Computational Analytical Mechanics



Simulation | Numerical solutions for the Euler-Lagrange equation

In the following exercises, you will solve numerically the Euler-Lagrange equation for each generalized coordinate. Plotting these solutions, using the given initial conditions and within the given time ranges, you will be simulating the dynamics of these systems.

Use $|\vec{q}| = 9.81 \,\mathrm{m \, s^{-2}}$ for the magnitude of the acceleration due to gravity.

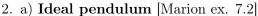
Exercises marked with (*) have extra difficulty, don't hesitate to ask for help.

1. Atwood machine

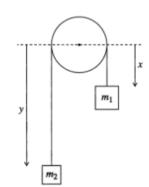
Time from t = 0s to t = 10s. Parameters and initial conditions: $\ell_{\text{rope}} > 150 \,\text{m}, \, R_{\text{pulley 1}} = 0.5 \,\text{m},$

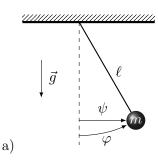
$$m_1 = 8 \,\mathrm{kg}, \, m_2 = 1 \,\mathrm{kg}, \, M_{\mathrm{pulley}} = 4 \,\mathrm{kg},$$

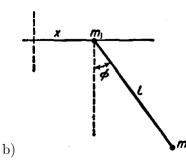
$$x(t=0) = 25 \,\mathrm{m}, \, \dot{x}(t=0) = -10 \,\mathrm{m \, s^{-1}}.$$

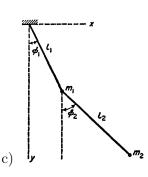


- - b) Pendulum with free support [Landau §5 ex. 2]
 - c) Double pendulum [Landau §5 ex. 1]









Time from t = 0 s to t = 10 s. Parameters and initial conditions:

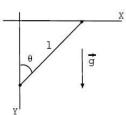
(a)
$$m = 3 \text{ kg}, \ \ell = 2 \text{ m}, \ \varphi(t = 0) = \frac{\pi}{4}, \ \dot{\varphi}(t = 0) = 0.$$

(b)
$$m_1 = 3 \text{ kg}, m_2 = 1 \text{ kg}, \ell = 2 \text{ m}, x(t=0) = 1 \text{ m}, \dot{x}(t=0) = 0.5 \text{ m s}^{-1}, \phi(t=0) = \frac{\pi}{8}, \dot{\phi}(t=0) = 0.$$

(c)
$$m_1 = 3 \text{ kg}, m_2 = 1 \text{ kg}, \ell_1 = 1 \text{ m}, \ell_2 = 1 \text{ m}, \phi_1(t=0) = \frac{\pi}{8}, \dot{\phi}_1(t=0) = 0, \phi_2(t=0) = \frac{\pi}{4}, \dot{\phi}_2(t=0) = -\frac{\pi}{16} \text{s}^{-1}.$$

3. Pendulum of linked beads moving on rigid thin wires

Time from t = 0 s to t = 10 s. Parameters and initial conditions: $m_1 = m_2 = m = 2 \text{ kg}, \ l = 2 \text{ m}, \ \theta(t = 0) = \frac{\pi}{4}, \ \dot{\theta}(t = 0) = 0.$



4. (*) Compound Atwood machine [Marion ex. 7.8]

Time from t = 0 s to t = 5 s. Parameters and initial conditions: $\ell_{\rm top} = 15\,\mathrm{m},\, R_{\rm top~pulley} = 0.5\,\mathrm{m},\, \ell_{\rm bottom} = 15\,\mathrm{m},\, R_{\rm bottom~pulley} = 0.5\,\mathrm{m},$ $m_1 = 1 \text{ kg}, m_2 = 2 \text{ kg}, m_3 = 3 \text{ kg}, M_{\text{top pulley}} = 4 \text{ kg}, M_{\text{bottom pulley}} = 4 \text{ kg},$ $y(t=0) = 1 \text{ m}, \ \dot{y}_1(t=0) = 0, \ y_2(t=0) = 2 \text{ m}, \ \dot{y}_2(t=0) = 0$

