

Datalog and Answer Set Programming (part 3)

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Positive Datalog with constraints

Constraints

A **constraint** is a new kind of rule of the form:

$$:- \beta_1, \dots, \beta_n$$

where:

- n is a positive integer
- every β_i is an atom

That is, a constraint is a rule with an empty head.

Examples of constraints:

$$:- p(X, Y), r(Y, Z).$$

$$:- p(a, b), q(b).$$

$$:- s(Y, X).$$

A constraint is **ground** if it does not contain occurrences of variables.

Datalog programs with constraints

A **Datalog program with constraints** is a set of positive rules and constraints.

Semantics of constraints

A ground constraint $\text{:- } \beta_1, \dots, \beta_n$ is **satisfied** in an interpretation I if at least one of its atoms β_i does **not** belong to I .

We naturally extend the notion of grounding of a Datalog program P to the presence of non-ground constraints in P :

The **grounding** of a **constraint** c with respect to a set of constants C , denoted as $\text{ground}(c, C)$, is the set of all ground constraints that can be obtained from c by replacing, for every variable x occurring in c , every occurrence of x with a constant from C .

The **grounding** of a (non-ground) positive Datalog **program** with constraints P , denoted as $\text{ground}(P)$, is the ground Datalog program obtained by the union of all the sets $\text{ground}(r, HU(P))$ such that r is a rule in P , and all the sets $\text{ground}(c, HU(P))$ such that c is a constraint in P .

Semantics of programs with constraints

An interpretation I is a **model** for a Datalog program with constraints P if every ground rule and every ground constraint in $ground(P)$ is satisfied in I .

(analogous definition of minimal model as in the case of positive Datalog)

Property: every positive Datalog program with constraints P has either no models (and hence no minimal models) or exactly one minimal model (and in the latter case we denote such a model by $MM(P)$).

Reasoning over programs with constraints

The techniques for reasoning with positive Datalog programs (naive or semi-naive evaluation) can be easily extended to the presence of constraints in the program.

Let P be a Datalog program with constraints. Then:

- Let P' be the program obtained from P eliminating all the constraints;
- Compute (using e.g. the naive or semi-naive evaluation) $MM(P')$, the minimal model of P' ;
- Check whether every constraint in P is satisfied in $MM(P')$:
 - if this is the case, then $MM(P')$ is the minimal model of P ;
 - otherwise P has no models (and hence no minimal models).

(Of course, every constraint in P is satisfied in $MM(P')$ iff every ground constraint in $ground(P)$ is satisfied in $MM(P')$)

Example

Let P be the following program with constraints:

```
r(X, Y) :- p(X, Y).  
r(X, Z) :- p(X, Y), r(Y, Z).  
s(X, Y) :- r(Y, X).  
:- p(X, X). [c1]  
:- r(X, Y), r(Y, X). [c2]  
p(a, b).  
p(b, c).  
p(c, d).
```

First, we notice that the program P' obtained from P eliminating the two constraints c1 and c2 corresponds to the previous program for which we have computed the minimal model through the semi-naive computation.

Example

So, the program P' has the following minimal model $MM(P')$:

$$\{ p(a, b), p(b, c), p(c, d), r(a, b), r(b, c), r(c, d), r(a, c), r(b, d), \\ s(b, a), s(c, b), s(d, c), r(a, d), s(c, a), s(d, b), s(d, a) \}$$

Now we have to check whether the constraints $c1$ and $c2$ are satisfied in $MM(P')$. We have:

$$\begin{aligned} \text{ground}(c1, HU(P)) = \\ & \text{:- } p(a, a). \\ & \text{:- } p(b, b). \\ & \text{:- } p(c, c). \\ & \text{:- } p(d, d). \end{aligned}$$

Example

$ground(c2, HU(P)) =$

- $\vdash r(a, a), r(a, a).$
- $\vdash r(a, b), r(b, a).$
- $\vdash r(a, c), r(c, a).$
- $\vdash r(a, d), r(d, a).$
- $\vdash r(b, a), r(a, b).$
- $\vdash r(b, b), r(b, b).$
- $\vdash r(b, c), r(c, b).$
- $\vdash r(b, d), r(d, b).$
- $\vdash r(c, a), r(a, c).$
- $\vdash r(c, b), r(b, c).$
- $\vdash r(c, c), r(c, c).$
- $\vdash r(c, d), r(d, c).$
- $\vdash r(d, a), r(a, d).$
- $\vdash r(d, b), r(b, d).$
- $\vdash r(d, c), r(c, d).$
- $\vdash r(d, d), r(d, d).$

Example

It is easy to verify that every ground constraint in $ground(c1, HU(P))$ is satisfied in $MM(P')$, and that every ground constraint in $ground(c2, HU(P))$ is satisfied in $MM(P')$.

Consequently, $MM(P')$ is the minimal model of P .

Example

Now let P'' be the program obtained from P adding the following constraint:

$$:- r(X, Y), r(Y, W), r(W, Z), s(Z, X). \text{ [c3]}$$

Among others, the following ground constraint belongs to $ground(c3, HU(P))$:

$$:- r(a, b), r(b, c), r(c, d), s(d, a).$$

This ground constraint is NOT satisfied in $MM(P')$ (because all the atoms in the body of the constraints belong to $MM(P')$), therefore $c3$ is non satisfied in $MM(P')$. Consequently, P'' has no models (and hence no minimal models).