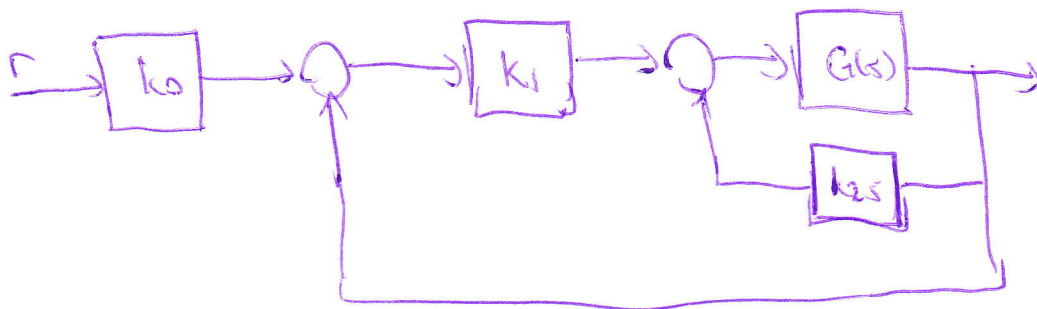


$$(a) \frac{Y(s)}{R(s)} = \frac{k_1(s-1)}{(1+k_2)s^2 + (k_1-k_2)s + (k_1+4)}$$

$$= \frac{\frac{k_1}{1+k_2} (s-1)}{s^2 + \frac{k_1-k_2}{1+k_2}s - \frac{k_1+4}{1+k_2}}$$

If is not possible to find a set of k_1 and k_2 such that $T(s) = \frac{Y(s)}{R(s)}$. We introduce an additional gain (a precompensator) at the ref. i/p.



$$\left. \begin{aligned} \text{where } \frac{k_1-k_2}{1+k_2} &= 5.2 \\ -\frac{k_1+4}{1+k_2} &= 5 \end{aligned} \right\} \begin{aligned} k_1 &= -2.66 \\ k_2 &= -1.268 \end{aligned}$$

$$\frac{k_0 k_1}{1+k_2} = -1.8 \Rightarrow k_0 = -0.181$$

$\Rightarrow \frac{Y(s)}{R(s)}$ will implement $T(s)$