COMP.4510/COMP.5490 Mobile Robotics

Fall 2018

Prof. Yanco

**Getting Started**

Please do the following:

1. *(required)* Go to the CS office, and sign up for a student account on the “CS” server. When you submit code, make sure that it says “submission successful” at the end of the submission output. Otherwise, your submission may have failed.
2. *(recommended)* Install ROS on your computer: <http://wiki.ros.org/kinetic/Installation/Ubuntu> . While IT is generously managing the vLabs for us, the system could go down for maintenance, crash, etc. Therefore, it is advisable to have alternative access to ROS.