

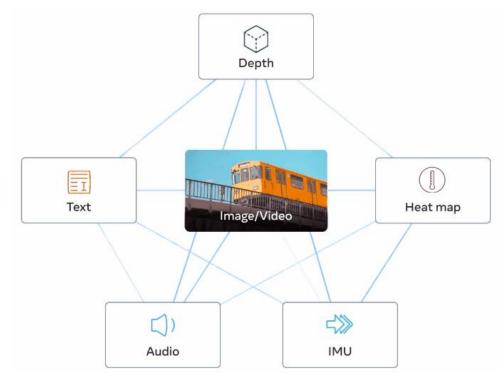
#### IMAGEBIND: One Embedding Space To Bind Them All

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#### Overview

- Background: towards generalizing to various multi-modality tasks
- Motivation: Binding all to the most informative modality
- Method: Emergent alignment only using image-based pairs
- Experiment
- Quiz





# Background

towards generalizing to various multi-modality tasks

#### Traditional multi-modal learning:

- Often image-text pairs only
- Feed with humorous data
- Large computation cost

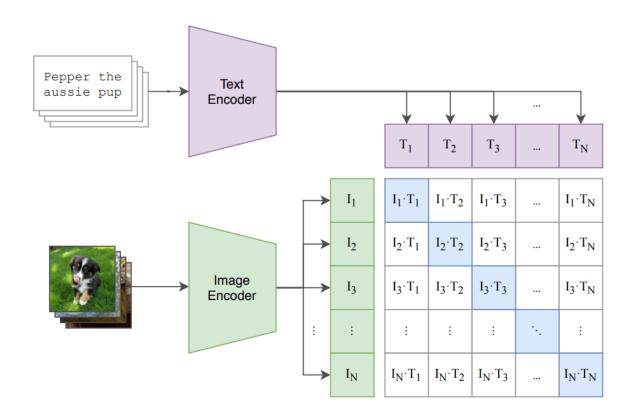


Illustration of the Clip: The boring graph that appears everywhere in our daily life.

Ensemble multiple modalities:

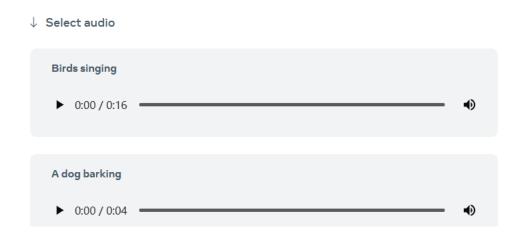
Can we learn an MM model performs well on various types of downstream tasks more than image-text?



#### Using audio to retrieve images

ImageBind can instantly suggest images by using an audio clip as an input. For example, from an audio recording of a bird, the model can generate images of what that bird might look like.

Select an audio clip below and ImageBind will retrieve image options corresponding with the audio prompt.

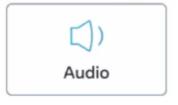


#### Challenges

If we align different modalities in traditional ways:

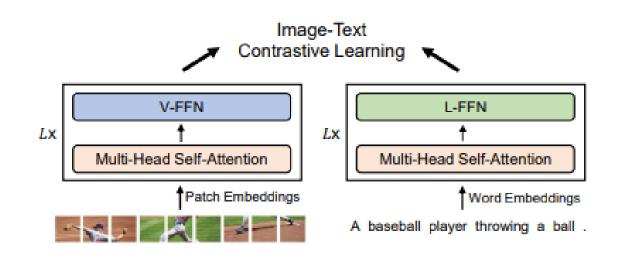
- 1. Given N modalities, we have  $O(N^2)$  multi-modal tasks and each task needs corresponding paired data
- 2. Some types of paired data is not sufficient

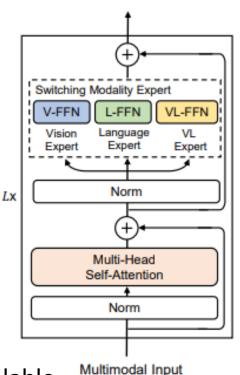




Does anyone like to record the temperature when there is a piece of music?

Solution: parameters shared across modalities





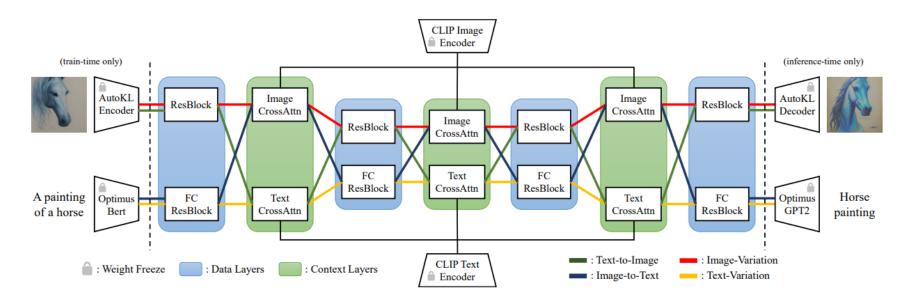
Problem: Only consider image and text and hard to be scalable

[1] Bao H, Wang W, Dong L, et al. Vlmo: Unified vision-language pre-training with mixture-of-modality-experts[J]. Advances in Neural Information Processing Systems, 2022, 35: 32897-32912.

MoME Transformer with Shared Parameters



Solution: parameters shared across tasks / multi-flow network



Problem: only for generation task, not for pretraining

[2] Xu X, Wang Z, Zhang G, et al. Versatile diffusion: Text, images, and variations all in one diffusion model[C]//Proceedings of the IEEE/CVF International Conference on Computer Vision. 2023: 7754-7765.



### Motivation

Bind to the most informative modality

#### Something still remains unsolved:

- Parameter sharing is a good way to fusion modalities but we still need  $O(N^2)$  contrastive losses.
- Multi-flow network might reduce the size of model but it requires  $O(N^2)$  data-flows and feed-forwards
- Current solutions still need paired data or context models pretrained with the pairs

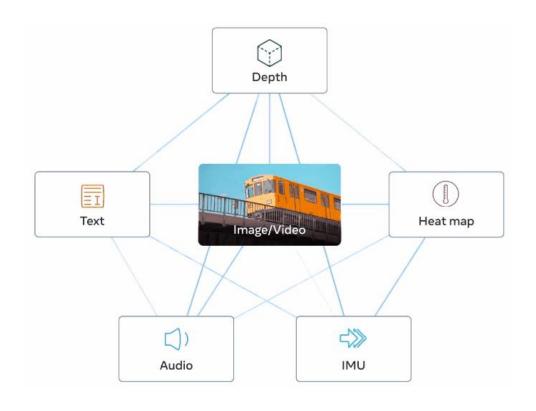
#### To unify different modalities, we might expect:

- Each modality is aligned with other modalities
- O(N) Contrastive losses
- Each modality could only appear in one combination of paired modalities

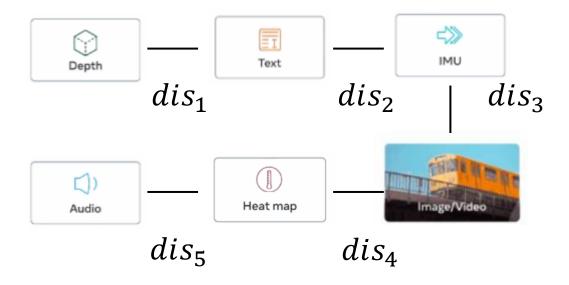
#### **Insight: connected graph**

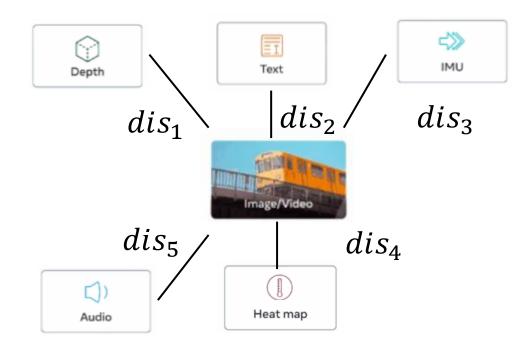
If two modalities are aligned with a loss term, we add an edge between them.

The min number of edges could be N-1.

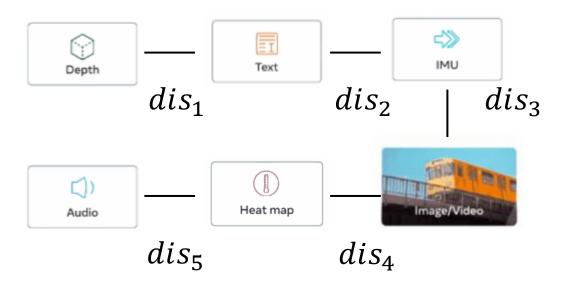


#### Which one would be better:

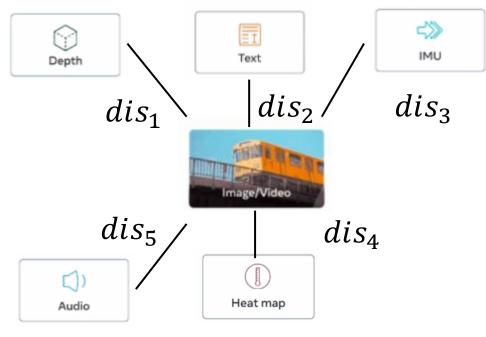




#### Maybe the right one has a tighter upper bound



$$dis(D., A.) \leq \sum dis_i$$

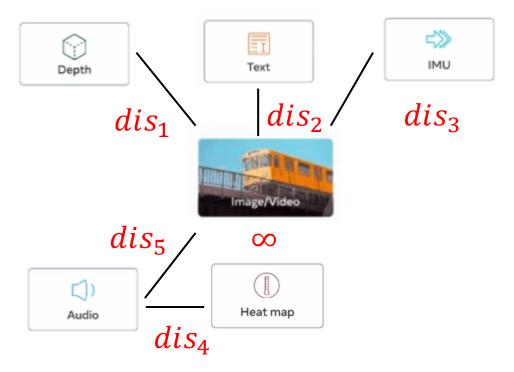


$$dis(D.,A.) \leq dis_1 + dis_5$$

#### Remaining question: how to choose the anchor

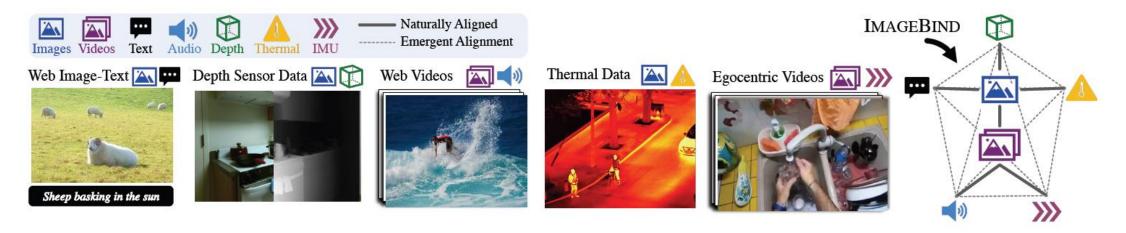
There should exist correlations between the anchor and other modalities:

- Paired data
- Connection of semantics of different modalities



We don't like the case that we have paired data and true relationships as shown above

In this paper, image is used as anchor

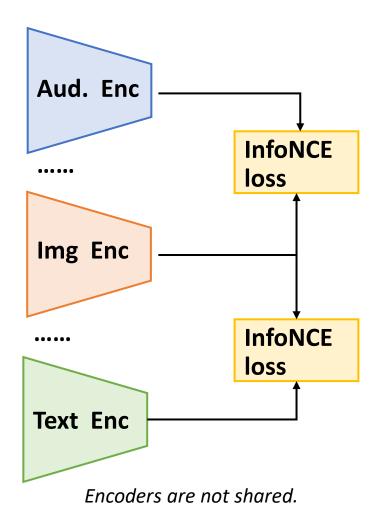


- Each considered modality is closely related to the image(video) modality
- Each modality has paired data with images



## Method

Emergent alignment only using image-based pairs



Given a (img, M) pair, we calculate the following InfoNCE:  $L_{I,M} + L_{M,I}$ 

$$L_{\mathcal{I},\mathcal{M}} = -\log \frac{\exp(\mathbf{q}_i^{\mathsf{T}} \mathbf{k}_i / \tau)}{\exp(\mathbf{q}_i^{\mathsf{T}} \mathbf{k}_i / \tau) + \sum_{j \neq i} \exp(\mathbf{q}_i^{\mathsf{T}} \mathbf{k}_j / \tau)}$$

We might be interested in the data:

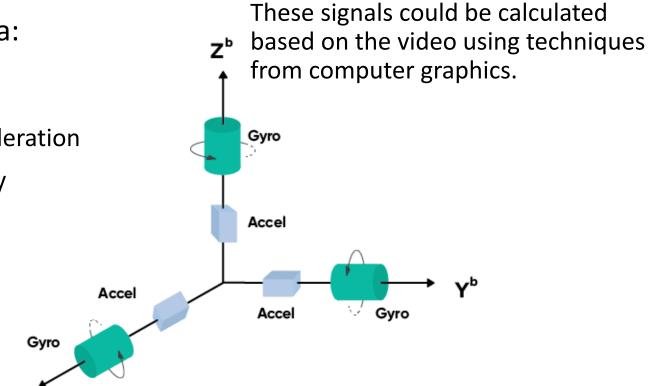
Inertial Measurement Unit (IMU)

Accelerometers: Measure linear acceleration

Gyroscopes: Measure angular velocity



They are 1-D signals, the paper uses 1-D conv and transformers to encode them.



https://www.advancednavigation.com/tech-articles/inertial-measurement-unit-imu-an-introduction/

We might be interested in the data:

Depth data

- Distance information
- Viewpoint

It is related to some 3-D tasks.

Color



image with similar object semantics to the raw image.

It can be viewed as a 1-channel







Improved depth

https://rgbd.cs.princeton.edu/

We might be interested in the data:

#### Thermal data

Temperature variations of objects or environments.

It can be viewed as a 1-channel image with similar object semantics to the raw image.



(a) dual-spectrum camera



(b) different field of views





(c) images after registration

https://bupt-ai-cz.github.io/LLVIP/

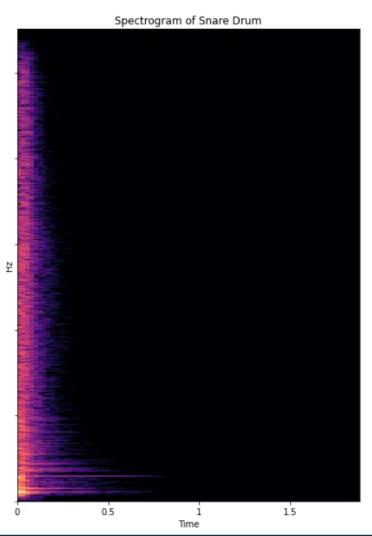
We might be interested in the data:

#### Audio data

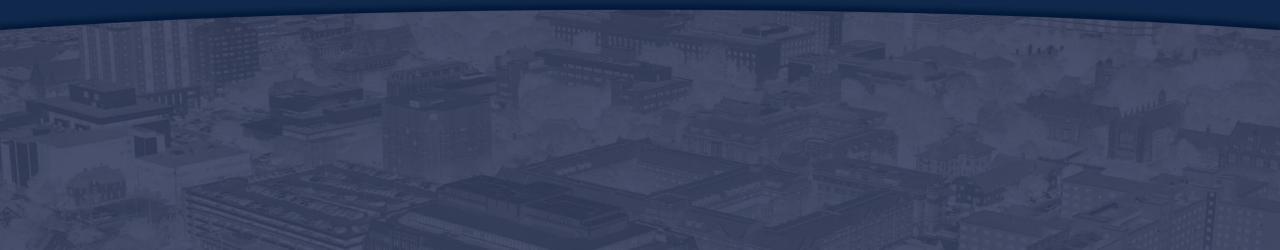
 A sequential data, this paper converts a 2 second audio sampled at 16kHz into spectrograms

It can be viewed as a 1-channel image when training.

https://towardsdatascience.com/learning-from-audio-spectrograms-37df29dba98c







#### Backbones

Image-text: Clip-text

Video-audio: Vit-B

Image-depth: Vit-S

Image-thermal: Vit-B

• Image-IMU: 1-D conv +

transformer

Dataset	Task	#cls	Metric	#test
Audioset Audio-only (AS-A) [18]	Audio cls.	527	mAP	19048
ESC 5-folds (ESC) [58]	Audio cls.	50	Acc	400
Clotho (Clotho) [16]	Retrieval	-	Recall	1045
AudioCaps (AudioCaps) [36]	Retrieval	-	Recall	796
VGGSound (VGGS) [8]	Audio cls.	309	Acc	14073
SUN Depth-only (SUN-D) [67]	Scene cls.	19	Acc	4660
NYU-v2 Depth-only (NYU-D) [64]	Scene cls.	10	Acc	653
LLVIP (LLVIP) [31]	Person cls.	2	Acc	15809
Ego4D (Ego4D) [22]	Scenario cls.	108	Acc	68865

Task 1: zero-shot with text embeddings

							<b>1</b> 0)				<b>&gt;&gt;&gt;</b>
	IN1K	P365	K400	MSR-VTT	NYU-D	SUN-D	AS-A	VGGS	ESC	LLVIP	Ego4D
Random	0.1	0.27	0.25	0.1	10.0	5.26	0.62	0.32	2.75	50.0	0.9
IMAGEBIND	77.7	45.4	50.0	36.1	54.0	35.1	17.6	27.8	66.9	63.4	25.0
Text Paired	-	-	-	-	41.9*	25.4*	28.4 <sup>†</sup> [26]	-	68.6 <sup>†</sup> [26]	-	-
Absolute SOTA	91.0 [80]	60.7 [65]	89.9 [78]	57.7 [77]	76.7 [20]	64.9 [20]	49.6 [38]	52.5 [35]	97.0 [9]	-	-

Random < Baseline < ImageBind < Supervised

Conclusion: it transfers the text supervision associated with images to other modalities.

Task 2: zero-shot audio retrieval with text

	Emergent	Clotho		AudioCaps		<b>ESC</b>		
		R@1	R@10	R@1	R@10	Top-1		
Uses audio and text supervision								
AudioCLIP [26]	X	_	_	_	_	68.6		
Uses audio and text loss								
AVFIC [50]	X	3.0	17.5	8.7	37.7	_		
No audio and text supervision								
IMAGEBIND	✓	6.0	28.4	9.3	42.3	66.9		
Supervised								
AVFIC finetuned [50]	X	8.4	38.6	_	72.1	_		
ARNLQ [52]	X	12.6	45.4	24.3	72.1	_		

Table 3. Emergent zero-shot audio retrieval and classification.

Task 3: zero-shot video retrieval with text embeddings

	Modality	Emergent	MSR-VTT			
			R@1	R@5	R@10	
MIL-NCE [48]	V	X	8.6	16.9	25.8	
SupportSet [56]	V	X	10.4	22.2	30.0	
FIT [5]	V	X	15.4	33.6	44.1	
AVFIC [50]	A+V	X	19.4	39.5	50.3	
IMAGEBIND	A	✓	6.8	18.5	27.2	
IMAGEBIND	A+V	X	36.8	61.8	70.0	

Table 4. Zero-shot text based retrieval on MSR-VTT 1K-A.

Task 4: Few-shot classification on audio and depth

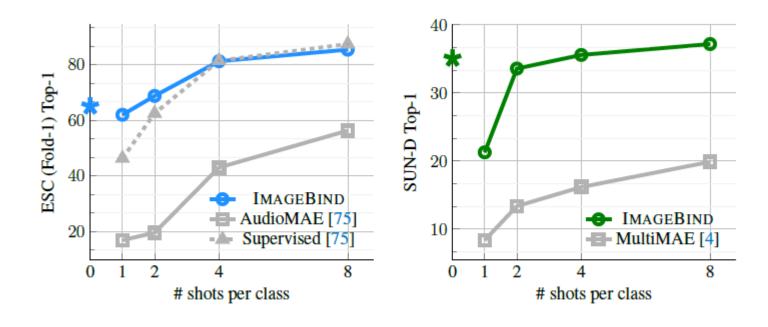


Figure 3. Few-shot classification on audio and depth.

Task 4: Few-shot classification on audio and depth

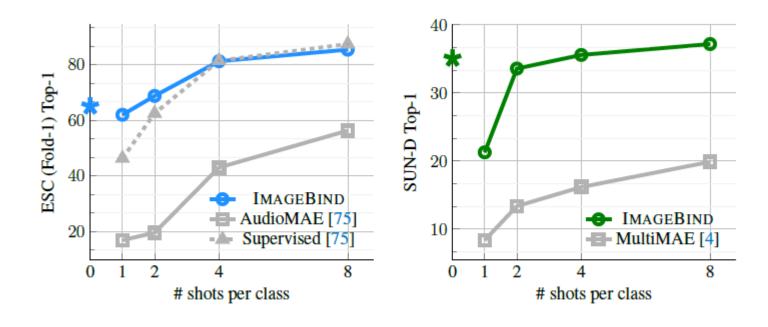
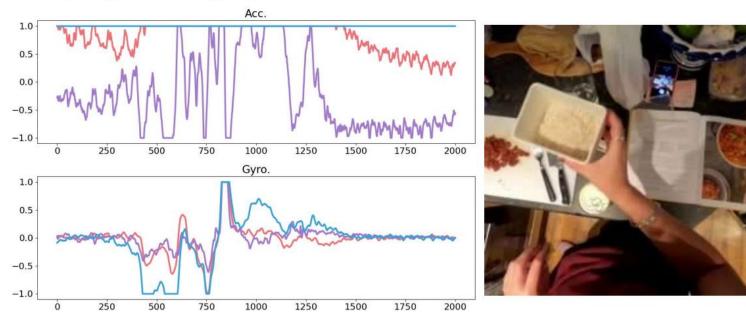


Figure 3. Few-shot classification on audio and depth.

In the appendix of the paper, the proposed model can retrieval images based on IMU signals

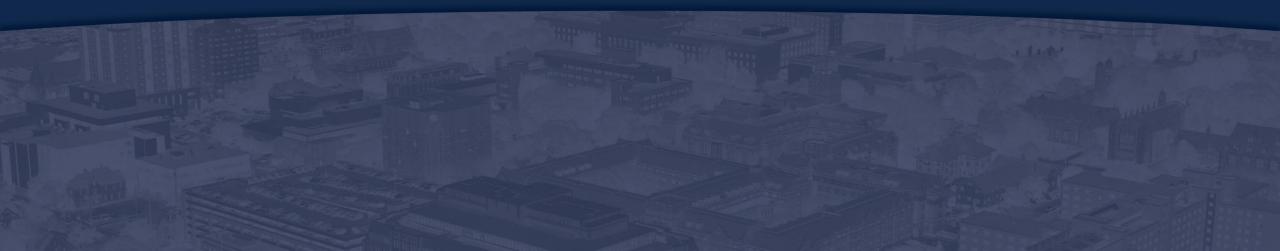
**Text query:** "Cooking a meal"



https://arxiv.org/pdf/2305.05665.pdf



# Quiz



### Opening questions

Q1: Can biomedical data be bonded to the image?

### Open questions

Q2: Can modalities bind to others like sensor data?

I think there is an existing work considering binding modalities to the text side.

Zhu B, Lin B, Ning M, et al. LanguageBind: Extending Video-Language Pretraining to N-modality by Language-based Semantic Alignment[J]. arXiv preprint arXiv:2310.01852, 2023.