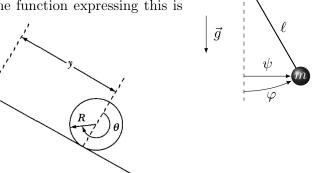
### Constraint forces | Lagrange multipliers

#### 1. Ideal pendulum

Calculate the tension in the string using the method of Lagrange multipliers. The constraint is that the bead is always at  $\vec{r} = \ell \hat{\rho}$ , ergo, the function expressing this is  $f(\rho) = \rho - \ell = 0.$ 



 $\alpha$ 

- 2. Cylinder rolling over an inclined plane [Marion ex. 7.5]
  - (a) Write the equations of motion,
  - (b) find the angular acceleration,
  - (c) and the constraint forces.

## 3. **Double Atwood machine** [Marion ex. 7.8 and 7-37]

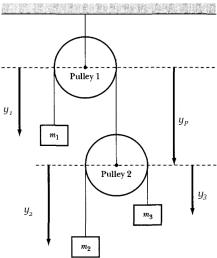
Use the frame of reference shown in the figure. For this system of pulleys, determine:

- (a) the equations of motion,
- (b) and the tensions in both strings using the method of Lagrange mul- y<sub>t</sub> tipliers.

Results: 
$$Q_1 = \frac{g(32m_1m_2m_3 + 8m_1m_2m_p + 20m_1m_3m_p + 4m_1m_p^2 + 8m_2m_3m_p + 2m_2m_p^2 + 4m_3m_p^2 + m_p^3)}{4m_1m_2 + 4m_1m_3 + 2m_1m_p + 16m_2m_3 + 6m_2m_p + 14m_3m_p + 3m_p^2}$$

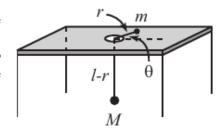
$$Q_2 = \frac{gm_3 \cdot (16m_1m_2 + 6m_1m_p + 4m_2m_p - m_p^2)}{4m_1m_2 + 4m_1m_3 + 2m_1m_p + 16m_2m_3 + 6m_2m_p + 14m_3m_p + 3m_p^2}$$

$$Q_2 = \frac{gm_3 \cdot \left(16m_1m_2 + 6m_1m_p + 4m_2m_p - m_p^2\right)}{4m_1m_2 + 4m_1m_3 + 2m_1m_p + 16m_2m_3 + 6m_2m_p + 14m_3m_p + 3m_p^2}$$



# 4. Weights linked by a rope [Taylor 7.50]

A particle of mass m that lies over a table is linked to another particle of mass M by a rope of length l that passes through a hole in the table, without friction. The second one is hanging vertically at a distance  $y = \ell - \rho$ from the table, where  $\rho$  is the distance between the first particle and the hole.



(a) Assuming that  $\theta$  is not necessarily constant, find the Lagrange equations for  $\rho$  and y. Result:

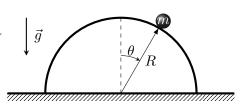
$$-Mg + M\ddot{y} + \lambda_1 = 0 \qquad \lambda_1 - m\rho\dot{\theta}^2 + m\ddot{\rho} = 0$$

(b) Solve the system for  $\rho, y$  and the lagrange multiplier  $\lambda_1$  finding the tensions exerted upon both particles.

Result: 
$$Q_{\rho} = \frac{Mm(g+\rho\dot{\theta}^2)}{M+m}$$

# Result: $Q_{\rho} = \frac{Mm(g+\rho\dot{\theta}^2)}{M+m}$ 5. Particle slidding over a semi-sphere [Marion ex. 7.10]

The particle of mass m, considered as a point particle, slides over a semi-sphere of radius R without friction.



(a) Find the constraint force.

Result: 
$$F_{\rho}^{\text{constraint}} = m \left( -R\dot{\theta}^2 + g\cos(\theta) \right)$$

(b) Calculate the angle at which the particle leaves the semi-sphere. Result:  $\approx 48.19^{\circ}$ 

#### Computational Analytical Mechanics



To find the angle at which the particle leaves the semi-sphere, you must solve the differential equation you'll get after working out the rather tough constraint force, which will be  $\ddot{\theta} = \frac{g \sin(\theta)}{R}$ . This expression can be integrated for the perticle's trajectory. This is easier after applying the chain rule to insert derivatives with respect to  $\theta$ .

$$\ddot{\theta} = \frac{d\dot{\theta}}{dt} = \frac{d\theta}{dt} \frac{d\dot{\theta}}{d\theta} = \dot{\theta} \frac{d\dot{\theta}}{d\theta}$$

Since the particle starts at  $\theta(t=0)=0$  with  $\dot{\theta}(t=0)=0$ :

$$\begin{split} \ddot{\theta} &= \dot{\theta} \frac{d\dot{\theta}}{d\theta} = \frac{g}{R} \sin(\theta) \\ \dot{\theta} d\dot{\theta} &= \frac{g}{R} \sin(\theta) d\theta \\ \int_{0}^{\dot{\theta}_{\text{leaving}}} \dot{\theta} d\dot{\theta} &= \frac{g}{R} \int_{0}^{\theta_{\text{leaving}}} \sin \theta d\theta \\ \frac{\dot{\theta}^{2}}{2} \bigg|_{0}^{\dot{\theta}_{\text{leaving}}} &= \frac{g}{R} (-\cos \theta) \bigg|_{0}^{\theta_{\text{leaving}}} \\ \frac{\dot{\theta}_{\text{leaving}}^{2}}{2} &= \frac{g}{R} (-\cos(\theta_{\text{leaving}}) + 1) \end{split}$$

After this, you have to substitute  $\dot{\theta}^2$  in an expression for  $F_{\rho}^{\text{constraint}}$ , that must vanish at the moment of leaving the semi-sphere.