pattern database

simplify the problem by removing some variables

variable removal

how:

```
given: planning problem and state
(not necessarily the initial state!)
aim: estimate distance to the goal from the state
use: guide the search (A*, greedy best-first search,...)
```

- remove some variables from the problem and the state
- compute optimal plan
- its length estimates the length of the optimal plan in the original problem

example

```
a: x \Rightarrow y, z
b: y \Rightarrow -z
c: x,y,-z \Rightarrow w
goal: w, z
calculate h(x-y-z-w)
optimal plan from state: a,b,c,a (lenght 4)
perfect heuristics is h(x-y-z-w) = 4
```

keep only z and w

```
a: x \Rightarrow y, z

b: y \Rightarrow -z

c: x, y, -z \Rightarrow w

goal: w, z

b: \Rightarrow -z

c: -z \Rightarrow w

goal: w, z

remove x and y

state x-y-z-w becomes -z-w

optimal plan from state: c, a (lenght 2)

heuristics h_{zw}(x-y-z-w)=2
```

[note] Actions a and b have no precondition after removal. They can be executed in every state.

keep only x and w

```
a: x \Rightarrow y, z a: x \Rightarrow b: y \Rightarrow -z c: x, y, -z \Rightarrow w goal: w, z goal: w
```

remove y and z

state x-y-z-w becomes x-w

optimal plan from state: c (length 1)

heuristics $h_{xw}(x-y-z-w)=1$

[note] Actions a and b end up with no effects after removal of variables. They are irrelevant to planning, so they could be deleted altogether. They still are of interest for the theoretical analysis.



observations

- 1. variables removed ⇒ shorter plans (4 becomes 2 or 1)
- 2. optimal plan length depends on which variables are deleted (2 or 1 depending on which variables are deleted)

is observation 1 true in general?

plan length

a plan for the original instance is also a plan after deletion:

- deleting preconditions makes actions still executable in the same state
- deleting effects in general makes some other actions no longer executable, but not in this case: effects also deleted from preconditions of all other actions
- same for deleting variables for the goal

deletion may introduce new plans (examples above)

what is this used for?

A*, greedy best-first search, etc. need an heuristics h(s)

heuristics:

h(s) = length of shortest plan from s to the goal after deleting variables

after deletion, compute shortest plan for all states in the example: a plan for -z-w, a plan for -z-w, a plan for z-w and a plan for z-w only four plans, not sixteen

why "pattern database"?

why this name?

originates from the 15-puzzle

8	7	10	13	1	2	3	4
3	15	14	2	5	6	7	8
6	9	5	12	9	10	11	12
1		4	11	13	14	15	
<u></u>	-	_	13	1	2	3	4
_ 3	_ _	_ _	13 2	1 5			4
3	- - 9	_ _ 5	13 2 -	1 5 9			4 -

fix some tiles, for example 1, 2, 3, 4, 5, 9, 13 each disposition of these and the empty square is a pattern for each pattern, store the minimal number of moves to get the tiles in position

database of minimal plan lengths for each pattern

erasing some tiles ⇒ delete some variables

search space

a: $x \Rightarrow y, z$

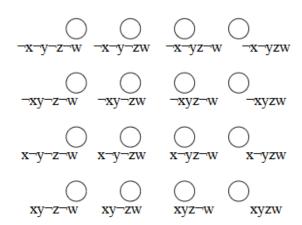
b: $y \Rightarrow -z$

c: $x, y, -z \Rightarrow w$

goal: w,z

restricting to some variables simplifies the problem obvious when looking at the search spaces

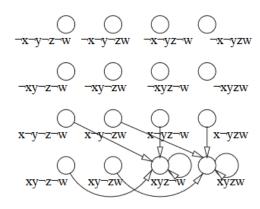
states



original problem

search space, no actions

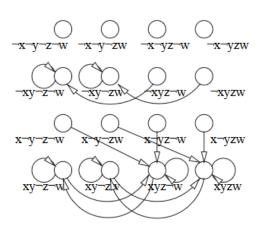
action a



original problem

states and action a: $x \Rightarrow y, z$

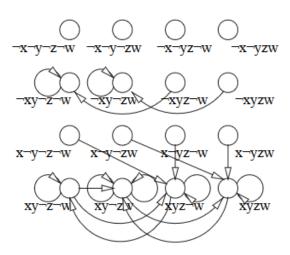
action b



original problem

states and actions a and b: $y \Rightarrow -z$

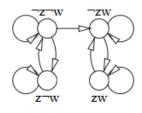
action c



original problem

states and all three actions, including c: $x, y, -z \Rightarrow w$

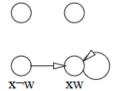
search space: only z and w



two variables ⇒ four states

example: executing a in -zw leads to itself

search space: only x and w



smaller is better?

more variables removed:

- smaller search space
 ⇒ easier to search for an optimal plan but...
- optimal plan may become too short
 ⇒ heuristics underestimate the cost too much

grouping states

deleting variables affects the search space

for example, the four states in the original instance:

-xy-z-w,

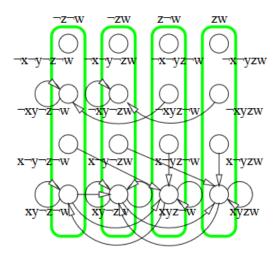
x-y-z-w,

xy-z-w

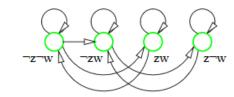
when deleting xy, all become:

-z-w

grouping states, in the search space



every column of four states form a group every group is a state of the simplified problem



abstraction heuristics

group sets of states

grouping by ignoring some variables ⇒ pattern database other methods exist