Operating Systems

IPC

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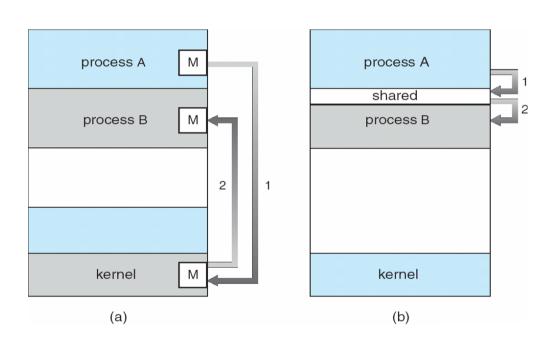
Interprocess Communication

In a complex system, processes might need to communicate with other processes

- sharing information
- enhancing the efficience of the computation
- improving modularity
- cross check

Basic IPC

- message passing (a)
- shared memory (b)



Message Passing

Compared to shared memory, passing a message requires copying memory

- Pro: easier implementation
- Cons: decreased efficiency

Three operations

- send(sender/mailbox, message)
- •receive(sender/mailbox, message)

Communication

- synchronous (blocking) vs asynchronous (nonblocking)
- direct (process) vs indirect (mailbox)
- limited vs unlimited

Message Passing

A message queue is a system-managed object that implements a mailbox

Processes need to know an identifier of the queue to operate on it

Functionalities

- open (creates or attaches to a message queue)
- close (detaches from a message queue)
- unlink (destroy)
- get/set attr (inspects the status of a queue/sets operation flags)
- put a message
- •wait for a message/ notify when a message is ready

Posix message interface

- -mq_close() close a message queue
- mq_getattr() get the current attributes of a message queue
- mq_notify() notify the calling process when the queue becomes nonempty
- •mq_open() open or create a message queue
- •mq_receive() receive a message from a queue
- •mq_send() put a message into a message queue
- •mq_setattr() set the flags for a message queue
- •mq_unlink() unlink (i.e. delete) a message queue

Message Queue Example

```
#define OUEUE NAME
                    "/test queue"
                                                       void * queueClient(void * args) {
#define MAX SIZE
                    1024
                                                        mad t ma;
#define MSG STOP
                    "exit"
                                                         char buffer[MAX SIZE];
int run=1;
                                                         mq = mq_open(QUEUE_NAME, O_WRONLY);
void * queueServer(void * args) {
                                                         int count = 0;
  mqd_t mq;
                                                         while(run) {
  ssize t bytes read;
                                                           snprintf(buffer, sizeof(buffer),
                                                                   "MESSAGE %d", count++);
  struct mg attr attr;
  char buffer[MAX SIZE + 1];
                                                           printf("CLIENT: Send message... \n");
  /* initialize the queue attributes */
                                                           mg send(mg, buffer, MAX SIZE, 0);
  attr.mq flags = 0;
                                                           fflush(stdout);
                                                           usleep(7.33 * 1e6);
  attr.mg maxmsg = 10;
  attr.mg msgsize = MAX SIZE;
  attr.mq_curmsgs = 0;
                                                         mq close(mq);
  /* create the message queue */
                                                         return NULL;
  mq = mq_open(QUEUE_NAME,
               O CREAT | O RDONLY | O NONBLOCK,
               0644, &attr);
  while(run) {
                                                       int main(int argc, char** argv) {
    memset(buffer, 0x00, sizeof(buffer));
                                                         pthread t client, server;
    bytes read = mg receive(mg, buffer,
                                                         printf("Start...\n");
                                                         pthread_create(&server, 0, &queueServer, 0);
                            MAX_SIZE, NULL);
    if(bytes_read >= 0) {
                                                         pthread_create(&client, 0, &queueClient, 0);
      printf("SERVER: Received message: %s\n", buffer);
    } else {
                                                         char c = getchar();
      printf("SERVER: None \n");
                                                         run=0;
                                                         pthread_join(server, NULL);
    fflush(stdout);
                                                         pthread join(client, NULL);
    usleep(0.725 * 1e6);
                                                         printf("Done...\n");
  mq_close(mq);
                                                         return (EXIT_SUCCESS);
  mq_unlink(QUEUE_NAME);
                                                       }
  return NULL;
```

Checking the queues

 From a shell, when the program is running you should see in the following directory /dev/mqueue all queues created by the running processes and also those not

A queue survives the creating process

unlinked

 Doing cat <queue_file> displays the status of the queue

Shared Memory

- Is a memory area shared between processes
- Similar to the message queues or the semaphores, multiple shared memories can be present
- Functionalities are similar to those of processes
 - opening
 - closing
 - destroying
- A shared memory, once opened needs to be "mapped" to the memory area of a process through mmap

Shared Memory Writer

```
int main(int argc, char** argv) {
  // create a shared memory object at key argv[1]
  char* resource name=argv[1];
  int fd=shm open(resource name, O RDWR|O CREAT, 0666);
  if (fd<0){
    printf("cannot create shared memory object, error: %s \n", sys errlist[errno]);
    exit(-1);
  int ftruncate_result = ftruncate(fd, SHMEM_SIZE);
  if (ftruncate result<0) {</pre>
    printf("cannot truncate shared memory object, error: %s \n", sys errlist[errno]);
    exit(-1);
  // map the descriptor to the memory of the process
  void * my_memory_area = mmap(NULL, SHMEM_SIZE, PROT_WRITE, MAP_SHARED,
                     fd, 0);
  int num rounds=100;
  for (int i=0; i<num rounds; ++i) {</pre>
    char* buffer=(char*) my_memory_area;
    sprintf(buffer, "This is the message %d", i);
    printf("writing [%s]\n", buffer);
    sleep(1);
  int unlink_result=shm_unlink(resource_name);
  if (unlink result<0) {</pre>
    printf("cannot unlink shared memory object, error: %s \n", sys_errlist[errno]);
    exit(-1);
```

Shared Memory Reader

```
int main(int argc, char** argv) {
  // create a shared memory object at key argv[1]
  char* resource name=argv[1];
  int fd=shm open(resource name, O RDONLY, 0666);
  if (fd<0){
   printf("cannot link to shared memory object, error: %s \n", sys errlist[errno]);
    exit(-1);
  int SHMEM SIZE=0;
  struct stat shm status;
  int fstat result = fstat(fd, &shm status); /* To obtain file size */
  if (fstat_result<0){</pre>
    printf("cannot get stats from memory object, error: %s \n", sys errlist[errno]);
    exit(-1);
  SHMEM SIZE = shm status.st size;
  void * my memory area = mmap(NULL, SHMEM SIZE, PROT READ, MAP SHARED,
                     fd, 0);
 while (1) {
    char* buffer=(char*) my_memory_area;
    printf("%s\n", buffer);
   usleep(100000);
  int unlink_result=shm_unlink(resource_name);
  if (unlink_result<0) {</pre>
    printf("cannot unlink shared memory object, error: %s \n", sys_errlist[errno]);
   exit(-1);
```

Checking the Shmem

- Similar to /dev/mqueue the shared memory is accessible through a virtual file in /dev/shm
- reading/writing to that file results in reading/weiting to the shmem

Considerations

- •We have seen the POSIX IPC API
- In conjunction to this API there is another set of functions that implement the SystemV primitives. These were prior the POSIX standardization
- In general the api is rather coherent for all objects
 - creation/opening: requires a string (filename) and returns an int (file descriptor)
 - specific functions operate on the object, solely based on the file descriptor
 - little things to remember, you can guess a lot

Exercises

 Implement a message queue by using a shared memory and semaphores