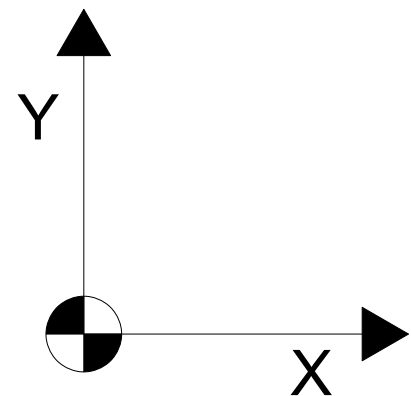
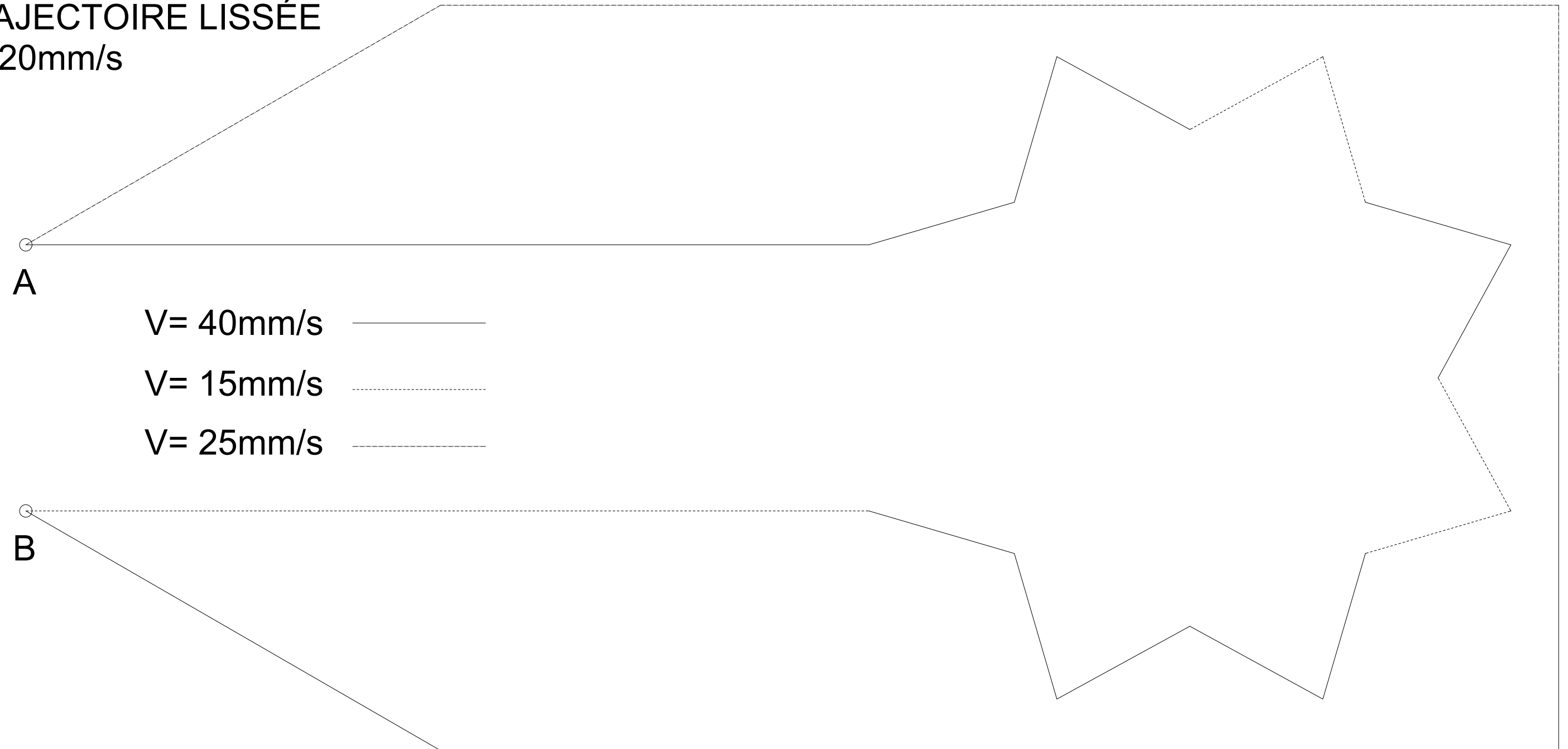


TRAJECTOIRE LISSÉE  
V= 20mm/s



ROBOTIQUE DE BASE  
TP2 - CRÉATION D'UN CHEMIN LISSÉ