

OUTLINE

- I. Radar imaging - Spatial resolution**
- II. Polarization - Polarimetry**
- III. Radar response sensitivity**
- IV. Relief effects**
- V. Speckle and Filtering**

the ERS Satellite

ERS-1: juillet 1991

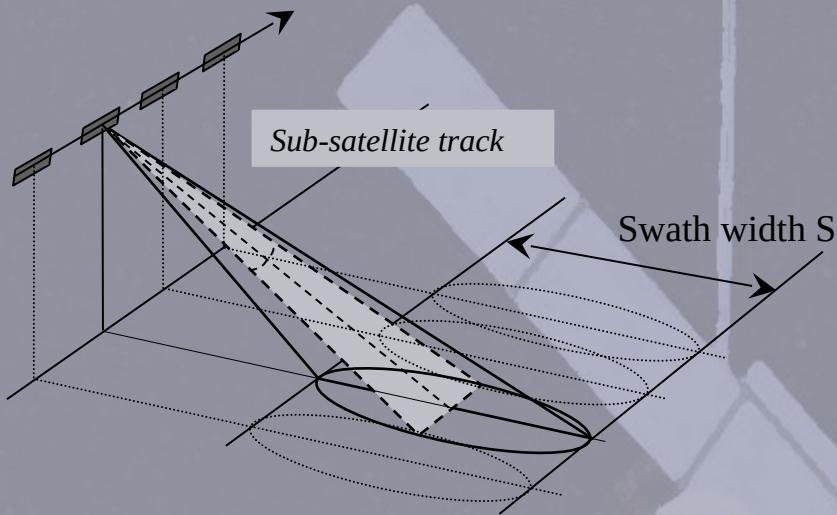
ERS-2: avril 1995

(SAR)

Scatterometer
ESCAT

Altimeter

Side looking radar sensors ($\lambda > cm$)



Scatterometers

: SAR: Synthetic Aperture Radar

Raw echoes recording

Incoherent sum (I)

Low (25 – 50 km)

High (400 Looks)

sea (winds)

Coherent sum (A, ϕ)

fine (1 - 30 m)

Low (speckle)

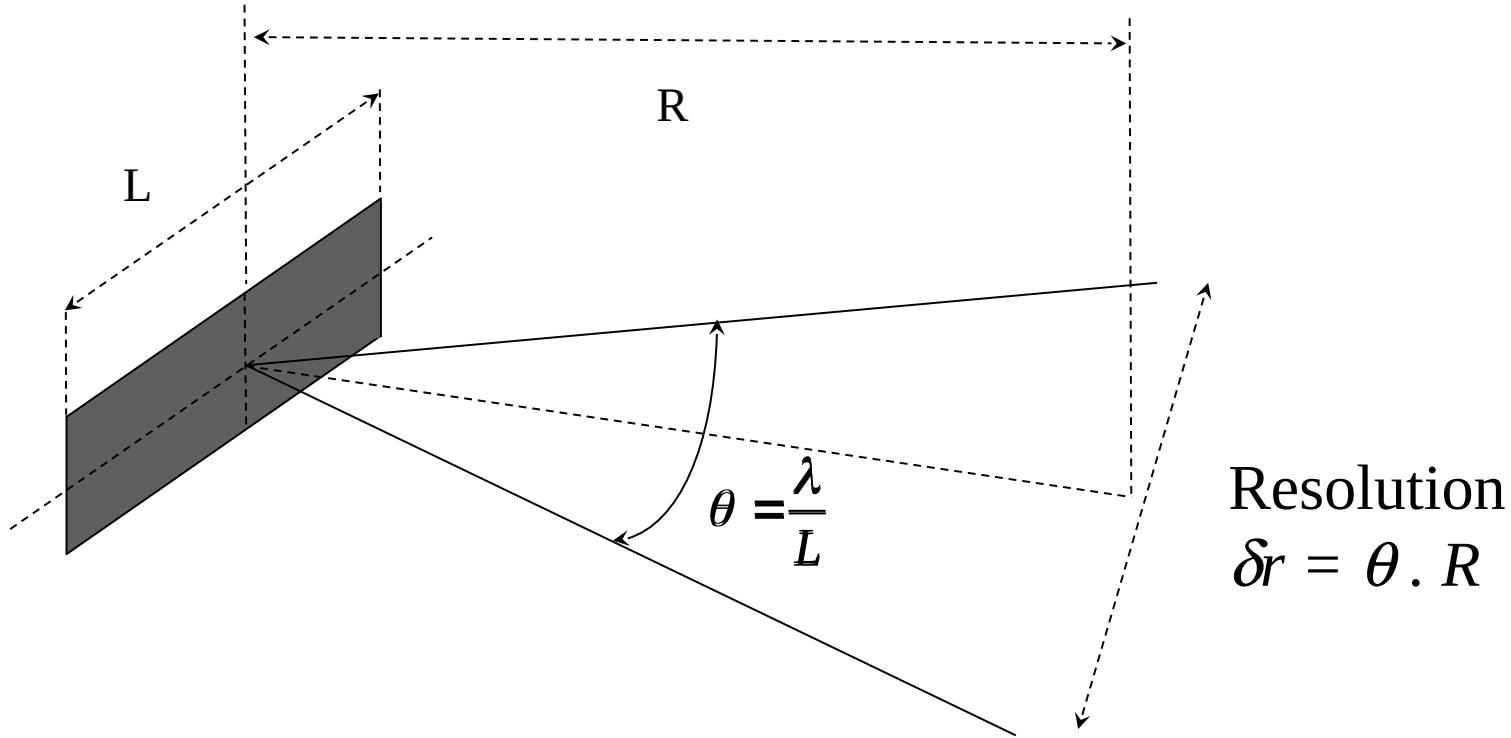
Land - sea

Spatial resolution

Radiometric resolution

Original application

ANTENNA APERTURE



Ex.: $L = 4 \text{ m}$, $R = 4 \text{ km}$ (airborne), $\lambda = 3 \text{ cm}$ (X band) $\delta r = 30 \text{ m}$

$L = 10 \text{ m}$, $R = 800 \text{ km}$ (spaceborne), $\lambda = 6 \text{ cm}$ (C band) $\delta r = 4,5 \text{ km}$

Spatial resolution:

smallest distance allowing the separation of two objects

Optical data:

sensor spatial resolution < image pixel size

==> pixel size same as spatial resolution

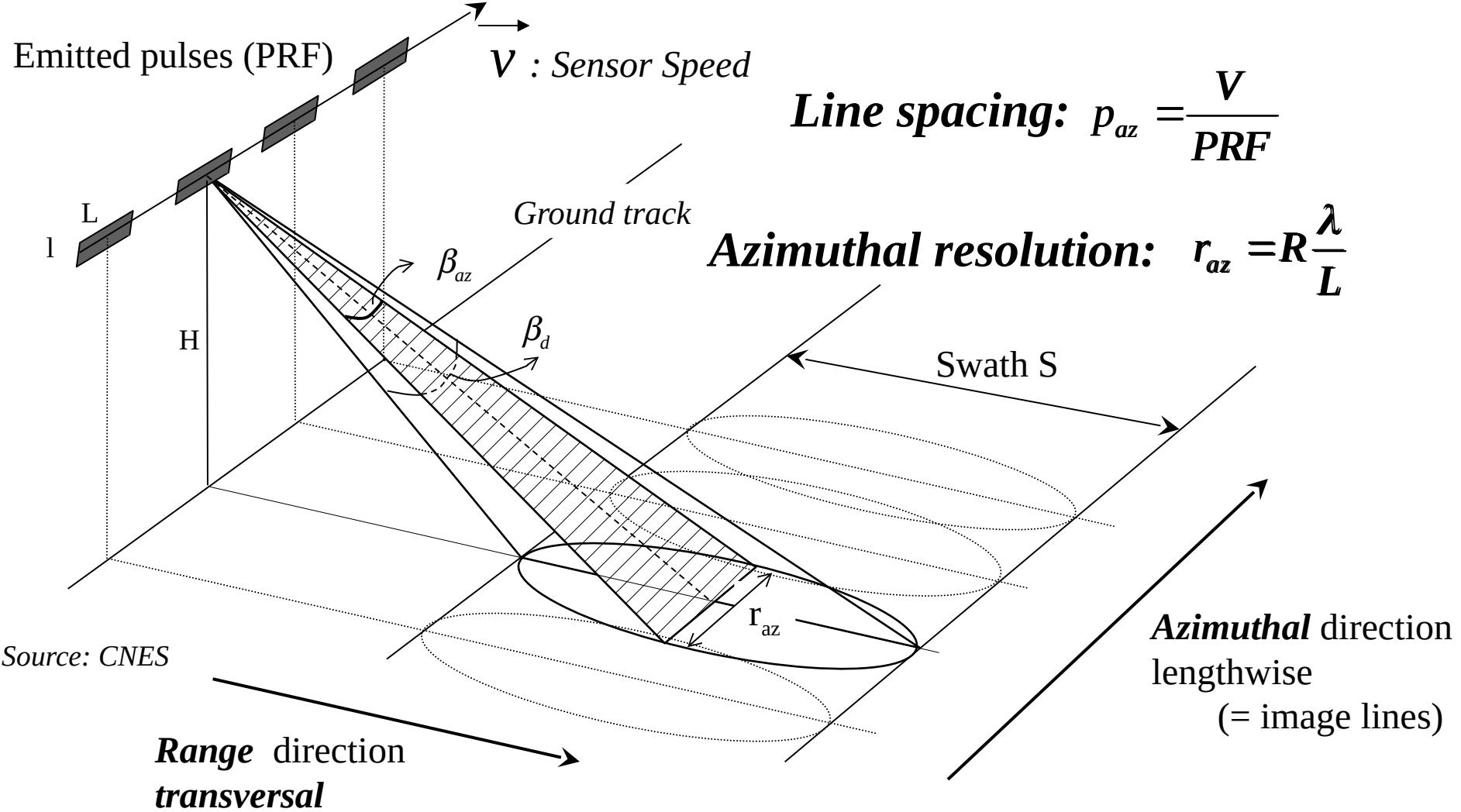
hence the use of one word for the other

Radar data:

sensor spatial resolution > image pixel size

==> these 2 notions remain different

Radar Imaging - spatial resolution



Numerical Application (ERS):

$$PRF = 1680 \text{ Hz}, V = 7 \text{ km/s}$$

$$p_{az} \quad 5 \text{ m}$$

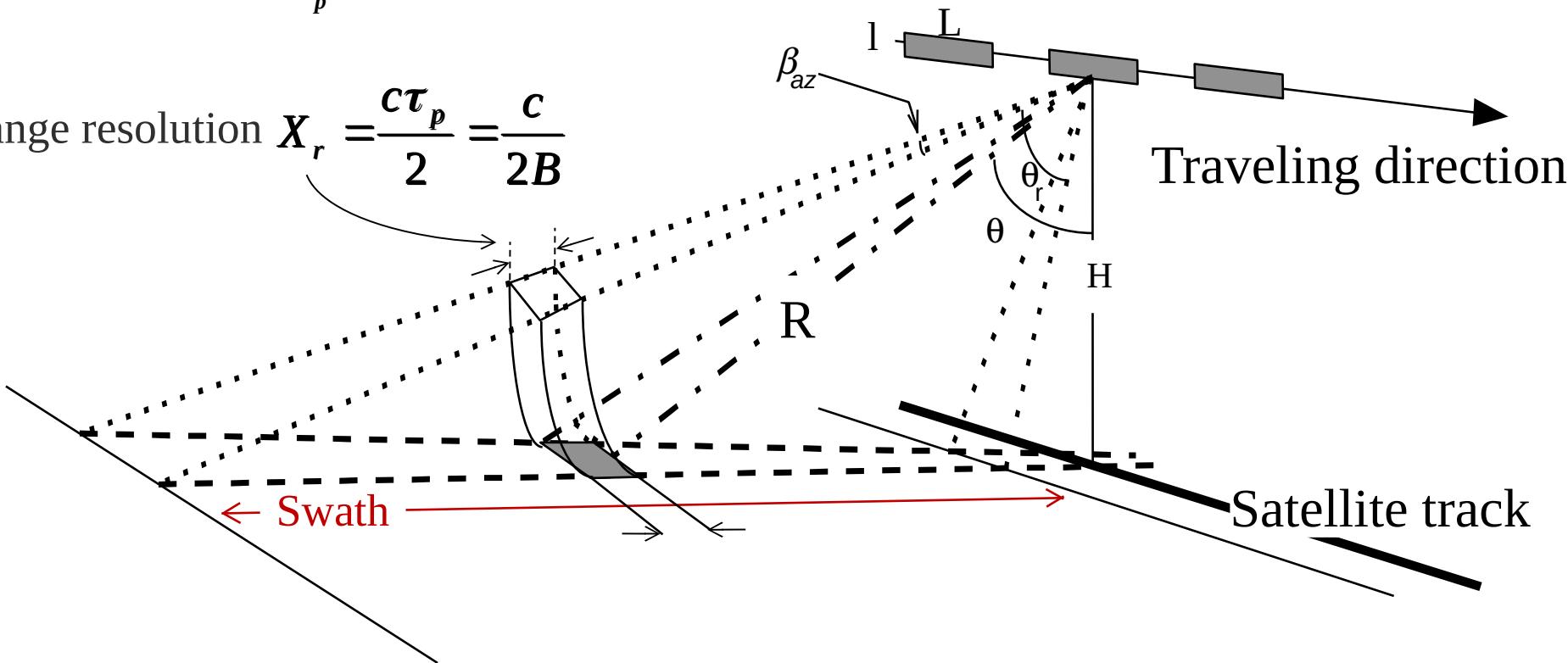
$$L = 10 \text{ m}, \lambda = 5.6 \text{ cm}, H = 700 \text{ km}, \theta = 23^\circ$$

$$r_{az} \quad 4.2 \text{ km}$$

Radar Imaging - spatial resolution

Pulse duration = $\tau_p =$

$$\text{Range resolution } X_r = \frac{c\tau_p}{2} = \frac{c}{2B}$$



◊ Increase the pulse B

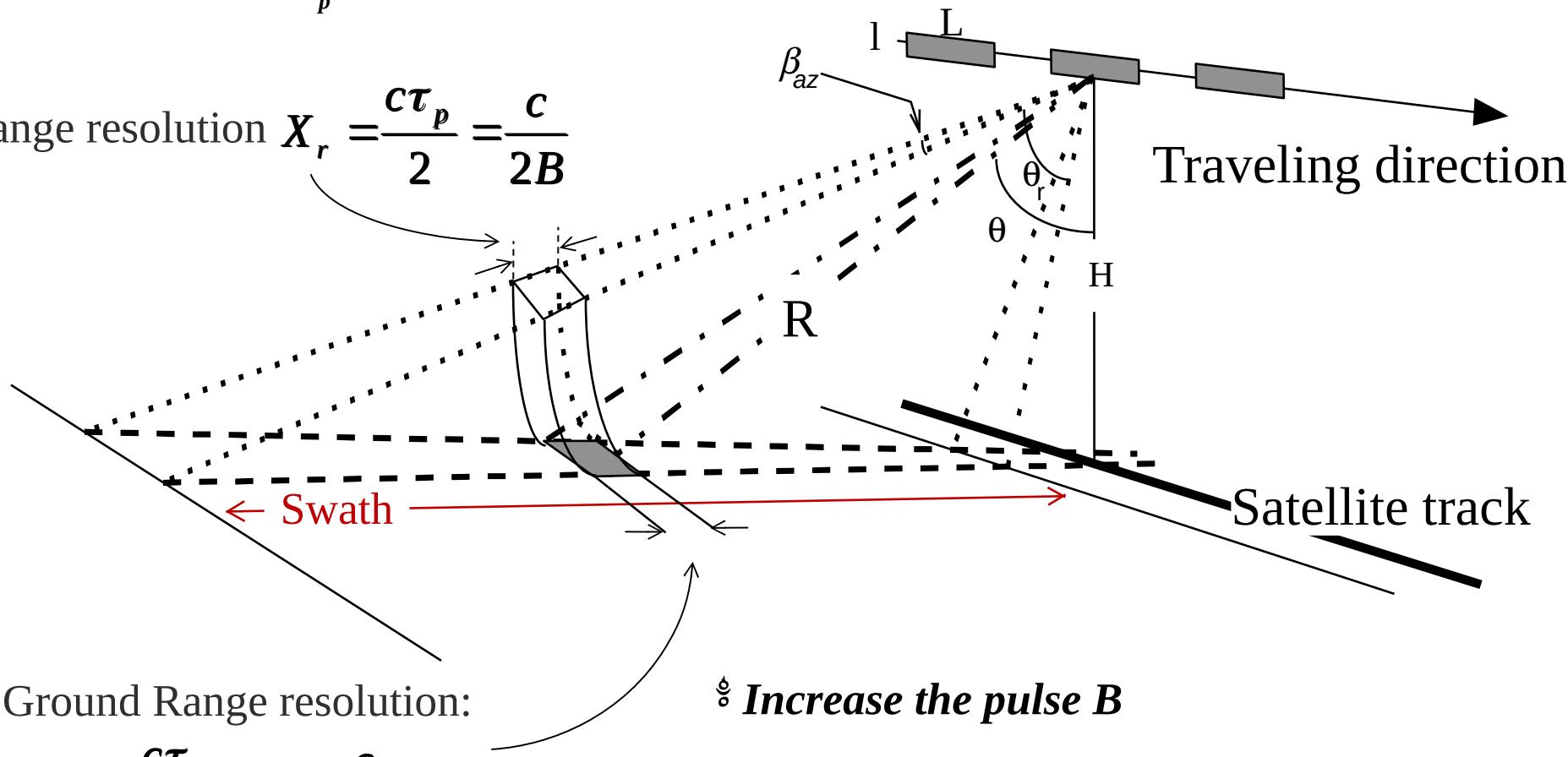
Num. Appl. (ERS): $\tau_p = 37 \mu s$ B ~~30 kHz~~ 15.5 MHz

X_r 10 m

Radar Imaging - spatial resolution

Pulse duration = $\tau_p =$

$$\text{Range resolution } X_r = \frac{c\tau_p}{2} = \frac{c}{2B}$$



Ground Range resolution:

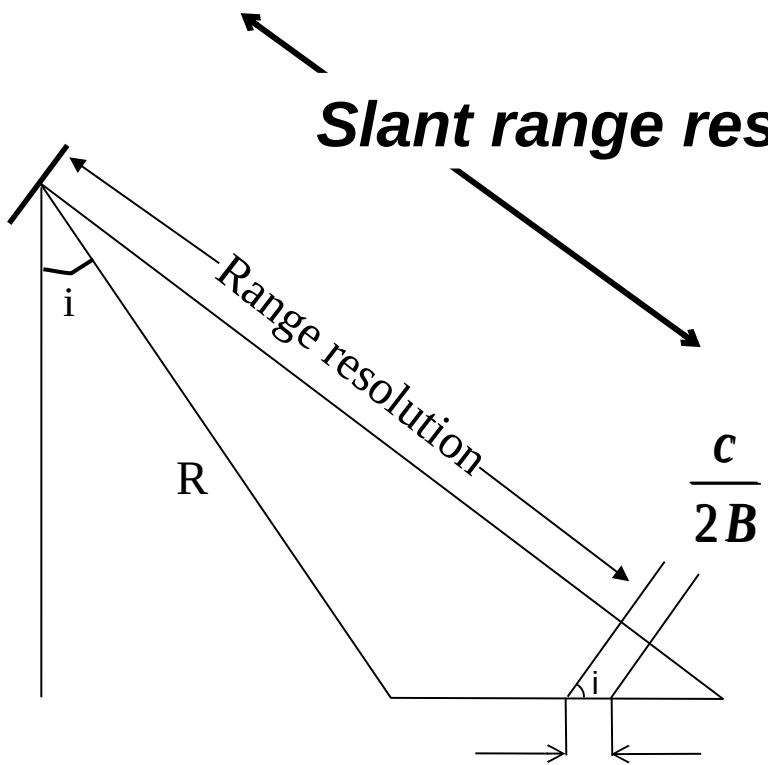
$$X_{gr} = \frac{c\tau_p}{2 \sin \theta} = \frac{c}{2B \sin \theta}$$

⌚ Increase the pulse B

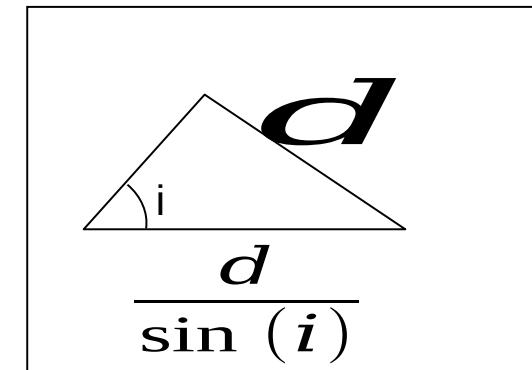
Num. Appl. (ERS): $\tau_p = 37 \mu s$ $B = 30 \cancel{kHz}$ 15.5 MHz

$X_r = 10 \text{ m}$

Radar Imaging - spatial resolution



Slant range resolution:



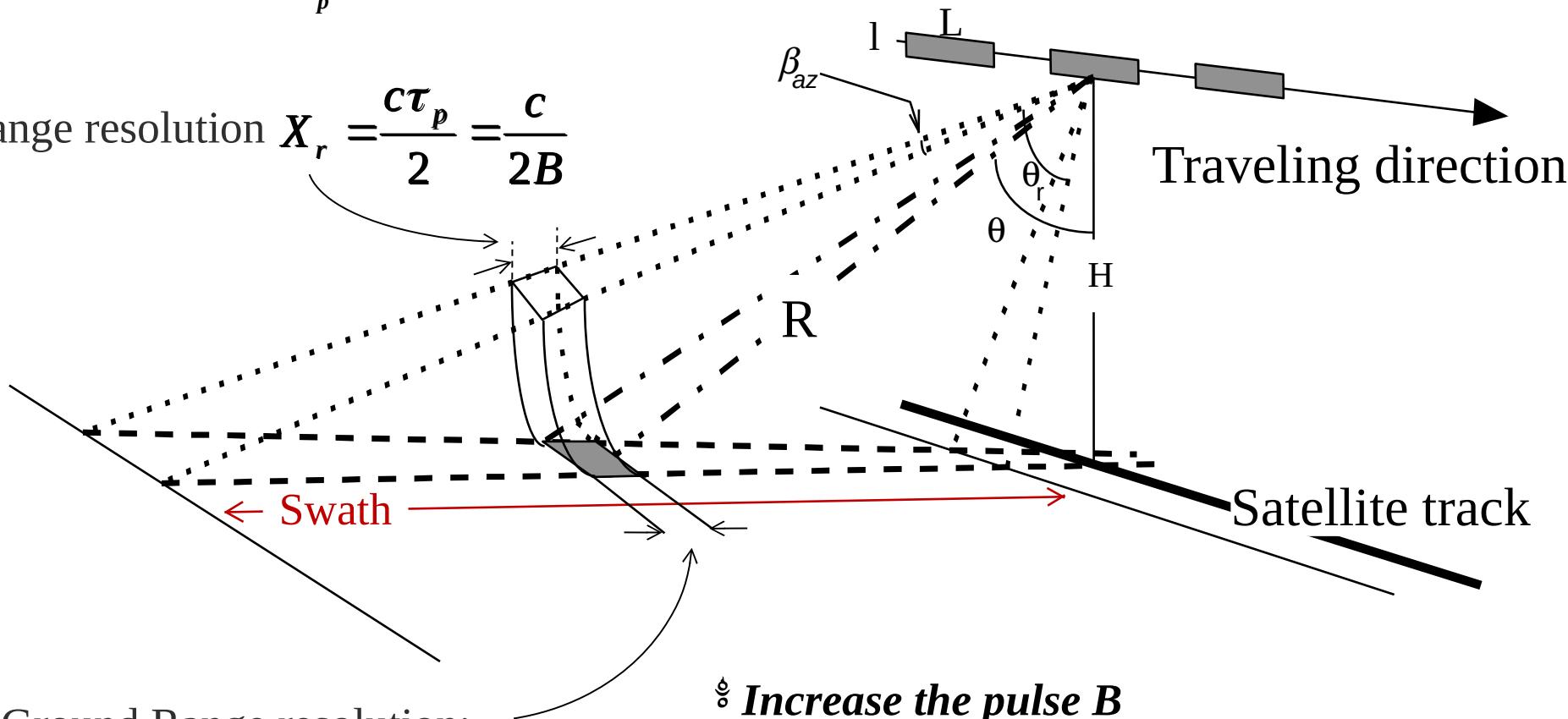
$$\frac{c}{2 B \cdot \sin i} \text{ Ground range resolution}$$

Ground range resolution: $X_{gr} = \frac{c}{2 B \sin(i)}$

Radar Imaging - spatial resolution

Pulse duration = $\tau_p =$

$$\text{Range resolution } X_r = \frac{c\tau_p}{2} = \frac{c}{2B}$$



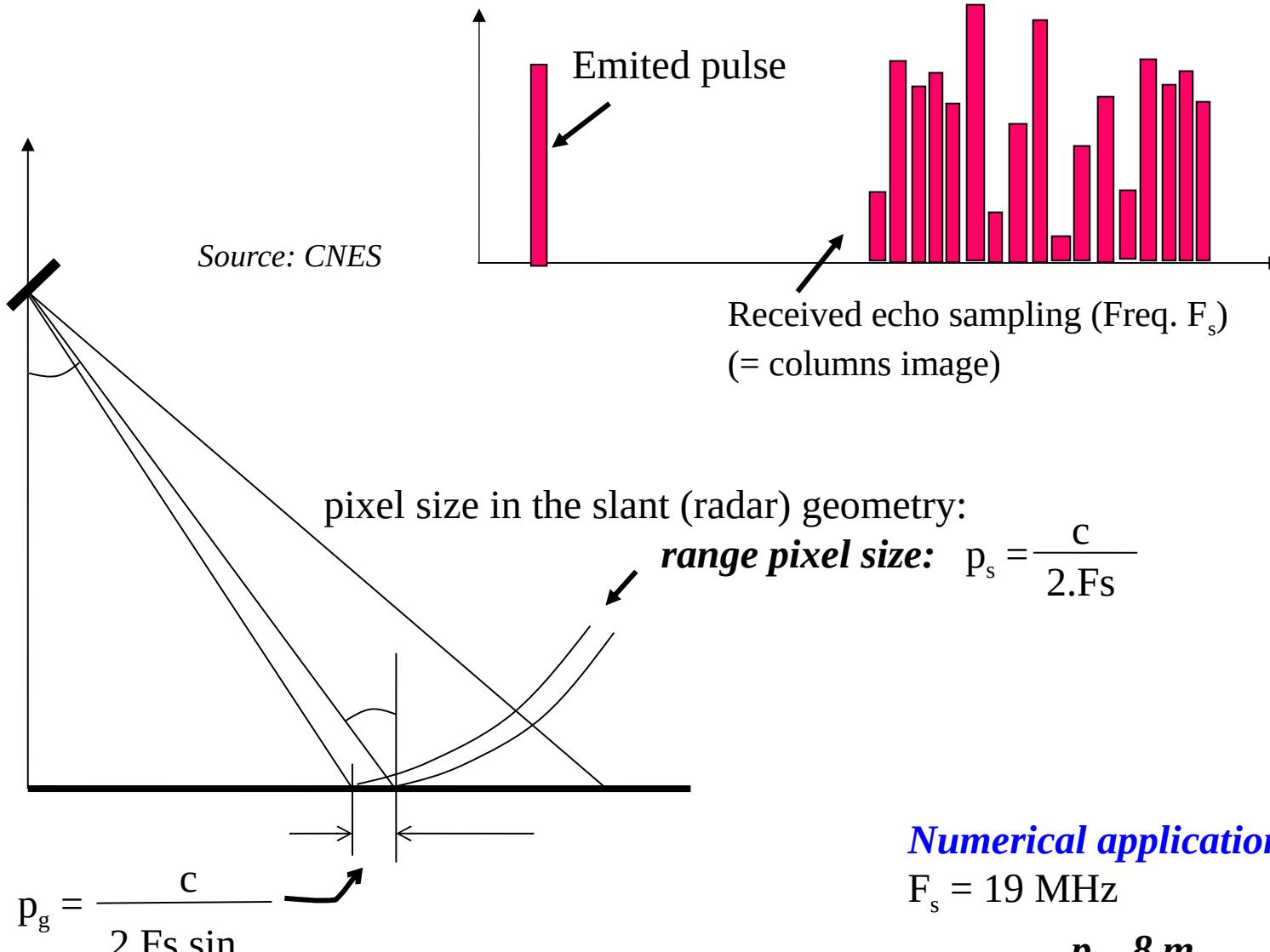
Ground Range resolution:

$$X_{gr} = \frac{c\tau_p}{2 \sin \theta} = \frac{c}{2B \sin \theta}$$

Num. Appl. (ERS): $\tau_p = 37 \mu s$ $B = \cancel{30 \text{ kHz}}$ 15.5 MHz

$$X_r \quad 10 \text{ m} \quad X_{gr} \quad 25 \text{ m}$$

Radar Imaging - spatial resolution



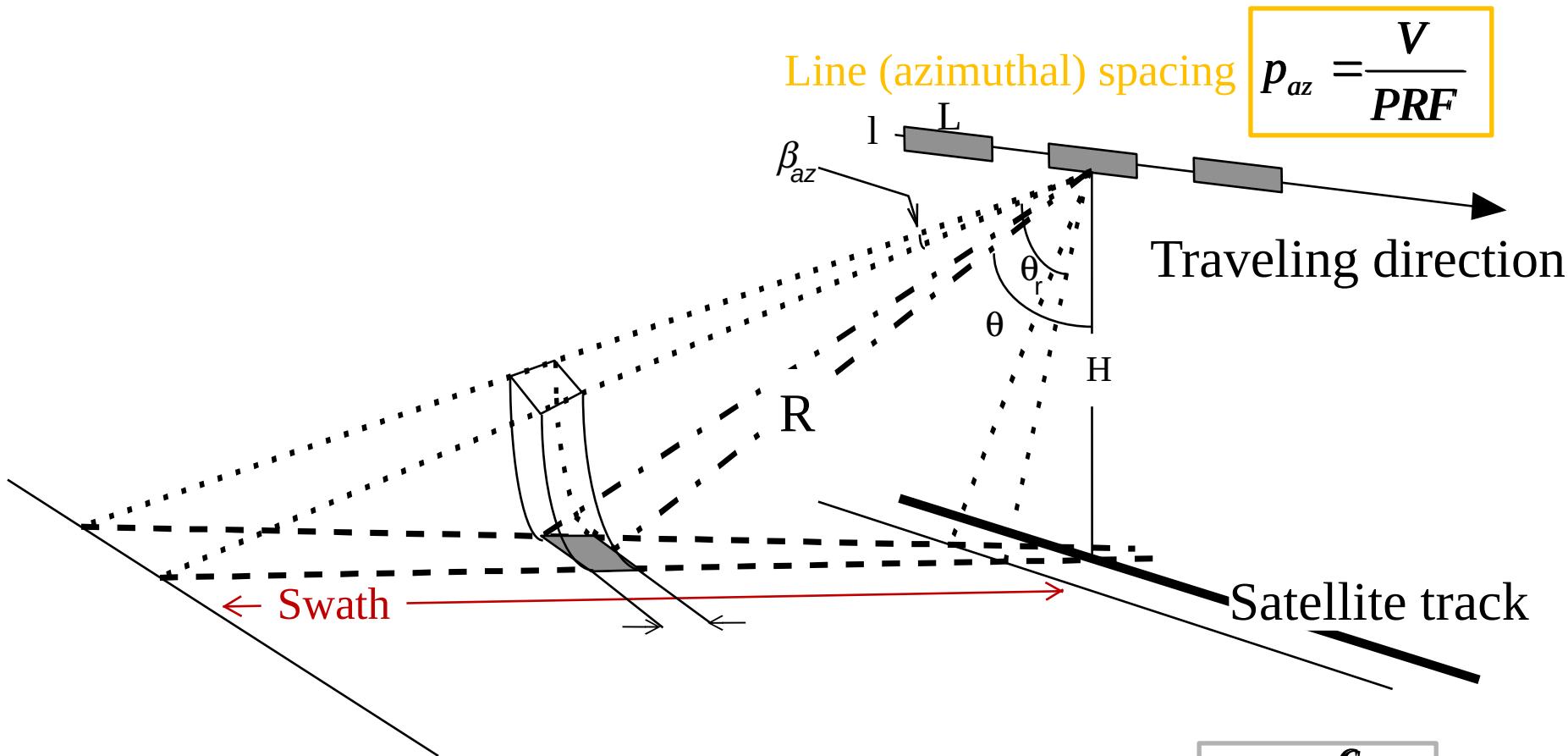
Numerical application: ERS

$$F_s = 19 \text{ MHz}$$

$$p_s \quad 8 \text{ m}$$

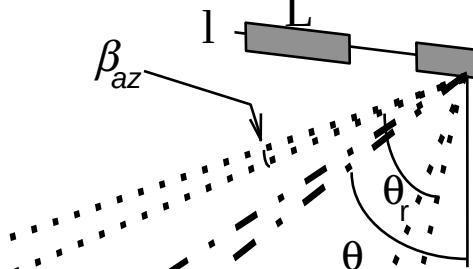
$$p_g \quad 20 \text{ m}$$

Radar Imaging - spatial resolution



Line (azimuthal) spacing

$$p_{az} = \frac{V}{PRF}$$



Traveling direction

R

← Swath

Satellite track

Range pixel (column)
size

Ground range pixel size

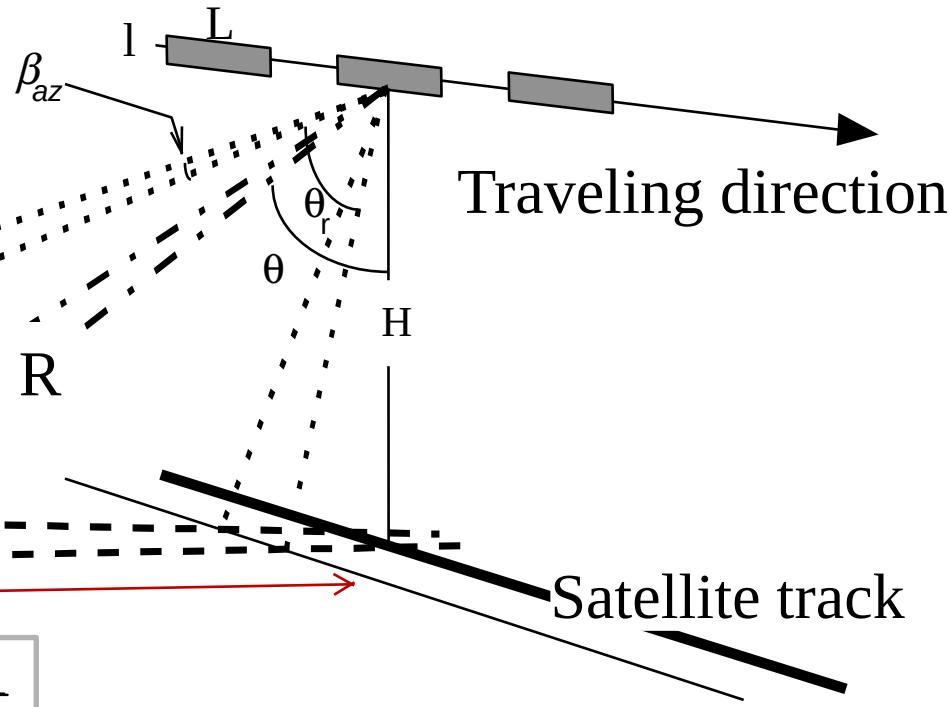
$$p_s = \frac{c}{2 F_s}$$

$$p_{gr} = \frac{c}{2 F_s \sin(\theta)}$$

Radar Imaging - spatial resolution

Range resolution

$$X_s = \frac{c\tau_{ps}}{2} = \frac{c}{2B}$$



Ground range resolution

$$X_{gr} = \frac{c}{2B \sin \theta}$$

Azimuthal resolution

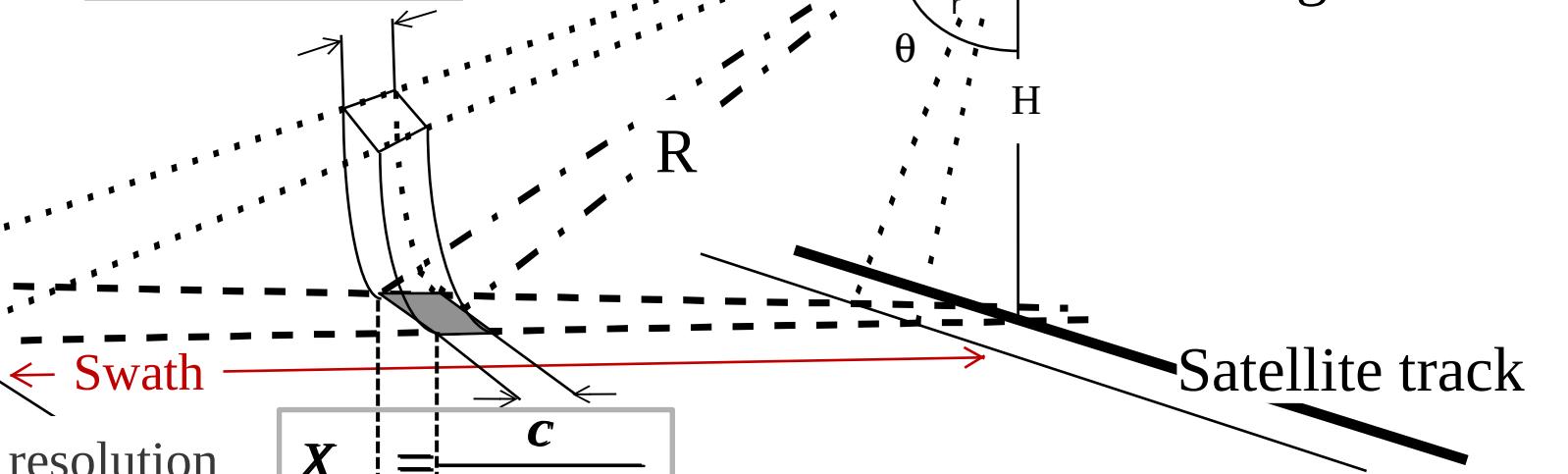
$$X_{az} = \frac{\lambda R}{L}$$

Pulse duration = $\tau_p = 1/B$

Radar Imaging - spatial resolution

Range resolution

$$X_s = \frac{c\tau_{ps}}{2} = \frac{c}{2B}$$



Ground range resolution

$$X_{gr} = \frac{c}{2B \sin \theta}$$

Azimuthal resolution

$$X_{az} = \frac{\lambda}{L} R$$

Pulse duration = τ_p = $1/B$

Line (azimuthal) spacing

$$p_{az} = \frac{V}{PRF}$$

Traveling direction

Range pixel (column)
size

Ground range pixel size

$$p_s = \frac{c}{2F_s}$$

$$p_{gr} = \frac{c}{2F_s \sin(\theta)}$$

Radar Imaging - spatial resolution

Case of ERS

	Range	Azimuth
Resolution	Slant (radar) $X_s = \frac{c}{2B} = 10 \text{ m}$	Ground $X_{gr} = \frac{c}{2B \sin(\theta)} = 25 \text{ m} - 32 \text{ m}$
Pixel size	$p_s = \frac{c}{2 F_s} = 8 \text{ m}$	$p_{gr} = \frac{c}{2 F_s \sin(\theta)} = 20 \text{ m} - 26 \text{ m}$

$$\lambda = 5.6 \text{ cm}$$

$$V = 7 \text{ km/s}$$

$$\text{PRF} = 1680 \text{ Hz}$$

$$F_s = 19 \text{ MHz}$$

$$= 18-24^\circ$$

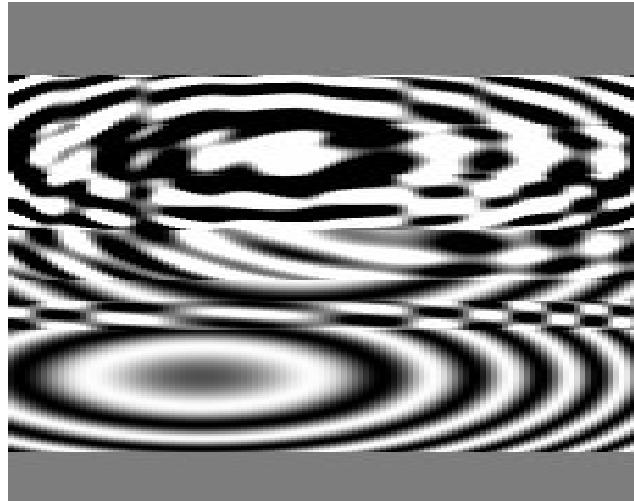
$$B = 15.5 \text{ MHz}$$

$$R = 15.5 \text{ MHz}$$

$$L = 10 \text{ m}$$

FLIGHT DIRECTION

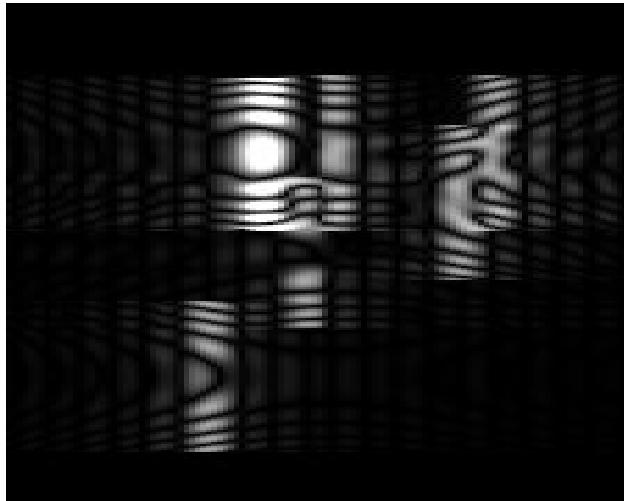
Raw echoes



Ideal scene



Compression in distance



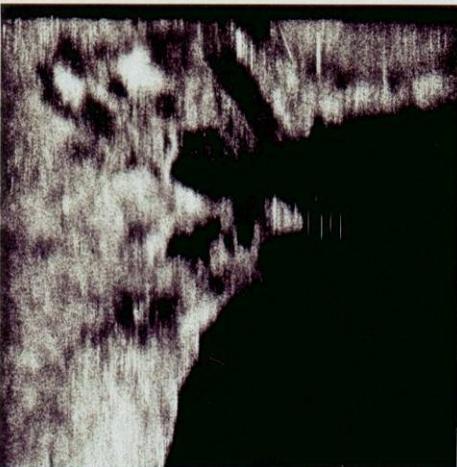
RANGE (Viewing) DIRECTION

FLIGHT DIRECTION



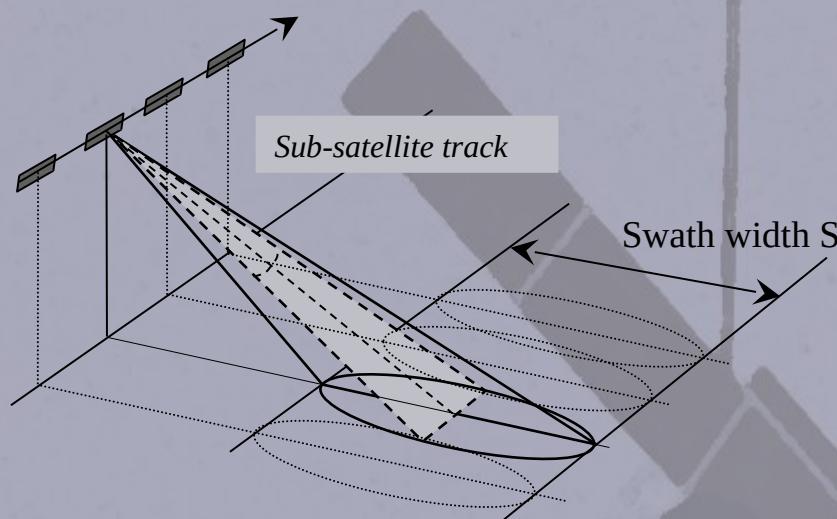
NON COMPRIME DISTANCE
NON COMPRIME AZIMUT

Document



COMPRIME DISTANCE
NON COMPRIME AZIMUT

Side looking radar sensors ($\lambda > cm$)



SAR: Synthetic Aperture Radar

Raw echoes recording

Coherent sum (A, ϕ)

Spatial resolution

fine (1 - 30 m)

Radiometric resolution

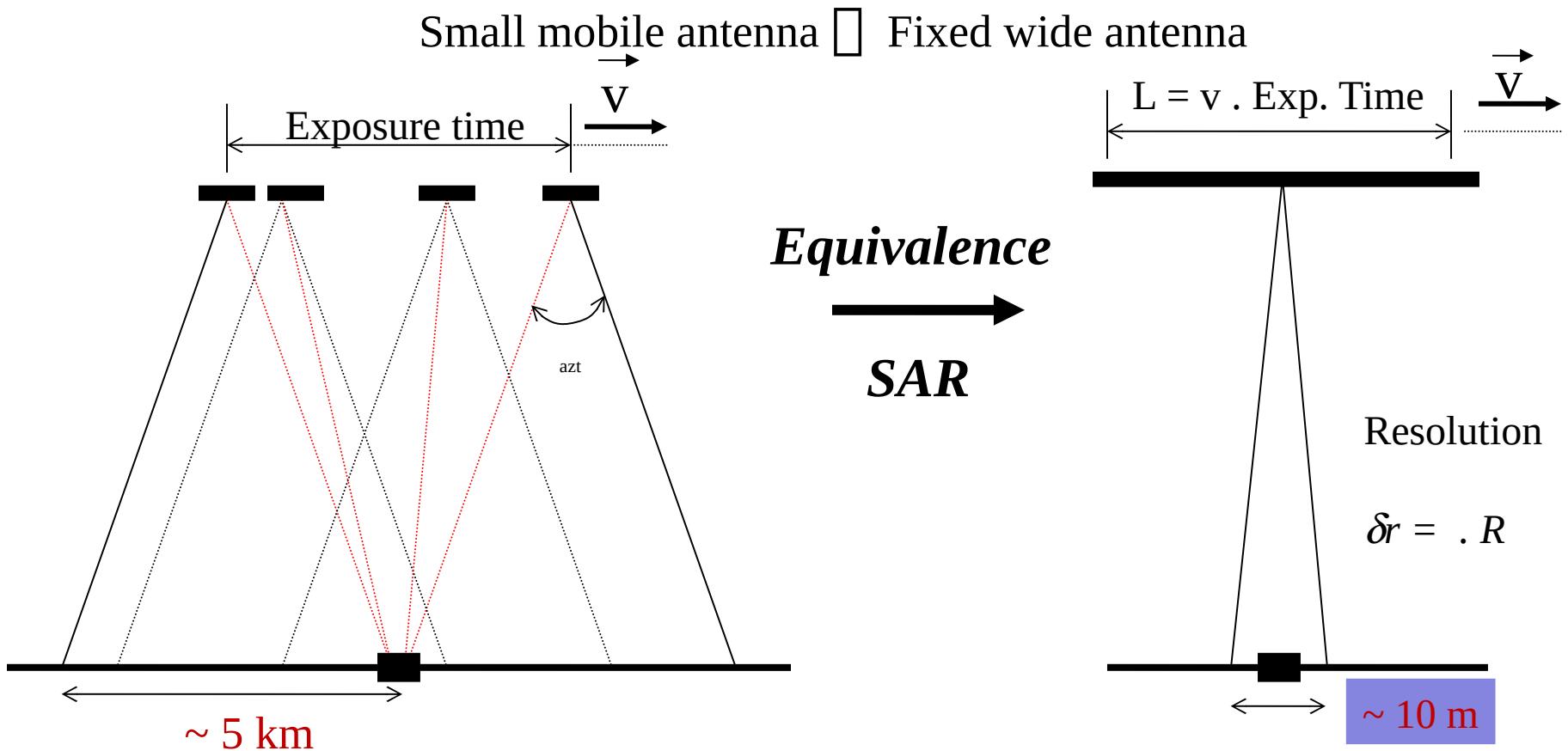
Low (speckle)

Original application

Land - sea

Radar Imaging - spatial resolution

Synthetic Aperture Radar: (i.e. improvement of azimuthal resolution)



Coherent sum of the successive echoes

Adaptative filtering (Doppler Bandwidth)

$$B_D = \frac{2V}{L}$$

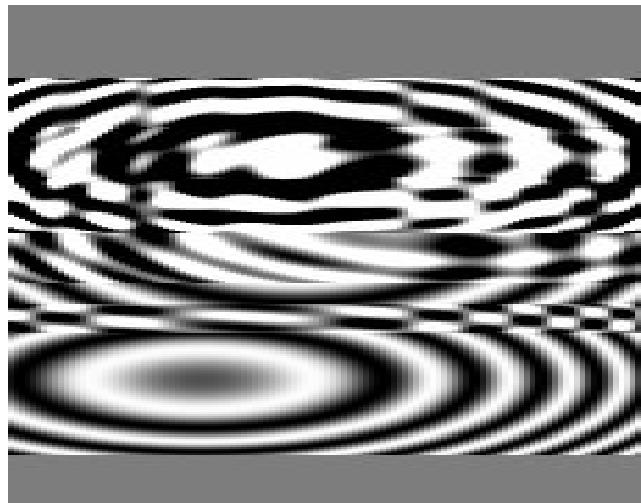


Gain in azimuthal resolution

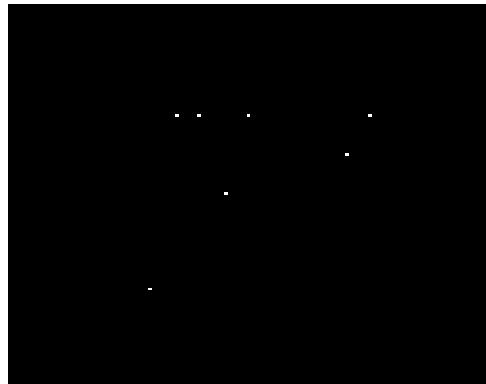
$$X_{az} = \frac{V}{B_D} \Rightarrow X_{az} = \frac{L}{2}$$

FLIGHT DIRECTION

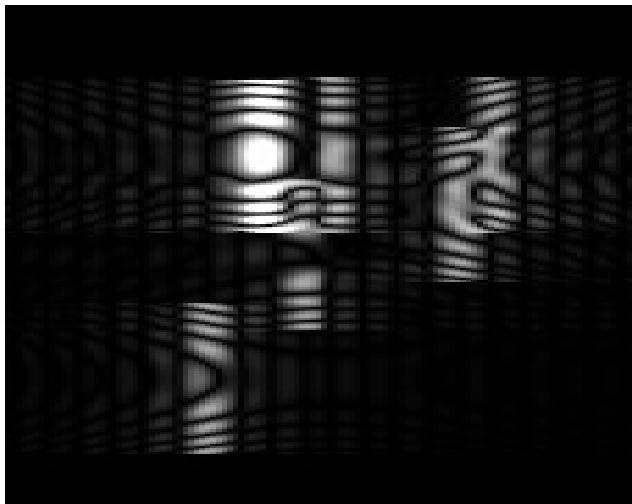
Raw echoes



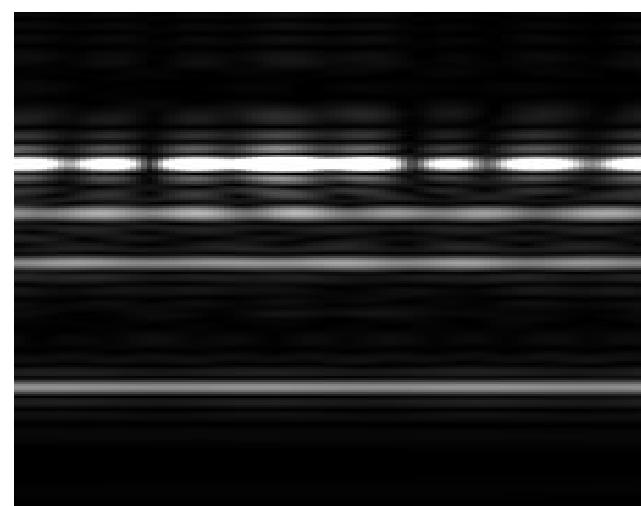
Ideal scene



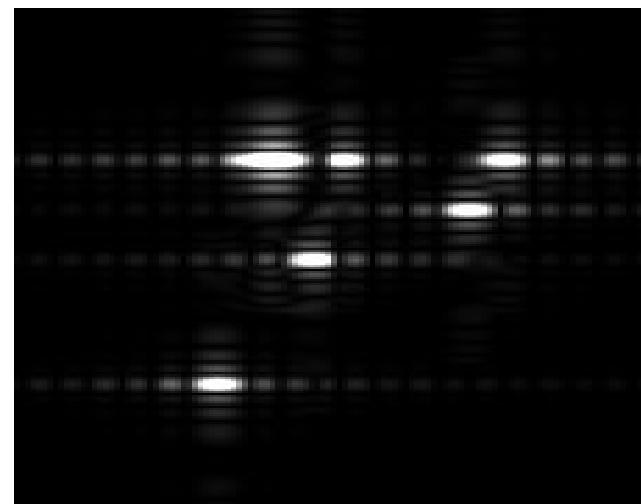
Compression in distance



Compression in Azimuth

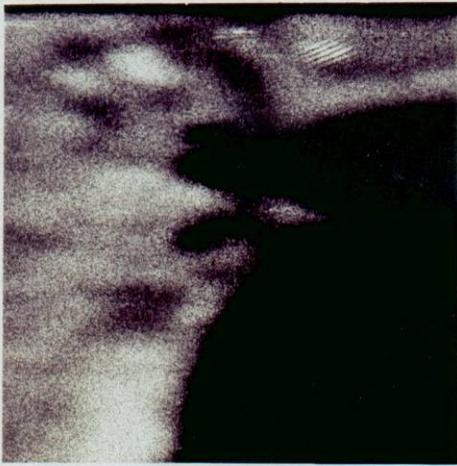


radar Image Single Look Complex (SLC)

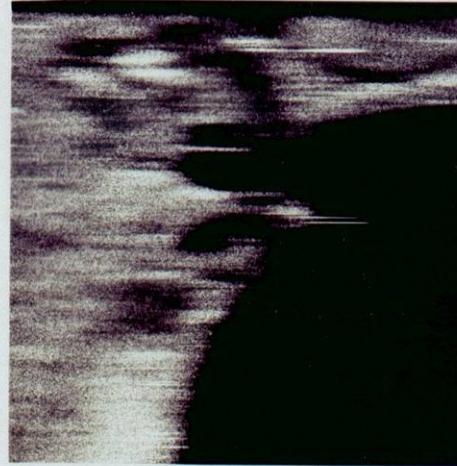


RANGE (Viewing) DIRECTION

FLIGHT DIRECTION

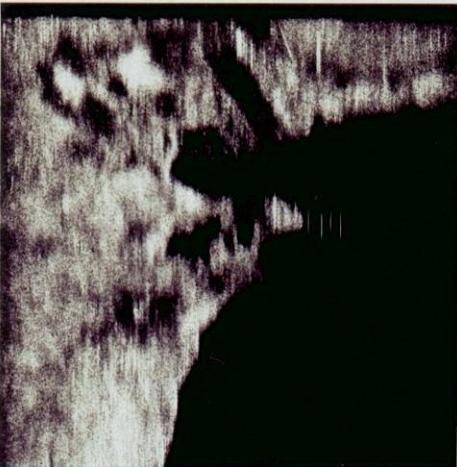


NON COMPRISE DISTANCE
NON COMPRISE AZIMUT

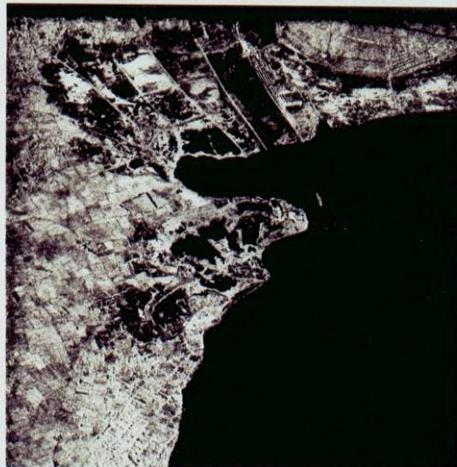


NON COMPRISE DISTANCE
COMPRISE AZIMUT

Document CNES



COMPRISE DISTANCE
NON COMPRISE AZIMUT



COMPRISE DISTANCE
COMPRISE AZIMUT

RANGE (Viewing) DIRECTION

Radar Imaging - spatial resolution

Case of ERS SAR (after aperture synthesis)

	Range	Azimuth	
	Slant (radar)	Ground	
Resolution	$X_r = \frac{c}{2B} = 10 \text{ m}$	$X_r = \frac{c}{2B \sin(\theta)} = 25 \text{ m} - 32 \text{ m}$	$X_{az} = \frac{\lambda}{L_{synth}} R = 10 \text{ m}$
Pixel size	$p_s = \frac{c}{2F_s} = 8 \text{ m}$	$p_{gr} = \frac{c}{2F_s \sin(\theta)} = 19 \text{ m} - 26 \text{ m}$	$p_{az} = \frac{V}{PRF} = 4 \text{ m}$

Case of TERRASAR-X

	Range	Azimuth	
	Slant (radar)	Ground	
Resolution	1.2 m	$1.5 \text{ m} - 3.5 \text{ m}$	1.1 m
Pixel size	0.6 m	$0.75 \text{ m} - 1.75 \text{ m}$	0.6 m

RADARSAT - Scansar Wide : 27 mars 1999



Spat. res. 150 m

The Ouessant Rail
RADARSAT - Standard 6 : 3 Aug.1999



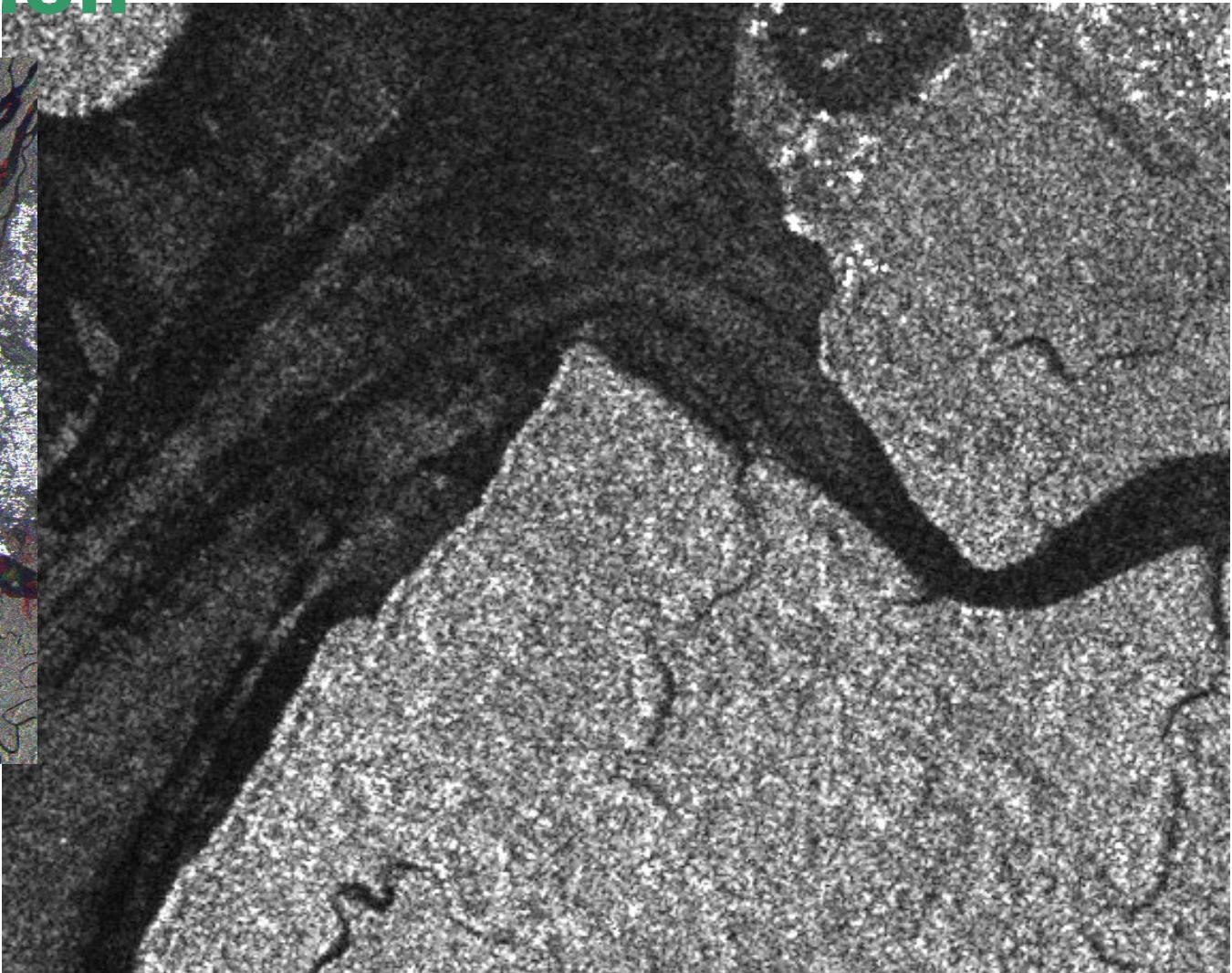
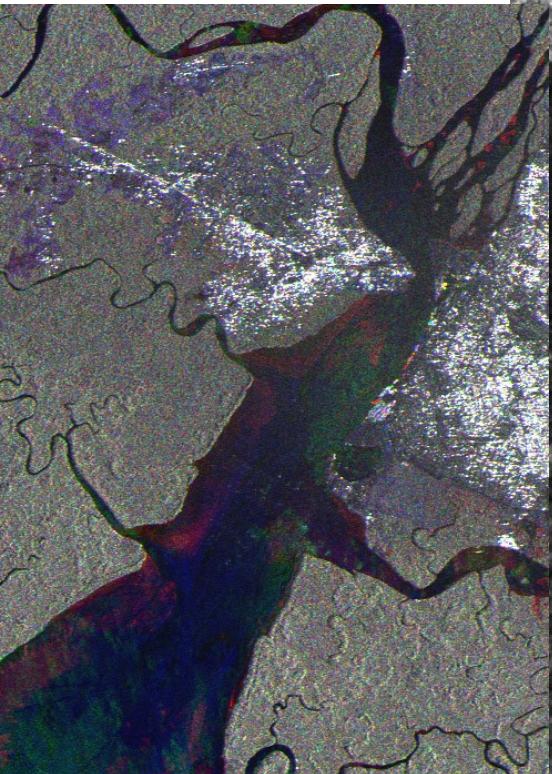
Spat. res. 30 m



The Channel
ASAR
22 novembre 2003

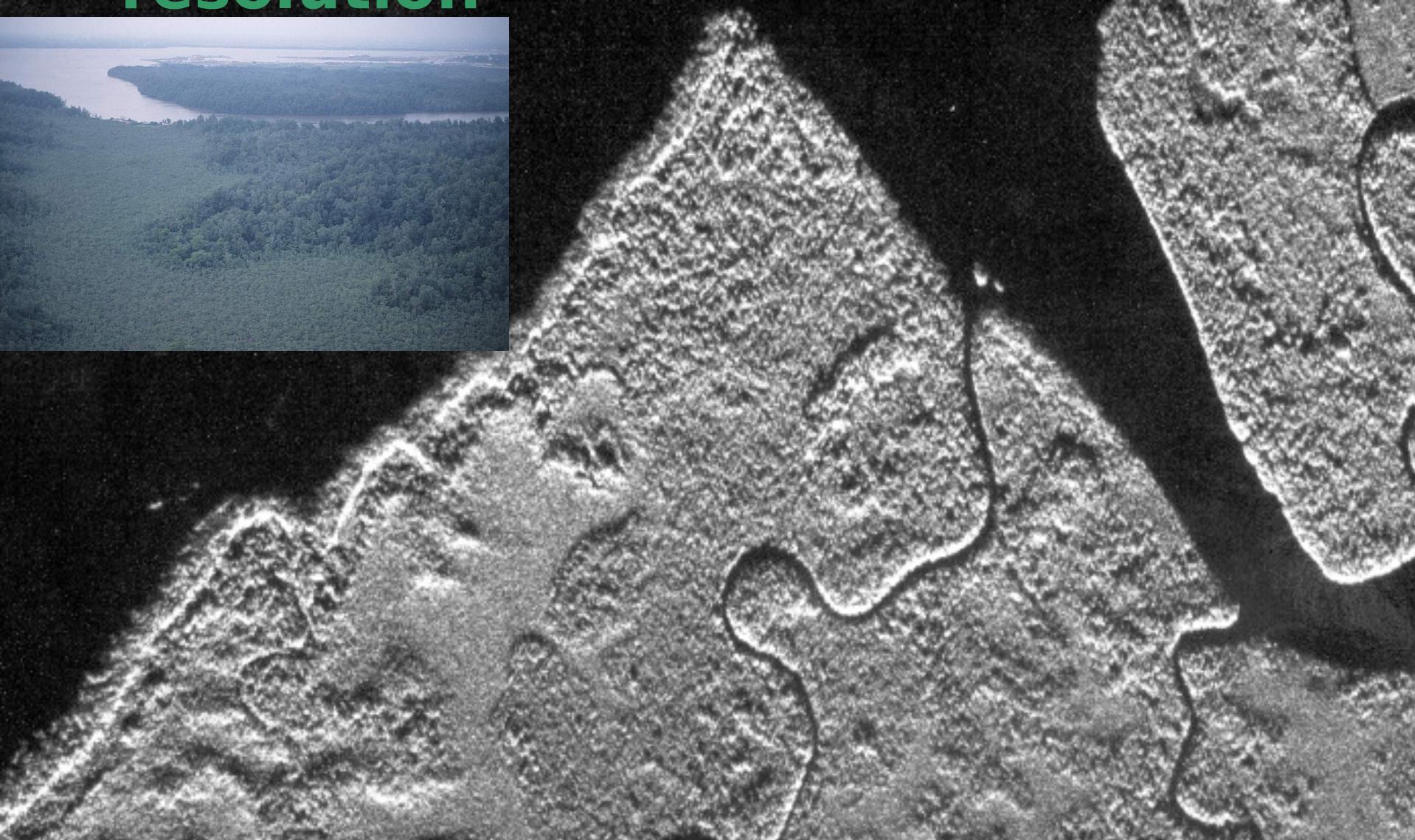
spat. res. 150 m

Radar Imaging - spatial resolution



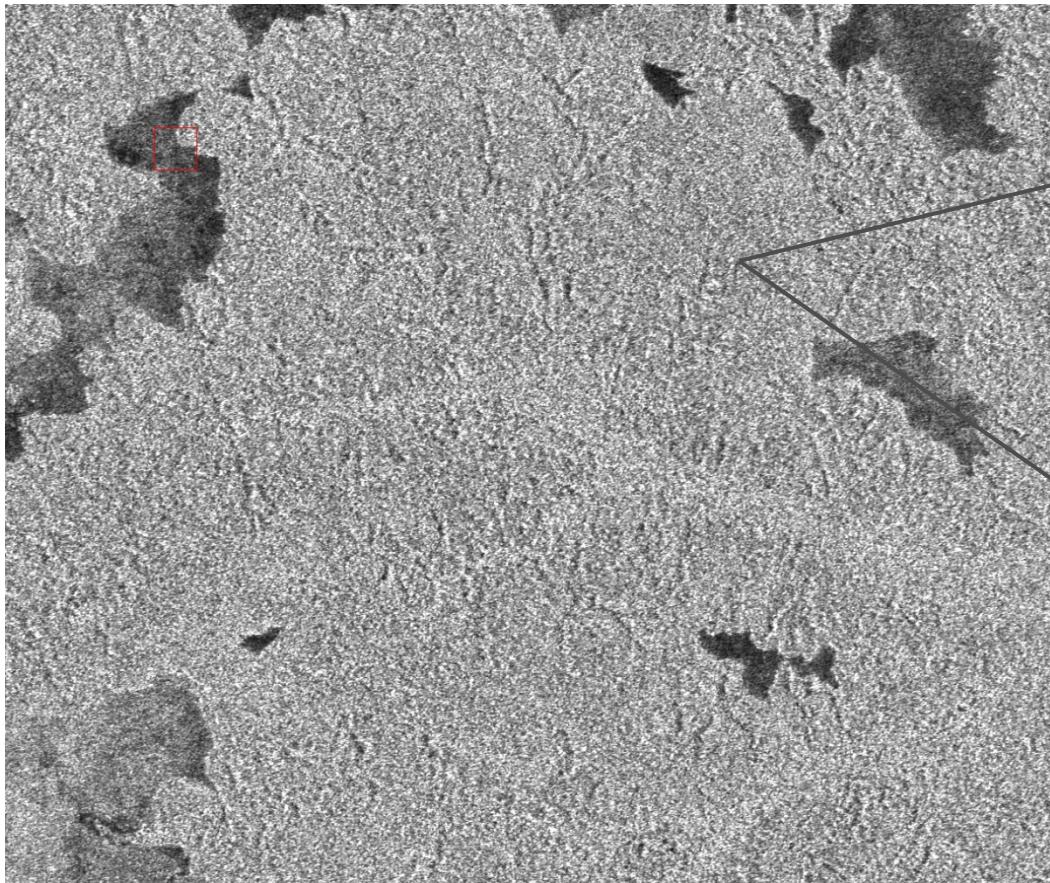
ERS Resolution ~ 25 m, pixel 12,5m

Radar Imaging - spatial resolution

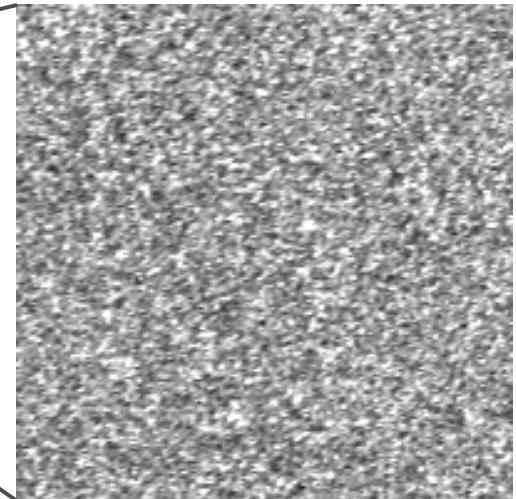


DLR airplane radar resolution ~ 3 m

Radar Imaging - spatial resolution



Radar data

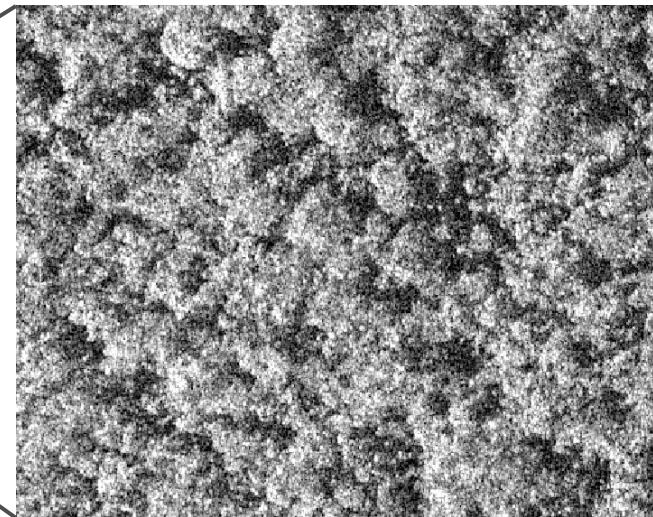


**Forest in Congo Bassin,
PALSAR,
Polar: HH,
Spat.Resolution: 20 m**

Radar Imaging - spatial resolution



Radar data

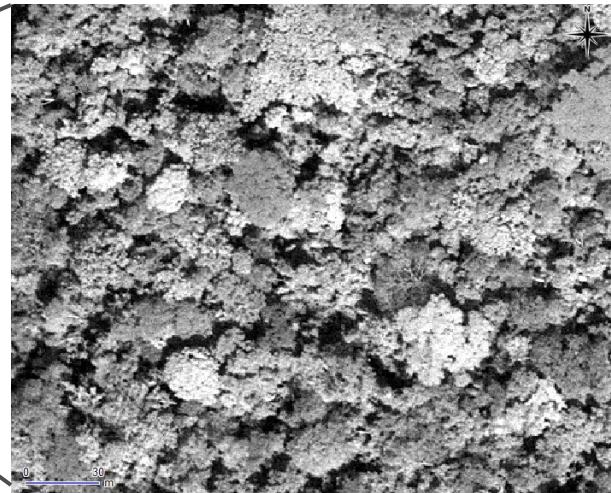


**Forest in Cameroon,
TerraSAR-X, Spot
Light,
Polar: HH,
Spat.Resolution: 1 m**

Radar Imaging - spatial resolution



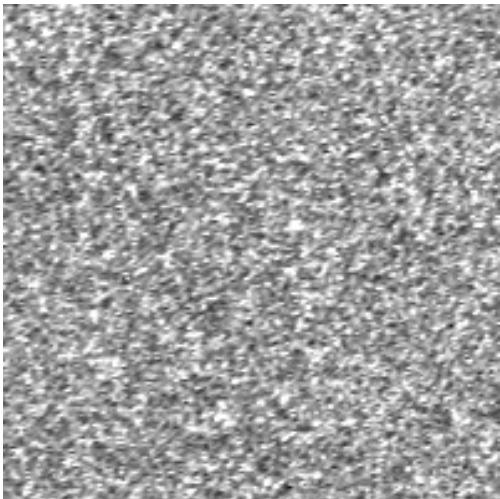
Optical data



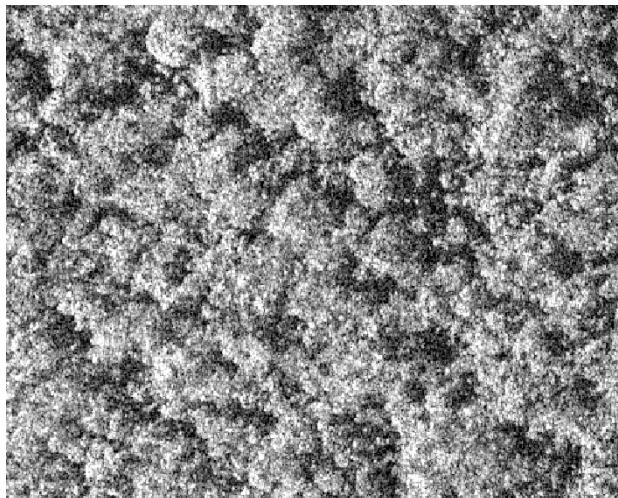
**Forest in Cameroon,
Geoeye, Panchromatic,
Spat.Resolution: 0.5 m**

Radar Imaging - spatial resolution

RADAR Data

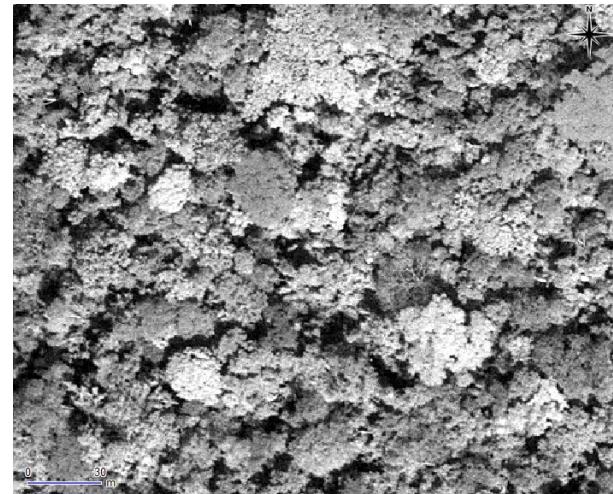


Forest in Congo Bassin,
PALSAR,
Polar: HH,
Spat.Resolution: 15 m



Forest in Cameroon,
TerraSAR-X, Spot
Light,
Polar: HH,
Spat.Resolution: 1 m

Optical Data



Forest in Cameroon,
Geoeye, Panchromatic,
Spat.Resolution: 0.5 m