

Diagonalisation of Matrices

MTH1004M Linear Algebra



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What is diagonalisation?

Suppose that

$$A = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}$$

has 2 real eigenvalues λ_1, λ_2 . Is A related to the diagonal matrix?

$$D = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} \quad ?$$

The answer is yes! We are going to see why and how.

Example

We have found (in the last slides) that the matrix

$$A = \begin{bmatrix} 4 & -5 \\ 2 & -3 \end{bmatrix}$$

⇒ has the eigenvalue $\lambda_1 = 2$ with eigenvector $u_1 = \begin{bmatrix} 5 \\ 2 \end{bmatrix}$

⇒ and $\lambda_2 = -1$ with $u_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$.

Let's construct a matrix with columns the eigenvectors of A :

$$P = \begin{bmatrix} 5 & 1 \\ 2 & 1 \end{bmatrix}.$$

Its inverse P^{-1} is:

$$P^{-1} = \frac{1}{3} \begin{bmatrix} 1 & -1 \\ -2 & 5 \end{bmatrix}$$



Example

We Perform the operation $P^{-1}AP$:

$$P^{-1}AP = \frac{1}{3} \begin{bmatrix} 1 & -1 \\ -2 & 5 \end{bmatrix} \begin{bmatrix} 4 & -5 \\ 2 & -3 \end{bmatrix} \begin{bmatrix} 5 & 1 \\ 2 & 1 \end{bmatrix} = \begin{bmatrix} 2 & 0 \\ 0 & -1 \end{bmatrix} = D ,$$

and we observe that the output matrix D is not only diagonal but contains the eigenvalues $\lambda_1 = 2$ and $\lambda_2 = -1$ in the same order as the order of the eigenvector columns in P .

The Diagonal Form of a Matrix

So, observe that, given:

- ⇒ a 2×2 matrix A which has real eigenvalues λ_1, λ_2 ,
- ⇒ two linearly independent eigenvectors u_1, u_2 ,
- ⇒ and a diagonal matrix D with entries λ_1, λ_2

A and D are related by a matrix P whose columns are formed by the eigenvectors u_1, u_2 :

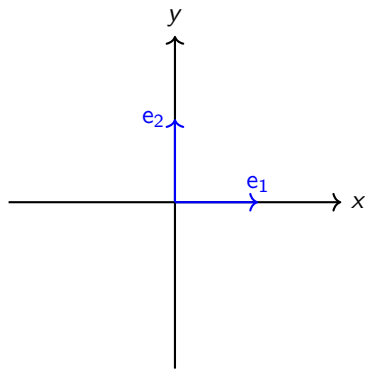
$$P = \begin{bmatrix} | & | \\ u_1 & u_2 \\ | & | \end{bmatrix} .$$

P is called the *eigenvector matrix* and it holds that:

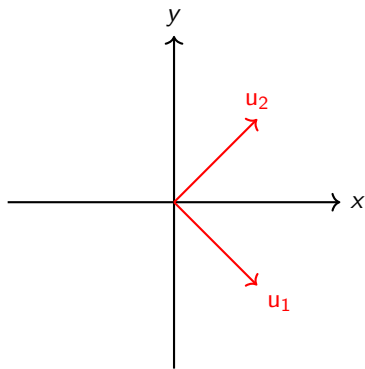
$$D = P^{-1}AP \quad \text{or} \quad AP = PD .$$

Remark: The eigenvalues will come up in D in the same order as their corresponding eigenvectors in P .

What this means geometrically?



Geometrically this means that, given a matrix $A = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}$ which is naturally expressed in \mathbb{R}^2 with basis the standard orthonormal vectors e_1, e_2



... when expressed in another basis of \mathbb{R}^2 , the basis formed by the eigenvectors u_1 and u_2 , then A is viewed as the diagonal matrix $D = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix}$.

Definitions

► Let A, B be $n \times n$ matrices. A is called **similar** to B if there is an invertible $n \times n$ matrix P , such that $P^{-1}AP = B$.



► An $n \times n$ matrix A is called **diagonalisable** if it is similar to the diagonal matrix D whose entries are the n real eigenvalues $\lambda_1, \lambda_2, \dots, \lambda_n$.

Example

Let

$$A = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 1 & 1 & 0 \end{bmatrix}, \quad D = \begin{bmatrix} 2 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$

Verify that the matrix A with eigenvectors $u_1 = [1, 1, 1]^T$, $u_2 = [1, 1, -2]^T$ and $u_3 = [-1, 1, 0]^T$ is similar to the diagonal matrix D .

It is always easier to prove that $AP = PD$, which requires two matrix multiplications, than finding the inverse of the matrix P . The matrix P is:

$$P = \begin{bmatrix} 1 & 1 & -1 \\ 1 & 1 & 1 \\ 1 & -2 & 0 \end{bmatrix}.$$

$$\text{Then } AP = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 1 & 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 1 & -1 \\ 1 & 1 & 1 \\ 1 & -2 & 0 \end{bmatrix} = \begin{bmatrix} 2 & -1 & -1 \\ 2 & -1 & 1 \\ 2 & 2 & 0 \end{bmatrix}$$

$$\text{and } PD = \begin{bmatrix} 1 & 1 & -1 \\ 1 & 1 & 1 \\ 1 & -2 & 0 \end{bmatrix} \begin{bmatrix} 2 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 2 & -1 & -1 \\ 2 & -1 & 1 \\ 2 & 2 & 0 \end{bmatrix} \quad \square$$

How to prove that a matrix A is diagonalisable

- If P is the matrix with columns the eigenvectors of A .
- P is invertible if $\det P \neq 0$.
- If P is invertible, then its columns, the eigenvectors are linearly independent.

So, to prove that a matrix A is diagonalisable, it is easier to use the following Theorem.

Theorem

Let A be an $n \times n$ matrix. Then A is **diagonalisable** if and only if A has n linearly independent eigenvectors.

Example: A non-diagonalisable matrix

Show that the matrix:

$$A = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$$

is non-diagonalisable.

A has two eigenvalues $\lambda_1 = 1$, $\lambda_2 = 1$. The eigenvectors u_1, u_2 are found by setting:

$$Au_1 = \lambda_1 u_1 \quad \text{or} \quad (A - \lambda_1 I)u_1 = 0 \quad \text{which is} \quad (A - I)u_1 = 0$$

$$\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ y_1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

and yields the system

$$\begin{cases} 0x_1 + 1y_1 = 0 \\ 0x_1 + 0y_1 = 0 \end{cases}$$

with null space the eigenspace:

$$V_{\lambda_1} = \left\{ \begin{bmatrix} x_1 \\ y_1 \end{bmatrix} \text{ in } \mathbb{R}^2 : y_1 = 0, x_1 \text{ in } \mathbb{R} \right\} = \left\{ \begin{bmatrix} x_1 \\ 0 \end{bmatrix} : x_1 \text{ in } \mathbb{R} \right\} = \text{span} \left(\begin{bmatrix} 1 \\ 0 \end{bmatrix} \right)$$

Example: A non-diagonalisable matrix

Hence,

$$u_1 = [1, 0]^T.$$

is the eigenvector associated with λ_1

Following the same process for u_2 we find that:

$$V_{\lambda_2} = \left\{ \begin{bmatrix} x_2 \\ y_2 \end{bmatrix} \text{ in } \mathbb{R}^2 : y_2 = 0, x_2 \text{ in } \mathbb{R} \right\} = \left\{ \begin{bmatrix} x_2 \\ 0 \end{bmatrix} : x_2 \text{ in } \mathbb{R} \right\} = \text{span} \left(\begin{bmatrix} 1 \\ 0 \end{bmatrix} \right)$$

So, $u_2 = u_1$.

Since $u_1 = u_2$ A is non-diagonalisable.

⇒ **Remark:** When it is not obvious that the eigenvectors are linearly dependent, you can show that the matrix P is *non-invertible*, by showing that $\det P \neq 0$.

Example: A diagonalisable matrix

Let

$$A = \begin{bmatrix} 4 & 1 & -1 \\ 2 & 5 & -2 \\ 1 & 1 & 2 \end{bmatrix}$$

with real eigenvalues $\lambda_1 = 3$, $\lambda_2 = 3$ and $\lambda_3 = 5$. Show that A is diagonalisable.

We first find the eigenvectors u_1, u_2, u_3 of the matrix A . For $\lambda_1 = 3$, the equation $(A - \lambda I)x = 0$ becomes:

$$\left(\begin{bmatrix} 4 & 1 & -1 \\ 2 & 5 & -2 \\ 1 & 1 & 2 \end{bmatrix} - 3 \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} x_1 \\ y_1 \\ z_1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 & -1 \\ 2 & 2 & -2 \\ 1 & 1 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ y_1 \\ z_1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

and is equivalent to the following system:

$$\begin{cases} x_1 + y_1 - z_1 = 0 \\ 2x_1 + 2y_1 - 2z_1 = 0 \\ x_1 + y_1 - z_1 = 0 \end{cases} .$$

This system is reduced to a single equation $x_1 + y_1 - z_1 = 0$. The eigenspace is:

$$\begin{aligned} V_{\lambda_1} &= \left\{ \begin{bmatrix} x_1 \\ y_1 \\ z_1 \end{bmatrix} \text{ in } \mathbb{R}^3 : z_1 = x_1 + y_1 \right\} = \left\{ \begin{bmatrix} x_1 \\ y_1 \\ x_1 + y_1 \end{bmatrix} : x_1, y_1 \text{ in } \mathbb{R} \right\} \\ &= \text{span} \left(\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \right) \end{aligned}$$

so it yields that

$$u_1 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, u_2 = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$$

and that $\dim V_{\lambda_1} = 2$ (Check that they are linearly independent!).

For the last eigenvector associated to $\lambda_3 = 5$, we have $(A - \lambda_3 I)u_3 = 0$, or:

$$\begin{bmatrix} -1 & 1 & -1 \\ 2 & 0 & -2 \\ 1 & 1 & -3 \end{bmatrix} \begin{bmatrix} x_3 \\ y_3 \\ z_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$



that is equivalent to the system:

$$\begin{cases} -x_3 + y_3 - z_3 = 0 \\ 2x_3 - 2z_3 = 0 \\ x_3 + y_3 - 3z_3 = 0 \end{cases}.$$

The above system is reduced to the following:

$$\begin{cases} -2x_3 + y_3 = 0 \\ z_3 = x_3 \end{cases}$$

with eigenspace

$$\begin{aligned} V_{\lambda_3} &= \left\{ \begin{bmatrix} x_3 \\ y_3 \\ z_3 \end{bmatrix} \text{ in } \mathbb{R}^3 : y_3 = -2x_3, z_3 = x_3 \right\} = \left\{ \begin{bmatrix} x_3 \\ -2x_3 \\ x_3 \end{bmatrix} : x_3 \text{ in } \mathbb{R} \right\} \\ &= \text{span} \left(\begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix} \right) \end{aligned}$$

Hence, the eigenvector is $u_3 = [1, -2, 1]^T$.



So, we produce the matrix P by introducing to its columns the components of the eigenvectors u_1, u_2, u_3 :

$$P = \begin{bmatrix} | & | & | \\ u_1 & u_2 & u_3 \\ | & | & | \end{bmatrix}$$

and we get:

$$P = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & -2 \\ 1 & 1 & 1 \end{bmatrix}$$

So, now, is the matrix A diagonalisable? Since

$$\det P = 1 \begin{vmatrix} 1 & -2 \\ 1 & 1 \end{vmatrix} + 1 \begin{vmatrix} 0 & 1 \\ 1 & 1 \end{vmatrix} = (1 + 2) + (-1) = 2 \neq 0$$

the answer is yes, the matrix A is diagonalisable, which also implies that u_1, u_2, u_3 are linearly independent. \square

Definitions and Remarks

⇒ We call **geometric multiplicity** of an eigenvalue λ the dimension of the space V_λ spanned by the eigenvectors.

⇒ If an $n \times n$ matrix A has:

→ n real eigenvalues where $\lambda_1 \neq \lambda_2 \neq \dots \neq \lambda_n$

then it yields that their corresponding eigenvectors u_1, u_2, \dots, u_n are linearly independent, and hence, the matrix A is diagonalisable.

→ 2 equal eigenvalues $\lambda_1 = \lambda_2 = \lambda$ with linearly independent eigenvectors

we say that the *algebraic multiplicity* of λ is 2. The geometric multiplicity of λ is 2.

→ 2 equal eigenvalues $\lambda_1 = \lambda_2 = \lambda$ with linearly dependent eigenvectors

then the geometric multiplicity of λ is 1, while the algebraic multiplicity of λ is 2.

Remark *Diagonalisation* is checked on the eigenvectors. *Invertibility* is checked on the eigenvalues.

Lemma

If A is an $n \times n$ matrix, then the geometric multiplicity of each eigenvalue is less than or equal to its algebraic multiplicity.

⇒ *less than* implies that the matrix is non-diagonalisable.

⇒ *equal to* implies that the matrix is diagonalisable.

Application: The n -th power of a Matrix

Let A be a 2×2 diagonalisable matrix. Find A^n .

If A is diagonalisable then, there is a matrix P and a diagonal matrix D , such that:

$$A = PDP^{-1}$$

It is then:

$$\begin{aligned} A^n &= (PDP^{-1})^n = (PDP^{-1})(PDP^{-1}) \dots (PDP^{-1})(PDP^{-1}) \\ &= PD \underbrace{P^{-1}P \dots P^{-1}P}_n DP^{-1} = P \underbrace{DD \dots D}_n P^{-1} \\ &= PD^n P^{-1} = P \begin{bmatrix} \lambda_1^n & 0 \\ 0 & \lambda_2^n \end{bmatrix} P^{-1}. \quad \square \end{aligned}$$

Application: The n -th power of a Matrix

$$\text{Let } A = \begin{bmatrix} -3 & -2 \\ 4 & 3 \end{bmatrix}. \text{ Find } A^{100}.$$

Of course, we will never calculate A^{100} with A in its original form.
We first search for the eigenvalues λ .

$$\det(A - \lambda I) = \det \begin{bmatrix} -3 - \lambda & -2 \\ 4 & 3 - \lambda \end{bmatrix} = (-3 - \lambda)(3 - \lambda) - 4(-2) = \lambda^2 - 1$$

The condition $\det(A - \lambda I) = 0$ implies $\lambda^2 = 1$, so there are two non-equal eigenvalues $\lambda_1 = -1$ and $\lambda_2 = 1$.

$$\begin{aligned} A^{100} &= (PDP^{-1})^{100} = \text{..show that..} = PD^{100}P^{-1} = P \begin{bmatrix} (-1)^{100} & 0 \\ 0 & (1)^{100} \end{bmatrix} P^{-1} \\ &= PIP^{-1} = PP^{-1} = I. \quad \square \end{aligned}$$

Example: Symmetric Matrices

Prove that any symmetric matrix of the form:

$$A = \begin{bmatrix} a & b \\ b & a \end{bmatrix}$$

where $a \neq b$, a, b in \mathbb{R} , is diagonalisable and find P .

Show that A has two real eigenvalues: $\lambda_1 = a + b$, $\lambda_2 = a - b$ (it one of our practical problems for this week). These eigenvalues are non-equal as long as $b \neq 0$. So there are two cases:

(i) $b \neq 0$, where a 2×2 matrix with two non-equal eigenvalues has two linearly independent eigenvectors, therefore A is diagonalisable, and

(ii) $b = 0$, where A becomes $A = \begin{bmatrix} a & 0 \\ 0 & a \end{bmatrix}$, so it is diagonal in its original form.

⇒ Therefore, any symmetric 2×2 matrix A is diagonalisable.

Example: Symmetric Matrices

Only for case (i) $b \neq 0$ is necessary to find the eigenvectors. (Why?)

In order to find the matrix P , we need the eigenvectors u_1, u_2 , which we get by replacing the eigenvalues into $(A - \lambda I)x = 0$.

✧ For $\lambda_1 = a + b$ it is:

$$\left(\begin{bmatrix} a & b \\ b & a \end{bmatrix} - (a+b) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} x_1 \\ y_1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -b & b \\ b & -b \end{bmatrix} \begin{bmatrix} x_1 \\ y_1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

where the components of the eigenvectors u_1 follow the equation $-bx_1 + by_1 = 0$, or equivalently $-x_1 + y_1 = 0$, because $b \neq 0$, so the eigenspace for $\lambda_1 = a + b$ is:

$$V_{\lambda_1} = \left\{ \begin{bmatrix} x_1 \\ y_1 \end{bmatrix} \text{ in } \mathbb{R}^2 : y_1 = x_1, x_1 \text{ in } \mathbb{R} \right\} = \left\{ \begin{bmatrix} x_1 \\ x_1 \end{bmatrix} : x_1 \text{ in } \mathbb{R} \right\} = \text{span} \left(\begin{bmatrix} 1 \\ 1 \end{bmatrix} \right)$$

The eigenvector is $u_1 = [1, 1]^T$.

Example: Symmetric Matrices

We follow the same process for λ_2 .

✧ For $\lambda_2 = a - b$ it is:

$$(A - \lambda_2 I)u_2 = 0$$

$$\left(\begin{bmatrix} a & b \\ b & a \end{bmatrix} - (a - b) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} x_2 \\ y_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} b & b \\ b & b \end{bmatrix} \begin{bmatrix} x_2 \\ y_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

where the components of the eigenvectors u_2 follow the equation $bx_2 + by_2 = 0$ or $x_2 + y_2 = 0$ ($b \neq 0$), so the eigenspace for $\lambda_2 = a - b$ is:

$$V_{\lambda_2} = \left\{ \begin{bmatrix} x_2 \\ y_2 \end{bmatrix} \text{ in } \mathbb{R}^2 : y_2 = -x_2, x_2 \text{ in } \mathbb{R} \right\} = \left\{ \begin{bmatrix} x_2 \\ -x_2 \end{bmatrix} : x_2 \text{ in } \mathbb{R} \right\} = \text{span} \left(\begin{bmatrix} 1 \\ -1 \end{bmatrix} \right)$$

and we get $u_2 = [1, -1]^T$.

So the matrix P is $P = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$ \square

Example: Skew-Symmetric Matrices

Is the skew-symmetric matrix

$$A = \begin{bmatrix} 0 & -\omega \\ \omega & 0 \end{bmatrix},$$

with $\omega > 0$ diagonalisable?

⇒ There are cases where a matrix has *no real eigenvalues*.

⇒ A is a skew-symmetric matrix, which means that $A^T = -A$.

Here it is:

$$\det(A - \lambda I) = \det \begin{bmatrix} -\lambda & -\omega \\ \omega & -\lambda \end{bmatrix} = \lambda^2 + \omega^2$$

so, the condition $\det(A - \lambda I) = 0$ implies that $\lambda^2 + \omega^2 = 0$ and consequently that $\lambda_1 = i\omega$, $\lambda_2 = -i\omega$. Since the matrix A has two purely imaginary complex conjugate eigenvalues, it cannot be diagonalised over \mathbb{R} . \square