EE141 Digital Signal Processing (Fall 2003) Solution Manual

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Text: A.V. Oppenheim, R.W. Schafer, and J. R. Buck, *Discrete-Time Signal Processing*, 2nd edition, Prentice-Hall, 1999.

HW#1: P2.1 (a), (c), (e), (g); P2.4; P2.24 HW#2: P2.5; P2.18; P2.29 (a), (c), (e) HW#3: P2.40; P2.41; P3.27 (a), (c) HW#4: P3.6 (d), (e); P3.20; P4.1; P4.3 HW#5: P4.5; P4.7; P5.2; P5.3 HW#6: P5.10; P5.12; P5.15 HW#7: P6.7; P6.8; P6.11; P6.25; P7.15

HW#1: P2.1 (a), (c), (e), (g); P2.4; P2.24

<u>P2.1</u>

- (a) T(x[n]) = g[n]x[n];
 - Stable if g[n] is bounded;
 - Causal output is not decided by future input;
 - Linear T(ax[n] + by[n]) = ag[n]x[n] + bg[n]y[n] = aT(x[n]) + bT(y[n]);
 - Time variant -T(x[n-m]) = g[n]x[n-m];
 - Memoryless output only depends on x[n] with same n;

(c)
$$T(x[n]) = \sum_{k=n-n_0}^{n+n_0} x[k];$$

- Stable:
- Causal only if $n_0 = 0$, else non-causal;
- Linear T(ax[n] + by[n]) = aT(x[n]) + bT(y[n]);
- Time Invariant $-T(x[n-m]) = \sum_{k=n-m-n_0}^{n-m+n_0} x[k] = \sum_{k'=n-n_0}^{n+n_0} x[k'-m];$
- Memoryless only if $n_0 = 0$;
- (e) $T(x[n]) = e^{x[n]}$;
 - Stable;
 - Causal;
 - Nonlinear $T(ax[n] + by[n]) \neq aT(x[n]) + bT(y[n])$;
 - Time Invariant $T(x[n-m]) = e^{x[n-m]}$;
 - Memoryless output only depends on x[n] with same n;
- (g) T(x[n]) = x[-n];

- Stable;
- Non-Causal output depends on future input;
- Linear T(ax[n] + by[n]) = aT(x[n]) + bT(y[n]);
- Time Variant;
- Not Memoryless;

P2.4

As $y[n] - \frac{3}{4}y[n-1] + \frac{1}{8}y[n-2] = 2x[n-1]$, the Fourier transform is

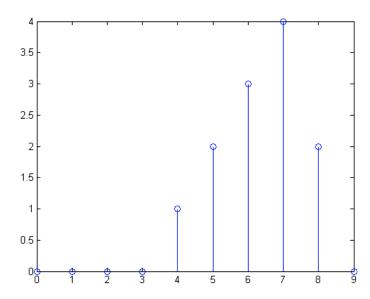
$$Y(e^{jw}) - \frac{3}{4}Y(e^{jw})e^{-jw} + \frac{1}{8}Y(e^{jw})e^{-2jw} = 2X(e^{jw})e^{-jw}$$

When $x[n] = \delta[n] \Rightarrow X(e^{jw}) = 1$, thus

$$Y(e^{jw}) = \frac{2e^{-jw}}{1 - (3/4)e^{-jw} + (1/8)e^{-2jw}} = 8\left(\frac{1}{1 - (1/2)e^{-jw}} - \frac{1}{1 - (1/4)e^{-jw}}\right)$$
$$y[n] = 8\left(\left(\frac{1}{2}\right)^n - \left(\frac{1}{4}\right)^n\right)u[n]$$

P2.24

As $h[n] = [1 \ 1 \ 1 \ 1 \ -2 \ -2]$ for n from 0 to 5 and x[n] = u[n-4], the system response is: $y[n] = x[n] * h[n] = [0 \ 0 \ 0 \ 1 \ 2 \ 3 \ 4 \ 2 \ 0 \]$; The sketch is shown as follows:



HW#2: P2.5; P2.18; P2.29 (a), (c), (e)

P2.5

(a) The roots for polynomial $1-5z^{-1}+6z^{-2}=0$ are 2 and 3, so the homogeneous response for the system is:

$$y[n] = A_1 2^n + A_2 3^n$$

(b) As y[n] - 5y[n-1] + 6y[n-2] = 2x[n-1] and $x[n] = \delta[n]$, the impulse response of the system is:

$$H(e^{jw}) = \frac{2e^{-jw}}{1 - 5e^{-jw} + 6e^{-2jw}} = 2\left(\frac{1}{1 - 3e^{-jw}} - \frac{1}{1 - 2e^{-jw}}\right)$$

$$\Rightarrow h[n] = 2(3^n - 2^n)u[n]$$

(c) As y[n] - 5y[n-1] + 6y[n-2] = 2x[n-1] and x[n] = u[n], the step response of the system is:

$$Y(z) = H(z)X(z) = \frac{2z^{-1}}{(1 - 5z^{-1} + 6z^{-2})(1 - z^{-1})} = \frac{1}{1 - z^{-1}} - \frac{4}{1 - 2z^{-1}} + \frac{3}{1 - 3z^{-1}}, |z| > 3$$

$$\Rightarrow y[n] = (3^{n+1} - 2^{n+2} + 1)u[n]$$

P2.18

(a) $h[n] = (1/2)^n u[n]$

Causal, the output of the system does not depend on future input;

(b)
$$h[n] = (1/2)^n u[n-1]$$

Causal, the output of the system does not depend on future input;

(c)
$$h[n] = (1/2)^{|n|}$$

Non-Causal, the output of the system depends on future input;

(d)
$$h[n] = u[n+2] - u[n-2]$$

Non-Causal, the output of the system depends on future input;

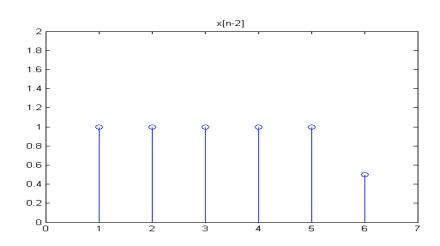
(e)
$$h[n] = (1/3)^n u[n] + 3^n u[-n-1]$$

Non-Causal, the output of the system depends on future input;

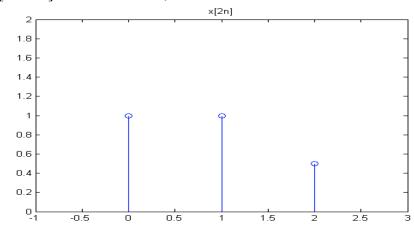
P2.29

 $\overline{\text{As x}[n]} = [1 \ 1 \ 1 \ 1 \ 1 \ 1/2] \text{ for n from } -1 \text{ to } 4,$

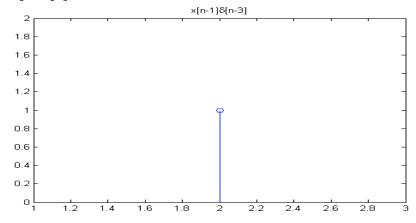
(a) $x[n-2] = [1 \ 1 \ 1 \ 1 \ 1/2]$ for n from 1 to 6; The sketch is:



(c) $x[2n] = [1 \ 1 \ 1/2]$ for n from 0 to 2; The sketch is:



(e) $x[n-1]\delta[n-3] = x[2]$; The sketch is:



HW#3: P2.40, P2.41, P3.27 (a), (c)

P2.40

$$x[n] = \cos(\pi n)u[n] = (-1)^n u[n]$$

$$h[n] = (\frac{j}{2})^n u[n]$$

$$y[n] = h[n] * x[n] = \sum_{k=-\infty}^{\infty} h[k]x[n-k] = \sum_{k=-\infty}^{\infty} (\frac{j}{2})^k u[k](-1)^{n-k} u[n-k] = (-1)^n \sum_{k=0}^n (-\frac{j}{2})^k u[n-k] = (-1)^n \sum_{$$

$$= (-1)^n \frac{1 - (-j/2)^{n+1}}{1 - (-j/2)}$$

Since
$$\lim_{n\to\infty} \frac{1-(-j/2)^{n+1}}{1-(-j/2)} = \frac{1}{1+j/2}$$

The steady state response to the excitation $x[n] = (-1)^n u[n]$ is

$$(-1)^n \frac{1}{1+j/2} = \frac{\cos(\pi n)}{1+j/2}$$

P2.41

Given a periodic impulse train $x[n] = \sum_{k=-\infty}^{\infty} \delta[n+kN]$, we can write its Fourier transform as

$$X(e^{j\omega}) = \frac{2\pi}{N} \sum_{k=-\infty}^{\infty} \delta(\omega + 2\pi k / N)$$
 (1)

(Refer to Signal and Systems, 2nd edition by A.V. Oppenheim and A.S. Willsky, Page 371 for its proof)

In problem, 2.41, N=16, so its Fourier transform is

$$X(e^{j\omega}) = \frac{2\pi}{16} \sum_{k=-\infty}^{\infty} \delta(\omega + 2\pi k/16)$$
 (2)

Let $Y(e^{j\omega})$ denotes the output of the system, then

$$Y(e^{j\omega}) = X(e^{j\omega})H(e^{j\omega})$$
(3)

If $|\omega| < 3\pi/8$, $H(e^{j\omega}) = e^{-j\omega 3}$

$$=e^{-j\omega 3}\frac{2\pi}{16}\sum_{k=-\infty}^{\infty}\delta(\omega+2\pi k/16)=\frac{2\pi}{16}[\delta(\omega)+e^{j3\pi/8}\delta(\omega+\pi/8)+e^{-j3\pi/8}\delta(\omega-\pi/8)]$$
(4)

If
$$|\omega| \ge 3\pi/8$$
, $H(e^{j\omega}) = 0$, thus $Y(e^{j\omega}) = 0$, (5)

So
$$Y(e^{j\omega}) = \frac{2\pi}{16} [\delta(\omega) + e^{j3\pi/8} \delta(\omega + \pi/8) + e^{-j3\pi/8} \delta(\omega - \pi/8)]$$
 (6)

Take the inverse Fourier transform, we can get

$$y[n] = \frac{1}{16} (1 + e^{j3\pi/8} e^{-n\pi/8} + e^{-j3\pi/8} e^{n\pi/8}) = \frac{1}{16} (1 + e^{-(n-3)\pi/8} + e^{(n-3)\pi/8})$$

$$= \frac{1}{16} (1 + 2\cos\frac{\pi}{8}(n-3)) = \frac{1}{16} + \frac{1}{8}\cos(\frac{\pi}{8}(n-3))$$
(7)

Note: Take a look at (3), $H(e^{j\omega})$ is band limited, $X(e^{j\omega})$ is infinite pulse train. If we multiply them together, we can only consider those pulses falling into the band $(-3\pi/8, 3\pi/8)$. The rest pulses are cancelled due to the multiplication with 0. There are

three pulses falling into the band $\frac{2\pi}{16}\delta(\omega)$, $\frac{2\pi}{16}\delta(\omega+\pi/8)$, $\frac{2\pi}{16}\delta(\omega-\pi/8)$, so we get (6)

P3.27

<u>(a)</u>

$$X(z) = \frac{1}{(1 + \frac{1}{2}z^{-1})^2(1 - 2z^{-1})(1 - 3z^{-1})} = \frac{A}{(1 + \frac{1}{2}z^{-1})^2} + \frac{B}{1 + \frac{1}{2}z^{-1}} + \frac{C}{1 - 2z^{-1}} + \frac{D}{1 - 3z^{-1}}$$

X (z)'s poles are z=-1/2, 2, 3, if it is stable, the ROC is $|z| \in (1/2,2)$

$$A = X(z)(1 + \frac{1}{2}z^{-1})^{2}\Big|_{z=-1/2} = \frac{1}{(1 - 2z^{-1})(1 - 3z^{-1})}\Big|_{z=-1/2} = \frac{1}{35}$$

$$C = X(z)(1 - 2z^{-1})\Big|_{z=2} = \frac{1}{(1 + \frac{1}{2}z^{-1})^2(1 - 3z^{-1})}\Big|_{z=2} = -\frac{1568}{1225}$$

$$D = X(z)(1 - 3z^{-1})\Big|_{z=3} = \frac{1}{(1 + \frac{1}{2}z^{-1})^2(1 - 2z^{-1})}\Big|_{z=3} = \frac{2700}{1225}$$

Also, Let $z^{-1} = 0$ at both sides,

$$X(z)\Big|_{z^{-1}=0} = 1 = A + B + C + D$$

Thus,
$$B = 1 - A - C - D = \frac{58}{1225}$$

$$X(z) = \frac{1}{(1 + \frac{1}{2}z^{-1})^2(1 - 2z^{-1})(1 - 3z^{-1})} = \frac{1/35}{(1 + \frac{1}{2}z^{-1})^2} + \frac{58/1225}{1 + \frac{1}{2}z^{-1}} - \frac{1568/1225}{1 - 2z^{-1}} + \frac{2700/1225}{1 - 3z^{-1}}$$

Since the ROC is $|z| \in (1/2,2)$,

$$x[n] = \frac{1}{35}(n+1)(-\frac{1}{2})^n u[n+1] + \frac{58}{1225}(-\frac{1}{2})^n u[n] + \frac{1568}{1225}2^n u[-n-1] - \frac{2700}{1225}3^n u[-n-1]$$

Note: To get the inverse Z-Transform of second-order term or multiple order term, we can use the differentiation property $nx[n] \leftrightarrow -z \frac{dX(z)}{dz}$ (Refer to page122 of textbook for its proof)

E.g. right side sequence $x[n] = a^n u[n] \leftrightarrow \frac{1}{1 - az^{-1}} (ROC: |z| > |a|)$

$$na^{n}[n] \leftrightarrow -z[\frac{d(\frac{1}{1-az^{-1}})}{dz}] = \frac{az^{-1}}{(1-az^{-1})^{2}}, \text{ So } na^{n-1}[n] \leftrightarrow \frac{z^{-1}}{(1-az^{-1})^{2}}$$

<u>(c)</u>

$$x[n] \leftrightarrow X(z) = \frac{z^3 - 2z}{z - 2} = z^2 + 2z + \frac{2}{1 - 2z^{-1}}$$

X(z) has its only pole at z=2. If x[n] is a left-sided sequence, the ROC is |z| < 2 $x[n] = \delta[n+2] + 2\delta[n+1] - 2(2)^n u[-n-1]$

or
$$x[n] = \delta[n+2] + 2\delta[n+1] - 2^{n+1}u[-n-1]$$

P3.1

(g)

 $(\frac{1}{2})^n(u[n]-u[n-10] = \sum_{n=0}^{9} (\frac{1}{2})^n \delta[n]$ is a finite length sequence, so its ROC is $|z| \neq 0$. The solution in the textbook is right.

HW#4: P3.6 (d), (e); P3.20; P4.1; P4.3

P3.6

(d)
$$X(z) = \frac{1 - (1/2)z^{-1}}{1 - (1/4)z^{-2}}$$
 $|z| > 1/2$

• Partial Fraction Expansion:

$$X(z) = \frac{1 - (1/2)z^{-1}}{1 - (1/4)z^{-2}} = \frac{1 - (1/2)z^{-1}}{(1 - (1/2)z^{-1})(1 + (1/2)z^{-1})} = \frac{1}{1 + (1/2)z^{-1}}$$
$$\Rightarrow x[n] = \left(-\frac{1}{2}\right)^n u[n]$$

• Power Series Expansion:

$$X(z) = \frac{1 - (1/2)z^{-1}}{1 - (1/4)z^{-2}} = 1 - (1/2)z^{-1} + (1/4)z^{-2} - (1/8)z^{-3} + (1/16)z^{-4} + \cdots$$
$$\Rightarrow x[n] = \left(-\frac{1}{2}\right)^n u[n]$$

• Fourier Transform exists as the ROC including unit circle.

(e)
$$X(z) = \frac{1 - az^{-1}}{z^{-1} - a}$$
 $|z| > |1/a|$

• Partial Fraction Expansion:

$$X(z) = \frac{1 - az^{-1}}{z^{-1} - a} = \frac{1}{z^{-1} - a} - \frac{az^{-1}}{z^{-1} - a} = \frac{1}{z^{-1} - a} - a - \frac{a^{2}}{z^{-1} - a} = \frac{-1/a}{1 - (1/a)z^{-1}} - a + \frac{a}{1 - (1/a)z^{-1}}$$

$$\Rightarrow x[n] = -\left(\frac{1}{a}\right)^{n+1} u[n] - a\delta[n] + \left(\frac{1}{a}\right)^{n-1} u[n] = -\left(\frac{1}{a}\right)^{n+1} u[n] + \left(\frac{1}{a}\right)^{n-1} u[n-1]$$

• Power Series Expansion:

$$X(z) = \frac{1 - az^{-1}}{z^{-1} - a} = \frac{1}{z^{-1} - a} - \frac{az^{-1}}{z^{-1} - a}$$

$$\frac{1}{z^{-1} - a} = \left(-\frac{1}{a}\right) \left(1 + \frac{1}{a}z^{-1} + \frac{1}{a^{2}}z^{-2} + \frac{1}{a^{3}}z^{-3} + \cdots\right) \Rightarrow x1[n] = \left(-\frac{1}{a}\right) \left(\frac{1}{a}\right)^{n} u[n] = -\left(\frac{1}{a}\right)^{n+1} u[n]$$

$$-\frac{az^{-1}}{z^{-1} - a} = z^{-1} + \frac{1}{a}z^{-2} + \frac{1}{a^{2}}z^{-3} + \frac{1}{a^{3}}z^{-4} + \cdots \Rightarrow x2[n] = \left(\frac{1}{a}\right)^{n-1} u[n-1]$$

$$\Rightarrow x[n] = x1[n] + x2[n] = -\left(\frac{1}{a}\right)^{n+1} u[n] + \left(\frac{1}{a}\right)^{n-1} u[n-1]$$

Fourier Transform exists when the ROC including unit circle, which means |a| < 1.

P3.20

- (a) As the ROC of X(z) is |z| > 3/4, and the ROC of Y(z) is |z| > 2/3, the ROC of H(z)should be |z| > 2/3;
- (b) As the ROC of X(z) is |z| < 1/3, and the ROC of Y(z) is 1/6 < |z| < 1/3, the ROC of H(z) should be |z| > 1/6;

P4.1
As $x_c(t) = \sin[2\pi(100t)]$ and T = 1/400 sec,

$$x[n] = x_c(nT) = \sin[2\pi(100nT)] = \sin\left(\frac{n\pi}{2}\right)$$

P4.3

As $x_c(t) = \cos[4000\pi t]$ and $x[n] = \cos\left[\frac{n\pi}{3}\right]$,

(a) Let
$$x[n] = x_c(nT) \Rightarrow T = \frac{1}{12,000}$$

(b) T is not unique, for example, $T = \frac{5}{12,000}$

HW#5: P4.5; P4.7; P5.2; P5.3

(a) From Nyquist Sampling theorem, to avoid aliasing in the C/D converter, the sampling frequency $\Omega_s = \frac{1}{T} \ge 2\Omega_m = 2 * 5000 Hz = 10^4 Hz$, so $T_s \le 10^{-4} s$

$$(\underline{b})\Omega_{cutoff} = \frac{f_{cutoff}}{2\pi}\Omega_s = \frac{\pi/8}{2\pi}10^4 = 625Hz$$

$$(\underline{c})\Omega_{cutoff} = \frac{f_{cutoff}}{2\pi}\Omega_s = \frac{\pi/8}{2\pi}2\times10^4 = 1250Hz = 1.25kHz$$

Note: The relation between digital frequency f and analog frequency Ω is $\frac{\Omega}{\Omega_s} = \frac{f}{2\pi}$, where Ω_s is the sampling frequency, f is in radians.

P4.7

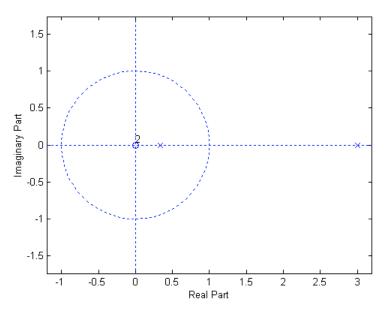
$$\begin{split} & \chi_c(t) = s_c(t) + \alpha s_c(t - \tau_d) \\ & \chi_c(j\Omega) = S_c(j\Omega)(1 + \alpha e^{-j\Omega\tau_d}) \\ & \text{Consider sampling, } x[n] = x_c(nT) \text{, in frequency domain (refer to Eq4.19 in textbook, P147),} \\ & \chi\left(e^{j\Omega T}\right) = \frac{1}{T}\sum_{k=-\infty}^{\infty} X_c(j(\Omega - \frac{2\pi k}{T})) \\ & \chi\left(e^{j\Omega T}\right) = \frac{1}{T}\sum_{k=-\infty}^{\infty} X_c(j(\Omega - \frac{2\pi k}{T})) \\ & \chi\left(e^{j\Omega}\right) = \chi\left(e^{j\Omega T}\right) = \frac{1}{T}\sum_{k=-\infty}^{\infty} X_c(j(\Omega - \frac{2\pi k}{T})) = \frac{1}{T}(1 + \alpha e^{-j\Omega\tau_d})\sum_{k=-\infty}^{\infty} S_c(j(\Omega - \frac{2\pi k}{T})) \\ & = \frac{1}{T}(1 + \alpha e^{-j\omega\tau_d/T})\sum_{k=-\infty}^{\infty} S_c(j(\frac{\omega}{T} - \frac{2\pi k}{T})) \\ & \frac{\text{(b)}}{H(e^{j\omega})} = 1 + \alpha e^{-j\omega\tau_d/T} \\ & \text{(c)} \\ & h[n] = \frac{1}{2\pi}\int_{-\pi}^{\pi} H(e^{j\omega})e^{jn\omega}d\omega = \frac{1}{2\pi}\int_{-\pi}^{\pi} (1 + \alpha e^{-j\omega\tau_d/T})e^{jn\omega}d\omega = \frac{1}{2\pi}\int_{-\pi}^{\pi} e^{jn\omega}d\omega + \frac{1}{2\pi}\int_{-\pi}^{\pi} \alpha e^{-j\omega(n-\tau_d/T)}d\omega \\ & = \frac{\sin(n\pi)}{n\pi} + \alpha\frac{\sin[(n-\tau_d/T)\pi]}{(n-\tau_d/T)\pi} \\ & \text{if } \tau_d = T, \ h[n] = \frac{\sin(n\pi)}{n\pi} + \alpha\frac{\sin[(n-1)\pi]}{(n-1)\pi} = \delta[n] + \alpha\delta[n-1] \\ & \text{if } \tau_d = T/2, \ h[n] = \frac{\sin(n\pi)}{n\pi} + \alpha\frac{\sin[(n-1/2)\pi]}{(n-1)\pi} = \delta[n] + \alpha\frac{\sin[(n-1/2)\pi]}{(n-1)\pi} \end{split}$$

P5.2

$$y[n-1] - \frac{10}{3}y[n] + y[n+1] = x[n]$$
$$z^{-1}Y(z) - \frac{10}{3}Y(z) + zY(z) = X(z)$$

$$H(z) = \frac{Y(z)}{X(z)} = \frac{1}{z^{-1} - \frac{10}{3} + z} = \frac{z^{-1}}{(1 - (1/3)z^{-1})(1 - 3z^{-1})} = \frac{-3/8}{1 - (1/3)z^{-1}} + \frac{3/8}{1 - 3z^{-1}}$$

(a) H (z) has two zeroes: $0, \infty$; two poles: 1/3, 3



(b) The system is stable, so the ROC includes the unit circle. The ROC is 1/3 < |z| < 3

$$h[n] = -\frac{3}{8} (\frac{1}{3})^n u[n] - \frac{3}{8} 3^n u[-n-1]$$

P5.3

$$y[n-1] + \frac{1}{3}y[n-2] = x[n]$$

$$z^{-1}Y(z) + \frac{1}{3}z^{-2}Y(z)) = X(z)$$

$$H(z) = \frac{Y(z)}{X(z)} = \frac{1}{z^{-1} + (1/3)z^{-2}} = \frac{1}{z^{-1}(1 + (1/3)z^{-1})} = \frac{z}{1 + (1/3)z^{-1}}$$

The poles are: 1/3, there are two ROC, 0 < |z| < 1/3, |z| > 1/3

(1)
$$0 < |z| < 1/3$$
: $h[n] = -(-\frac{1}{3})^{n+1}u[-n-2]$, choose (d)

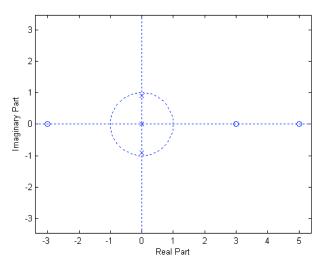
(2)
$$|z| > 1/3$$
: $h[n] = (-\frac{1}{3})^{n+1}u[n+1]$, choose (a)

HW#6: P5.10; P5.12; P5.15

P5.10

As one of the zeros of H(z) is at $z = \infty$, the corresponding pole of Hi(z) will be also at infinity. The existence of a pole at $z = \infty$ implies that the system is not causal.

P5.12 (a)



As the poles of H(z) are 0.9, -0.9, ROC includes the unit circle, the system is stable.

(b)
$$H(z) = \frac{(1+0.2z^{-1})(1+3z^{-1})(1-3z^{-1})}{(1+j0.9z^{-1})(1-j0.9z^{-1})}$$

$$= \frac{-9(1+0.2z^{-1})(1+(1/3)z^{-1})(1-(1/3)z^{-1})}{(1+j0.9z^{-1})(1-j0.9z^{-1})} \underbrace{(z^{-1}+1/3)(z^{-1}-1/3)}_{H_{ap}(z)}$$

$$= H_1(z)H_{ap}(z)$$

P5.15

Generalized Linear Phase – GLP; Linear Phase – LP;

- (a) As $h[n] = 2\delta[n] + \delta[n-1] + 2\delta[n-2] \Rightarrow H(jw) = (1 + 4\cos w)e^{-jw}$, $A(jw) = 1 + 4\cos w$ and $\alpha = 1, \beta = 0$, it is a GLP, but not LP as A(jw) is not always nonnegative for all w;
- (b) It is not a GLP or LP as it is not a symmetric filter;
- (c) As $h[n] = \delta[n] + 3\delta[n-1] + \delta[n-2] \Rightarrow H(jw) = (3 + 2\cos w)e^{-jw}$, $A(jw) = 3 + 2\cos w$ and $\alpha = 1, \beta = 0$, it is a GLP and also LP as A(jw) is always nonnegative for all w;

(d) As
$$h[n] = \delta[n] + \delta[n-1] \Rightarrow H(jw) = 2\cos(w/2)e^{-j(w/2)}$$
,

 $A(jw) = 2\cos(w/2)$ and $\alpha = 1/2$, $\beta = 0$, it is a GLP, but not LP as A(jw) is not always nonnegative for all w;

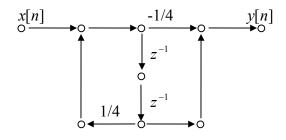
(e) As $h[n] = \delta[n] - \delta[n-2] \Rightarrow H(jw) = 2\sin w e^{-j(w-\pi/2)}$, $A(jw) = 2\sin w$ and $\alpha = 1, \beta = \pi/2$, it is a GLP, but not LP as A(jw) is not always nonnegative for all w;

<u>HW#7: P6.7; P6.8; P6.11; P6.25; P7.15</u> P6.7

The difference equation is: $y[n] - \frac{1}{4}y[n-2] = x[n-2] - \frac{1}{4}x[n]$

Z-Transform:
$$Y(z) - \frac{1}{4}Y(z)z^{-2} = X(z)z^{-2} - \frac{1}{4}X(z)$$

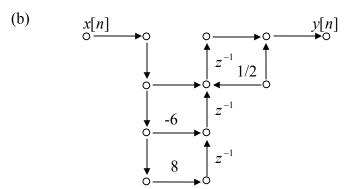
Transfer function: $H(z) = \frac{Y(z)}{X(z)} = \frac{-\frac{1}{4} + z^{-2}}{1 - \frac{1}{4}z^{-2}}$



$$\frac{\mathbf{P6.8}}{y[n] - 2y[n-2]} = 3x[n-1] + x[n-2]$$

P6.11

$$H(z) = \frac{z^{-1}(1-2z^{-1})(1-4z^{-1})}{1-\frac{1}{2}z^{-1}} = \frac{z^{-1}-6z^{-2}+8z^{-3}}{1-\frac{1}{2}z^{-1}}$$



P6.25

(a)
$$H(z) = [H_1(z) + H_2(z)]H_3(z) = [\frac{1 - \frac{1}{2}z^{-1}}{1 - \frac{3}{8}z^{-1} + \frac{7}{8}z^{-2}} + (1 + 2z^{-1} + z^{-2})](\frac{1}{1 - z^{-1}})$$

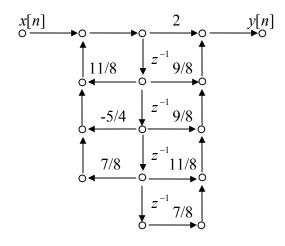
The Z-Transfer function:

$$H(z) = \frac{2 + \frac{9}{8}z^{-1} + \frac{9}{8}z^{-2} + \frac{11}{8}z^{-3} + \frac{7}{8}z^{-4}}{1 - \frac{11}{8}z^{-1} + \frac{5}{4}z^{-2} - \frac{7}{8}z^{-3}}$$

(b)

The difference equation:

$$y[n] - \frac{11}{8}y[n-1] + \frac{5}{4}y[n-2] - \frac{7}{8}y[n-3] = 2x[n] + \frac{9}{8}x[n-1] + \frac{9}{8}x[n-2] + \frac{11}{8}x[n-3] + \frac{7}{8}x[n-4]$$
(c)



P7.15

Specifications:

(a) Pass band ripple: $\delta_p = 0.05$, $A_p = 20 \log \delta_p = -26.02 dB$

Stop band ripple: $\delta_s = 0.1$, $A_s = 20 \log \delta_s = -20 dB$

Pass band edge: $\omega_p = 0.25\pi$ Stop band edge: $\omega_s = 0.35\pi$

Cutoff:
$$\omega_c = 0.3\pi$$

The peak approximate error $20 \log_{10} \delta < -26.02 dB$

Among the windows in Table 7.1 (Page 471), Hanning, Hamming, Blackman can be used (b)

Hanning:
$$0.1\pi = \frac{8\pi}{M}$$
, $M = 80$, $L = M + 1 = 81$

Hamming:
$$0.1\pi = \frac{8\pi}{M}$$
, $M = 80$, $L = M + 1 = 81$

Blackman:
$$0.1\pi = \frac{12\pi}{M}$$
, $M = 120$, $L = M + 1 = 121$

Note that the estimation is not accurate. We can use MATLAB to find the minimum of filter order to meet the requirements.