

The Berkson Measurement Error (MEB) model

Parametrization

This is an implementation of the Berkson measurement error model for a fixed effect. The observed covariate is w but it is x that goes into the linear predictor

$$\eta = \dots + \beta x + \dots ,$$

where $x = w + u$ and u is Gaussian with precision $\tau_u \cdot s$, and s is a vector of fixed scalings (default all are 1).

Hyperparameters

This model has 2 hyperparameters, $\theta = (\theta_1, \theta_2)$. The hyperparameter specification is as follows:

$$\theta_1 = \beta$$

and the prior is defined on θ_1 ,

$$\theta_2 = \log(\tau_u)$$

and the prior is defined on θ_2 .

Specification

The MEB is specified inside the `f()` function as

```
f(w, [<weights>], model="meb", hyper = <hyper>, scale = <s>)
```

Here, `w` are the observed covariates, and the fixed scaling of the observational precision is given in argument `scale`. If the argument `scale` is not given, then s is set to 1.

Note that only the unique values of `w` are used, so if two or more elements of `w` are *identical*, then they refer to the *same* element in the covariate x .

Hyperparameter specification and default values

hyper

theta1

```
name    beta
short.name  b
prior    gaussian
param    1 0.001
initial    1
fixed    FALSE
to.theta  function(x) x
from.theta function(x) x
```

theta2

```
name    prec.obs
short.name  prec
prior    loggamma
param    1 1e-04
initial    6.90775527898214
```

```

    fixed FALSE
    to.theta function(x) log(x)
    from.theta function(x) exp(x)

constr FALSE

nrow.ncol FALSE

augmented FALSE

aug.factor 1

aug.constr

n.div.by

n.required FALSE

set.default.values FALSE

status experimental

pdf meb

```

Example

```

n = 100
beta = 2
w = rnorm(n)
prec.u = 100
prec.y = 1000
s = runif(n, min = 0.5, max = 1/0.5)
x = w + rnorm(n, sd = 1/sqrt(s*prec.u))
y = 1 + beta * x + rnorm(n, sd = 1/sqrt(prec.y))

formula = y ~ f(w, model="meb",
               hyper = list(prec = list(param = c(1, 0.01))))

r = inla(formula, data = data.frame(y, w, s),
         family = "gaussian")

```

Notes

- INLA provide the posterior of $\beta\tilde{x}$ and NOT \tilde{x} . The results comes in the order given by the sorted (from low to high) values of \mathbf{x} and the field ID gives the mapping.