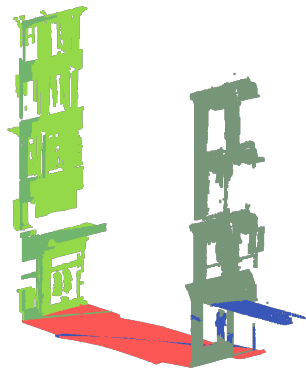
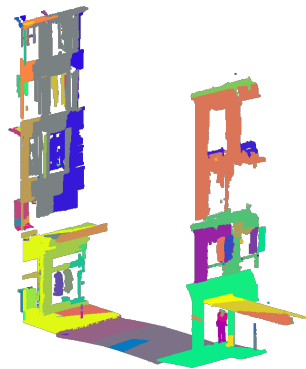


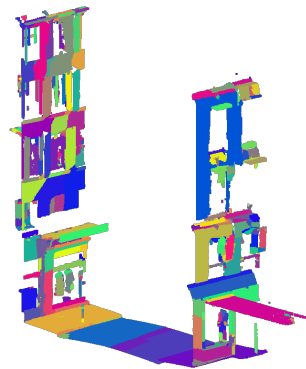
Point Cloud



Initialization



First iteration



Final segmentation