搜索 0921 补

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前重复后精确覆盖 以及 精确覆盖

```
const int WID = 110;
const int HGT = 150;
const int SIZE = WID * (HGT + 1) + 10;
int arr[WID][HGT], cnt[WID];
int best;
int N;
const int INF = 0x7FFFFFFF;
struct Dancer
   int L[SIZE], R[SIZE], U[SIZE], D[SIZE], C[SIZE], Row[SIZE];
   int S[WID + 10];
   int width, height;
   void init(int width, int height) //width列height行
       best = INF;
       this->width = width;
       this->height = height;
       int p, x, y, last, t;
       for (x = 1; x \le width; x++)
          L[x] = x - 1;
          R[x] = x + 1;
          U[x] = D[x] = x;
           S[x] = 0;
       R[width] = 0;
       p = width + 1;
       for (y = 1; y \le height; y++)
           last = R[0] = L[0] = 0;
          for (t = 1; t <= cnt[y]; t++)
              int x = arr[y][t];
              U[p] = U[x];
              C[p] = D[p] = x;
              L[p] = last;
              S[x]++;
              Row[p] = y;
              last = R[last] = U[x] = D[U[x]] = p++;
          R[last] = R[0];
          L[R[0]] = last;
       L[0] = width;
       R[0] = 1;
       S[0] = INF;
   void remove(const int &c)
       int i;
       for (i = D[c]; i != c; i = D[i])
          L[R[i]] = L[i];
          R[L[i]] = R[i];
   void resume(const int &c)
       int i;
       for (i = U[c]; i != c; i = U[i])
```

```
L[R[i]] = i;
       R[L[i]] = i;
void removeExact(int c)
   L[R[c]] = L[c];
   R[L[c]] = R[c];
   for (int i = D[c]; i != c; i = D[i])
       for (int j = R[i]; j != i; j = R[j])
           U[D[j]] = U[j];
           D[U[j]] = D[j];
           --S[C[j]];
       }
}
void resumeExact(int c)
   for (int i = U[c]; i != c; i = U[i])
       for (int j = L[i]; j != i; j = L[j])
           ++S[C[j]];
           U[D[j]] = j;
           D[U[j]] = j;
   L[R[c]] = c;
   R[L[c]] = c;
}
int h(int bound)
   bool hash[110];
   memset(hash, false, sizeof(hash));
   int ret = 0;
   for (int c = R[0]; c != 0; c = R[c])
       if (!hash[c] && c <= bound)</pre>
       {
           ret++;
           hash[c] = true;
           for (int i = D[c]; i != c; i = D[i])
              for (int j = R[i]; j != i; j = R[j])
                  hash[C[j]] = true;
           }
   return ret;
bool danceExact()
   if (R[0] == 0)
       return true;
   int c = 0, i, j;
    for (i = R[0]; i; i = R[i])
       if (S[i] < S[c])
```

```
c = i;
       removeExact(c);
       for (i = D[c]; i != c; i = D[i])
           for (j = R[i]; j != i; j = R[j])
              removeExact(C[j]);
           if (danceExact())
              return true;
           for (j = L[i]; j != i; j = L[j])
              resumeExact(C[j]);
       }
       resumeExact(c);
       return false;
   bool dance(int deep, int bound)
       if (deep + h(bound) >= best)
           return false;
       if (R[0] == 0 || R[0] > bound)
           best = min(best, deep);
           return true;
       int c = 0, i, j;
       bool flag = false;
       for (i = R[0]; i != 0; i = R[i])
           if (S[i] < S[c] && i <= bound)</pre>
              c = i;
       for (i = D[c]; i != c; i = D[i])
           remove(i);
           int idx = -1;
           for (j = R[i]; j != i; j = R[j])
               if (C[j] \le bound)
                  remove(j);
              else
                  idx = j;
           if (idx != -1)
              removeExact(C[idx]);
           if (dance(deep + 1, bound))
              flag = true;
           if (idx != -1)
              resumeExact(C[idx]);
           for (j = L[i]; j != i; j = L[j])
              if (C[j] <= bound)</pre>
                  resume(j);
           resume(i);
       return flag;
   }
};
```

IDA* 版重复覆盖

```
const int WID = 230;
const int HGT = 230;
const int SIZE = WID * (HGT + 1) + 10;
int arr[WID][HGT], cnt[WID];
int best;
const int INF = 0x7FFFFFFF;
struct Dancer
   int L[SIZE], R[SIZE], U[SIZE], D[SIZE], C[SIZE], Row[SIZE];
   int S[WID + 10];
   int width, height;
   void init(int width, int height)//width列height行
       best = INF;
       this->width = width;
       this->height = height;
       int p, x, y, last, t;
       for (x = 1; x \le width; x++)
          L[x] = x - 1;
          R[x] = x + 1;
          U[x] = D[x] = x;
           S[x] = 0;
       R[width] = 0;
       p = width + 1;
       for (y = 1; y <= height; y++)</pre>
           last = R[0] = L[0] = 0;
          for (t = 1; t <= cnt[y]; t++)
              int x = arr[y][t];
              U[p] = U[x];
              C[p] = D[p] = x;
              L[p] = last;
              S[x]++;
              Row[p] = y;
              last = R[last] = U[x] = D[U[x]] = p++;
          R[last] = R[0];
          L[R[0]] = last;
       L[0] = width;
       R[0] = 1;
       S[0] = INF;
   void remove(const int &c)
       int i;
       for (i = D[c]; i != c; i = D[i])
          L[R[i]] = L[i];
          R[L[i]] = R[i];
   void resume(const int &c)
       int i;
       for (i = U[c]; i != c; i = U[i])
```

```
L[R[i]] = i;
       R[L[i]] = i;
}
bool hs[260];
int h()
   memset(hs, false, sizeof(hs));
   int ret = 0;
   for (int c = R[0]; c != 0; c = R[c])
       if (!hs[c])
       {
           ret++;
           hs[c] = true;
           for (int i = D[c]; i != c; i = D[i])
              for (int j = R[i]; j != i; j = R[j])
                  hs[C[j]] = true;
           }
       }
   return ret;
int flg, lim;
int dance(int deep)
   int tmp = h();
   if (deep + tmp > lim)
       return deep + tmp;
   if (R[0] == 0)
       flg = true;
       return deep;
   int c = 0, i, j;
   for (i = R[0]; i != 0; i = R[i])
       if (S[i] < S[c])
          c = i;
   int nxt = INF;
   for (i = D[c]; i != c; i = D[i])
       remove(i);
       for (j = R[i]; j != i; j = R[j])
          remove(j);
       tmp = dance(deep + 1);
       if (flg)
          return tmp;
       nxt = min(nxt, tmp);
       for (j = L[i]; j != i; j = L[j])
          resume(j);
       }
       resume(i);
   return nxt;
```

```
}
int id_astar()
{
    lim = h();
    flg = false;
    while (!flg)
    {
        lim = dance(0);
    }
    return lim;
}
```

```
const int maxn = 60;
int limit, solved;
int M, N;
int mat[maxn][maxn];
int sx, sy;
int destx, desty;
int sd;
int dx[] =
{ -1, 0, 1, 0 };
int dy[] =
\{ 0, 1, 0, -1 \};
void init()
   for (int i = 1; i <= M; i++)</pre>
      for (int j = 1; j <= N; j++)</pre>
          scanf("%d", mat[i] + j);
   scanf("%d%d%d%d", &sx, &sy, &destx, &desty);
   char tmp[10];
   scanf("%s", tmp);
   if (tmp[0] == 'n')
      sd = 0;
   else if (tmp[0] == 'e')
      sd = 1;
   else if (tmp[0] == 's')
      sd = 2;
   else
      sd = 3;
}
inline int isok(int x, int y)
   && !mat[x][y + 1] && !mat[x + 1][y] && !mat[x + 1][y + 1];
int isok(int fx, int fy, int dir, int step)
   for (int i = 0, x = fx, y = fy; i \le step; x += dx[dir], y +=
dy[dir], i++)
      if (!isok(x, y))
         return 0;
   return 1;
}
int dec[] =
{ 3, 0, 1, 2 };
int inc[] =
{ 1, 2, 3, 0 };
int h(int x, int y)
   return (abs(destx - x) + abs(desty - y) + 2) / 3;
```

```
}
struct Node
   int x, y, dir;
   int g, h, f;
   Node()
   {
   bool operator<(const Node& p) const
       return f > p.f;
   }
   bool operator==(const Node& p) const
       return x == p.x && y == p.y && dir == p.dir;
   }
};
priority queue<Node> Q;
int f[maxn][maxn][4];
void handle(const Node& from, int x, int y, int dir)
   int tmp = h(x, y);
   if (f[x][y][dir] == -1 || f[x][y][dir] > tmp + from.g)
      Node next;
       next.x = x;
       next.y = y;
       next.dir = dir;
       next.g = from.g + 1;
       next.h = tmp;
       next.f = next.g + next.h;
       f[x][y][dir] = next.f;
       Q.push(next);
   }
}
int AStar()
   while (!Q.empty())
       Q.pop();
   memset(f, -1, sizeof(f));
   Node begin;
   begin.x = sx;
   begin.y = sy;
   begin.dir = sd;
   begin.h = h(sx, sy);
   begin.g = 0;
   begin.f = begin.h;
   f[sx][sy][sd] = begin.f;
   Q.push (begin);
   solved = 0;
   while (!solved && !Q.empty())
       Node current = Q.top();
       Q.pop();
       if (current.h == 0)
          return current.g;
```

```
handle(current, current.x, current.y, dec[current.dir]);
       handle(current, current.x, current.y, inc[current.dir]);
       for (int i = 1; i <= 3; i++)</pre>
           int nx = current.x + i * dx[current.dir];
           int ny = current.y + i * dy[current.dir];
           if (isok(nx, ny))
              handle(current, nx, ny, current.dir);
           }
           else
              break;
       }
   }
}
int vis[maxn][maxn];
void hasSolution(int x, int y)
   for (int i = 0; i < 4; i++)</pre>
       int nx = x + dx[i];
       int ny = y + dy[i];
       if (isok(nx, ny) && !vis[nx][ny])
           vis[nx][ny] = 1;
           hasSolution(nx, ny);
   }
}
int hasSolution()
   memset(vis, 0, sizeof(vis));
   if (!isok(sx, sy))
       return 0;
   vis[sx][sy] = 1;
   hasSolution(sx, sy);
   if (!vis[destx][desty])
       return 0;
   return 1;
}
void work()
   if (hasSolution())
       printf("%d\n", AStar());
   else
       puts("-1");
}
```

```
//启发函数h带系数
int limit;
int solved;
const int maxn = 20;
int arr[maxn];
void init()
   scanf("%d", &N);
   for (int i = 1; i <= N; i++)</pre>
       scanf("%d", arr + i);
}
int h(int arr[])
   int result = 0;
   for (int i = 0; i <= N - 1; i++)</pre>
       if (arr[i + 1] != arr[i] + 1)
           result++;
   return (result + 2) / 3;
}
int DFS(int deep, int arr[])
   int hvalue = h(arr);
   if (hvalue + deep > limit)
       return hvalue + deep;
   if (hvalue == 0)
       solved = 1;
       return deep;
   int next = 0x7FFFFFF;
   int tmp[maxn];
   tmp[0] = 0;
   for (int i = 1; i <= N; i++)</pre>
       for (int j = i; j <= N; j++)</pre>
           for (int k = 0; k \le N; k++)
               if (k >= i - 1 && k <= j)</pre>
                  continue;
               int cnt = 0;
               for (int 1 = 1; 1 <= k; 1++)</pre>
                   if (1 >= i && 1 <= j)</pre>
                      continue;
                   tmp[++cnt] = arr[1];
               for (int 1 = i; 1 <= j; 1++)</pre>
                  tmp[++cnt] = arr[1];
               for (int 1 = k + 1; 1 <= N; 1++)</pre>
                   if (1 >= i && 1 <= j)
                       continue;
                   tmp[++cnt] = arr[1];
               }
```

```
int v = DFS(deep + 1, tmp);
              if (solved)
               return v;
              next = min(next, v);
          }
   return next;
}
int IDAstar()
   solved = 0;
   limit = h(arr);
   while (!solved && limit <= 4)</pre>
      limit = DFS(0, arr);
   if (solved)
      return limit;
   return -1;
}
```