

# Entanglement Spectrum Resolved by Loop Symmetries

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# Take-home messages:

We provide a **rigorous analysis** of the **entanglement structure** of pure states with non-invertible Wilson-loop symmetries described by  $\text{Rep}(G)$ .

Our framework can be extended to **topological gauge theories** in arbitrary dimensions.

It provides an expression for **topological entanglement entropy** for **arbitrary manifolds and bipartitions**.

In 2D systems, the **Li-Haldane correspondence** holds for the gapped boundary.

# Outline

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Interrupt me anytime with questions!

# **[Review] Entanglement and Quantum Phases**

# Entanglement of Pure States: Linear Algebra

We will discuss entanglement only in pure states.

## Definition 1 (Entanglement for pure states)

Divide the system into  $N$  subsystems.

The entire state  $\psi$  is **not entangled** iff it can be written as

$$|\psi\rangle = |\psi_1\rangle|\psi_2\rangle\cdots|\psi_N\rangle. \quad (1)$$

Otherwise, the state  $\psi$  is **entangled**.



How can we detect it for a given state and a given partition?

It is hard to answer this question for arbitrary  $N$ .

However, the **entanglement spectrum** is a good diagnostic in the case  $N = 2$ .

# Entanglement of Pure States: Linear Algebra

## Definition 2 (Entanglement spectrum)

Let  $\{|k_i\rangle\}$  be an orthonormal basis of subsystem  $i \in \{1, 2\}$ . Expand the state  $|\psi\rangle$  as

$$|\psi\rangle = \sum_{k_1, k_2} \psi_{k_1, k_2} |k_1\rangle |k_2\rangle. \quad (2)$$

Define a rectangular matrix  $W$  as

$$W = \sum_{k_1, k_2} \psi_{k_1, k_2} |k_1\rangle \langle k_2|. \quad (3)$$

The **entanglement spectrum**  $\{\sqrt{\lambda_j}\}$  is the set of singular values of  $W$ .



## Proposition 3

For  $N = 2$ , the state  $\psi$  is not entangled  $\Leftrightarrow \sqrt{\lambda_1} = 1, \sqrt{\lambda_{j \geq 2}} = 0$ .



# Entanglement of Pure States: Linear Algebra

In the case  $N = 2$ , the **entanglement entropy** is also of interest.

## Definition 4 (Entanglement entropy)

1. Obtain the matrix  $W$  by the procedure above.
2. Define a square matrix  $\rho$  as  $\rho = WW^\dagger$ .
3. The **entanglement entropy**  $S$  between subsystems 1 and 2 is defined as

$$S = -\text{Tr } \rho \ln \rho. \quad (4)$$



The entanglement entropy  $S$  is a diagnostic of bipartite entanglement.

## Theorem 5

For  $N = 2$ ,  $S = 0 \Leftrightarrow \psi$  is not entangled. Equivalently,  $S \neq 0 \Leftrightarrow \psi$  is entangled.



Let's apply this to quantum phases!



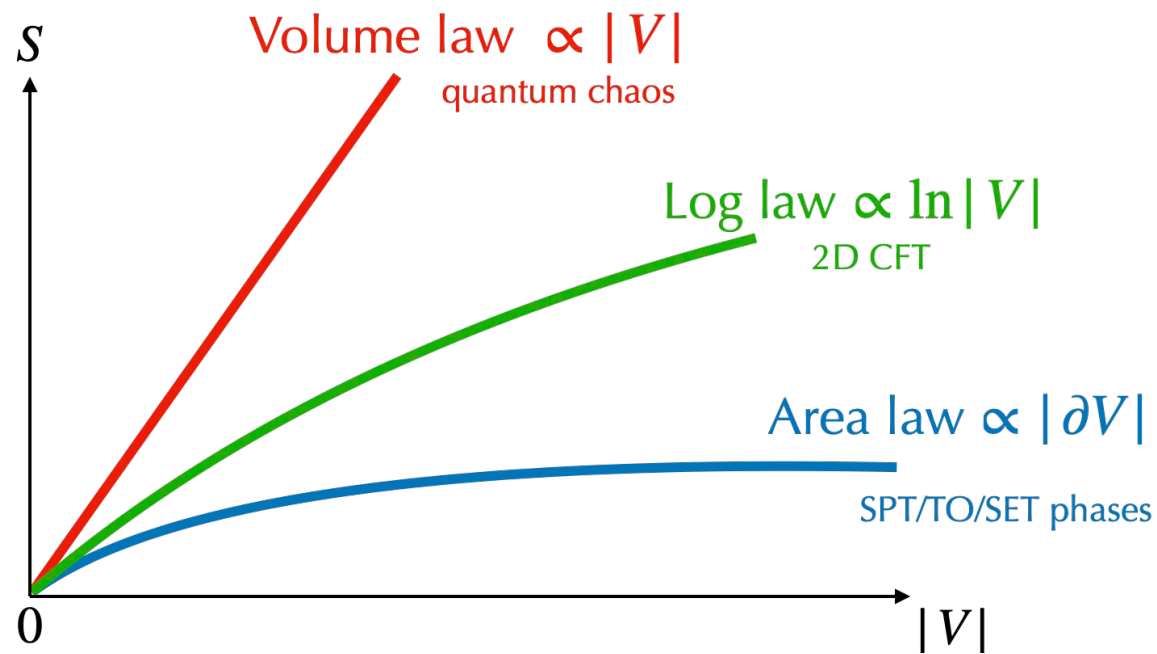
# Entanglement of Pure States: Quantum Phases

## Definition 6 (Page curve [Pag93])

The **Page curve** is a plot with the x-axis showing the subsystem volume (ratio) and the y-axis the entanglement entropy.



Its behavior is generally categorized into **area law**, **log law**, or **volume law**.



# Entanglement of Pure States: Quantum Phases

## Proposition 7 (Calabrese-Cardy formula [CC04, CC09, HLW94])

In  $(1 + 1)\mathbf{D}$  CFTs, the entanglement entropy takes the form

$$S = \frac{c}{6} \ln|V| + \dots \quad (5)$$

- $c$ : the **central charge** of the theory
- $V$ : subsystem



## Proposition 8 (Topological entanglement entropy [KP06, LW06])

In  $(2 + 1)\mathbf{D}$  TQFTs, the entanglement entropy (of connected  $\partial V$ ) takes the form

$$S = \alpha|\partial V| - \ln \mathcal{D} + \dots \quad (6)$$

- $\alpha$ : a non-universal coefficient
- $\mathcal{D}$ : the **total quantum dimension** of the theory



# Entanglement in Pure States: Resolved(?) by Symmetries

Entanglement entropy extracts important information from CFT and TQFT.

Then, can we do a similar thing for **SPT phases**? Here **symmetry** comes into play.

## Definition 9 (Group symmetry of the density matrix)

Fix a group  $G$  and a (possibly anomalous) representation  $D$ .

The density matrix  $\rho$  has  $G$  **symmetry** if  $[D(g), \rho] = 0$  for  $\forall g \in G$ .



## Proposition 10 (Symmetry-resolved entanglement)

Group symmetry **resolves** the density matrix  $\rho$  into irreducible sectors:

$$\rho = \bigoplus_{\alpha \in \text{Rep}(G)} \mathbb{1}_{d_\alpha} \otimes \rho_\alpha. \quad (7)$$



How about entanglement entropy?

# Entanglement in Pure States: Resolved(?) by Symmetries

## Remark

The entanglement entropy of SPT phases has a general expression known as **symmetry-resolved entanglement entropy**, but it **does not extract particularly important information** (e.g. topological index). See e.g. [AS20, Kus+23].

However, the entanglement spectrum **degeneracy reflects the topological class** [Pol+10, YMG25].

## Remark

Moreover, the entanglement **spectral statistics** can capture the presence of chaotic behavior in quantum many-body dynamics [GNR16].

The entanglement **spectrum** is much more **important!**

# Section Summary

## Important

Entanglement aids **extracting characteristics of quantum phases**.

## Important

**Entanglement entropy is sometimes not enough** to capture quantum phases.  
In such cases, **entanglement spectrum** may provide a good criterion.

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## Important

**Group symmetry resolves the density matrix** into irrep sectors.

However...

We encounter *generalized* symmetries in QFTs.

Do they resolve the entanglement spectrum?

And how?

# **[Review] Generalized Symmetries**

# Global Symmetry & Topological Defect

Henceforth, let  $d$  denote the spacetime dimension.

Consider a global symmetry with group  $G$ .

The following figures depict how symmetry acts in  $d = 3$ .

A coarse-grained picture of the consecutive actions of  $g, g' \in G$ :



Action on the state  $\phi$ :





# Global Symmetry & Topological Defect

Action on the operator:

$$\begin{array}{c}
 \text{Plane } U_g \\
 \downarrow \\
 \mathcal{O}(x) \bullet \\
 \uparrow \\
 \text{Plane } U_g^\dagger
 \end{array}
 =
 \bullet \mathcal{O}'(x) = U_g \mathcal{O}(x) U_g^\dagger$$

The symmetry operator can be topologically deformed:

$$\begin{array}{c}
 \text{Plane } M_{d-1} \text{ labeled } U_g \\
 \\
 \begin{array}{c}
 \text{Plane } U_g \\
 \downarrow \\
 \mathcal{O}(x) \bullet \\
 \uparrow \\
 \text{Plane } U_g^\dagger
 \end{array}
 \end{array}
 =
 \begin{array}{c}
 \text{Wavy surface } M'_{d-1} \text{ labeled } U_g \\
 \\
 \begin{array}{c}
 \text{Two hemispheres with } \bullet \text{ in center} \\
 = \\
 \text{Sphere } S^{d-1} \text{ with } \bullet \text{ in center}
 \end{array}
 \end{array}$$

# Global Symmetry & Topological Defect

Now we understand that

$$\{\text{Global Symmetry}\} \subset \{\text{Topological Defect}\}.$$

The notion of **generalized symmetry** simply identifies the two notions<sup>1</sup>:

$$\{\text{Generalized Symmetry}\} = \{\text{Topological Defect}\}.$$

- Seminal papers: [BT18, FRS02, Gai+15]
- Review papers: [Bha+23, Cho+23, McG23, Sch23, Sha24]

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<sup>1</sup>Except subsystem symmetry and modulated symmetry. Including them, the concept is a little bit enlarged as

$$\{\text{Generalized Symmetry}\} \supset \{\text{Topological Defect}\}.$$

# Global Symmetry & Topological Defect

Examples of generalized symmetry<sup>1</sup>:

***Higher-form symmetry.***

The dimension of the manifold on which the symmetry is defined is not  $d - 1$ .

***Non-invertible symmetry.***

The symmetry operators do not form a group.

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<sup>1</sup>There are also subsystem symmetry and modulated symmetry, and research has recently revived in contexts such as fractons.

# Higher-Form Symmetry

## Definition 11 ( $p$ -form symmetry)

A  $p$ -form symmetry

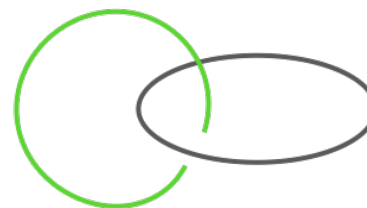
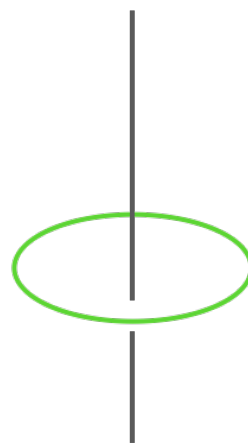
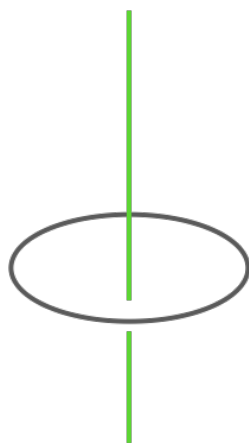
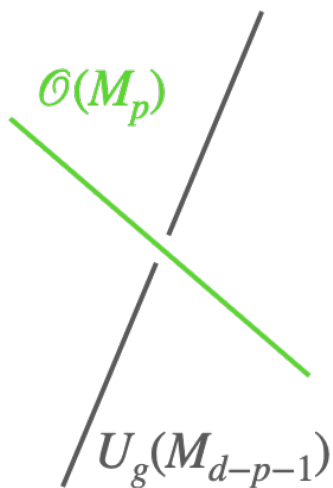
=  $(d - p - 1)$ -dimensional topological defect

= **codimension- $(p + 1)$  topological defect.**

A  $p$ -form symmetry with  $p \geq 1$  is called a higher-form symmetry.



A 1-form symmetry in a  $d = 3$  QFT:



# Higher-Form Symmetry

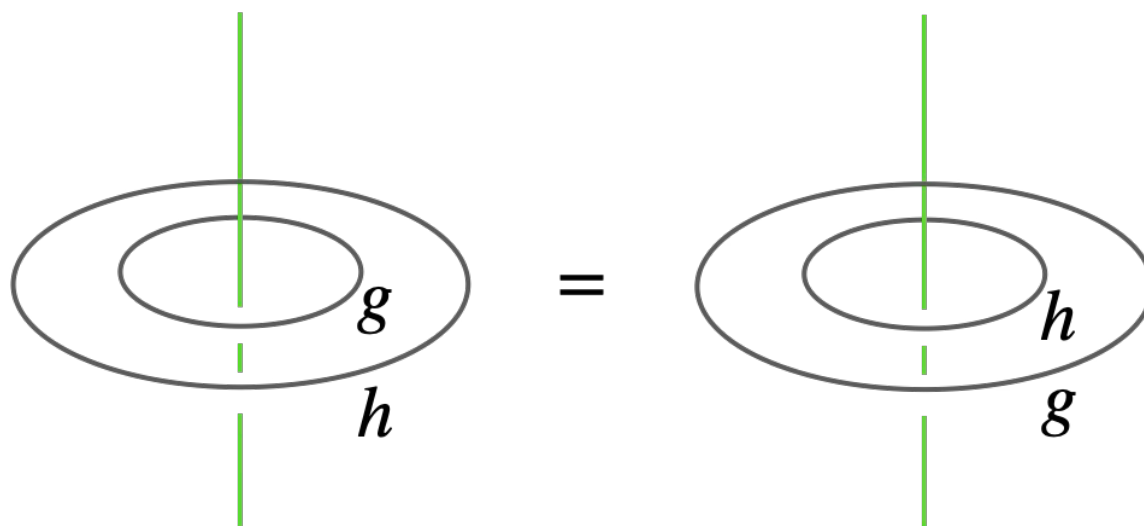
## Theorem 12

Higher homotopy groups are all Abelian.



## Corollary 12.1

Every higher-form group symmetry is Abelian.



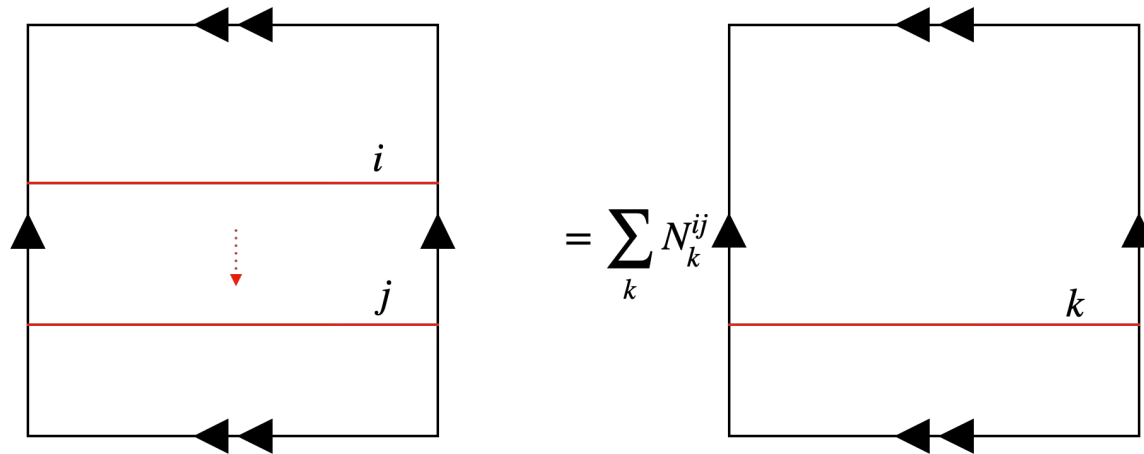
# Non-Invertible Symmetry

## Definition 13 (Non-invertible symmetry)

A symmetry whose actions **do not form a group**, but a **fusion category**.



*Example.* In 2D CFTs, the **Verlinde lines** form a non-invertible symmetry.

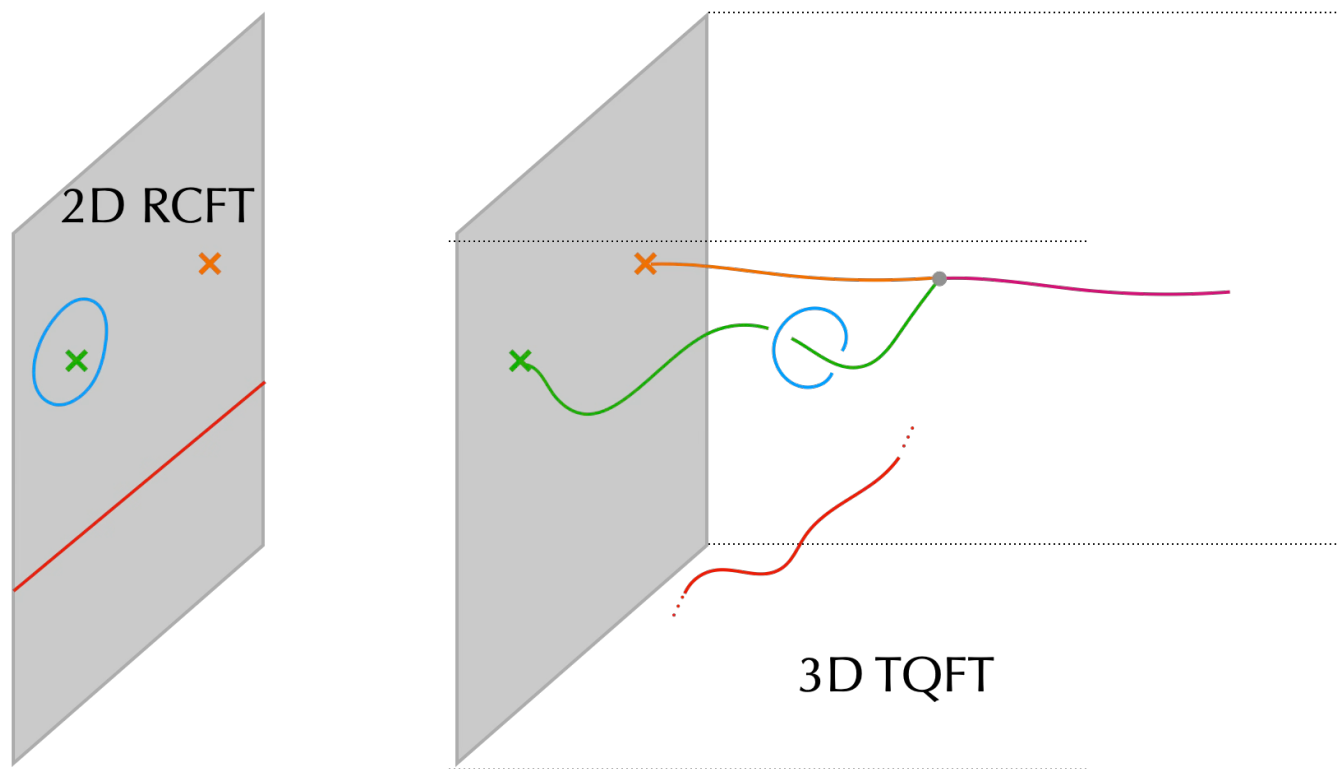


Given a modular  $S$  matrix, the fusion coefficient is given by the **Verlinde formula**:

$$N_k^{ij} = \sum_l \frac{S_{il} S_{jl} \overline{S_{lk}}}{S_{0l}}. \quad (8)$$

# Non-Invertible Symmetry

*Example.* Anyons and Verlinde lines in 2D RCFT form (generally non-invertible) **1-form symmetry** in 3D TQFT<sup>1</sup> [FMT24, FRS02, Sim23, Wit89].



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<sup>1</sup>This correspondence is called *topological holography*, *SymTFT*, *categorical symmetry*, and so on...

# Dual Theory and Dual Symmetry

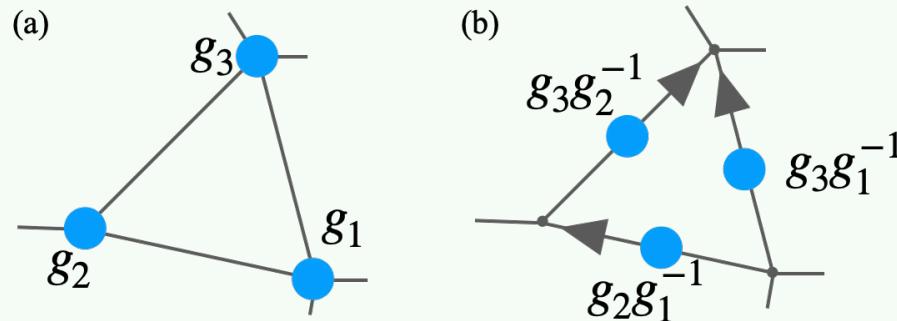
We now introduce **gauging** and **dual symmetry**, which are used in our paper. Let us start with the Kramers-Wannier transformation, which is familiar to us.

## Definition 14 (Kramers-Wannier transformation)

Fix a directed graph  $(V, E)$ . Place  $G$ -spins on each vertices in  $V$ .

A directed edge  $e \in E$  connects two vertices  $(v_e^+, v_e^-)$ .

The **Kramers-Wannier (KW) transformation** is a procedure to assign  $g_{v_e^+} g_{v_e^-}^{-1}$  to  $e$ .



This is nothing but the “**exterior derivative**”  $\delta^0 : C^0(M, G) \rightarrow C^1(M, G)$  in **non-Abelian cohomology** [Olu58].

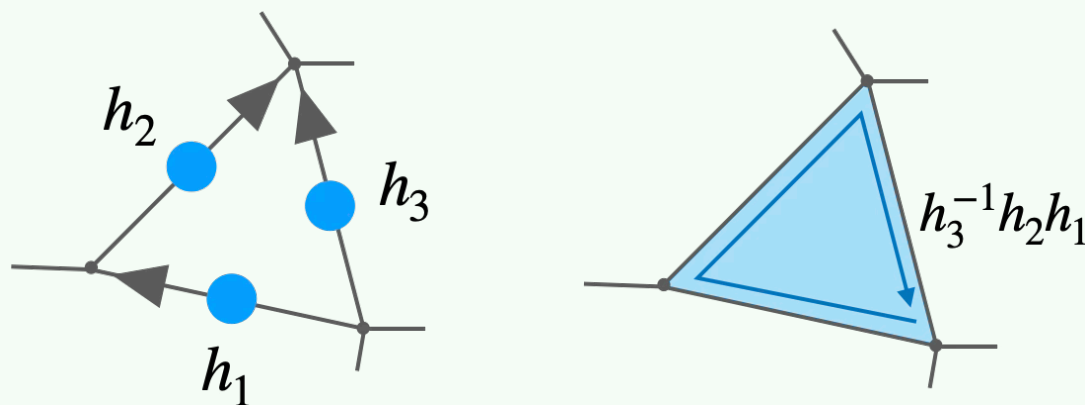




# Dual Theory and Dual Symmetry

## Definition 15

Similarly, we define the exterior derivative  $\delta^1 : C^1(M, G) \rightarrow C^2(M, G)$ :



## Remark

$$(\delta^1 \circ \delta^0)(*) = 1. \quad (9)$$

Namely, the KW transformation makes **holonomies along arbitrary loops trivial**.

# Dual Theory and Dual Symmetry

We focus on the theory of cochains  $c^1 \in C^1(M, G)$  which satisfy  $\delta^1 c^1 = 1$ :

namely, the Hilbert space dimension is the number of **cocycles**:  $\dim = |Z^1(M, G)|$ .

## Remark

Unlike the KW-transformation, the holonomies along **non-contractible loops** can be **nontrivial**. Contractible loops have trivial holonomies (called *flat* configurations).

## Remark

In such a theory, the Wilson loops are topological operators.

We call this a **loop symmetry**<sup>1</sup>.

The Wilson loops form fusion rules described by a fusion category  $\text{Rep}(G)$ .

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<sup>1</sup>Formally, this is nothing but  $(d - 2)$ -form  $\text{Rep}(G)$  symmetry.

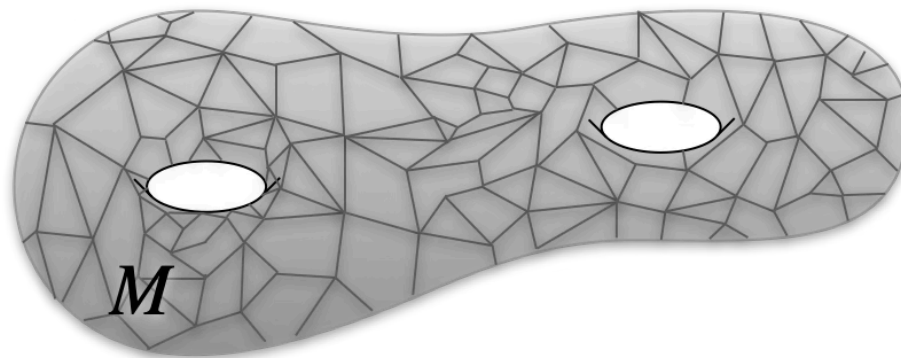
Question to be answered:

*How does the loop symmetry resolve  $W$ ?*

**[Results] Setup & General Algorithm**

# Detailed Setup - Defining the Theory

1. Fix a compact manifold  $M$  on which the theory is defined.<sup>1</sup>
2. Take a “good discretization” of  $M$  consisting of the set of vertices  $V$ , directed edges  $E$ , and plaquettes  $P$ .



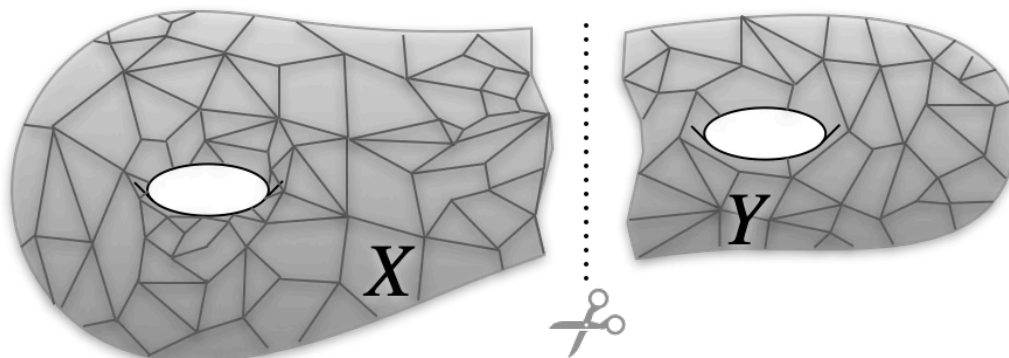
3. Fix a finite (generally non-Abelian) “gauge group”  $G$ .
4. Assign elements of  $G$  to each oriented edge to satisfy **the locally-flat condition**.
5. Take an (arbitrary) superposition of locally-flat states.

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<sup>1</sup>Although the conditions of closedness and connectivity can be relaxed remaining our result unchanged, we implicitly assume them for simplicity for now.

# Detailed Setup - Fixing the Bipartition

1. Divide  $M$  into  $X$  and  $Y$ .
2. Correspondingly, divide the set of
  - edges  $E$  into  $E_X$  and  $E_Y$ .
  - vertices  $V$  into  $V_X, V_Y$  and  $V_\partial$ .



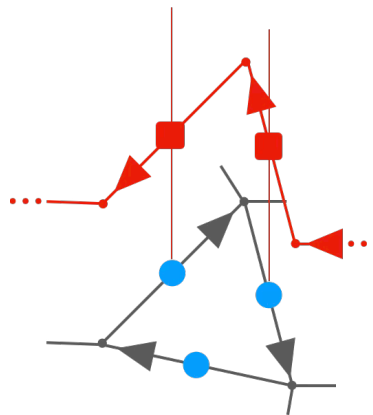
3. Place  $|G|$ -dimensional qudits ( $G$ -spins) on each directed edges.
  - The entire Hilbert space is simply the tensor product  $\mathbb{C}^{|G|^{|E|}}$ .
  - The Hilbert space for the subsystem  $X$  ( $Y$ ) is  $\mathbb{C}^{|G|^{|E_X|}}$  ( $\mathbb{C}^{|G|^{|E_Y|}}$ ).

# Detailed Setup - Imposing the Symmetry

1. Introduce a matrix product operator (MPO) whose building block is

$$\begin{array}{c} g' \\ | \\ i \leftarrow \text{red square} \rightarrow j \\ | \\ g \end{array} = D_{ij}^\alpha(g) \delta_{g,g'}$$

The MPO obeys the  $\text{Rep}(G)$  fusion rule. The MPO acts as a  $(d - 2)$ -form symmetry operator<sup>1</sup> as



<sup>1</sup>If its orientation aligns with (opposite to) that of the edge, we adopt the building block (with  $D_{ij}^\alpha(g)$  replaced by  $D_{ij}^\alpha(g^{-1})$ ).

# Detailed Setup - Imposing the Symmetry

2. Discard all states that do not make the MPO topological<sup>1</sup>.

## Theorem 16

A loop-symmetric configuration is equivalent to a flat configuration<sup>2</sup>.



3. We can expand the  $\text{Rep}(G)$  loop-symmetric many-body state as

$$|\Psi\rangle = \sum_{\{g\}_X, \{g\}_Y} \Psi_{\{g\}_X, \{g\}_Y}^{\text{flat}} |\{g\}_X\rangle |\{g\}_Y\rangle. \quad (10)$$

**Problem.** Find all the blocks and their sizes in

$$W = \sum_{\{g\}_X, \{g\}_Y} \Psi_{\{g\}_X, \{g\}_Y}^{\text{flat}} |\{g\}_X\rangle \langle \{g\}_Y|. \quad (11)$$

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<sup>1</sup>Topological deformation is now interpreted as “pulling through” move on plaquettes.

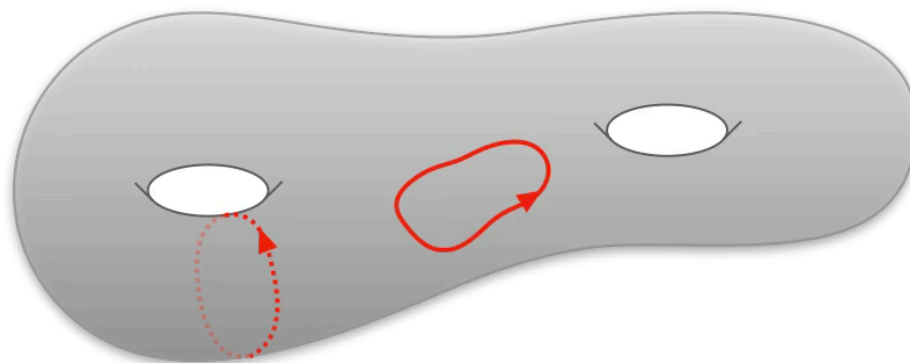
<sup>2</sup>The Appendix A in our paper [YG25] gives the proof.



## Detailed Setup - Imposing the Symmetry

### ⚠ Caution

The flatness condition admits nontrivial holonomy along non-contractible loops (the red dashed loop).



Let us explain our answer to this problem.

# Main Result: Algorithm by Category Theory

## Theorem 17 (The main result 1 of our paper)

The following commutative diagram is accompanied by the bipartition:

$$\begin{array}{ccc}
 \text{Hom}(\pi_1(M, A), G) & \xrightarrow{\Pi_X} & \text{Hom}(\pi_1(X, A), G) \\
 \Pi_Y \downarrow & & \downarrow r_X \\
 \text{Hom}(\pi_1(Y, A), G) & \xrightarrow{r_Y} & \text{Hom}(\pi_1(\partial, A), G)
 \end{array}$$

where  $A$  is the set of base points (one point per one connected component in  $\partial$ ).

Define  $\text{Im} \subset \text{Hom}(\pi_1(\partial, A), G)$  such that

$$\text{Im} = \{ \phi \mid \exists \Phi \in \text{Hom}(\pi_1(M, A), G), \phi = r_X \circ \Pi_X(\Phi) = r_Y \circ \Pi_Y(\Phi) \}. \quad (12)$$

Then, we find that  $W$  takes the form

$$W \in \left( \bigoplus_{\phi \in \text{Im}} \mathbb{C}^{|r_X^{-1}(\phi)| \times |r_Y^{-1}(\phi)|} \right) \otimes \left( \bigoplus_{j=1}^{|G|^{|V_\partial| - |A|}} \mathbb{C}^{|G|^{|V_X|} \times |G|^{|V_Y|}} \right). \quad (13)$$



# Main Result: Algorithm by Category Theory

⚠ **Absolutely my bad**

Sorry for skipping mathematical details!

Category theory is inevitable to explain our result!

Please refer to appendix or our paper.

# Main Result: Algorithm by Category Theory

It is worth remarking that:

## Corollary 17.1

The loop symmetry **does not yield degeneracies in the entanglement spectrum.**

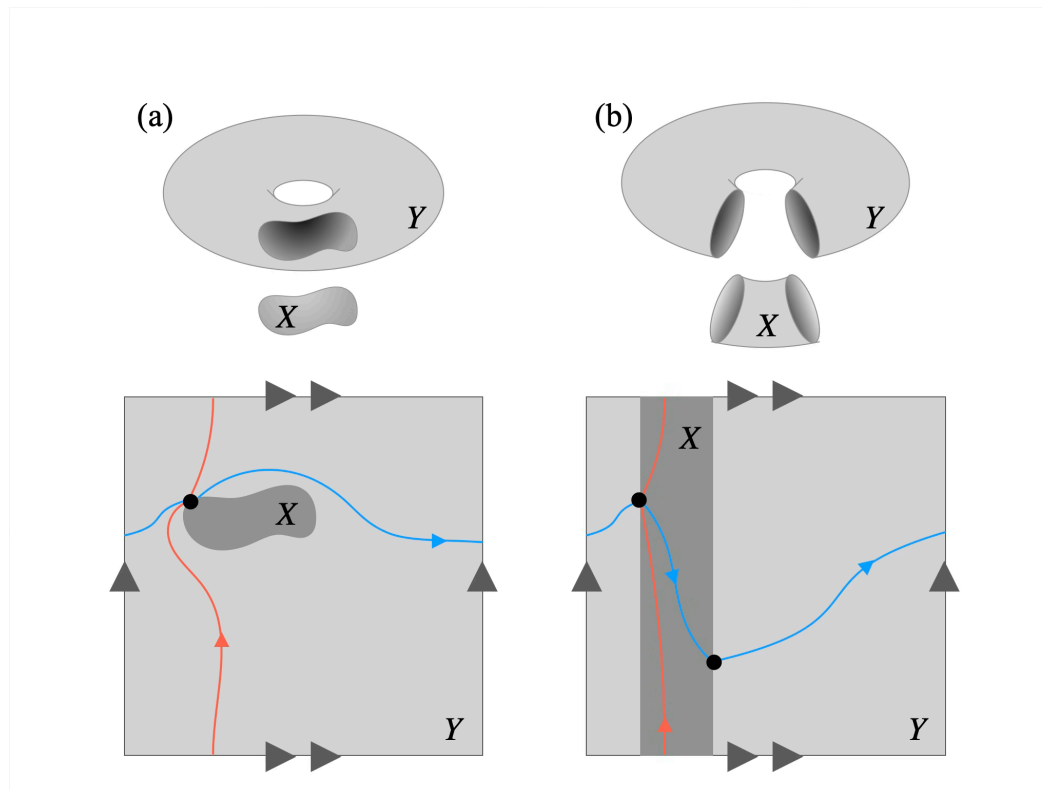


Although we can obtain such an important property, our algorithm seems conceptual. As illustrations, we see how it works in low-dimensional manifolds.

**[Results] Examples**

# Torus

There are two topologically distinct ways to bipartition the torus.



$$(a) \quad W \in \bigoplus_{j=1}^{|G|^{V_\partial|-1}} \mathbb{C}^{|G|^{V_X}|} \times |G|^{\text{Rep}(G)} |G|^{V_Y|}, \quad (b) \quad \bigoplus_{c \in G} \bigoplus_{j=1}^{|[c]| |G|^{V_\partial|-2}} \mathbb{C}^{|C_c| |G|^{V_X}|} \times |C_c| |G|^{V_Y|} \quad (14)$$

# General Orientable Surfaces

In general, closed orientable surfaces has a bipartition as follows:

$$\Sigma_{\gamma_X, n} \sqcup \sqcup^n S^1 \Sigma_{\gamma_Y, n} \mapsto \Sigma_{\gamma_X + \gamma_Y + n - 1}. \quad (15)$$

The matrix  $W$  for this is as follows:

$$W \in \bigoplus_{c \in G^{\times n}} \bigoplus_{j=1}^{|G|^{|V_\partial| - n}} \mathbb{C}^{R_{\gamma_X, n}(c) |G|^{|V_X|} \times R_{\gamma_Y, n}(c) |G|^{|V_Y|}} \quad (16)$$

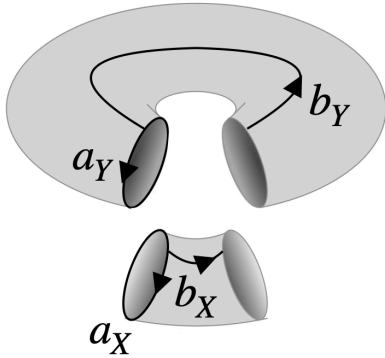
where  $R_{\gamma, n}(c)$  is defined by

$$R_{\gamma, n}(c) = \sum_{\alpha \in \text{Rep}(G)} \left( \frac{|G|}{d_\alpha} \right)^{2\gamma + n - 2} \prod_{i=1}^n \chi^\alpha(c_i). \quad (17)$$

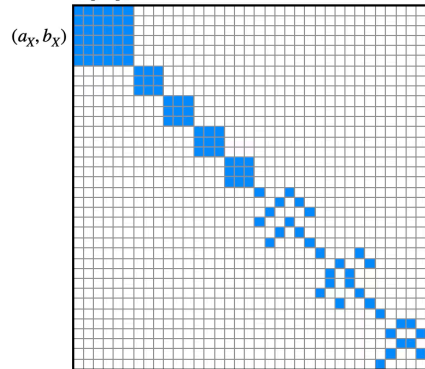
# 👊👊👊 Brute-Force Calculations 👊👊👊

Example:  $G = D_6 = \{1, r, r^2, s, sr, sr^2 \mid srs = r^2\}$

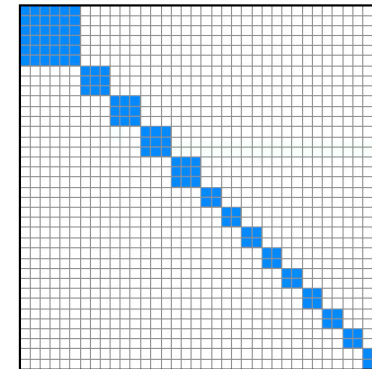
(a)



(a1)



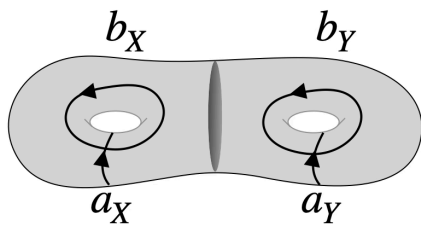
(a2)



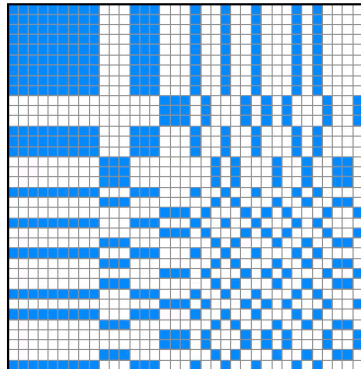
$$\blacksquare := \bigoplus_{j=1}^{|G|^{|\mathcal{V}_\partial| - |\mathcal{A}|}} \mathbb{C}^{|G|^{|\mathcal{V}_X|} \times |G|^{|\mathcal{V}_Y|}}$$

$$(\mathbb{C}^{6 \times 6} \oplus 4\mathbb{C}^{3 \times 3} \oplus 9\mathbb{C}^{2 \times 2}) \otimes \blacksquare$$

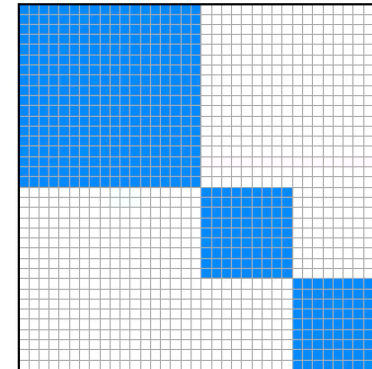
(b)



(b1)



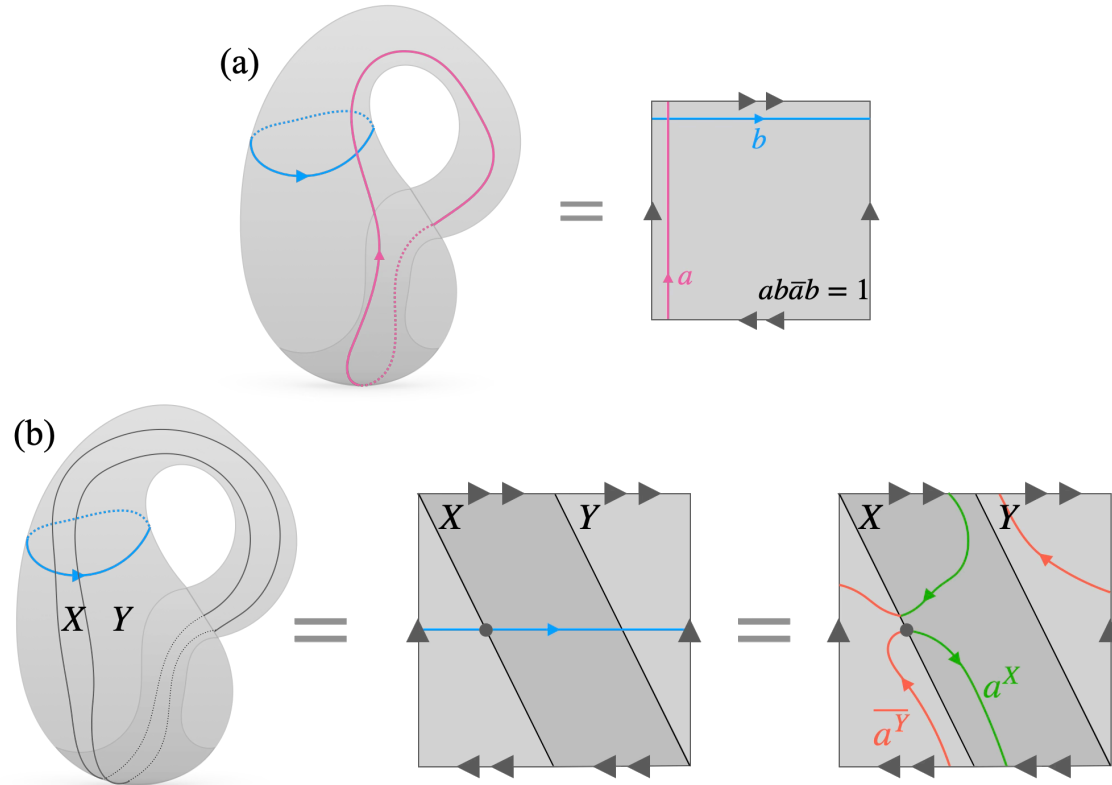
(b2)



$$(\mathbb{C}^{18 \times 18} \oplus 2\mathbb{C}^{9 \times 9}) \otimes \blacksquare$$



# The Klein bottle = Möbius band + Möbius band



$$\bigoplus_{c \in G} \bigoplus_{j=1}^{|G|^{V_\partial}-1} \mathbb{C}^{K(c) |G|^{V_X} \times K(c) |G|^{V_Y}}, \quad K(c) = \sum_{\alpha \in \text{Rep}(G)} \iota^\alpha \chi^\alpha(c) \quad (18)$$

# General Non-Orientable Surfaces

The difference between the orientable and non-orientable cases lies in the presence of the **Frobenius–Schur indicator**.

$$\iota^\alpha = \frac{1}{|G|} \sum_{g \in G} \chi^\alpha(g^2). \quad (19)$$

This indicator is related to time-reversal symmetry in TQFTs<sup>1</sup>.

Please refer to our paper [YG25] for explicit formulas for the block sizes.

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<sup>1</sup>See e.g. [Bar+20, FRS04, LT18, Ori25a, Ori25b, TY17].

# The Heegaard Splitting of 3-mfds

## Theorem 18 (Heegaard splitting)

Every compact, oriented 3-manifold can be obtained by gluing two genus- $\gamma$  handlebodies via Dehn twists.



Computing the gluing map becomes computationally hard for  $\gamma \geq 2$ .

We focus on the cases  $\gamma = 0, 1$ .

The case  $\gamma = 0$  is topologically trivial:

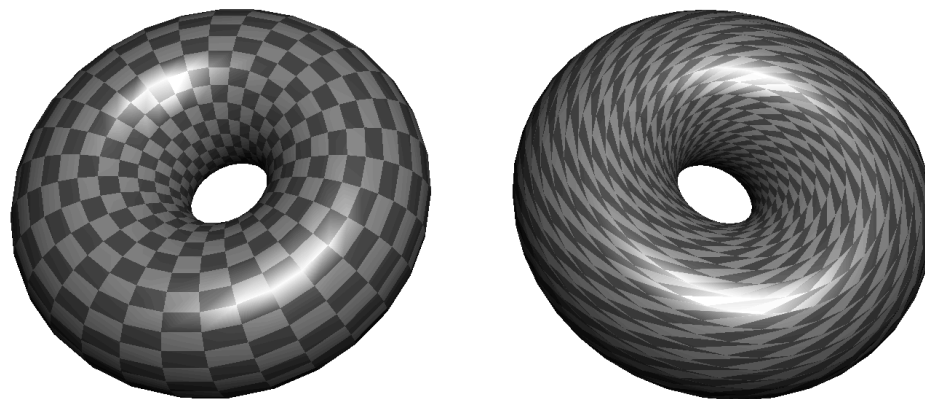
$$|\text{Im}| = |r_X^{-1}(\phi)| = |r_Y^{-1}(\phi)| = 1. \quad (20)$$

How about the case  $\gamma = 1$ ?

# Genus-1 Heegaard Splitting

Genus-1 Heegaard splitting

= precisely aligning and identifying the meshes drawn on the two tori:



namely, the **modular group**  $\mathrm{SL}(2, \mathbb{Z})$  describes the mapping:

$$\begin{pmatrix} p & r \\ q & s \end{pmatrix}, \quad ps - qr = 1, \quad p, q, r, s \in \mathbb{Z}. \quad (21)$$

# Genus-1 Heegaard Splitting

Define the **higher Frobenius-Schur indicator**  $\nu_n^\alpha$  as

$$\nu_n^\alpha = \frac{1}{|G|} \sum_{g \in G} \chi^\alpha(g^n). \quad (22)$$

Then, the  $W$  matrix takes the form

$$W \in \bigoplus_{\phi=1}^{\sum_{\alpha \in \text{Rep}(G)} d_\alpha \nu_q^\alpha} \bigoplus_{j=1}^{|G|^{|V_\partial| - |A|}} \mathbb{C}^{|G|^{|V_X|} \times |G|^{|V_Y|}}. \quad (23)$$

Note that **only**  $q$  enters the result and the **preimages have size 1**.

# The $n$ -Dimensional Torus

We computed the  $n$ -dimensional torus as an example of a higher-dimensional manifold.

**The setting:**

$$M = \mathbb{T}^n = (S^1)^n, \quad X = [0, \pi]^{\times k} \times (S^1)^{\times (n-k)}. \quad (24)$$

**The result:<sup>1</sup>**

$$W \in \bigoplus_{\phi \in \text{Comm}_{n-1}(G)} \bigoplus_{j=1}^{||[\phi]||G|^{|V_\partial|-2}} \mathbb{C}^{|C_\phi||G|^{|V_X|} \times |C_\phi||G|^{|V_Y|}} \quad (k=1), \quad (25)$$

$$W \in \bigoplus_{\phi \in \text{Comm}_{n-k}(G)} \bigoplus_{j=1}^{|G|^{|V_\partial|-1}} \mathbb{C}^{|G|^{|V_X|} \times |\text{Comm}_k(C_\phi)||G|^{|V_Y|}} \quad (k \geq 2).$$

It is interesting that  $k=1$  is the exceptional case.

---

<sup>1</sup>We defined as  $\text{Comm}_m(G) = \{(g_1, \dots, g_m) \in G^{\times m} | g_i g_j = g_j g_i \text{ for } \forall i, j = 1, \dots, m\}$ .

The part 1 is now complete.

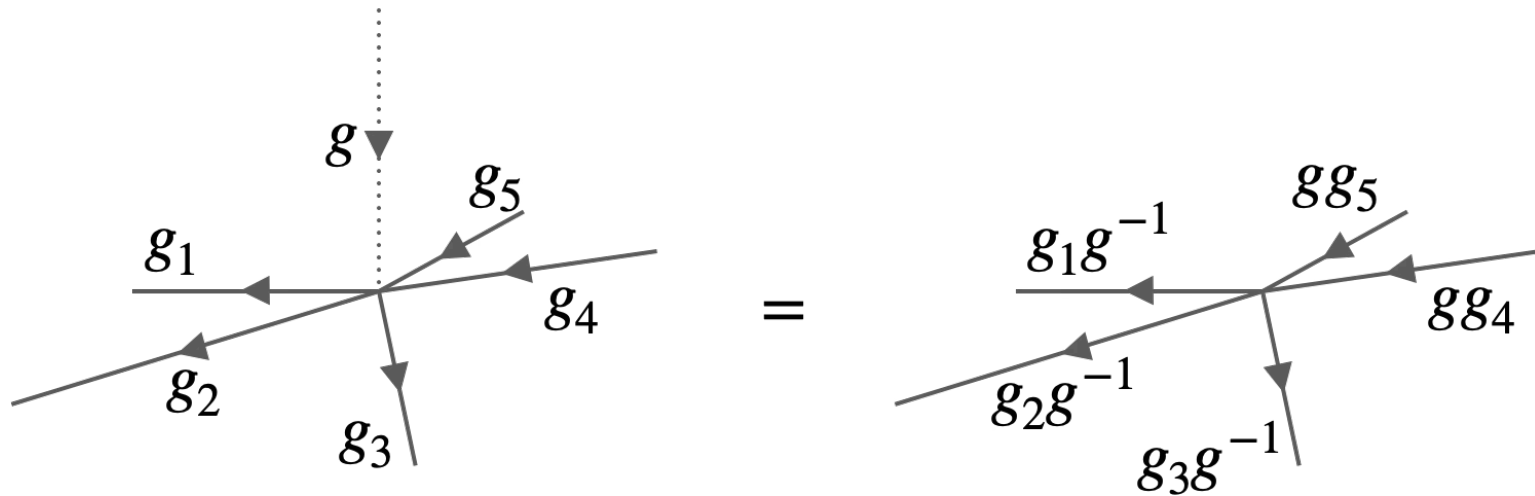
Do you have any questions?

## **[Results] Topological Entanglement**



# Gauge Invariance and Topological Gauge Theory

Graph gauge transformation:



## 💡 Topological Gauge Theory

Making the state gauge-invariant leads us to **topological gauge theory**.

$$|\Psi\rangle \mapsto \sum_{\{\text{gauge transf.}\}} \text{gauge transf.} \triangleright |\Psi\rangle \quad (26)$$

# Gauge Invariance and Topological Gauge Theory

The Hilbert space dimension of a topological gauge theory is a topological invariant:

$$\dim = |\mathrm{Hom}(\pi_1(M), G)/G|. \quad (27)$$

Here,  $*/G$  means identification up to conjugacy:  $a \sim gag^{-1}$ .

This reflects the Wilson loop is defined up to conjugacy classes.

**Problem.** Find all the blocks and their sizes in  $W$  of topological gauge theory

$$W = \sum_{\{g\}_X, \{g\}_Y} \Psi_{\{g\}_X, \{g\}_Y}^{\mathrm{flat}+\mathrm{gauge}} |\{g\}_X\rangle \langle \{g\}_Y|. \quad (28)$$

# Block Structure and Degeneracies

## Theorem 19 (The main result 2 of our paper)

The gauge-invariant  $W$  takes the form

$$\bigoplus_{[\phi] \in \text{Im } /G^{\times|A|}} \mathbb{1}_{|[\phi]|} \otimes \left( \bigoplus_{\alpha_{[\phi]}} \mathbb{C}^{x_{\alpha_{[\phi]}} \times y_{\alpha_{[\phi]}}} \otimes \mathbb{1}_{d_{\alpha_{[\phi]}}} \right) \otimes \bigoplus_{j=1}^{|G|^{|V_{\partial}| - |A|}} \mathbb{1}_{|G|^{|V_X|} \times |G|^{|V_Y|}}, \quad (29)$$

where

- $\alpha_{[\phi]}$  is an irrep of the stabilizer group  $G_{[\phi]}$  on  $[\phi]$ ,
- $\mathbb{1}_{|G|^{|V_X|} \times |G|^{|V_Y|}}$  is the all-ones matrix of size  $|G|^{|V_X|} \times |G|^{|V_Y|}$ ,
- $x_{\alpha_{[\phi]}} = \frac{1}{|G_{[\phi]}|} \sum_{\mathbf{g}_{[\phi]} \in G_{[\phi]}} \chi^{\alpha_{[\phi]}}(\mathbf{g}_{[\phi]}) \text{Tr } D_{[\phi]}^X(\mathbf{g}_{[\phi]})$  and  $y_{\alpha_{[\phi]}}$  is similarly defined.



# Topological Entanglement Entropy for General Manifolds and Bipartitions

## Corollary 19.1

The entanglement spectrum is  $|\phi|$   $d_{\alpha_{[\phi]}}$ -fold degenerate.



## Corollary 19.2 (General expression of topological entanglement entropy)

The entanglement entropy for an arbitrary manifold/bipartition<sup>1</sup> is given by

$$S = |V_{\partial}| \ln|G| - |A| \ln|G| - \sum_{[\phi] \in \text{Im } /G^{\times|A|}} |\phi| \sum_{\alpha_{[\phi]} \in \text{Rep}(G_{[\phi]})} d_{\alpha_{[\phi]}} \sum_{i=1}^{x_{\alpha_{[\phi]}}} \frac{|\psi_{\alpha_{[\phi]},i}|^2}{\mathcal{N}} \ln \frac{|\psi_{\alpha_{[\phi]},i}|^2}{\mathcal{N}}, \quad (30)$$

where  $\mathcal{N}$  is the normalization constant.



---

<sup>1</sup>To the best of my knowledge, no specific representation of entanglement entropy for 1-form non-Abelian topological gauge theory on a general manifold with a general partition was known.

# Verifying the Li-Haldane Conjecture in the Kitaev Quantum Double Model

## Proposition 20 (Li-Haldane conjecture [LH08])

The **entanglement** spectrum in **3D TQFT**  $\sim$  the **energy** spectrum of the **2D RCFT**.



## Definition 21 (Kitaev quantum double model)

The **Kitaev quantum double model** [Kit97] is a finite- $G$  topological gauge theory on a discretized 2D space.



# Verifying the Li-Haldane Conjecture in the Kitaev Quantum Double Model

## Corollary 21.1 (the Li-Haldane correspondence)

In the Kitaev quantum double model in 2D orientable surface  $\Sigma_{\gamma_X, n}$ ,  $x_{\alpha_{[\phi]}}$  given in our paper turns out to be

$$x_{\alpha_{[\phi]}} = \sum_{[g] \in G_{[\phi]}} \sum_{\beta \in \text{Rep}(C_{[g]})} S_{([g], \beta), (1, 1)}^{-2\gamma_X - n + 2} \prod_{j=1}^n S_{([g], \beta), (c_j, \alpha_j)}, \quad (31)$$

where  $S$  is the modular  $S$  matrix for finite group [CGR00].

This expression equals **the dimension of the conformal block in 2D RCFT** holographically dual to the Kitaev quantum double model [MS89, MS90].

This correspondence holds even when we define the Kitaev quantum double model in **non-orientable surfaces** [Bar+20].

The same holds for  $Y$ .



# Verifying the Li-Haldane Conjecture in the Kitaev Quantum Double Model

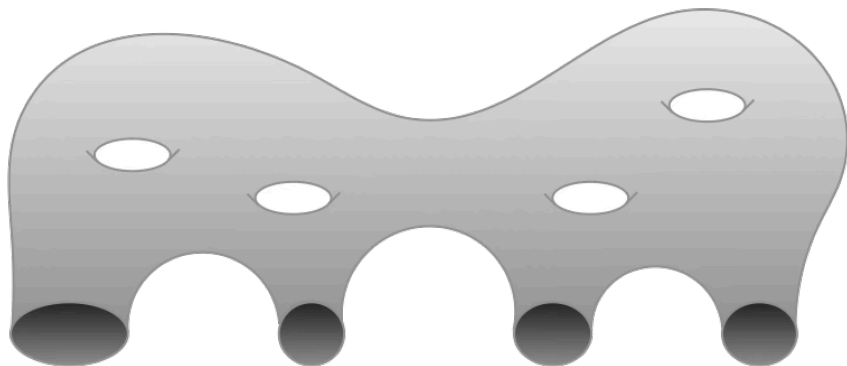
- For  $X = \Sigma_{0,1}$ , we find  $x_{\alpha_{[\phi]}} = \delta_{[c],1} \delta_{\alpha_{[c]},1}$ .
  - **Only vacuum** can live in  $X$ .
- For  $X = \Sigma_{0,2}$ , we find  $x_{\alpha_{[\phi]}} = \delta_{[c_1],[c_2^{-1}]} \delta_{\alpha_{[c_1]},\overline{\alpha_{[c_2]}}}$ .
  - The subsystem  $X$  is the **identity** of anyons.
- For  $X = \Sigma_{0,3}$ , we find

$$\begin{aligned}
 x_{\alpha_{[\phi]}} &= \sum_{[g],\beta_{[g]}} \frac{S_{([g],\beta_{[g]}),([c_1],\alpha_{[c_1]})} S_{([g],\beta_{[g]}),([c_2],\alpha_{[c_2]})} S_{([g],\beta_{[g]}),([c_3],\alpha_{[c_3]})}}{S_{([g],\beta_{[g]}),(1,1)}} \\
 &= N_{([c_1],\alpha_{[c_1]}),([c_2],\alpha_{[c_2]})}^{([c_3^{-1}],\overline{\alpha_{[c_3]}})}.
 \end{aligned} \tag{32}$$

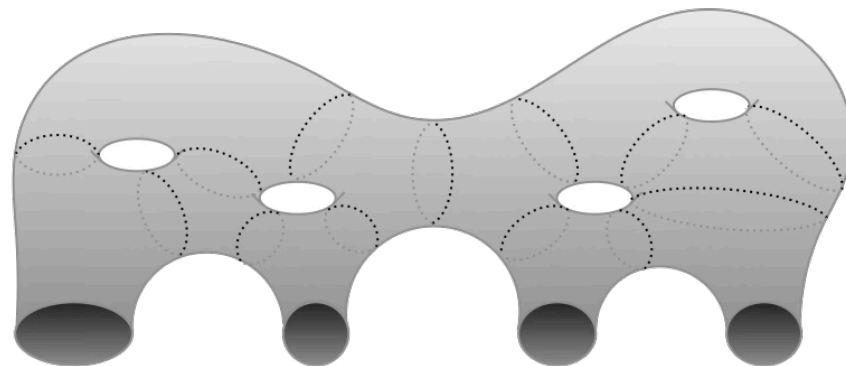
- Only the fusion following the **Verlinde formula** is allowed.
- For  $X = \Sigma_{0,4}$ , we find  $x_{\alpha_{[\phi]}} = \sum_m N_m^{ij} N_m^{\overline{kl}} = \sum_m N_m^{i\overline{k}} N_m^{j\overline{l}}$ .
  - The **F-move is trivial**.
- For general orientable surfaces,

# Verifying the Li-Haldane Conjecture in the Kitaev Quantum Double Model

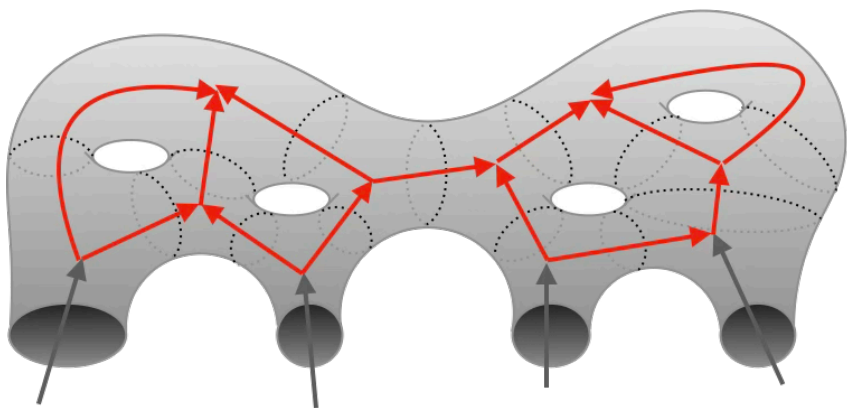
(a1)



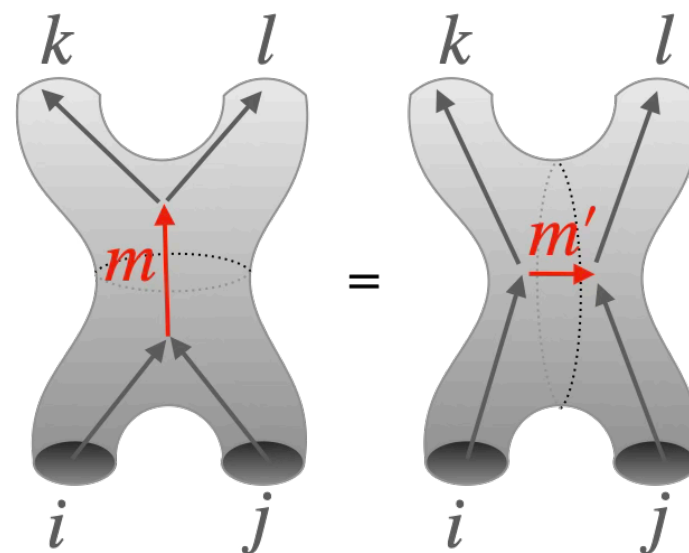
(a2)



(a3)



(b)





# Summary and Outlook

1. We explored the entanglement structure in **non-invertible loop-symmetric quantum many-body states**.
  - We developed a **categorical framework** to determine the entanglement.
  - We applied our result to **many examples**.
2. We explored the entanglement structure in **topological gauge theories in arbitrary dimensions**.
  - We found a **general formula of topological entanglement entropy**.
  - We verified the **Li-Haldane correspondence of gapped boundary version**.

The next step would be...

- multipartite entanglement,
- other generalized symmetries, or
- anomalous theories.

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Thank you for your attention!

**[Appendices]**

# Category Theory

## Definition 22 (Category of manifolds)

The category  $\mathbf{Mfd}$  is a category of manifolds.

The objects are manifolds. The morphisms are the continuous map.



## Definition 23 (Groupoid)

A **groupoid**<sup>1</sup>  $\mathcal{G}$  is a non-empty set with a product, satisfying

- associativity of the product,
- existence of identity, and
- existence of inverse.

However, **the product is NOT defined on all pairs**  $\forall (g_1, g_2) \in \mathcal{G} \times \mathcal{G}$ .



---

<sup>1</sup>The Wikipedia of groupoid is really misleading: do not confuse groupoid with the **magma**.

# Category Theory

## Definition 24 (Fundamental groupoid)

Fix a manifold and a set of base points  $A$ . The **fundamental groupoid** of  $M$  about the base points  $A$  is a groupoid consists of the homotopically equivalent classes of paths connecting base points and product defined by the path concatenation.



## Definition 25

A category  $\mathbf{Grpd}$  is a category of groupoids.

The objects are groupoids. The morphisms are the homomorphisms.



## Definition 26

A category  $\mathbf{Set}$  is a category of sets.

The objects are sets. The morphisms are the maps.





# Mathematics of Our Framework

The splitting can be captured by the commutative diagram in Mfd.

$$\begin{array}{ccc} M & \longleftarrow & X \\ \uparrow & & \uparrow \\ Y & \longleftarrow & \partial \end{array}$$

## Theorem 27 (Seifert-van Kampen theorem)

If one base point per one connected component in  $\partial$ , the commutative diagram above can be sent to the category of fundamental groupoids as follows.

$$\begin{array}{ccc} \pi_1(M, A) & \xleftarrow{p_X} & \pi_1(X, A) \\ \uparrow p_Y & & \uparrow i_X \\ \pi_1(Y, A) & \xleftarrow{i_Y} & \pi_1(\partial, A) \end{array}$$



## Proposition 28

Hereafter,  $\text{Hom}(*, G) : \text{Grpd} \rightarrow \text{Set}$  denotes the set of homomorphisms from  $*$  to  $G$ . This is a contravariant functor, which sends limits (colimits) to colimits (limits).

We can consider this as “consistent coloring by  $G$ ”. Then, the commutative diagram used in our result is reproduced.

$$\begin{array}{ccc}
 \text{Hom}(\pi_1(M, A), G) & \xrightarrow{\Pi_X} & \text{Hom}(\pi_1(X, A), G) \\
 \Pi_Y \downarrow & & \downarrow r_X \\
 \text{Hom}(\pi_1(Y, A), G) & \xrightarrow{r_Y} & \text{Hom}(\pi_1(\partial, A), G)
 \end{array}$$

To make sure the holonomies are consistent after gluing  $X$  and  $Y$  to  $M$ , we focus on

$$\text{Im} = \{\phi \mid \exists \Phi \in \text{Hom}(\pi_1(M, A), G), \phi = r_X \circ \Pi_X(\Phi) = r_Y \circ \Pi_Y(\Phi)\}. \quad (33)$$