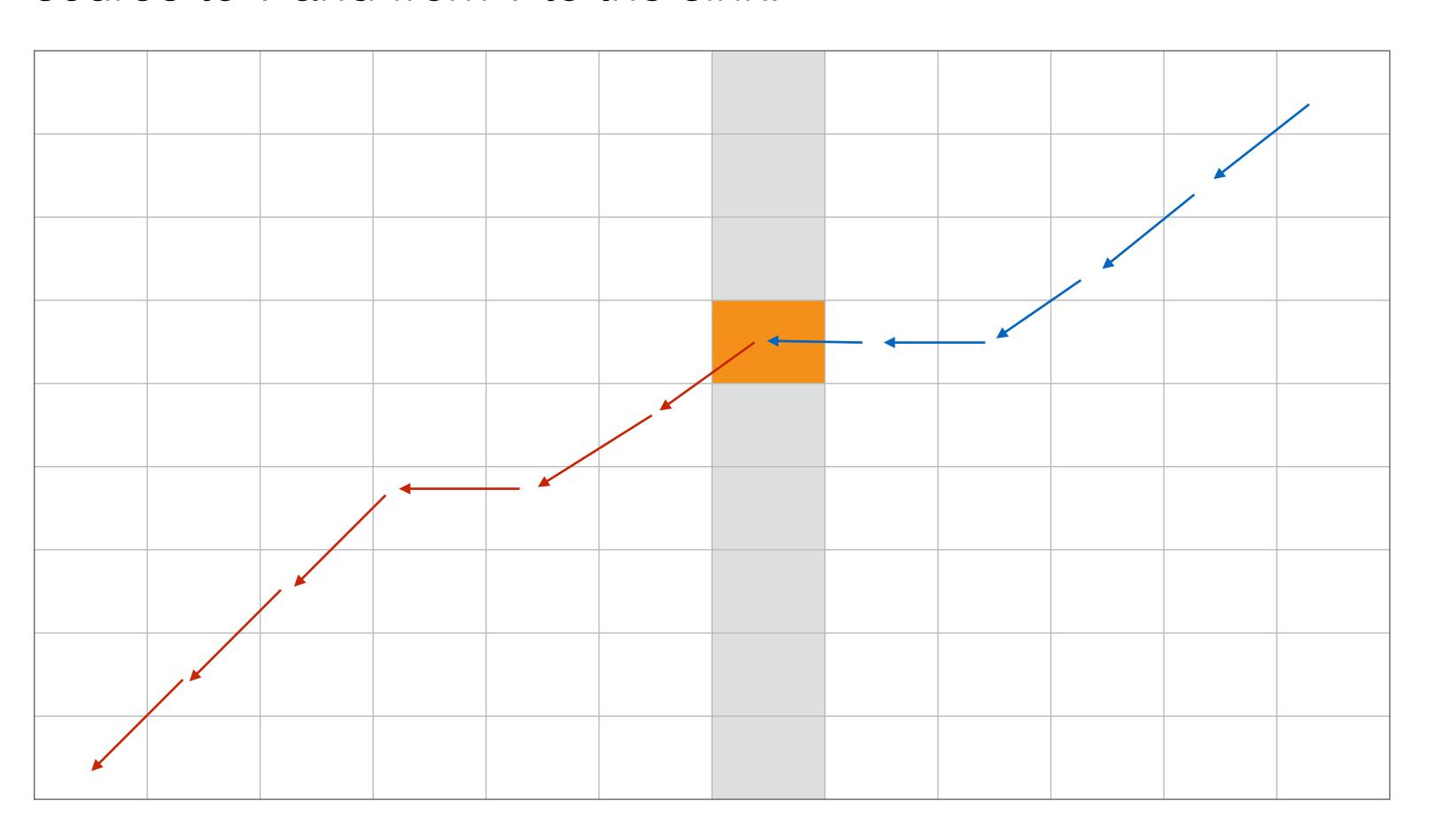
Can't get from here to there without passing through the middle.



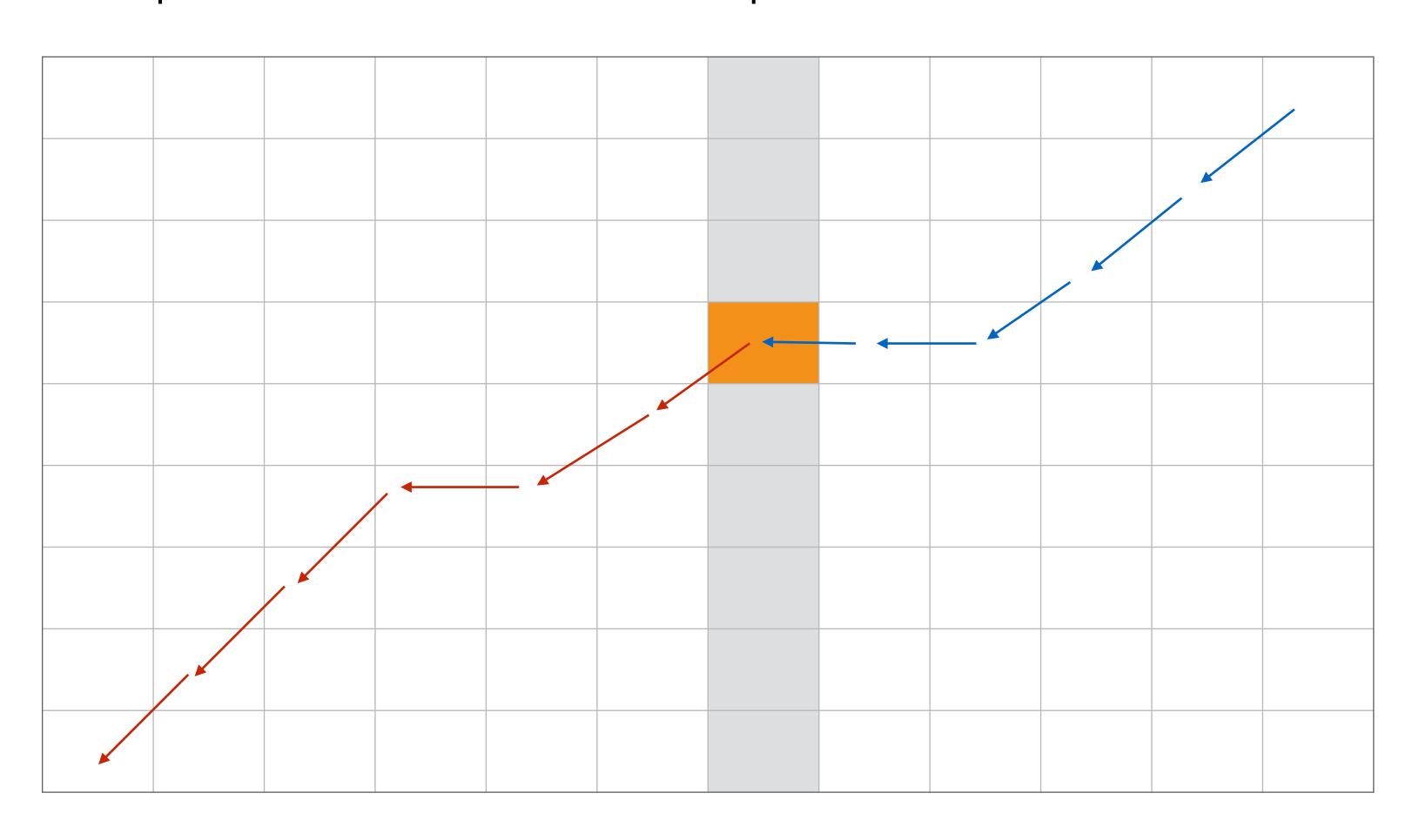
Consider the middle column — we *know* that the optimal aln. must use some cell in this column; which one?



It uses the cell (i,j) such that OPT[i,j] + OPT'[i,j] has the **highest score**. Equivalently, the *best path* uses some vertex *v* in the middle col. and glues together the best paths from the source *to* v and *from* v to the sink.

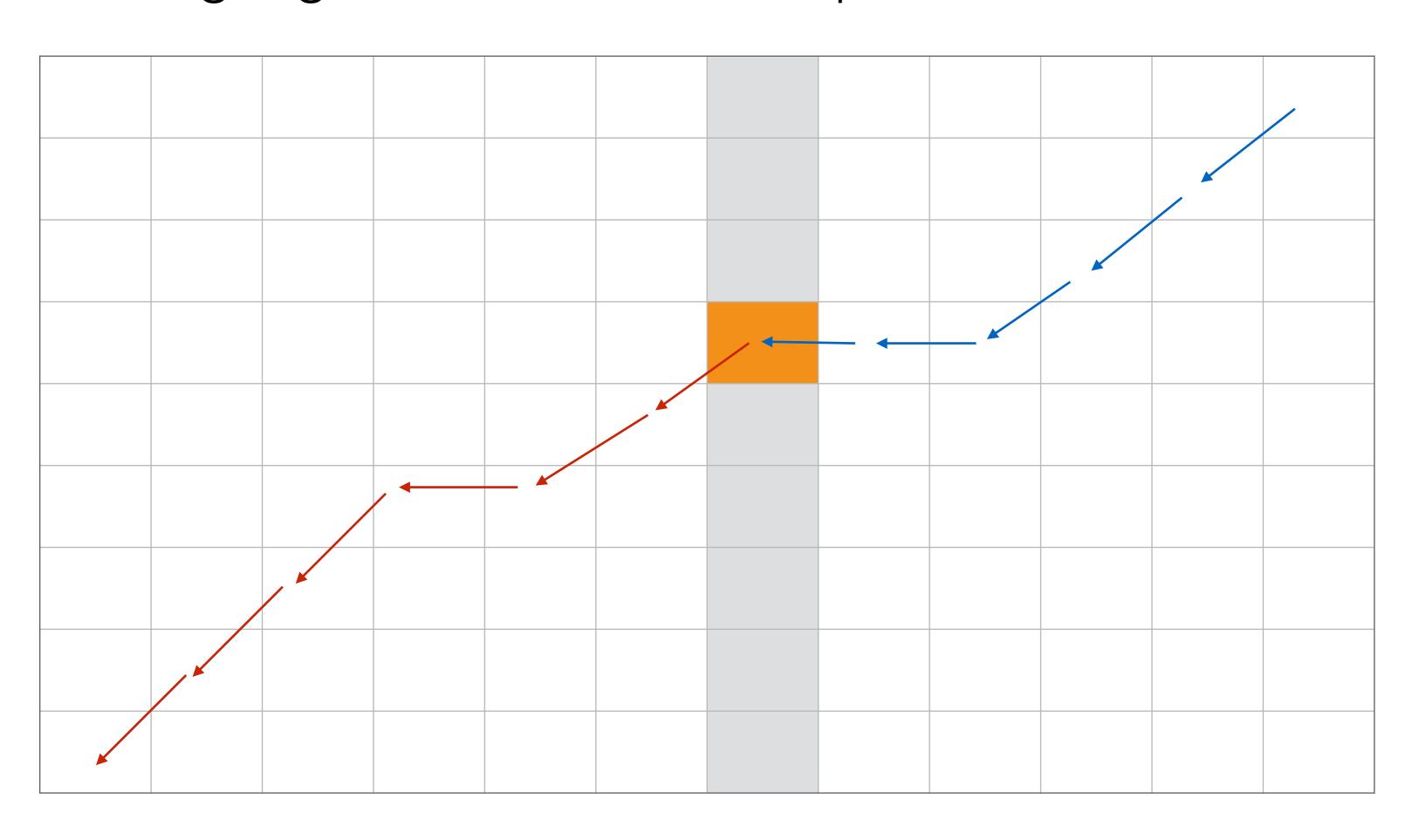


Claim: OPT[i,j] and OPT'[i,j] can be computed in linear space using the trick from above for finding an optimal **score** in linear space



Algorithmic Idea

Devise a D&C algorithm that finds the optimal alignment path recursively, using the space-efficient scoring algorithm for each subproblem.



D&C Alignment

```
DCAlignment(x, y):
    n = |x|
    m = |y|
    if m <= 2 or n <= 2:
        use "normal" DP to compute OPT(x, y)
    compute space-efficient OPT(x[1:n/2], y)
    compute space-efficient OPT'(x[n/2+1:n], y)
    let q be the index maximizing OPT[n/2,q] + OPT'[n/2,q]
    add back pointer of (n/2,q) to the optimal alignment P
    DCAlignment(x[1:n/2], y[1:q])
    DCAlignment(x[n/2+1:n], y[q+1:m])
    return P</pre>
```

D&C Alignment

How can we show that this entire process still takes quadratic time?

Let T(n,m) be the running time on strings **x** and **y** of length n and m, respectively. We have:

$$T(n,m) \leq cnm + T(n/2, q) + T(n/2, m-q)$$

$$DCAlignment(x[1:n/2], y[1:q]) \quad DCAlignment(x[n/2+1:n], y[q+1:m])$$

$$with base cases:$$

$$T(n,2) \le cn$$

 $T(2,m) \le cm$

D&C Alignment

Base:

$$T(n,2) \leq cn$$

$$T(2,m) \leq cm$$

Inductive:

$$T(n,m) \le cnm + T(n/2, q) + T(n/2, m-q)$$

Problem: we don't know what q is. First, assume both \mathbf{x} and \mathbf{y} have length n and q=n/2 (will remove this restriction later)

$$T(n) \le 2T(n/2) + cn^2$$

This recursion solves as $T(n) = O(n^2)$

Leads us to guess T(n,m) grows like O(nm)

Smarter Induction

```
Base:
T(n,2) \leq cn
T(2,m) \leq cm
Inductive:
T(n,m) \leq knm
Proof:
T(n,m) \le cnm + T(n/2, q) + T(n/2, m-q)
       \leq cnm + kqn/2 + k(m-q)n/2
       \leq cnm + kqn/2 + kmn/2 - kqn/2
      = [c+(k/2)] mn
Thus, our proof holds if k=2c, and T(n,m) = O(nm) QED
```

Conclusion

Trivially, we can compute the *cost* of an optimal alignment in linear space

By arranging subproblems intelligently we can define a "reverse" DP that works on suffixes instead of prefixes

Combining the "forward" and "reverse" DP using a divide and conquer technique, we can compute the optimal *solution* (not just the score) in linear space.

This still only takes O(nm) time; constant factor more work than the "forward"-only algorithm.