

# Zero-Shot Continual Learning

Ivan Skorokhodov

December 28, 2019

# Modern CL techniques

Modern CL techniques can be divided into three types:

- ▶ Regularization-based ([4], [1], etc): detect the weights which are important for previous tasks and do not change them much in the future.
- ▶ Replay-based ([2], [6], etc): store a part of previous data to replay it in the future.
- ▶ Component-based ([5], [3], etc): allocate different parts of the network to different tasks.

All of them has the loss in the form:

$$\mathcal{L}(\theta) = L_{\text{current task}} + L_{\text{forgetting}}$$

But what if we'll try to improve the performance on future tasks?

$$\mathcal{L}(\theta) = L_{\text{current task}} + L_{\text{forgetting}} + L_{\text{future transfer}}$$

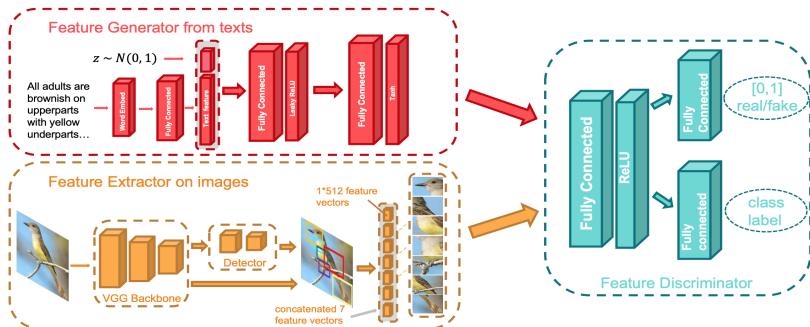
# Zero-Shot Learning (ZSL)

- ▶ For each class  $y \in \mathcal{Y}$  associate an attribute vector  $a_c$  which describes its characteristics.
- ▶ All the data is divided into two parts: seen  $D^s = \{X^s, Y^s, A^s\}$  and unseen  $D^u = \{X^u, Y^u, A^u\}$ .
- ▶ First, we train on seen data  $D^s$  using class attributes and then validate the performance on unseen data  $D^u$  (or on both  $D^s \cup D^u$ ).
- ▶ Using information from class descriptions we can detect classes that we have not seen during training.
- ▶ It can be used to improve future transfer for CL models.

# Generative Adversarial Zero-Shot Learning [7]

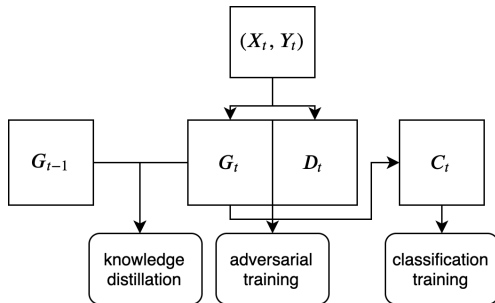
GAZSL approach for ZSL:

- ▶ Train a conditional GAN model to generate samples from class descriptions.
- ▶ Train a classifier to predict a class from the generated sample.
- ▶ At test time, generate unseen samples, compute a class prototype and compare test images to synthetic prototypes.



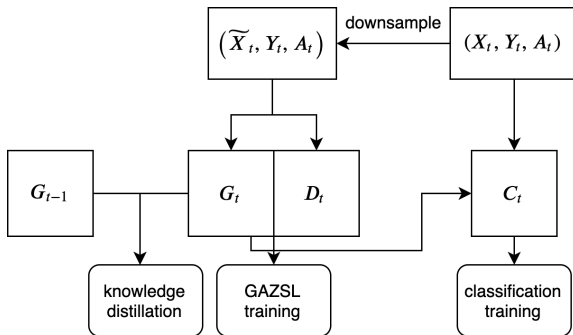
# Generative Memory for Continual Learning [6]

- ▶ For task  $t$ , train a conditional GAN model  $(G_t, D_t)$  to save current dataset.
- ▶ Distill the knowledge of previous generator  $G_{t-1}$  into  $G_t$  so not to forget previous data.
- ▶ Train a classifier  $C_t$  on top of  $G_t$ .










# Zero-Shot Continual Learning

- ▶ Merge two approaches: GAZSL + MeRGAN to improve future transfer.
- ▶ Since GAN model is difficult to train in high-scale image space, one can train it in either low-scale image space or latent space.



# References

-  [Rahaf Aljundi et al. "Memory Aware Synapses: Learning what \(not\) to forget". In: \*CoRR\* abs/1711.09601 \(2017\).](#)
-  [Arslan Chaudhry et al. "Efficient Lifelong Learning with A-GEM". In: \*International Conference on Learning Representations\*. 2019.](#)
-  [Chrisantha Fernando et al. "PathNet: Evolution Channels Gradient Descent in Super Neural Networks". In: \*CoRR\* abs/1701.08734 \(2017\).](#)
-  [James Kirkpatrick et al. "Overcoming catastrophic forgetting in neural networks". In: \*Proceedings of the National Academy of Sciences\* 114.13 \(2017\), pp. 3521–3526.](#)
-  [Joan Serra et al. "Overcoming Catastrophic Forgetting with Hard Attention to the Task". In: \*ICML\*. Vol. 80. \*Proceedings of Machine Learning Research\*. PMLR, Oct. 2018, pp. 4548–4557.](#)
-  [Chenshen Wu et al. "Memory Replay GANs: Learning to Generate New Categories without Forgetting". In: \*Advances in Neural Information Processing Systems 31\*. Curran Associates, Inc., 2018, pp. 5962–5972.](#)
-  [Yizhe Zhu et al. "A Generative Adversarial Approach for Zero-Shot Learning From Noisy Texts". In: \*CVPR\*. June 2018.](#)