

view_frames Result

Recorded at time: 366.560

map

Broadcaster: /slam_gmapping
Average rate: 20.303 Hz
Most recent transform: 366.580 (-0.020 sec old)
Buffer length: 3.300 sec

odom

Broadcaster: /gazebo
Average rate: 10.303 Hz
Most recent transform: 366.510 (0.050 sec old)
Buffer length: 3.300 sec

chassis

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (366.560 sec old)
Buffer length: 0.000 sec

camera

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (366.560 sec old)
Buffer length: 0.000 sec

hokuyo

Broadcaster: /robot_state_publisher
Average rate: 10.303 Hz
Most recent transform: 366.530 (0.030 sec old)
Buffer length: 3.300 sec

left_wheel

Broadcaster: /robot_state_publisher
Average rate: 10.303 Hz
Most recent transform: 366.530 (0.030 sec old)
Buffer length: 3.300 sec

right_wheel