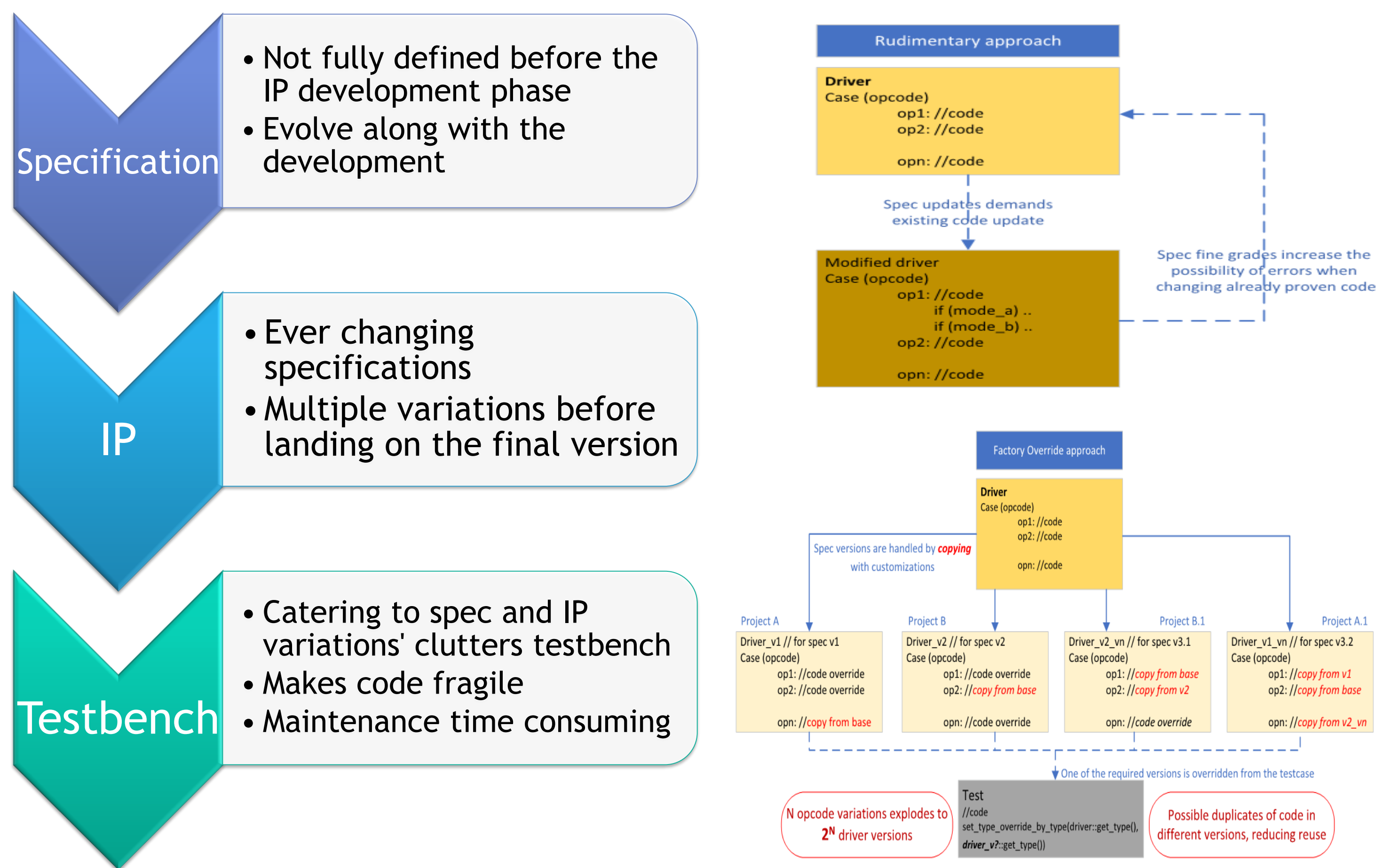
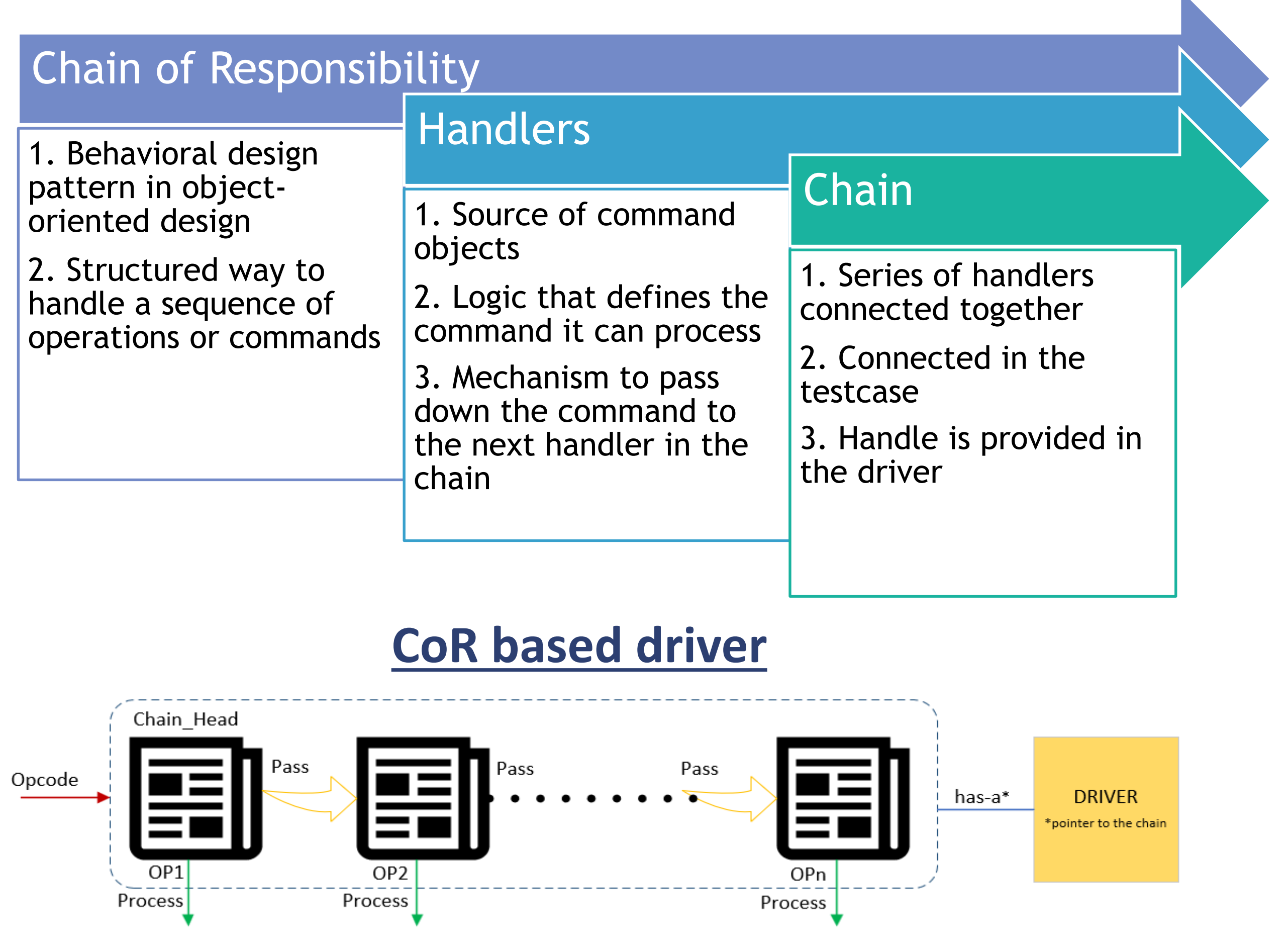


### Problem Statement - Driver for fluctuating specifications



### Proposed Methodology - Chain of Responsibility (CoR)



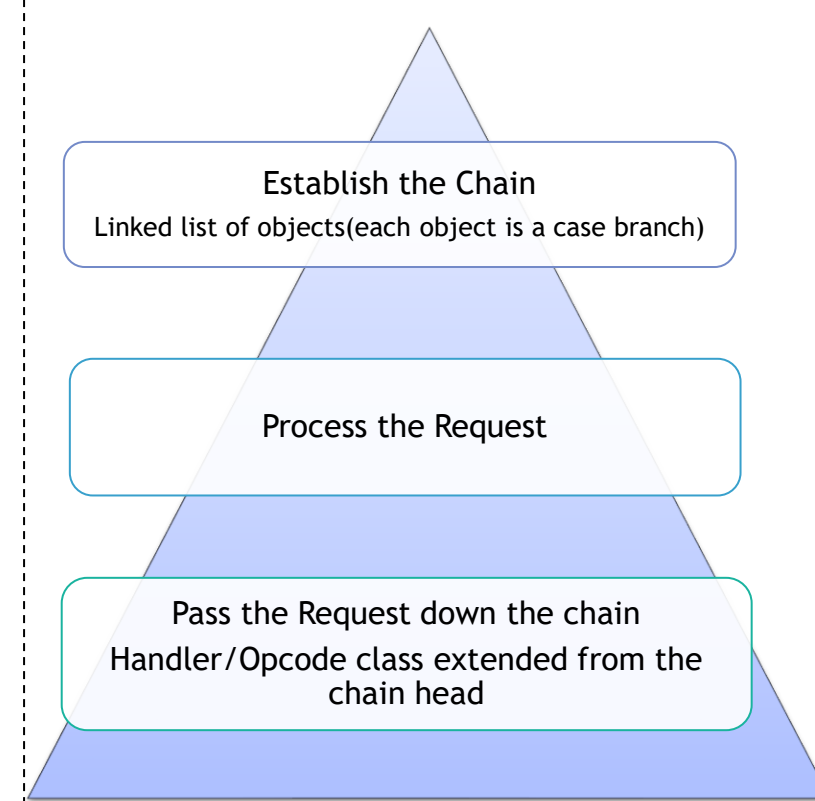
## Pseudocode – Converting UVM case-based driver to CoR driver

### Chain head with common mechanisms as base class

```
class chain_head extends luvu_object;
  chain_head _chain; // ptr of its own type
  task set_chain(chain_head chain);
  _chain = chain;
endtask : set_chain

virtual task exec_cmd(xaction cmd);
  _chain.exec_cmd(cmd);
endtask : exec_cmd

task exec_nxt(xaction cmd);
  if (_chain != null)
    _chain.exec_cmd(cmd)
  else
    $display("End of chain: no cmd found");
  endtask : exec_nxt
endclass : chain_head
```



Handle to the chain head in the driver

```
class driver extends uvm_driver #(req);
    // some code
    // handle to chain_head to stitch the ops
    chain_head _chain_head;

    function construct_cor();
        _chain_head = chain_head::type_id::create("_chain_head");
    endfunction : construct_cor
    // other driver logic
endclass : driver
```

### Handler classes extended from chain\_head

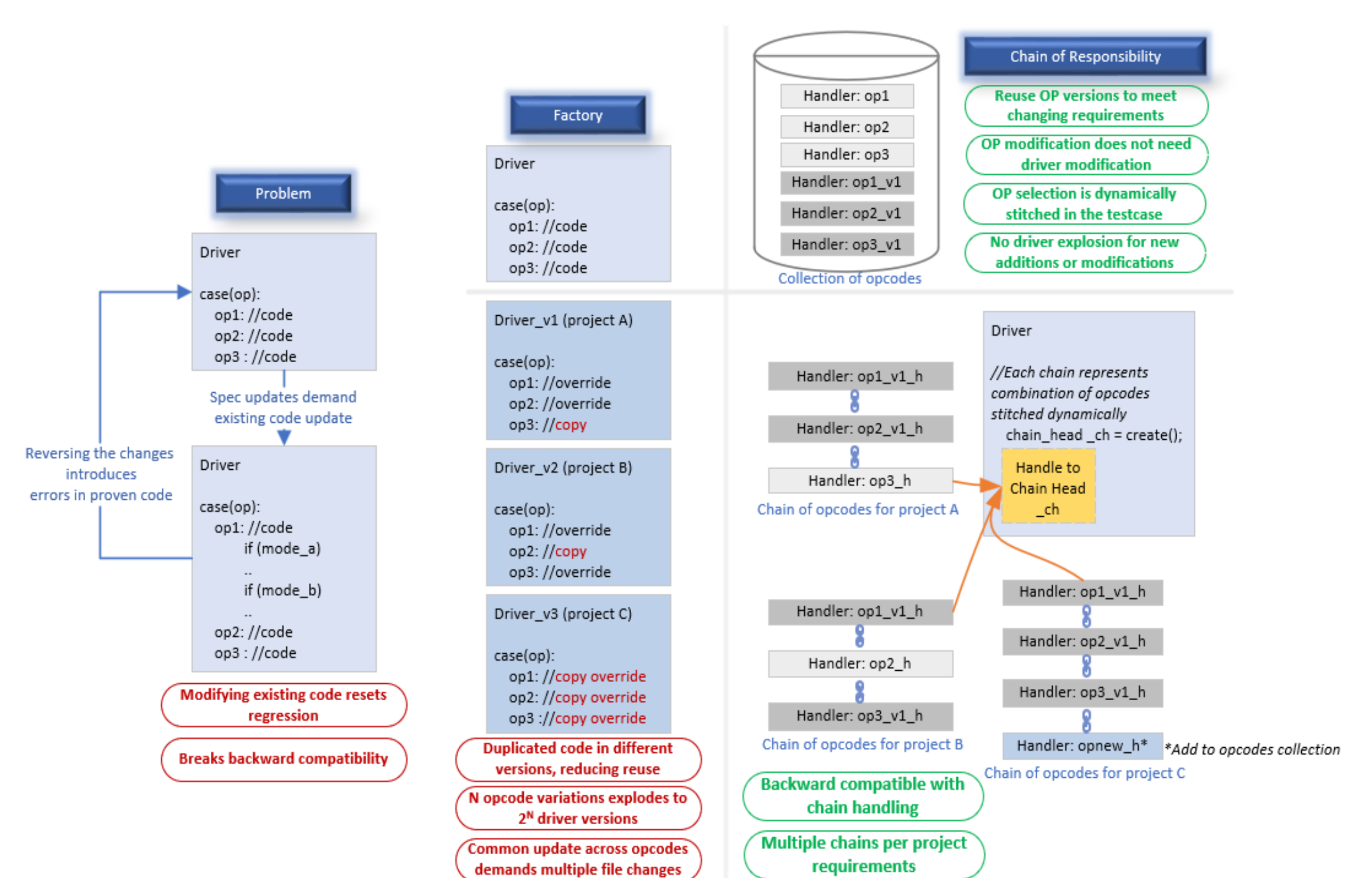
```
class op1_c extends chain_head;
    virtual task exec_cmd(xaction cmd);
        if (cmd.op == op1)
            do_op1;
        else
            exec_nxt(cmd);
    endtask : exec_cmd
endclass : op1_c

class op2_c extends chain_head;
    virtual task exec_cmd(xaction cmd);
        if (cmd.op == op2)
            do_op2;
        else
            exec_nxt (cmd);
    endtask : exec_cmd
endclass : op2_c
```

### Test constructing the chain

```
virtual function construct_chain();
    op1 = op1_c::type_id::create("op1");
    op2 = op2_c::type_id::create("op2");
    .
    opn = opn_c::type_id::create("opn");
    env.agent.driver._chain_head.set_chain(op1);
    op1.set_chain(.op2);
    .
    opn.set_chain(opn);
endfunction : construct_chain
```

## Implementation Details

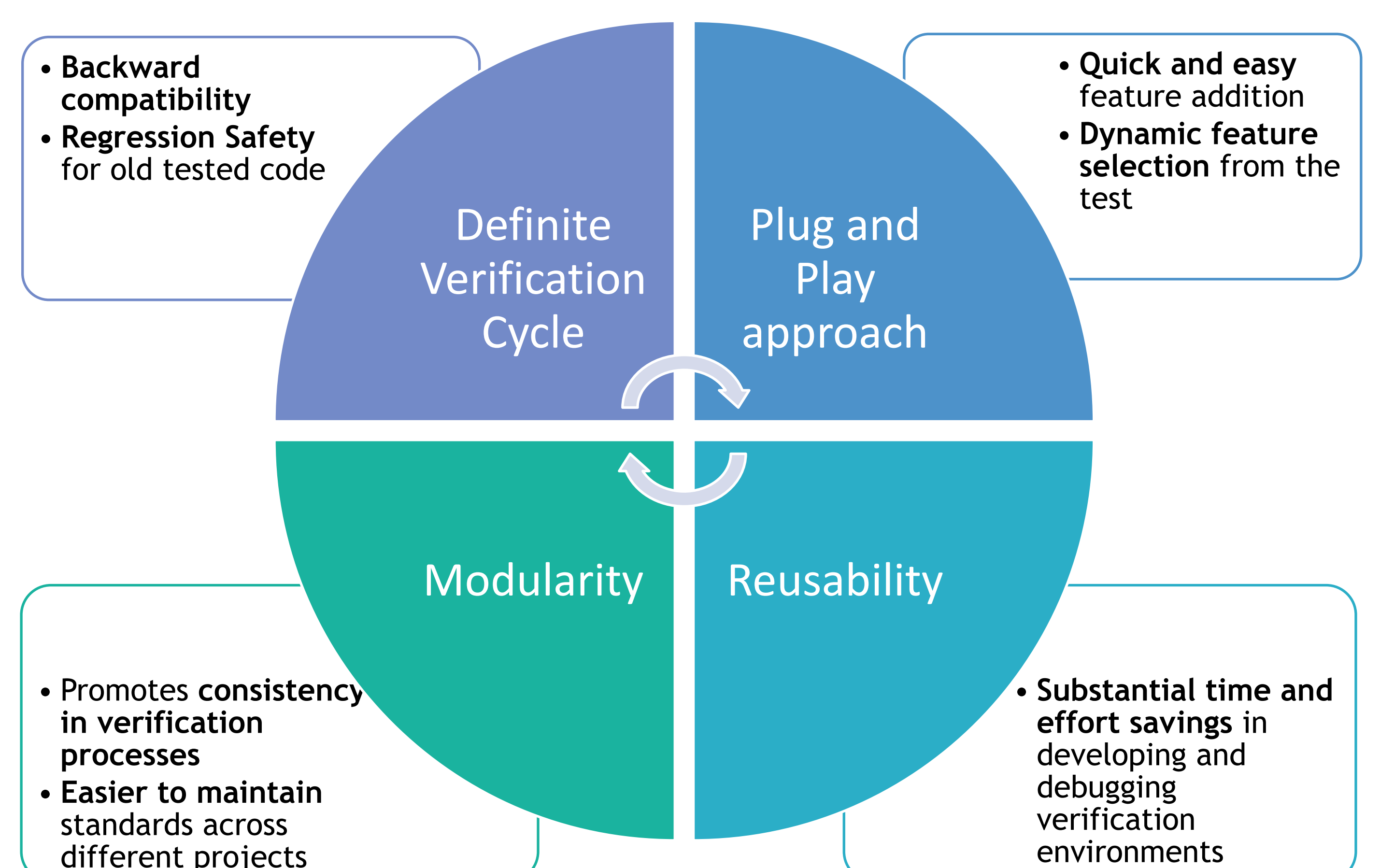


## Results

- **Successfully implemented in Serial IO PHY IPs' verification**, for the past few years, demonstrating its effectiveness in real-world applications.
- First time enablement took around ~3-4 weeks of man effort
- New feature addition or enhancement in less than a day without breaking backward compatibility

Indicators	Rudimentary Approach	UVM Factory based Approach	Chain of Responsibility
Backward compatibility	✗	✓	✓
Regression Safety	✗	Depends	✓
Reusability	✗	✓	✓
Code explosion	✓	✓	✗
Code duplication	✗	✓	✗
Opcode selection per test	✗ Static case statements	✓ Override from test	✓ Chain selection from test

## Conclusion



## REFERENCES

- [1] IEEE Standard for Universal Verification Methodology Language Reference Manual, IEEE Standard 1800.2-2017
- [2] Erich Gamma, Richard Helm, Ralph Johnson, John Vlissides, “Design Patterns Elements of Reusable Object-Oriented Software”, 22 Oct 2009
- [3] <https://edaplayground.com/x/PE9G>