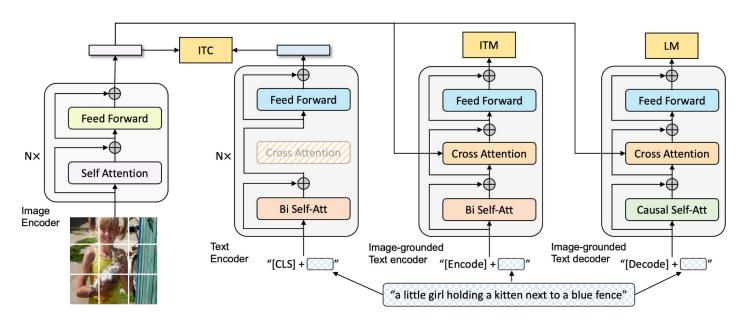
BLIP: **Bootstrapping** Language-Image Pre-training for Unified Vision-Language **Understanding and Generation**



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Motivation and Previous Work

 Model perspective: existing vision-language pretrained models lack flexibility when transferred to downstream tasks

Encoder based models: Less straightforward to directly transfer to text generation tasks (CLIP, ALBEF)

Encoder-Decoder models: Have not been successfully adopted for image-text retrieval tasks (SimVLM)

Data perspective: most models pre-train on image and alt-text pairs that are automatically

collected from the web

The web texts often do not accurately describe the visual content of the images, making them a noisy source of supervision



Caption: from bridge near my house Wrong image-text pair from the web

BLIP's solutions:

- a new model architecture that enables a wider range of downstream tasks than existing methods
- a new dataset bootstrapping method for learning from noisy web data.
 - https://arxiv.org/pdf/2103.00020.pdf
 - https://arxiv.org/pdf/2107.07651.pdf
 - https://arxiv.org/pdf/2108.10904.pdf

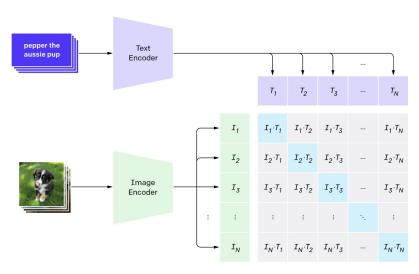
Vision Language Models background - Limitation 1

Most existing work on vision-language representation learning fall into two categories.

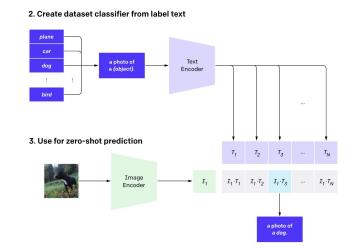
- The first category focuses on learning separate unimodal encoders for image and text.
- 2. The second category focuses on modelling the interactions between image and text features with transformer-based multimodal encoders.

Unimodal Encoders

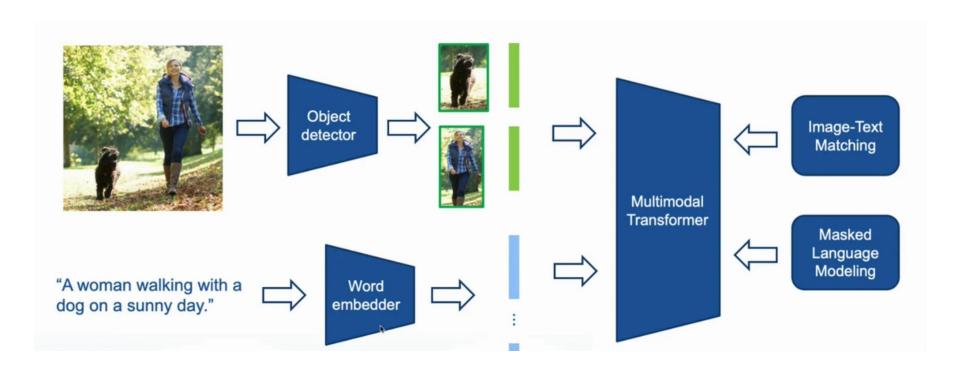
1. Contrastive pre-training



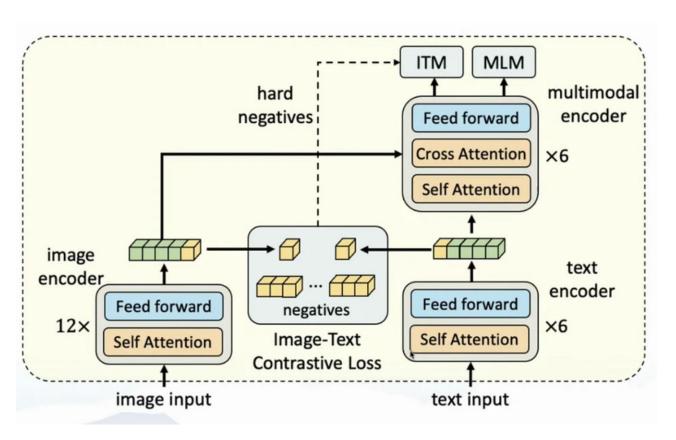
- Perform pre-training on massive noisy web data using a contrastive loss
- Remarkable performance on image-text retrieval tasks, but lack the ability to model more complex interactions between image and text for other V+L tasks.



Multimodal encoders



Multimodal encoders



- Image encoder: ViT
- Text encoder: Bert
- Multimodal encoder for fusion, using cross attention layer.
- ITCL for better alignment

Method overview

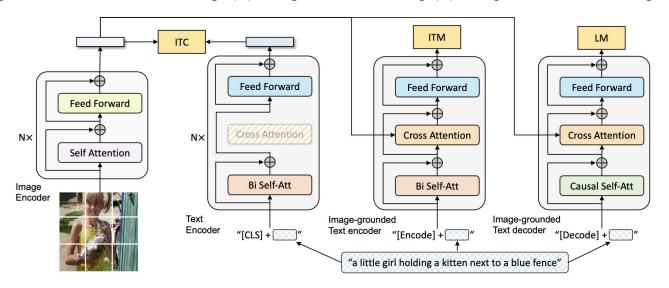
Unified model for vision-language understanding and generation called Multimodal mixture of Encoder-Decoder (MED):

3 architectural modes:

(1) Unimodal encoders (2) Image-grounded text encoder (3) Image-grounded text decoder

3 objectives:

(1) Image-text contrastive learning (2) Image-text matching (3) Image-conditioned language modeling



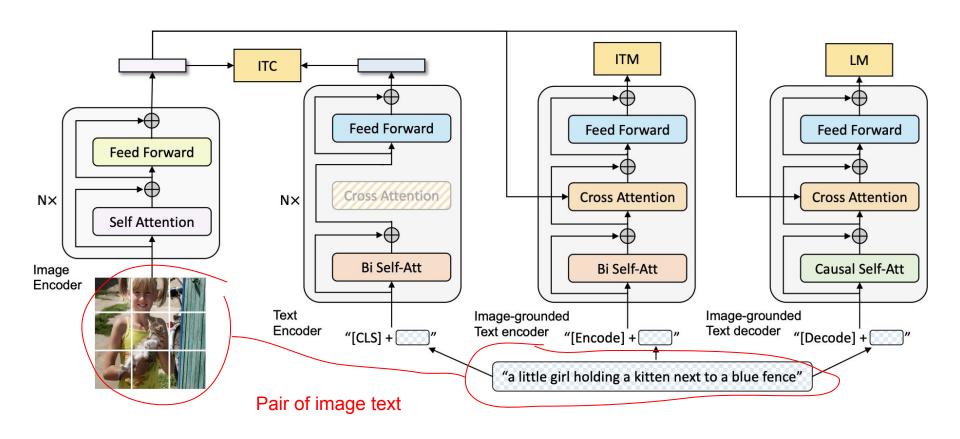
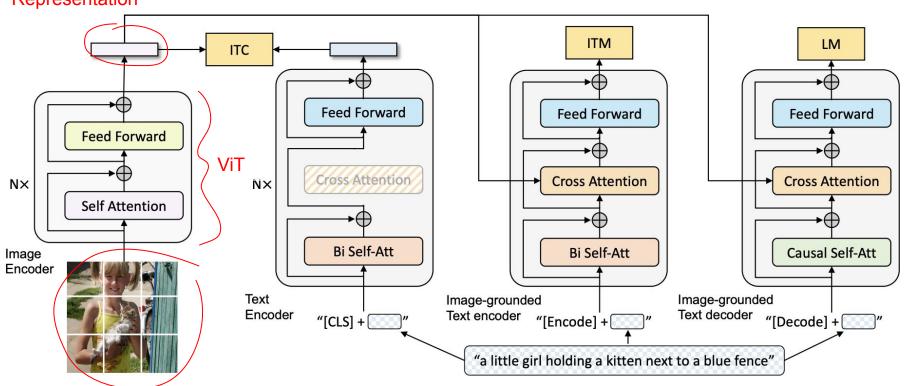
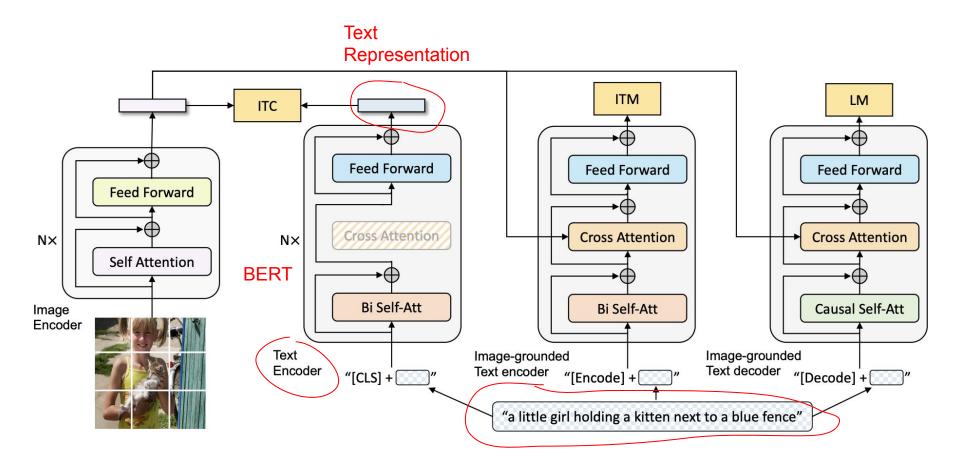
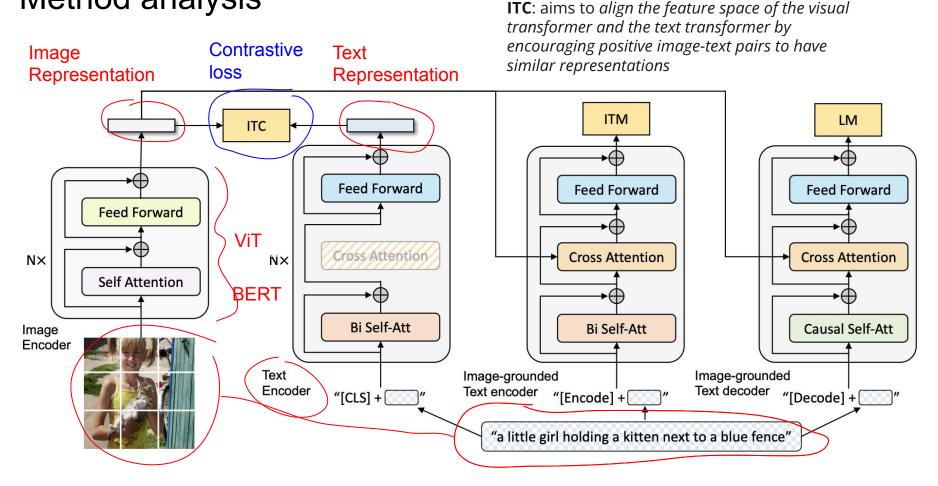


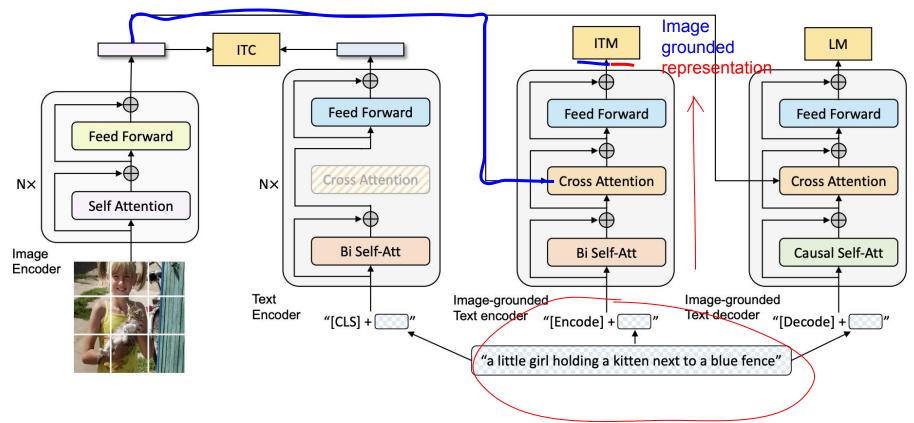
Image Representation



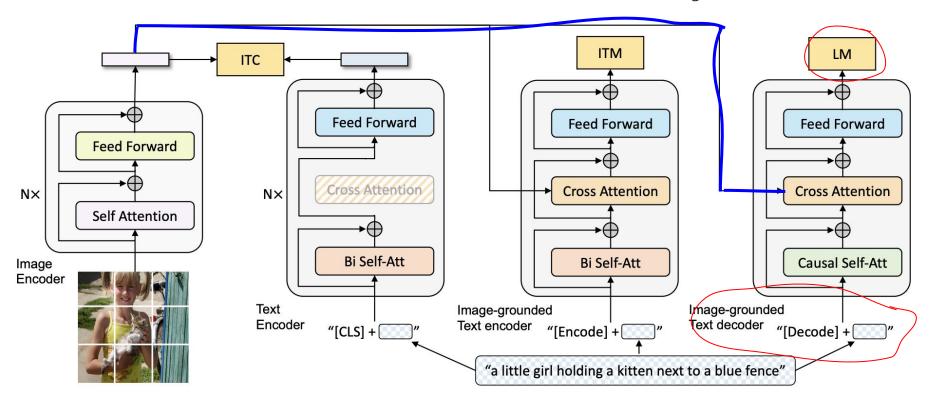




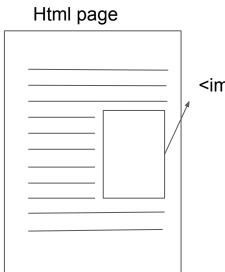
ITM is a binary classification task, where the model is asked to predict whether an image-text pair is positive (matched) or negative (unmatched)



LM: aims to generate textual descriptions conditioned on the images.



Limitation 2: Noisy web data



Not aligned image - text pairs



T_w: "from bridge near my house"

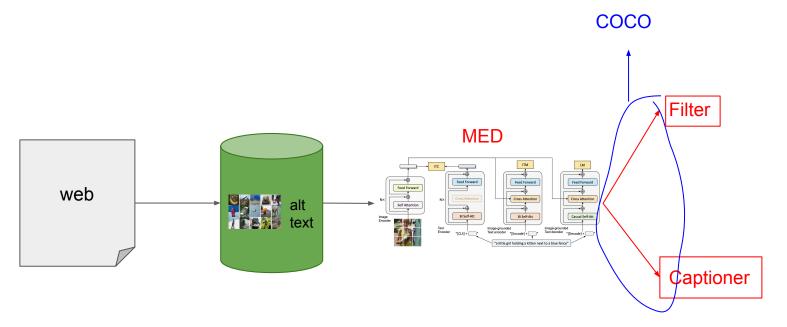


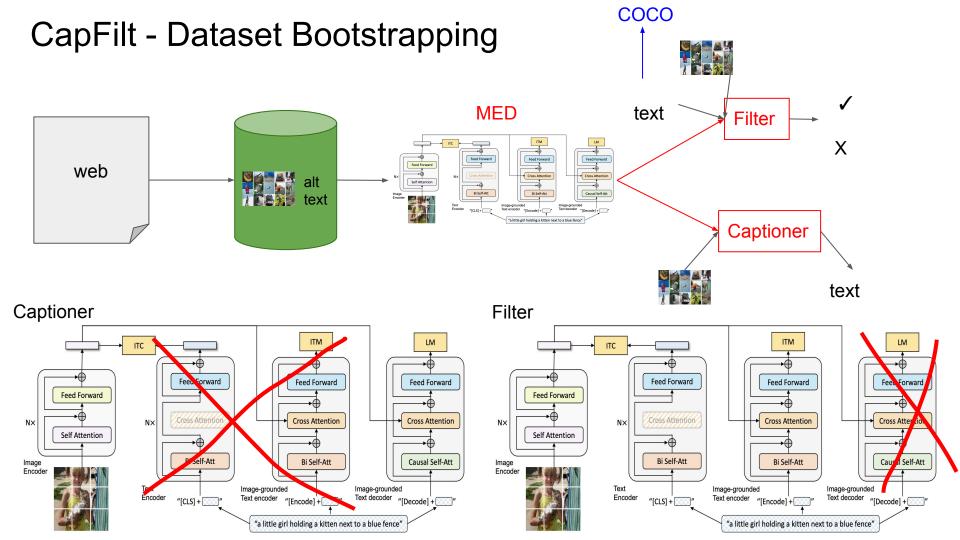


T_w: "in front of a house door in Reichenfels,
Austria"

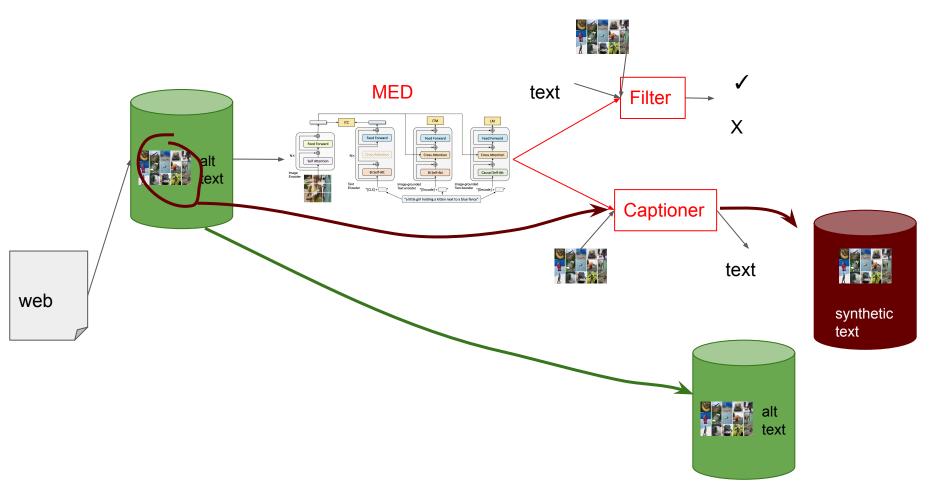
 T_s : "a potted plant sitting on top of a pile of rocks"

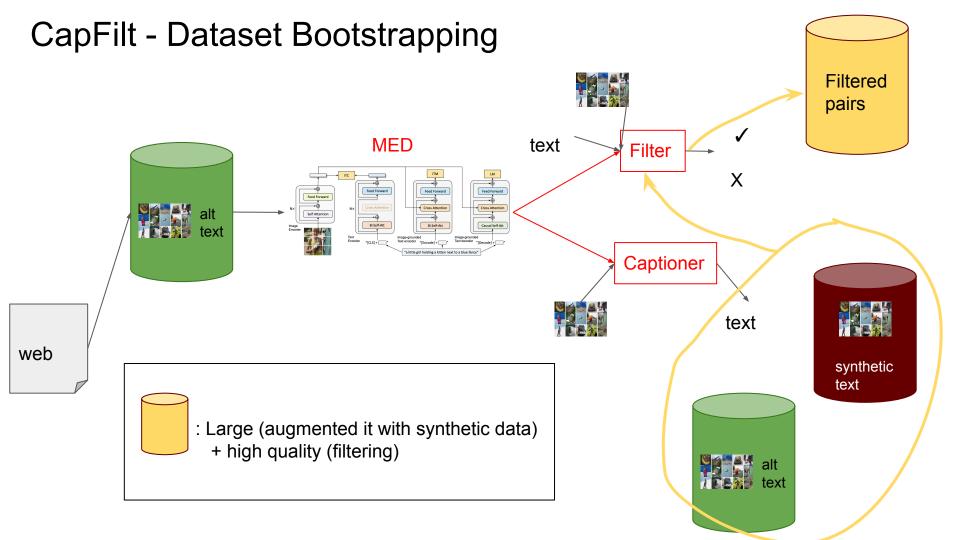
CapFilt - Dataset Bootstrapping





CapFilt - Dataset Bootstrapping





Experimental Setup

Model Architectures

Image encoder: Two variants of ViTs: ViT-B/16 and ViT-L/16

Text encoder: Bert

Models Initialization

- ViT pretrained on ImageNet
- Text transformer initialized from BERTbase

Pretraining

- Same pre-training dataset as Li et al. with 14M images in total
 - Two human-annotated datasets (COCO and Visual Genome)
 - Three web datasets (Conceptual Captions, Conceptual 12M, SBU captions).
- Additional web dataset, LAION (more noisy texts)

	COCO	VG	SBU	CC3M	CC12M	LAION
# image	113K	100K	860K	3M	10M	115M
# text	113K 567K	769K	860K	3M	10M	115M

Experiments

Effect of CapFilt

- Captioner and Filter can lead to performance improvement individually
- They lead to significant improvements collaboratively
- CapFilt works for different size of models and datasets
- Increase in data amount and model size as helpful as CapFilt

Pre-train	Boo	tstrap	Vision	Retrieval-	FT (COCO)	Retrieval-	ZS (Flickr)	Caption-l	FT (COCO)	Caption-Z	ZS (NoCaps)
dataset	C	F	backbone	TR@1	IR@1	TR@1	IR@1	B@4	CIDEr	CIDEr	SPICE
COCO+VG +CC+SBU (14M imgs)	X	X		78.4	60.7	93.9	82.1	38.0	127.8	102.2	13.9
	X	√B	ViT-B/16	79.1	61.5	94.1	82.8	38.1	128.2	102.7	14.0
	✓B	X	V11-B/16	79.7	62.0	94.4	83.6	38.4	128.9	103.4	14.2
	\checkmark_B	\checkmark_B		80.6	63.1	94.8	84.9	38.6	129.7	105.1	14.4
COCO+VG	X	X		79.6	62.0	94.3	83.6	38.8	130.1	105.4	14.2
	VB	✓B	ViT-B/16	81.9	64.3	96.0	85.0	39.4	131.4	106.3	14.3
+CC+SBU +LAION	\checkmark_L	\checkmark_L		81.2	64.1	96.0	85.5	39.7	133.3	109.6	14.7
(129M imgs)	X	X	ViT-L/16	80.6	64.1	95.1	85.5	40.3	135.5	112.5	14.7
	\checkmark_L	\checkmark_L	V11-L/16	82.4	65.1	96.7	86.7	40.4	136.7	113.2	14.8

[.] Evaluation of the effect of the captioner (C) and filter (F) for dataset bootstrapping.

Parameter sharing

I arrana ahanad	#========	Retrieval-FT (COCO)		Retrieval-	-ZS (Flickr)	Caption-	FT (COCO)	Caption-ZS (NoCaps)	
Layers shared	#parameters	TR@1	IR@1	TR@1	IR@1	B@4	CIDEr	CIDEr	SPICE
All	224M	77.3	59.5	93.1	81.0	37.2	125.9	100.9	13.1
All except CA	252M	77.5	59.9	93.1	81.3	37.4	126.1	101.2	13.1
All except SA	252M	78.4	60.7	93.9	82.1	38.0	127.8	102.2	13.9
None	361M	78.3	60.5	93.6	81.9	37.8	127.4	101.8	13.9

- During pre-training, the text encoder and decoder share all parameters except for the self-attention layers.
- The differences between the encoding and decoding tasks are best captured by the SA layers.
- On the other hand, the embedding layers, CA layers and FFN function similarly between encoding and decoding tasks, so they are being shared.

Experiments (Overview)

- Vision-Language (Understanding and Generation) Tasks and Datasets
 - Image-Text Retrieval: COCO and Flickr30K
 - Image Captioning: NoCaps and COCO
 - Increase performance by adding prompt at the beginning "A picture of"
 - Visual Question Answering (VQA)
 - VQA and NLVR
 - Generation instead of classification task
 - Outperform SOTAs with less parameters and data
 - Natural Language VIsual Reasoning
 - Visual Dialog: VisDial
 - Text-to-Video Retrieval and Video Question Answering: MSRVTT

Experiments (Image-Text retrieval)

Method	Pre-train		(COCO (5	COCO (5K test set)						Flickr30K (1K test set)				
Method	# Images	TR			IR			TR			IR				
	5	R@1	R@5	R@10	R@1	R@5	R@10	R@1	R@5	R@10	R@1	R@5	R@10		
UNITER (Chen et al., 2020)	4M	65.7	88.6	93.8	52.9	79.9	88.0	87.3	98.0	99.2	75.6	94.1	96.8		
VILLA (Gan et al., 2020)	4M	-	-	-	-	-	-	87.9	97.5	98.8	76.3	94.2	96.8		
OSCAR (Li et al., 2020)	4M	70.0	91.1	95.5	54.0	80.8	88.5	-	-	-	,=.:	-	-		
UNIMO (Li et al., 2021b)	5.7M	-	-	-	-	-	-	89.4	98.9	99.8	78.0	94.2	97.1		
ALIGN (Jia et al., 2021)	1.8B	77.0	93.5	96.9	59.9	83.3	89.8	95.3	99.8	100.0	84.9	97.4	98.6		
ALBEF (Li et al., 2021a)	14M	77.6	94.3	97.2	60.7	84.3	90.5	95.9	99.8	100.0	85.6	97.5	98.9		
BLIP	14M	80.6	95.2	97.6	63.1	85.3	91.1	96.6	99.8	100.0	87.2	97.5	98.8		
BLIP	129M	81.9	95.4	97.8	64.3	85.7	91.5	97.3	99.9	100.0	87.3	97.6	98.9		
BLIP _{CapFilt-L}	129M	81.2	95.7	97.9	64.1	85.8	91.6	97.2	99.9	100.0	87.5	97.7	98.9		
BLIP _{ViT-L}	129M	82.4	95.4	97.9	65.1	86.3	91.8	97.4	99.8	99.9	87.6	97.7	99.0		

BLIP achieves substantial performance improvement compared with existing methods. Using the same 14M pre-training images, BLIP outperforms the previous best model ALBEF by +2.7% in average recall@1 on COCO

Experiments (Zero-Shot Image-Text retrieval)

Method	Pre-train	Flickr30K (1K test set)								
Method	# Images		TR		IR					
		R@1	R@5	R@10	R@1	R@5	R@10			
CLIP	400M	88.0	98.7	99.4	68.7	90.6	95.2			
ALIGN	1.8B	88.6	98.7	99.7	75.7	93.8	96.8			
ALBEF	14M	94.1	99.5	99.7	82.8	96.3	98.1			
BLIP	14M	94.8	99.7	100.0	84.9	96.7	98.3			
BLIP	129M	96.0	99.9	100.0	85.0	96.8	98.6			
BLIP _{CapFilt-L}	129M	96.0	99.9	100.0	85.5	96.8	98.7			
BLIP _{ViT-L}	129M	96.7	100.0	100.0	86.7	97.3	98.7			

- Directly transferring the model finetuned on COCO to Flickr30K
- BLIP also outperforms existing methods by a large margin

Experiments (Image-Captioning)

Method	Pre-train	in-do:	main	NoCaps v near-domain		validation out-domain		overall		COCO Caption Karpathy test	
	#Images	C	S	C	S	C	S	C	S	B@4	C
Enc-Dec (Changpinyo et al., 2021)	15M	92.6	12.5	88.3	12.1	94.5	11.9	90.2	12.1	-	110.9
VinVL† (Zhang et al., 2021)	5.7M	103.1	14.2	96.1	13.8	88.3	12.1	95.5	13.5	38.2	129.3
LEMON _{base} † (Hu et al., 2021)	12M	104.5	14.6	100.7	14.0	96.7	12.4	100.4	13.8	=	-
LEMON _{base} † (Hu et al., 2021)	200M	107.7	14.7	106.2	14.3	107.9	13.1	106.8	14.1	40.3	133.3
BLIP	14M	111.3	15.1	104.5	14.4	102.4	13.7	105.1	14.4	38.6	129.7
BLIP	129M	109.1	14.8	105.8	14.4	105.7	13.7	106.3	14.3	39.4	131.4
BLIP _{CapFilt-L}	129M	111.8	14.9	108.6	14.8	111.5	14.2	109.6	14.7	39.7	133.3
LEMON _{large} † (Hu et al., 2021)	200M	116.9	15.8	113.3	15.1	111.3	14.0	113.4	15.0	40.6	135.7
SimVLM _{huge} (Wang et al., 2021)	1.8B	113.7	_	110.9	_	115.2	-	112.2	-	40.6	143.3
$BLIP_{ViT-L}$	129M	114.9	15.2	112.1	14.9	115.3	14.4	113.2	14.8	40.4	136.7

Comparison with state-of-the-art image captioning methods on NoCaps and COCO Caption. All methods optimize the crossentropy loss during finetuning. C: CIDEr, S: SPICE, B@4: BLEU@4. BLIPCapFilt-L is pre-trained on a dataset bootstrapped by captioner and filter with ViT-L. VinVL† and LEMON† require an object detector pre-trained on 2.5M images with human-annotated bounding boxes and high resolution (800×1333) input images. SimVLMhuge uses 13× more training data and a larger vision backbone than ViT-L.

Interesting Findings

Continue	Retrieval-	FT (COCO)	Retrieval-	ZS (Flickr)	Caption-F	T (COCO)	Caption-ZS (NoCaps)		
	TR@1	IR@1	TR@1	IR@1	B@4	CIDEr	CIDEr	SPICE	
Yes	80.6	63.0	94.5	84.6	38.5	129.9	104.5	14.2	
No	80.6	63.1	94.8	84.9	38.6	129.7	105.1	14.4	

- Continue training the original model does not help.
- This observation agrees with the common practice in knowledge distillation, where the student model cannot be initialized from the teacher.

Interesting Findings

CapFilt #Texts	Retrieval-	FT (COCO)	Retrieval-	ZS (Flickr)	Caption-F	T (COCO)	Caption-ZS (NoCaps)		
	TR@1	IR@1	TR@1	IR@1	B@4	CIDEr	CIDEr	SPICE	
No	15.3M	78.4	60.7	93.9	82.1	38.0	127.8	102.2	13.9
No	24.7M	78.3	60.5	93.7	82.2	37.9	127.7	102.1	14.0
Yes	24.7M	80.6	63.1	94.8	84.9	38.6	129.7	105.1	14.4

- The original web texts are replicated to have the same number of samples per epoch as the bootstrapped dataset.
- Results verify that the improvement from CapFilt is not due to longer training time.

Which layers of the text encoder and decoder in MED share parameters? Is there a way to use Bi-self attention for the decoder as well, instead of causal attention?

Which layers of the text encoder and decoder in MED share parameters? Is there a way to use Bi-self attention for the decoder as well, instead of causal attention?

- They share all parameters except for the SA layers. The differences between the encoding and decoding tasks are best captured by the SA layers.
 On the other hand, the embedding layers, CA layers and FFN function similarly between encoding and decoding tasks, so they are being shared.
- We mask the tokens coming after the current token and we only attend to the previous ones, then it is possible to use a bi self-attention for the decoder as well.

The bootstrapped dataset is used to train a new model rather than continue training the original model. What could explain this?

The bootstrapped dataset is used to train a new model rather than continue training the original model. What could explain this?

- The experiments revealed that continuing the training of the pre-existing model with the bootstrapped dataset did not yield any benefits.
- Avoiding Overfitting: If the student model were initialized with the teacher model's parameters, it might inherit any overfitting or biases present in the teacher model. Starting from scratch helps to mitigate this risk.