```
1 #!/usr/bin/python
 2 from common import *
 3 import pdb
 4 def p1(L):
5
       #Given:
6
      # L, a list of 1xN vectors with len(L) = M
7
      #Return:
8
      # MxN matrix of all the vectors stacked together
9
      #Par: 1 line
      #Instructor: 1 line
10
11
      #Hint: vstack/hstack/dstack, don't use a for loop
12
      P = np.vstack(L)
13
14
      return P
15
16 def p2(M):
17
       #Given:
18
      # M, a n x n matrix
19
      #Return:
20
      # v the eigenvector corresponding to the smallest eigenvalue
21
      #Par: 5 lines
22
      #Instructor: 3 lines
23
      #Hints:
24
      #
          1) np.linalg.eig
      #
25
           2) np.argmin
26
      #
          3) Watch rows and columns!
27
      wm, vm = np.linalg.eig(M)
28
      sm = np.argmin(wm)
29
      P=vm[:,sm]
30
31
      return P
32
33 def p3(M):
34
      #Given:
35
           a matrix M
36
      #Return:
37
      # M, but with all the negative elements set to 0
38
      #Par: 3 lines
39
      #Instructor: 2 lines (there's a fairly obvious one line solution -- hint
                             np.minimum/maximum/np.clip)
40
      #
      #Hint:
41
          1) if S is the same size as M and is True/False, you can refer to all
42
      #
43
          true entries via M[S]
44
      # 2) if M[S] is the set of all entries, you can assign to them all with
45
      \# M[S] = v for some value v
      P = np.clip(M, 0, np.amax(M))
46
47
48
      return P
49
50
51 def p4(t):
52
      #Given:
53
          a tuple of 3x3 rotation matrix R
54
          Nx3 matrix M
55
      #Return:
      # a Nx3 matrix of the rotated vectors
56
57
      #Par: 3 lines
58
      #Instructor: 1 line
59
      #Hint:
60
      #
           1) Applying a rotation to a vector is right-multiplying the rotation
61
      #
              matrix with the vector
62
           2) .T transposes; this may make your life easier
           3) np.dot matrix-multiplies
63
      #
64
      R, M = t #unpack
65
      P=np.dot(M,R.T)
```

```
67
        return P
 68
 69 def p5(M):
 70
        #Given:
 71
        # a NxN matrix M
 72
        #Return:
        # the upper left 4x4 corner - bottom right 4x4 corner
 73
 74
        #Par: 2 lines
        #Instructor: 1 line
 75
        #Hint:
 76
 77
            M[ystart:yend,xstart:xend] pulls out the sub-matrix
 78
                from rows ystart to (but not including!) yend
 79
                from columns xstart to (but not including!) xend
 80
        P = M[0:4,0:4]-M[-4:,-4:]
 81
 82
        return P
 83
 84 def p6(n):
 85
        #Given:
 86
        # n -- an integer
 87
        #Return:
 88
        # a nxn matrix of 1s, except the first and last 5 columns and rows are 0
 89
       #Par: 5 lines
 90
       #Instructor: 5 lines (can you make it shorter with np.zeros)
 91
        #Hints:
 92
            np.ones/np.zeros, it's ok to double-write
 93
 94
        M = np.zeros((n,n))
 95
        M[5:n-5,5:n-5] = 1
 96
 97
        return M
 98
99
100 def p7(M):
101
       #Given:
102
       # a NxF matrix M
103
        #return:
104
        # S -- the same matrix but where each row is scaled to have unit norm
       # (i.e., S[i,:] is unit norm, and S[i,j] = M[i,j]*a[i] for some a[i])
105
106
       #Par: 3 lines
107
        #Instructor: 1 line
108
       #Hints:
109
            1) The vector \mathbf{v} / ||\mathbf{v}|| is unit norm for \mathbf{v} != 0
            2) Compute the normalization factor as a Nx1 vector by N[i] = \sum_{i=1}^{n} M[i,j]^2
110
111
        #
            3) Elementwise divide a NxF matrix by a Nx1 vector -- see what happens!
        #
               (broadcasting)
112
        #
113
            4) If it won't go together -- np.expand dims or keepdims in np.sum or doing
114
               X[None,:] to add dimensions (try X[None,:] and X[None,:]) on a vector
115
      # N=np.square(N)
116
117
       # N=np.sum(M, axis=1)
       \# N = np.sqrt(N)
118
119
        \# P=M/N
120
121
        norm=np.linalg.norm(M,axis=1)
122
        norm = norm[None,:].T
123
        P = M/norm
124
125
126
        return P
127
128
129 def p8(M):
130
        #Given:
131
        # a matrix M
132
       #Return:
```

```
the same matrix but where each row is normalized to have mean 0 and std 1
133
            (i.e. mean(S[i,:]) = 0, std(S[i,:]) = 1 and S[i,j] = M[i,j]*a[i]+b[i] for some a[i],b[i])
135
        #Par: 3 lines
136
        #Instructor: 2 lines (but you can make it one)
        #Hints:
137
            1) If it won't broadcast, do np.expand dims, keepdims
138
        M-=np.mean(M,axis=1,keepdims=True)
139
        M/=np.std(M,axis=1,keepdims=True)
140
141
142
        return M
143
144 def p9(t):
145
        #Given a:
146
            query q -- (1xK)
        #
            keys k -- (NxK)
147
148
        #
            values \ v -- (Nx1)
149
        #Return
            sum_{i} exp(-||q-k_{i}||^{2}) * v[i]
150
151
        #Par: 3 lines
152
        #Instructor: 1 incomprehensible line, not written in one go
        #Hints:
153
154
            1) Again A NxK matrix and a 1xK vector go together the way you think
        #
155
               (broadcasting)
156
        #
            2) np.sum has an axis and keepdims arguments
157
        #
            3) np.exp, - and friends apply to matrices too
158
        Q, K, V = t \#unpack
159
160
        J=np.exp(-np.linalg.norm((Q-K),axis=1)**2)
161
        J = J[:,None]
162
        P=np.sum(J*V)
163
164
        return P
165
166 def p10(L):
167
        #given:
168
            a list NxF matrices of length M
169
        #return:
170
          a MxM matrix R where
            R ij = distance between the F-dimensional centroid of each matrix
171
        #Par: 12 lines
172
        #Instructor: 7 lines (there's a 9 line solution that avoids double work
173
174
        #
                     and apparently a 4 line solution too)
175
        #Hints:
176
            1) For loop over M
177
            2) Distances are symmetric, so don't double compute that
178
            3) Go one step at a time
179
        Cen = []*len(L)
180
        R = np.zeros((len(L), len(L)))
        for i in range(len(L)):
181
182
            Cen.append(np.sum(L[i],axis=0)/np.size(L[i],0))
183
184
        for i in range(len(L)):
            for j in range(len(L)):
185
186
                if j>=i:
187
                    R[i,j] = np.linalg.norm(Cen[i]-Cen[j])
188
                    R[j,i] = R[i,j]
189
190
        return R
191
192
193 def p11(M):
194
        #given:
195
            a NxF matrix M
196
        #compute the NxN matrix D
            D[i,j] = distance between M[i,:] and M[j,:]
197
            using ||x-y||^2 = ||x||^2 + ||y||^2 - 2x^T y
198
```

```
199
        #Par: 3 lines
        #Instructor: 2 lines (you can do this in one but it's wasteful compute-wise)
200
201
202
            1) If I add a Nx1 vector and a 1xN vector, what do I get?
            2) Look at the definition of matrix multiplication for the second bit
203
204
           3) transpose is your friend
205
          4) Note the square! -- square root it at the end
           5) On some computers, you may have issues with ||x||^2 + |x|^2 - 2x^Tx
206
       #
       #
207
               coming out as ever so slightly negative. Just make max(0, value) --
       #
208
               note that the distance between x and itself should be exactly 0.
209
       #
               Seems to occur on macs
210
           XNorm = np.sum(M**2,axis=1,keepdims=True)
211
212
           D_s = XNorm+XNorm.T - 2*np.dot(M,M.T)
213
          D = np.maximum(0,D s)**0.5
214
215
          return D
216
217
218 def p12(t):
       #Given:
219
220
       # a NxF matrix A
221
       # a MxF matrix B
222
       #compute the NxM matrix D
223
       #
           D[i,j] = distance between A[i,:] and B[j,:]
224
      #Par: 3 lines
225
      #Instructor: 1 line
226
       #Hints: same same but different; draw some boxes on a piece of paper
227
       A,B = t \#unpack
228
       XNorm = np.sum(A**2,axis=1,keepdims=True)
229
       YNorm = np.sum(B**2,axis=1,keepdims=True)
230
       D = np.maximum(0,XNorm+YNorm.T - 2*np.dot(A,B.T))**0.5
231
232
       return D
233
234
235 def p13(t):
236
       #Given:
       # a 1xF query vector q
237
       # NxF matrix M
238
239
       #Return:
240
       # the index i of the row with highest dot-product with q
       #Par: 1 line
241
242
       #Instructor: 1 line
243
       #Hint: np.argmax
244
       q, M = t #unpack
245
246
       ind=np.argmax(np.dot(M,q.T))
247
       return ind
248
249
250 def p14(t):
251
       #given a tuple of:
252
          X NxF matrix
       # y Nx1 vector
253
254
       #Return the w Fx1 vector such that
       #
            ||y-Xw||^2 2 is minimized
255
256
       #Par: 2 lines
257
       #Instructor: 1 line
258
       #Hint: np.linalg.lstsq or do it the old fashioned way (X^T X)^-1 X^T y
259
       X , y = t \#unpack
260
261
       W, * =np.linalg.lstsq(X,y,rcond=-1)
262
263
264
```

```
266
267
268 def p15(t):
        #Given a tuple of:
269
270
          X: Nx3 matrix
        # Y: Nx3 matrix
271
272
        #Return a matrix:
273
            C such that C[i,:] = the cross product between X[i,:] and Y[i,:]
274
       #Par: 1 line
275
       #Instructor: 1 line
276
        #Hint: np.cross and read the documentation or just try it
277
        X, Y = t \#unpack
278
        C= np.cross(X,Y)
279
280
        return C
281
282 def p16(X):
       #Given:
283
284
            a NxF matrix X
285
        #Return a Nx(F-1) matrix Y such that
286
          Y[i,j] = X[i,j] / X[i,-1]
287
       # for all i and j
       #Par: 1 line
288
289
        #Instructor: 1 line
290
        #Hint: if it doesn't broadcast, np.expand dims
291
292
        Y=X/np.expand dims(X[:,-1],axis=1)
293
294
        return Y[:,:2]
295
296 def p17(X):
297
        #Given:
298
            a NxF matrix X
299
        #Return a Nx(F+1) matrix Y such that
            Y[i,:F] = X[i,:] and
300
301
       #
            Y[i,F] = 1
302
       #Par: 1 line
303
       #Instructor: 1 lines
304
        #Hint: np.hstack, np.ones
305
306
        Y = np.hstack((X,np.ones((np.size(X,0),1))))
307
308
        return Y
309
310
311 def p18(t):
312
        #Given:
313
        # an integer n
314
        #
           a radius r
315
        # an x coordinate x
       #
316
            a y coordinate y
317
       #Return:
318
        # An nxn image I such that
319
        #
            I[i,j] = 1 \text{ if } ||[j,i] - [x,y]|| < r
       #
            I[i,j] = 0 otherwise
320
        #Par: 3 lines
321
322
        #Instructor: 2 lines
323
        #Hint:
324
            1) np.meshgrid and np.arange give you X,Y
325
            2) watch the <
326
            3) arrays have an astype method
327
        n,r,x,y = t \#unpack
328
329
        X,Y = np.meshgrid(np.arange(n),np.arange(n),sparse=True)
330
        I = ((X-x)**2 + (Y-y)**2 < r**2).astype(float)
```

return W

```
333
334
335 def p19(t):
       #Given:
336
337
           an integer n
       # a float s
338
           an x coordinate x
       #
339
      # a y coordinate y
340
341
      #Return:
342
       #
           a nxn image such that
      #
343
           I[i,j] = \exp(-||[j,i]-[x,y]||^2 / s^2)
344
      #Par: 3 lines
345
      #Instructor: 2 lines
       #Hint: watch the types -- float and ints aren't the same!
346
347
       n, s, x, y = t \#unpack
348
349
       X,Y = np.meshgrid(np.arange(n),np.arange(n),sparse=True)
350
       I = np.exp(-((X-x)**2+(Y-y)**2)/s**2)
351
352
       return I
353
354
355 \text{ def } p20(t):
356
       #Given:
357
           an integer n
358
       # a vector v = [a,b,c]
359
       #Return:
360
       #
           a matrix M such that M[i,j] is the distance from the line a*j+b*i+c=0
       #
361
       #
362
          Given a point (x,y) and line ax+by+c=0, the distance from x,y to the line
       # is given by abs((ax+by+c) / sqrt(a^2 + b^2)) (the sign tells you which side)
363
       #Par: 4 lines
364
365
      #Instructor: 2 lines
366
       #Hints:
       # np.abs works on matrices too
367
368
       n, v = t \#unpack
369
       X,Y = np.meshgrid(np.arange(n),np.arange(n),sparse=True)
370
371
       M=np.abs((v[0]*X+v[1]*Y+v[2])/np.sqrt(v[0]**2 + v[1]**2))
372
373
       return M
```

332

return I

```
[iunghuiui-MacBook-Pro:mastery_assignment ungheelee$ python3 run.py --alltests
Running p1
Running p2
Running p3
Running p4
Running p5
Running p6
Running p7
Running p8
Running p9
Running p10
Running p11
Running p12
Running p13
Running p14
Running p15
Running p16
Running p17
Running p18
Running p19
Running p20
Ran all tests
20/20 = 100.0
```

```
1 from common import *
 3
 4 def b1(M):
 5
      #Given:
      # a matrix M
 6
 7
      #Return:
 8
      # the matrix S such that S[i,j] = M[i,j]*10+100
 9
      #Hint: Trust that numpy will do the right thing
10
      S = M*10 + 100
11
12
      return S
13
14 def b2(t):
15
      #Given:
16
      # a nxn matrix M1
      # a nxn matrix M2
17
18
      #Return:
19
     # the matrix P such that P[i,j] = M1[i,j]+M2[i,j]*10
20
      #Hint: Trust that numpy will do the right thing
21
      M1, M2 = t #unpack
22
      P = M1 + M2*10
23
24
      return P
25
26 def b3(t):
27
      #Given:
28
      # a nxn matrix M1
29
      #
          a nxn matrix M2
30
      #Return:
31
      # the matrix P such that P[i,j] = M1[i,j]*M2[i,j]-10
32
      #Hint: By analogy to + , * will do the same thing
33
     M1, M2 = t #unpack
34
      P = M1*M2-10
35
36
     return P
37
38 def b4(t):
39
     #Given:
     # a nxn matrix M1
40
      # a nxn matrix M2
41
42
      #Return:
     # the matrix product M1 M2
43
44
      #Hint: Not the same as *!
45
      M1, M2 = t #unpack
46
      P = M1.dot(M2)
47
48
     return P
49
50 def b5(M):
51
     #Given:
52
      # a nxn matrix M of floats
53
     #Return:
54
      # a nxn matrix M of integers
      #Hint: astype
55
56
      # M.astype(int)
57
      M=np.int64(M)
58
59
      return M
60
61 def b6(t):
62
       #Given:
63
      # a nx1 vector M of integers
64
      # a nx1 vector D of integers
```

```
65
        #Return:
 66
        # the ratio (M/D), treating them as floats (i.e., 1/5 \Rightarrow 0.2)
        #Hint: dividing one integer by another is not the same as dividing two floats
 67
 68
        M, D = t #unpack
 69
        P=M/D
 70
 71
        return P
 72
 73 def b7(M):
 74
        #Given:
 75
        # a nxm matrix M
 76
        #Return:
       # a vector v of size (nxm)x1 containing the entries of M, listed in row order
 77
 78
        #Hint:
 79
        #
           1) np.reshape
 80
           2) you can specify an unknown dimension as -1
 81
       P = np.reshape(M, (-1, 1))
 82
 83
        return P
 84
 85 def b8(n):
 86
        #Given:
 87
       # an integer n
 88
       #Return:
 89
       # a nx(2n) matrix of ones
 90
       #Hint:
 91
           data type not understood with calling np.zeros/np.ones is guaranteed
 92
           to be an issue where you passed in two arguments, not a tuple
 93
       P = np.ones((n,2*n), dtype=float)
 94
 95
        return P
 96
 97 def b9(M):
 98
        #Given:
99
            a matrix M where each entry is between 0 and 1
100
       #Return:
       # a matrix S where S[i,j] = True if M[i,j] > 0.5
101
       #Hint: Trust python to do the right thing
102
103
       S = M > 0.5
104
105
        return S
106
107 def b10(n):
108
      #Given:
       # an integer n
109
      #Return:
110
      # the n-entry vector of 0, ..., n-1
111
       #Hint: range+np.array/np.arange
112
113
       result=np.arange(n)
114
115
       return result
116
117 def bl1(t):
      #Given:
118
       # a NxF matrix A
119
120
       #
           a Fx1 vector v
121
       #Return:
       # the matrix-vector product Av
122
123
       A, v = t
       P = A.dot(v)
124
125
126
        return P
127
128 def b12(t):
129
       #Given:
```

```
130
                                  a NxN matrix A, full rank
131
                                  a Nx1 vector v
132
                      #Return:
133
                      # the inverse of A times v: A^-1 v
134
                      A, v = t
135
                      P = np.linalg.inv(A).dot(v)
136
137
                      return P
138
139
140 def b13(t):
141
                      #Given:
142
                      #
                                 a Nx1 vector u
                      #
143
                                 a Nx1 vector v
144
                      #Return:
145
                      # the innner product u^T v
146
                      #Hint:
147
                      # .T
148
                     u, v = t
149
                      P=np.transpose(u).dot(v)
150
151
                      return P
152
153 def b14(v):
154
                      #Given:
                                  a Nx1 vector v
155
                      #Return:
156
157
                                 the L2-norm without calling np.linalg.norm
                      \#norm = (\sum_{i=1}^{N} v_{i} = 1^{N} v_{i} =
158
159
                      P = np.linalg.norm(v)
160
161
                      return P
162
163 def b15(t):
164
                      #Given:
165
                                 a NxF matrix M
                     #
166
                                 an integer i
167
                     #Return:
                     # the ith row of M
168
                     M, i = t
169
                      P = M[i,:]
170
171
172
                      return P
173
174 def b16(M):
175
                      #Given:
176
                                 a NxF matrix M
177
                      #Return:
                     #
                                 the sum of all the entrices of the matrix
178
179
                     #Hint:
180
                      # np.sum
181
                      P = np.sum(M)
182
183
                      return P
184
185 def b17(M):
                      #Given:
186
187
                      # a NxF matrix M
188
                      #Return:
                                  a N-entry vector S where S[i] is the sum along row i of M
189
                      #
190
                      #Hint:
191
                                 np.sum has an axis optional arg; note keepdims if you already know this
192
                      P = np.sum(M, axis=1)
193
194
                      return P
```

```
196 def b18(M):
197
       #Given:
198
       # a NxF matrix M
199
       #Return:
      \# a F-entry vector S where S[j] is the sum along column j of M
200
201
       #Hint: same as above
       P = np.sum(M, axis=0)
202
203
204
       return P
205
206 def b19(M):
207
       #Given:
       # a NxF matrix M
208
209
      #Return:
       # a Nx1 matrix S where S[i,1] is the sum along row i of M
210
211
       #Hint:
212
       # Watch axis, keepdims
213
      P = np.sum(M, axis=1)
214
       P = P.reshape(-1,1)
215
216
       return P
217
218
219 def b20(M):
       #Given:
220
221
       # a NxF matrix M
222
       #Return:
      # a Nx1 matrix S where S[i] is the L2-norm of row i of M
223
224
       #Hint:
225
       # Put it together
226
      P =np.linalg.norm(M,axis=1)
      P = P.reshape(-1,1)
227
228
229
     return P
```

```
[iunghuiui-MacBook-Pro:mastery_assignment ungheelee$ python3 run.py --allwarmups
Running b1
Running b2
Running b3
Running b4
Running b5
Running b6
Running b7
Running b8
Running b9
Running b10
Running b11
Running b12
Running b13
Running b14
Running b15
Running b16
Running b17
Running b18
Running b19
Running b20
Ran warmup tests
20/20 = 100.0
```