

# Chapter 35

# Approximation Algorithm

Algorithm Analysis

School of CSEE

1. Try to develop the most efficient algorithm possible
2. For sufficiently small input  $\rightarrow$  applying exponential algorithm might be O.K.
3. Restrict input  $\rightarrow$  isolate special cases that are solvable in polynomial time
4. Accept potentially incorrect solution in return for polynomial running time  $\rightarrow$  **approximation algorithm**

Given optimization problem on input of size  $n$ , let

$C^*$  = cost of optimal solution

$C$  = cost of approximation algorithm solution.

Ratio bound:  $\rho(n)$

$$\max\left\{\frac{C}{C^*}, \frac{C^*}{C}\right\} \leq \rho(n)$$

Relative error bound:  $\varepsilon(n)$

$$\frac{|C - C^*|}{C^*} \leq \varepsilon(n)$$

# Traveling salesperson problem

- Input: undirected complete graph with edge length  $c(u, v)$
- Output: a cyclic tour of minimum length that visits each vertex exactly once
- This problem is NP-hard.

# Most efficient one?

- Brute force
- Greedy : does not work
- Dynamic Programming
- Branch and Bound

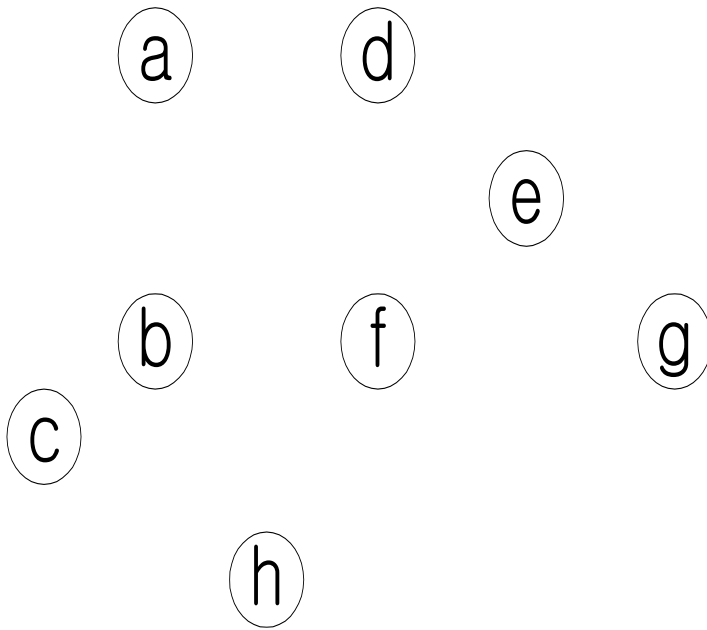
Approx-TSP-Tour( $G, c$ )

1. select a vertex  $r \in V(G)$  to be a root vertex
2. compute a minimum spanning tree  $T$  for  $G$  from root  $r$
3. let  $L$  be the list of vertices visited in a preorder tree walk of  $T$
4. **return** the hamiltonian cycle  $H$  that visits the vertices in the order  $L$

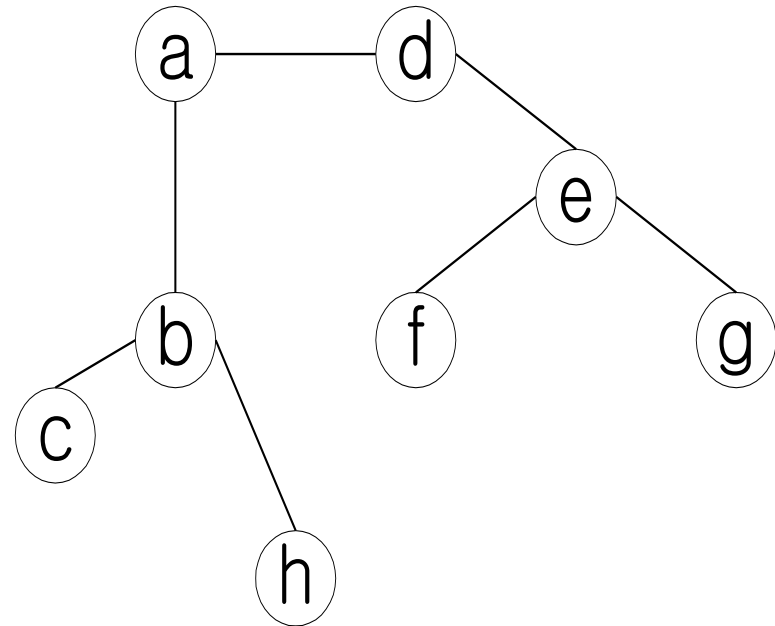
**The running time is  $\Theta(V^2)$ .**

# Example: Approx-TSP-Tour

The input graph

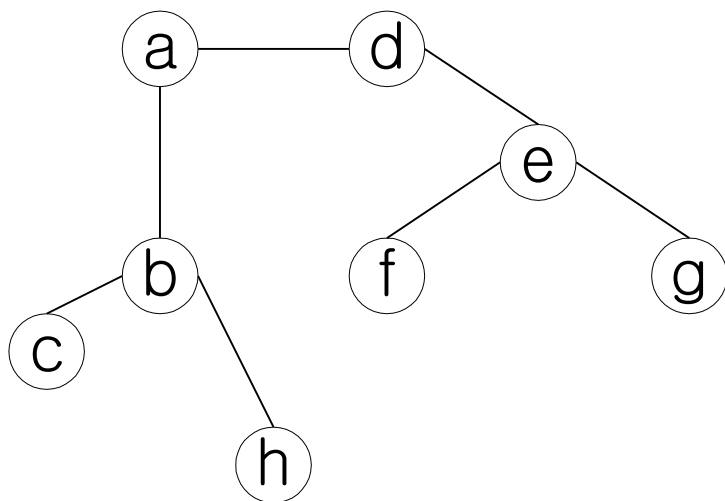


Step 1: a minimum spanning tree

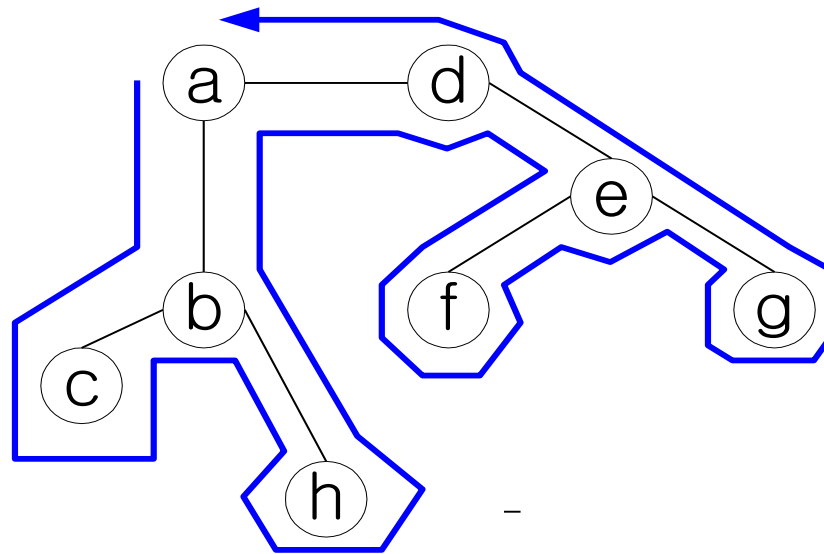


# Example: Approx-TSP-Tour

Step 1: a minimum spanning tree



Step 2: a walk of T



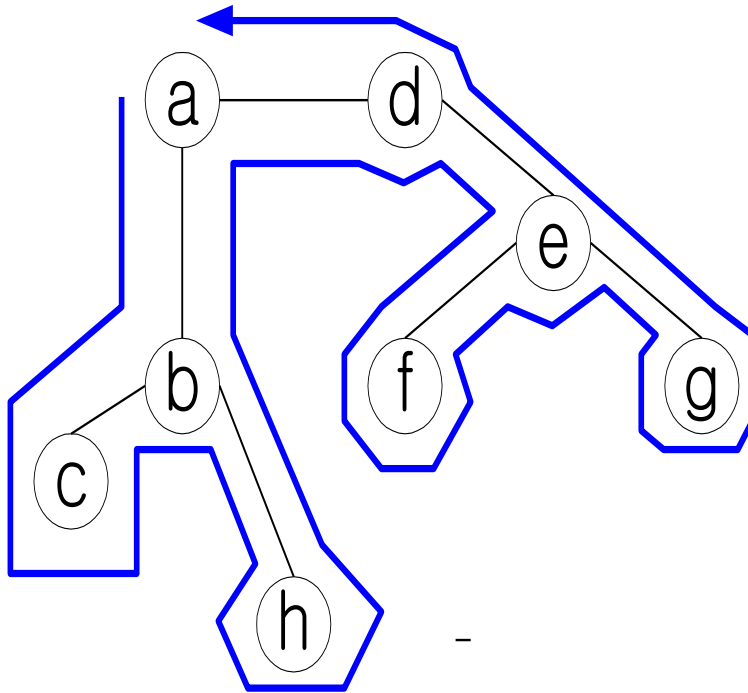
A full walk of T:

$W = \{a, b, c, b, h, b, a, d, e, f, e, g, e, d, a\}$



# Example: Approx-TSP-Tour

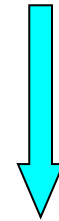
Step 2: a walk of  $T$



$W = \{a, b, c, b, h, b, a, d, e, f, e, g, e, d, a\}$

Step 3: remove from  $W$  all but the first visit to each vertex.

$W = \{a, b, c, b, h, b, a, d, e, f, e, g, e, d, a\}$

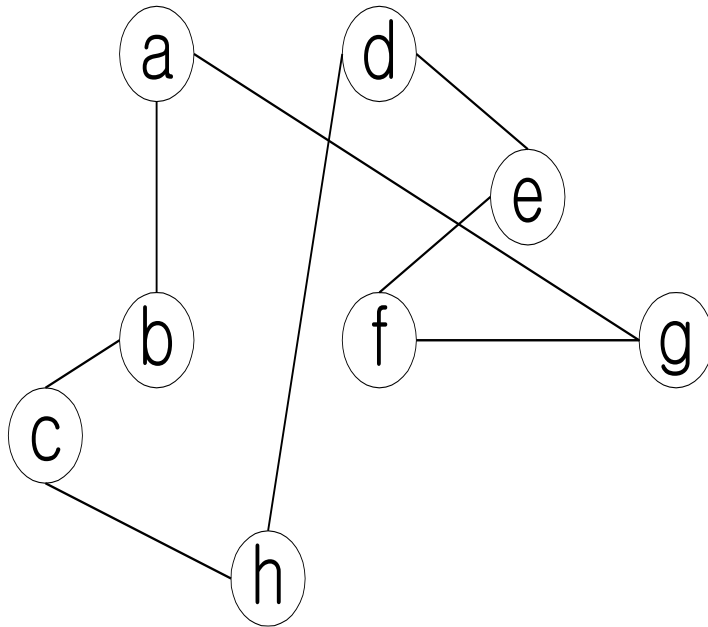


$H = \{a, b, c, h, d, e, f, g\}$   
 : preorder walk

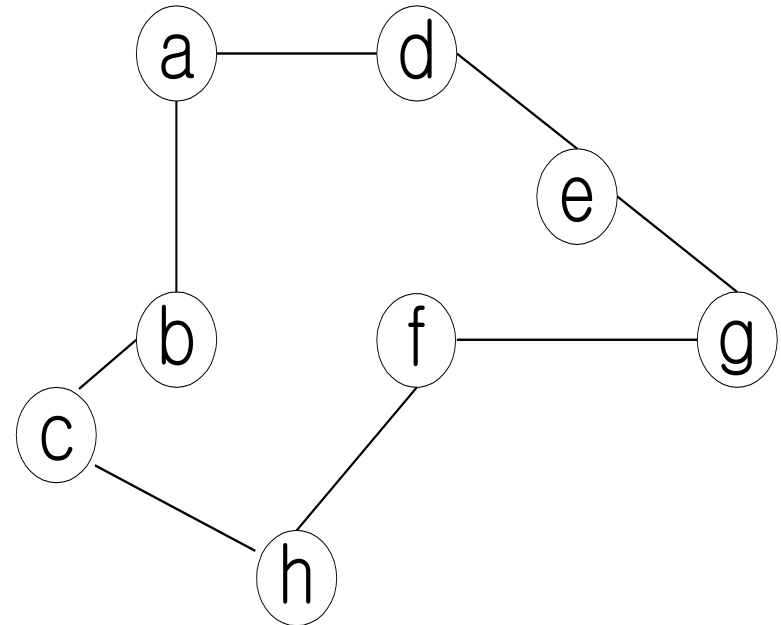
# Example: Approx-TSP-Tour

A tour by Approx-TSP-Tour

$H = \{a, b, c, h, d, e, f, g\}$



An optimal tour  $H^*$



$$c(H^*) \leq c(H) \leq 2c(H^*)$$

Approx-TSP-Tour is a polynomial-time 2-approximation algorithm for the traveling salesman problem