

Input and Output Uncertainty in Medical Image Analysis

Koen Van Leemput

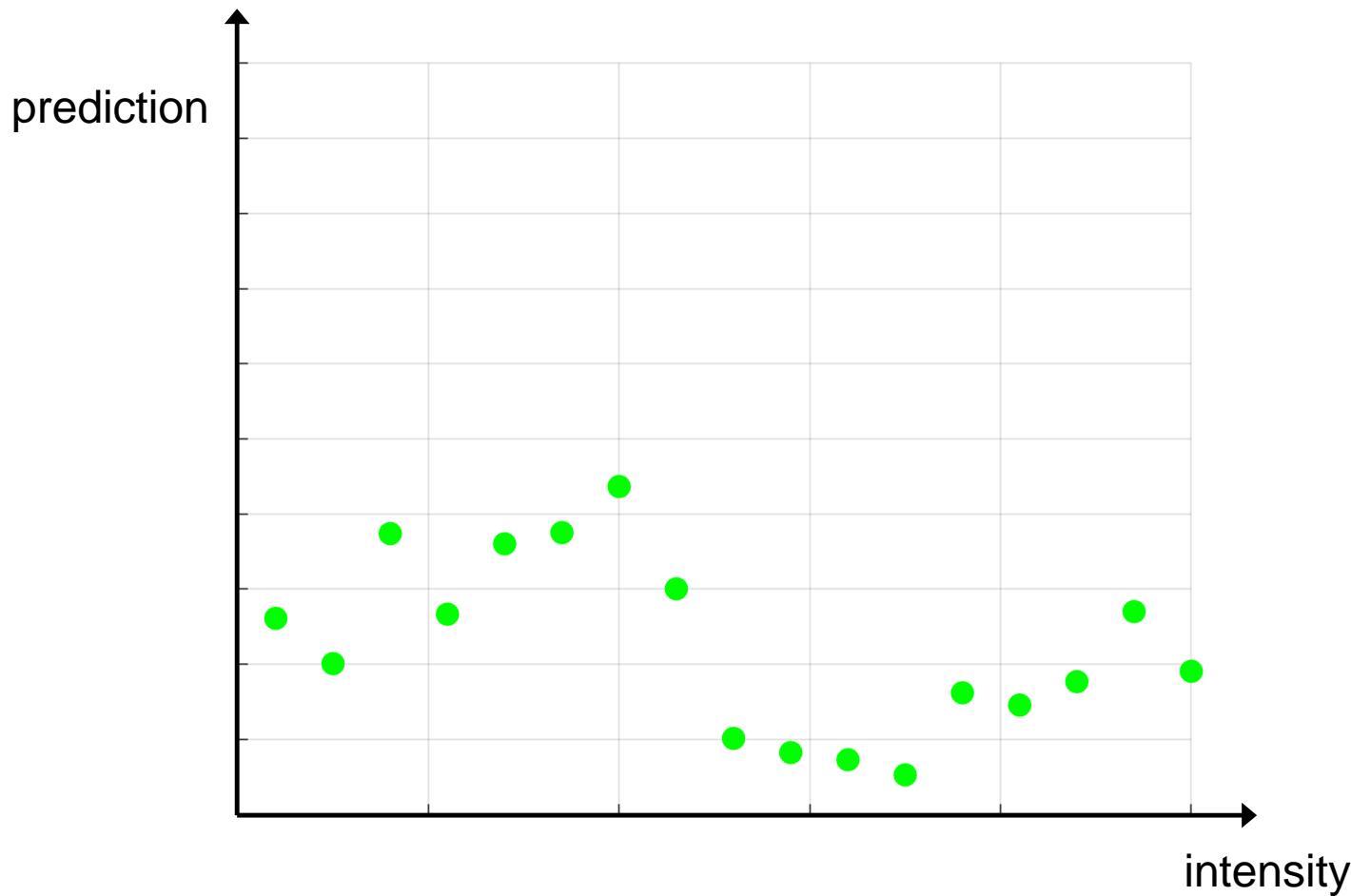
*October 17, 2019
MICCAI UNSURE Workshop
Shenzhen, China*

MGH/HST Athinoula A. Martinos
Center for Biomedical Imaging

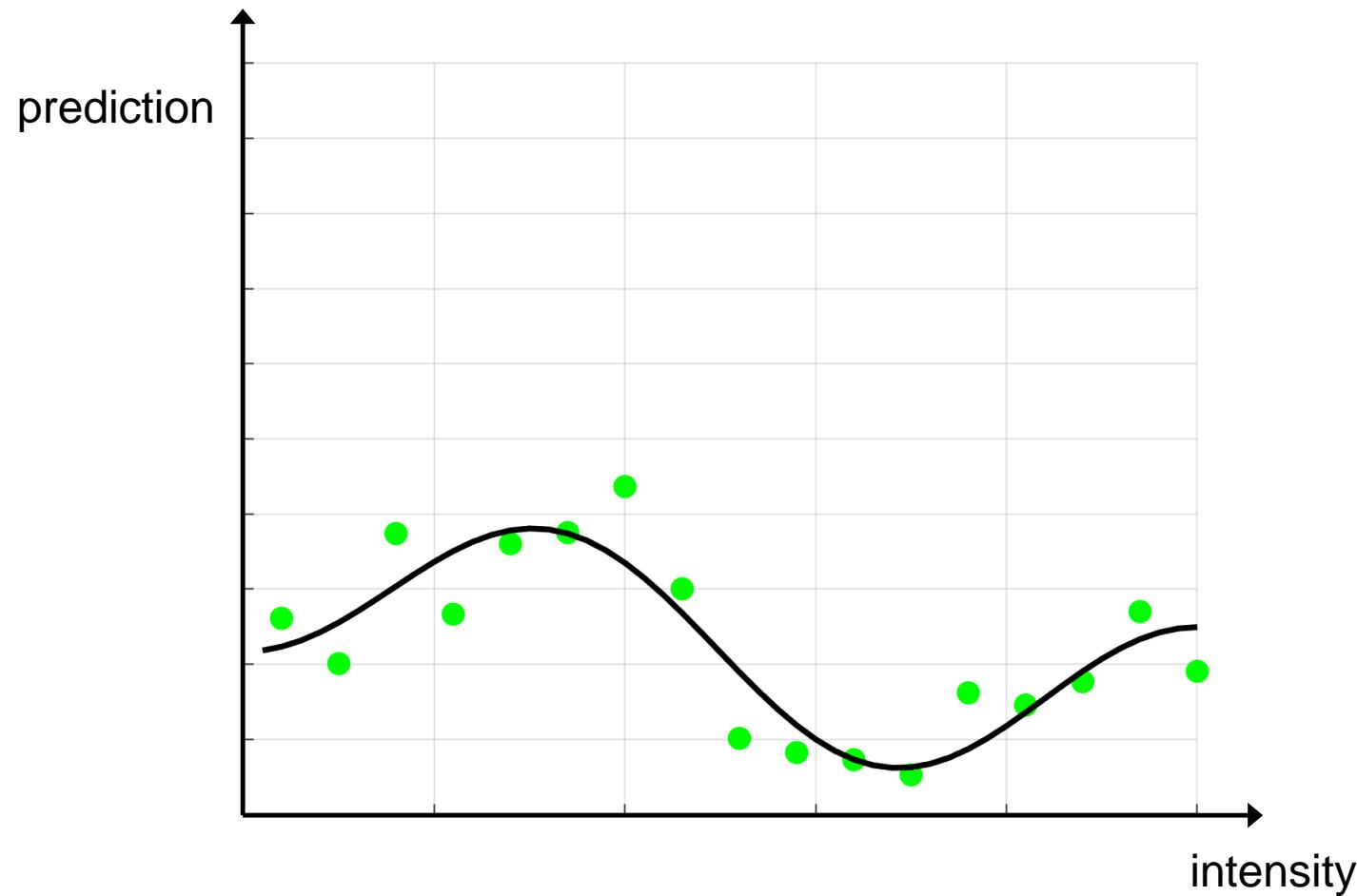


Technical University of Denmark

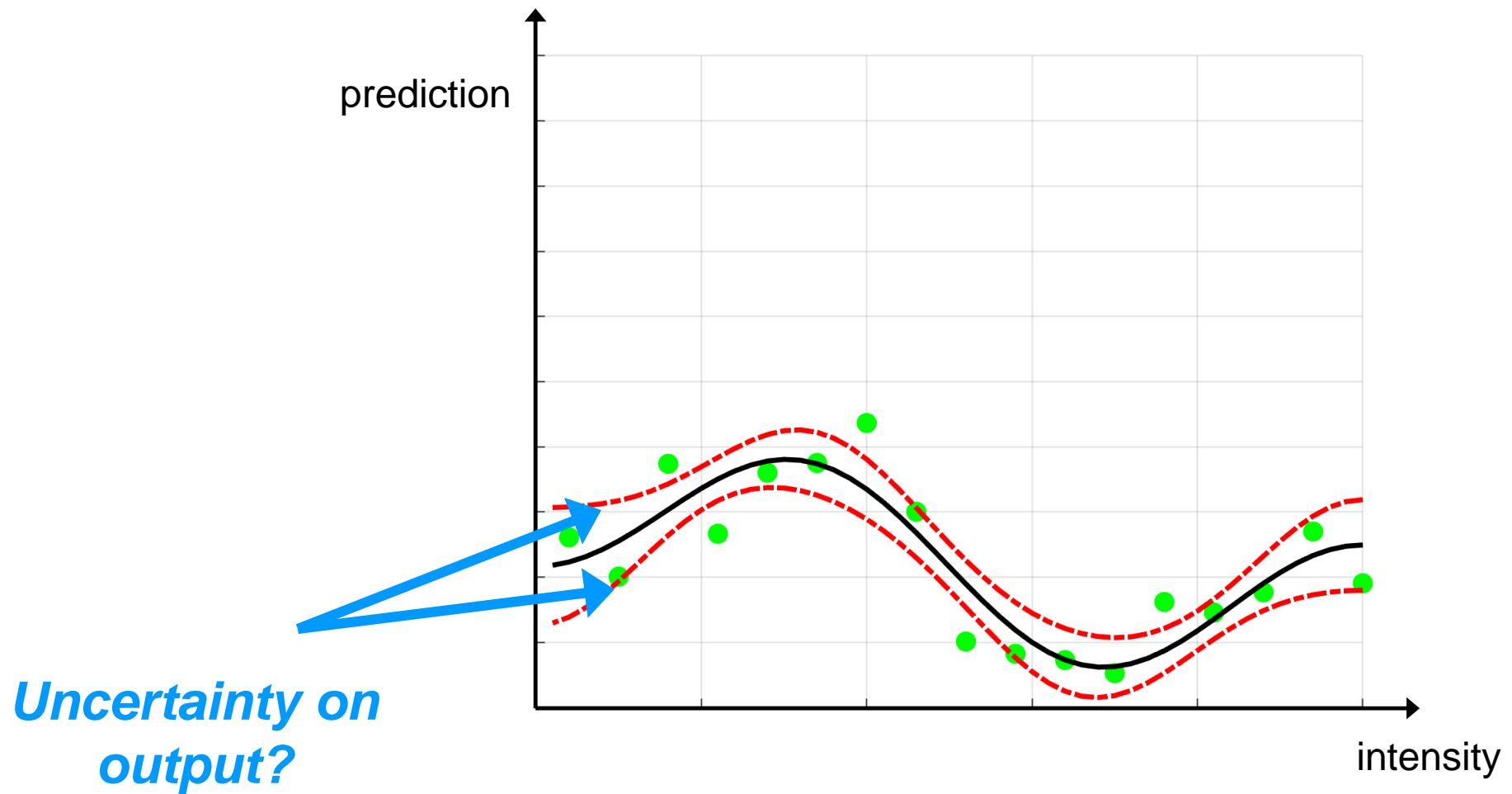
Uncertainty in input and output?



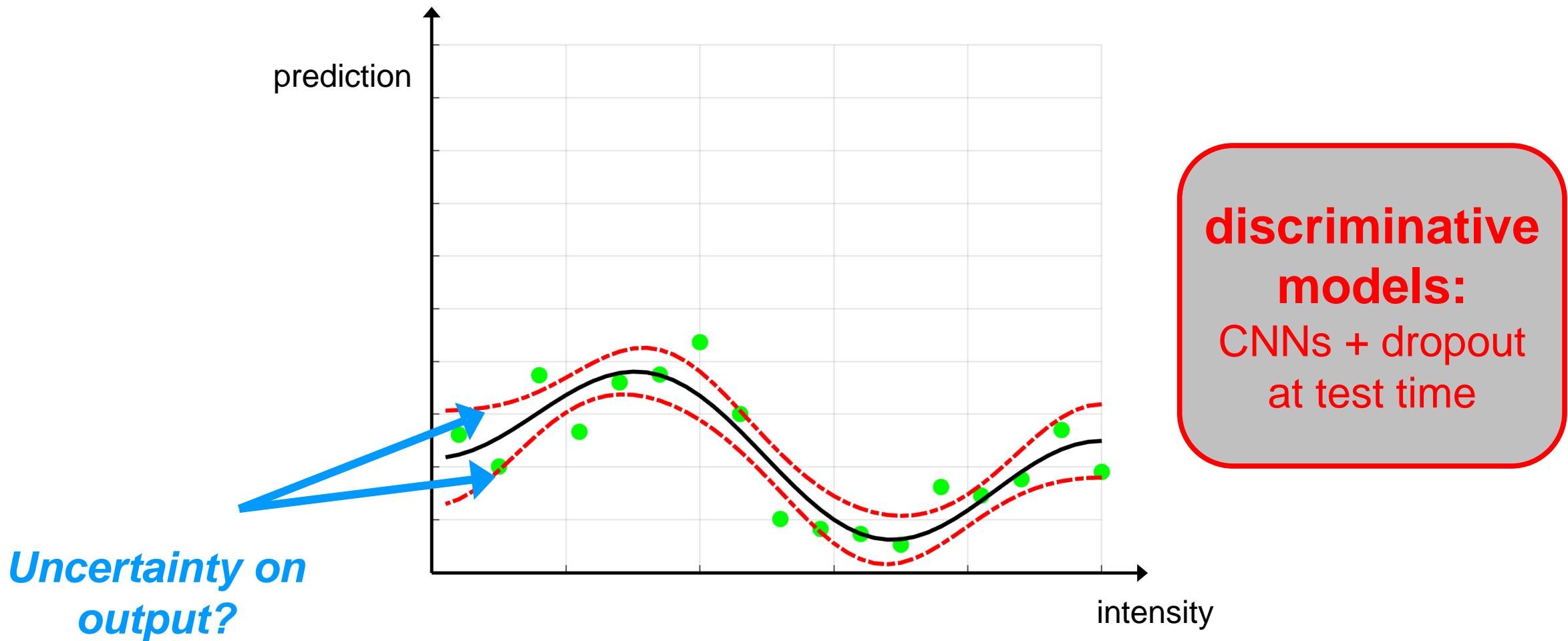
Uncertainty in input and output?



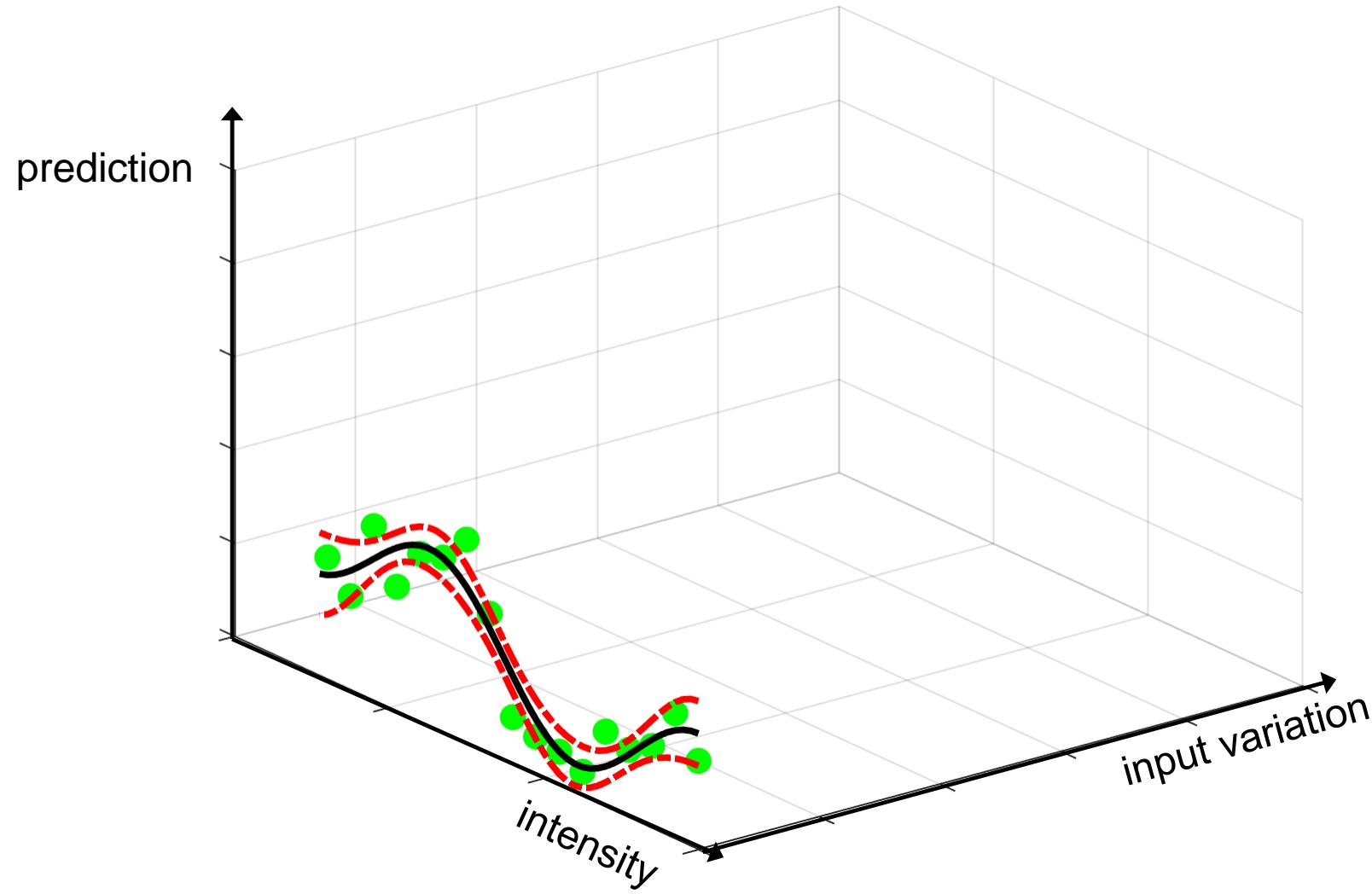
Uncertainty in input and output?



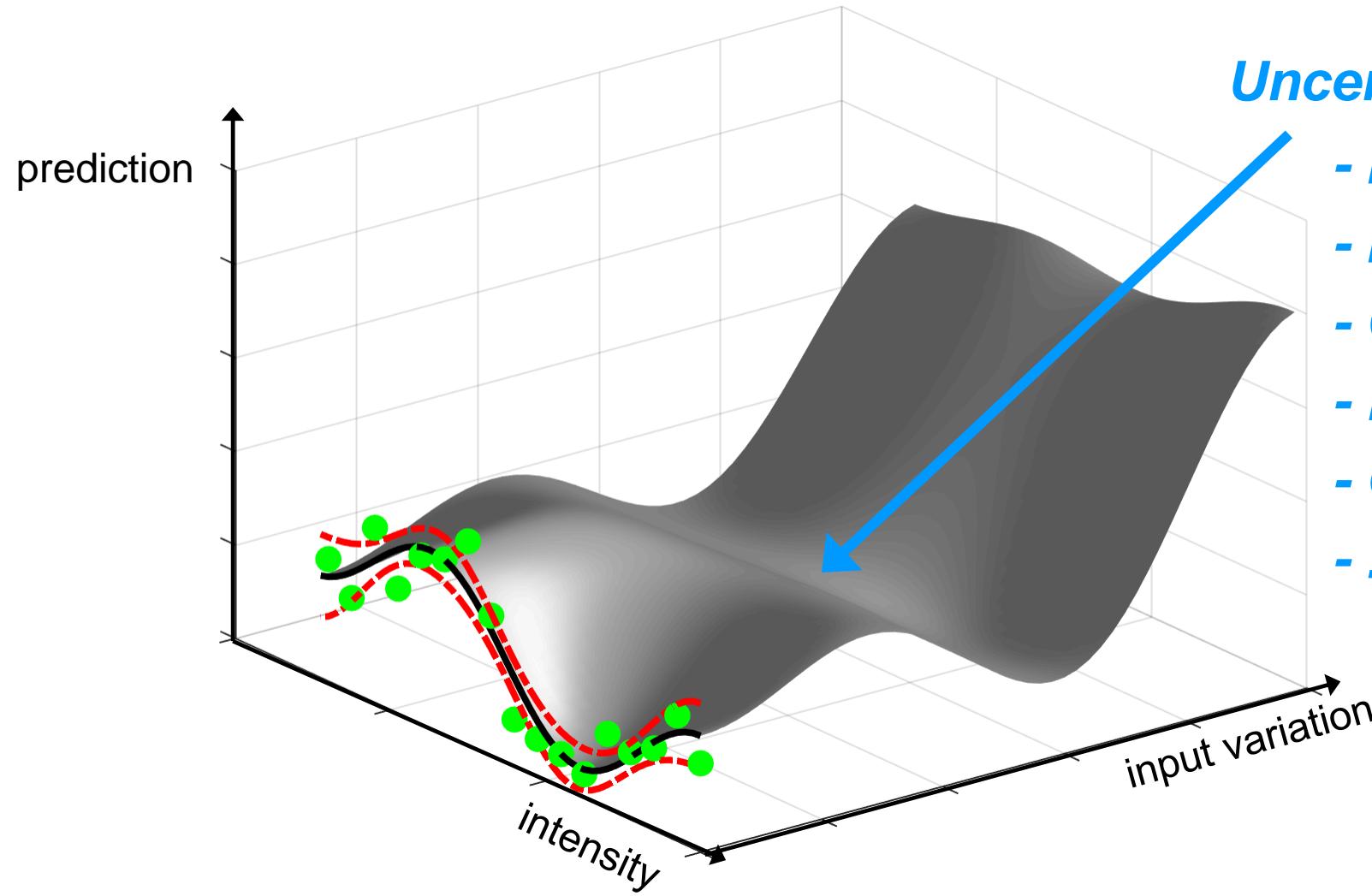
Uncertainty in input and output?



Uncertainty in input and output?



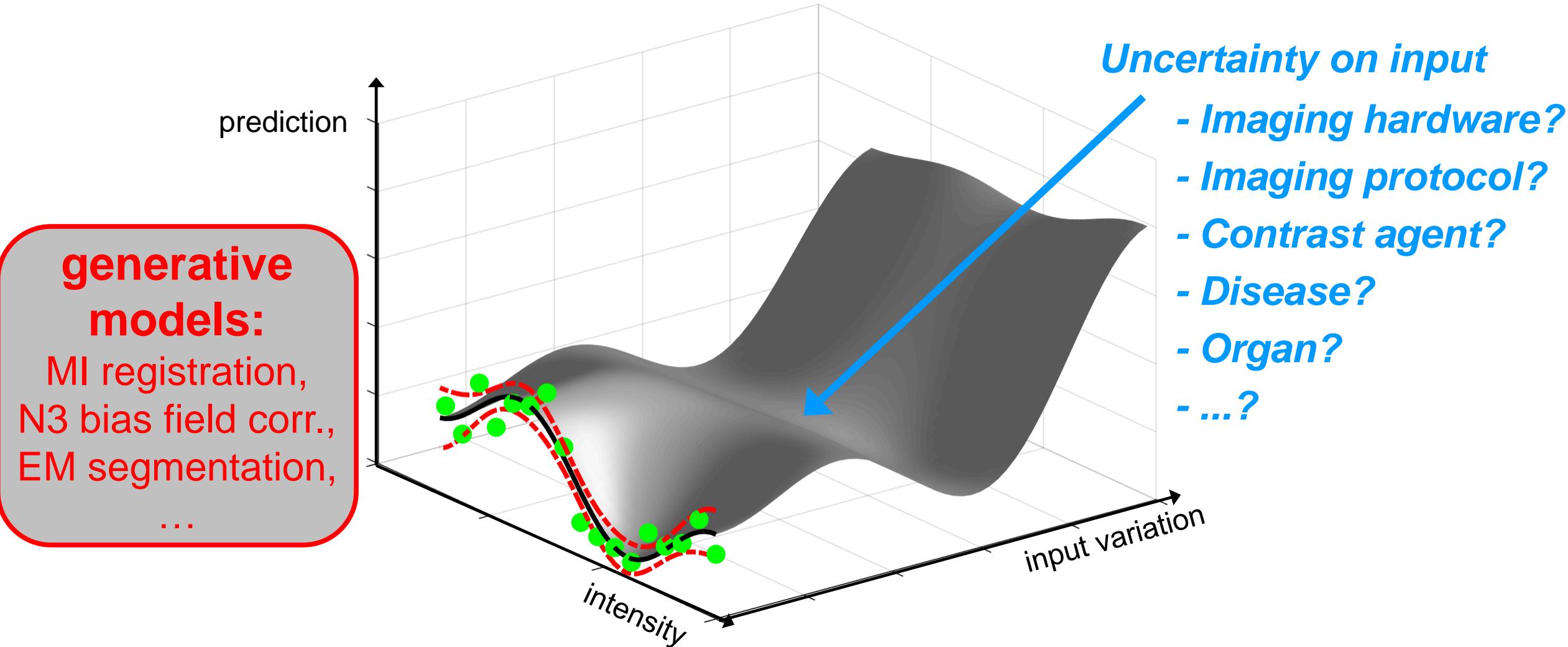
Uncertainty in input and output?



Uncertainty on input

- Imaging hardware?
- Imaging protocol?
- Contrast agent?
- Disease?
- Organ?
- ...?

Uncertainty in input and output?



Overview

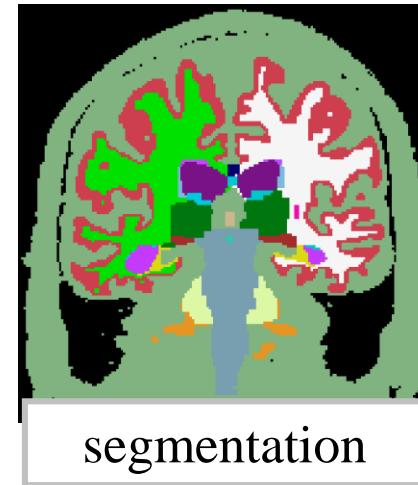
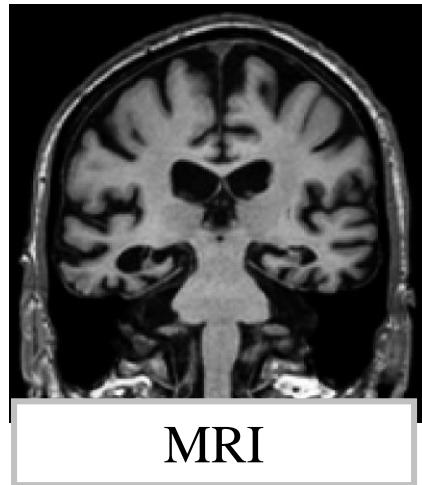


Uncertainty on input using generative models

Uncertainty on output using Monte Carlo sampling

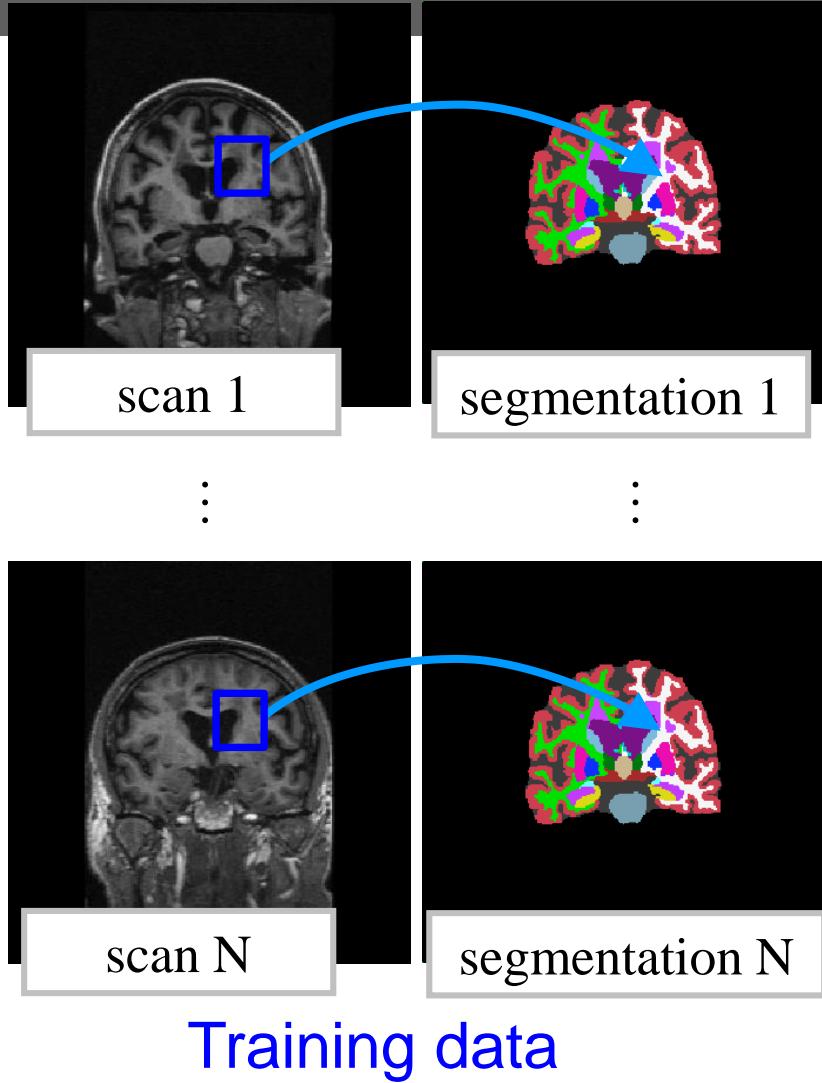
Discussion and conclusion

Brain segmentation in the clinic

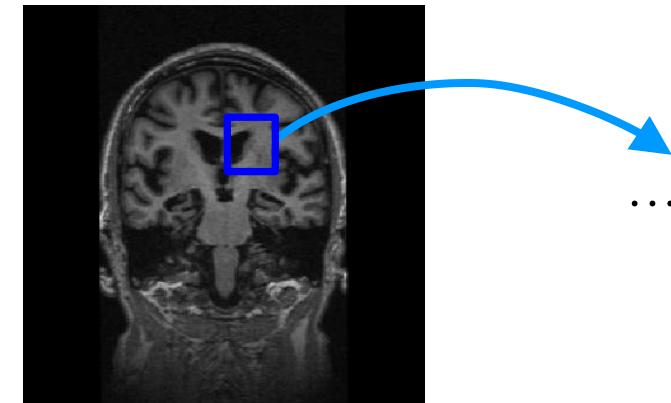


Focus: translation into clinical settings!

Discriminative methods?



Directly learn to predict
segmentation labels from
intensities



***“Monkey see,
monkey do!”***

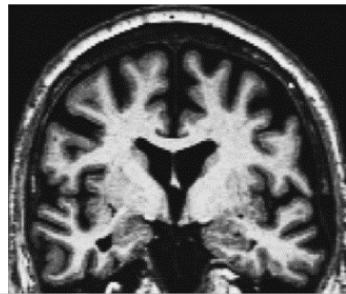
Discriminative methods?

How long to manually label one MRI scan?

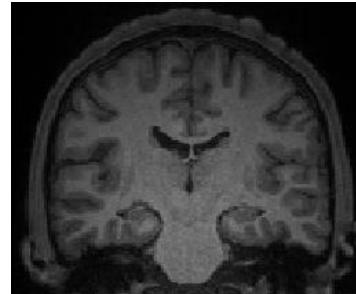


Discriminative methods?

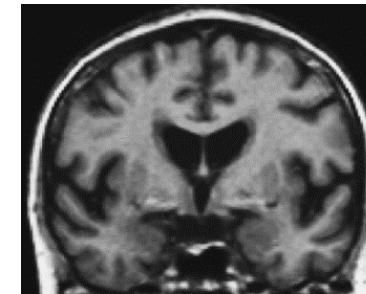
Tissue contrast depends on hardware and pulse sequence



Siemens Vision
1.5T MPRAGE



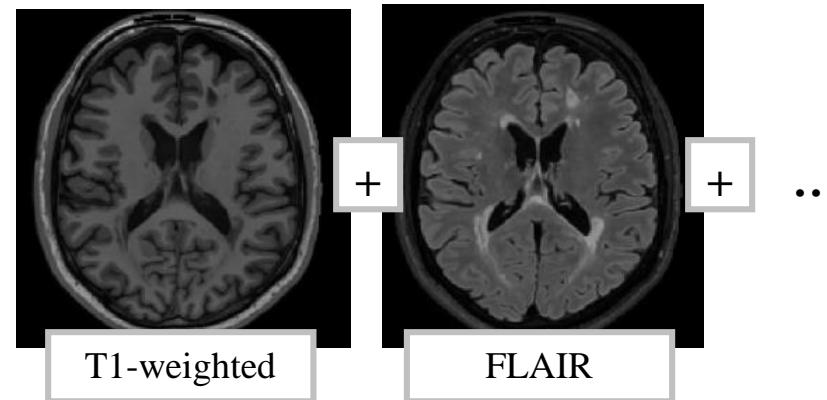
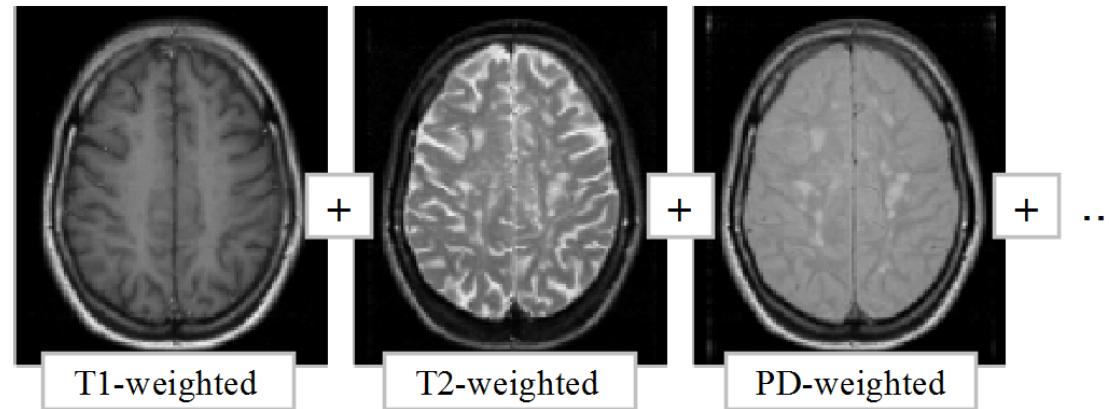
Siemens Tim Trio 3T
MPRAGE



GE Signa 1.5T
SPGR

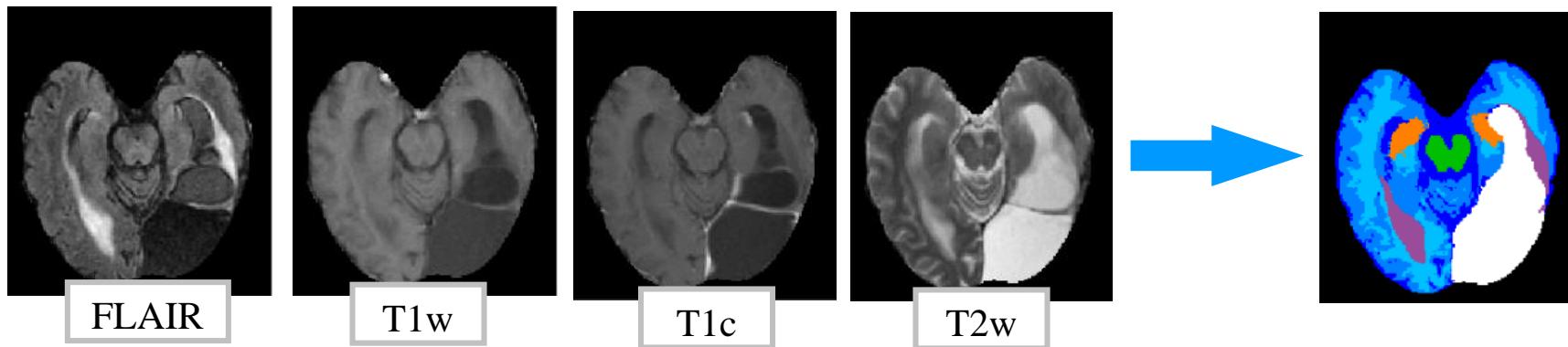
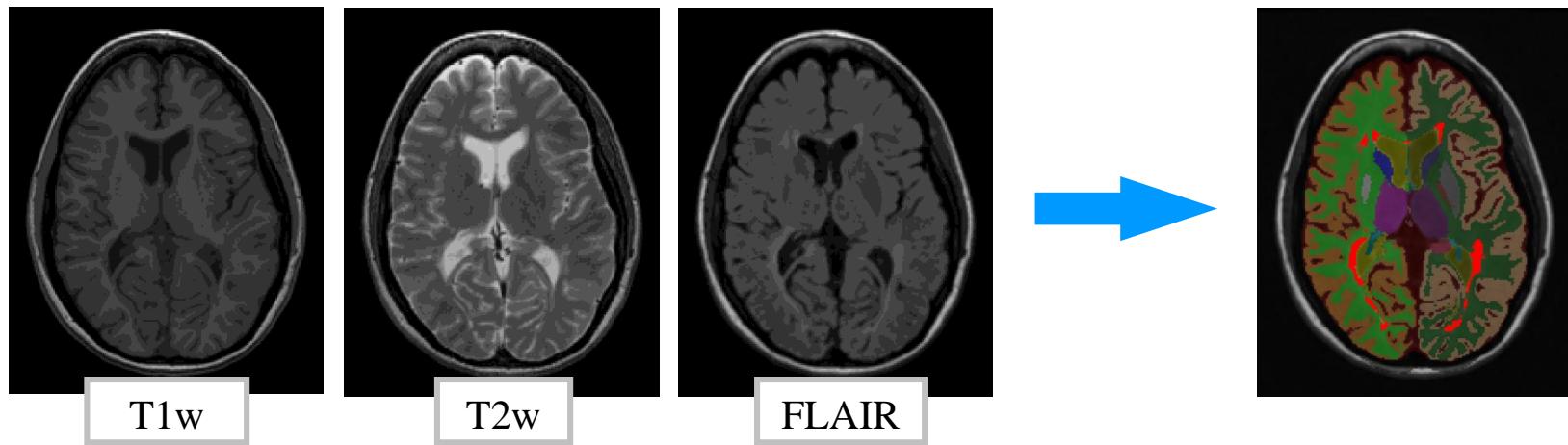
Discriminative methods?

No standard protocol for clinical imaging (multi-contrast)



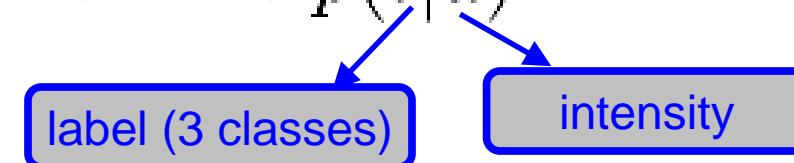
Discriminative methods?

Many different brain diseases



Generative methods: Gaussian mixture model

- Voxel-wise classification: maximize $p(l|d)$



Generative methods: Gaussian mixture model

- Voxel-wise classification: maximize $p(l|d)$

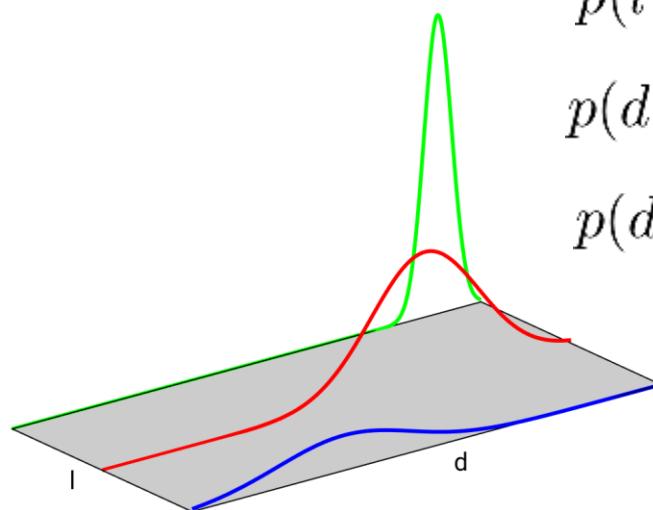
label (3 classes) intensity

- Idea: model the joint distribution $p(d, l)$ instead

$$p(l = k) = \pi_k$$

$$p(d|l = k) = \mathcal{N}(d|\mu_k, \sigma_k^2)$$

$$p(d, l) = p(d|l)p(l)$$



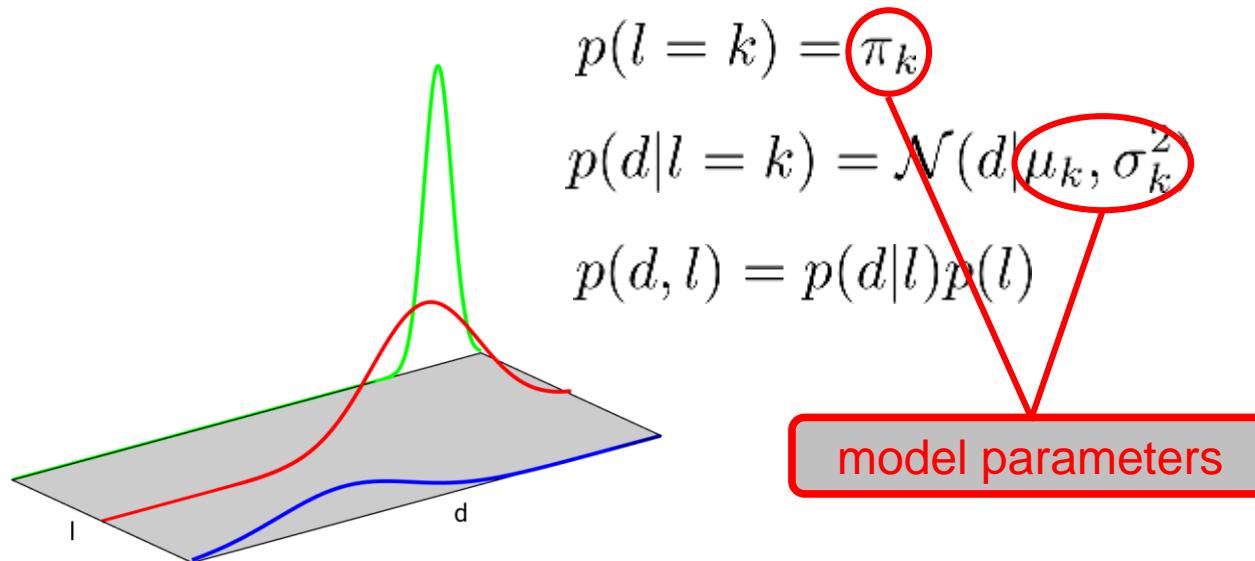
Generative methods: Gaussian mixture model

- Voxel-wise classification: maximize $p(l|d)$

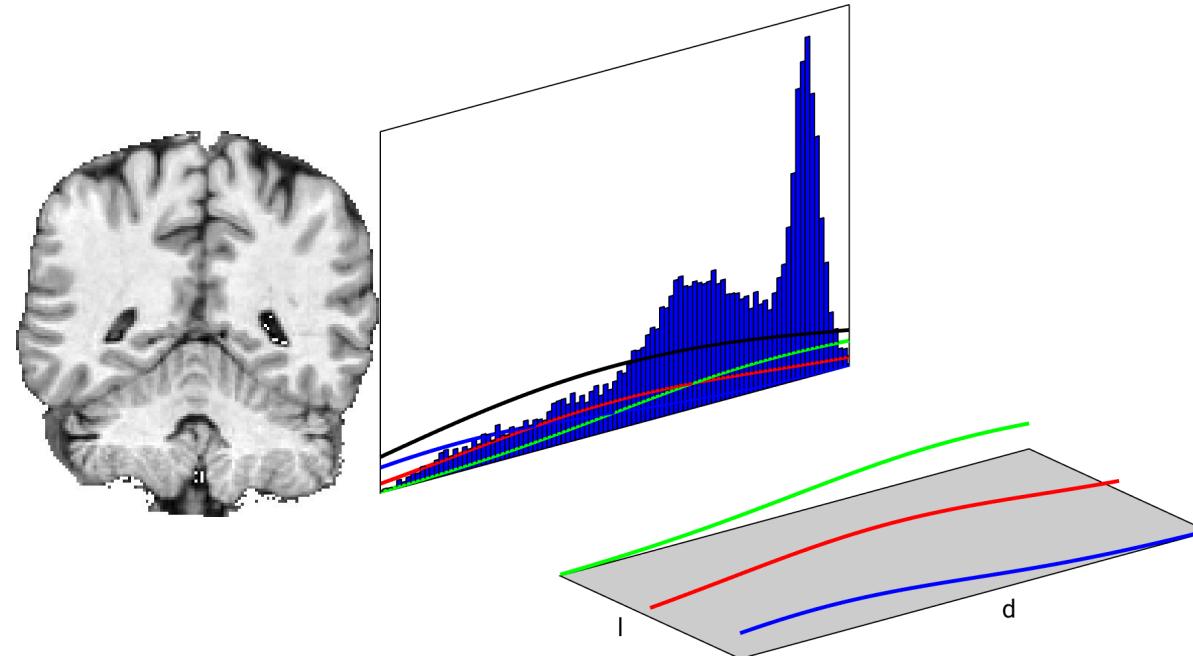
label (3 classes)

intensity

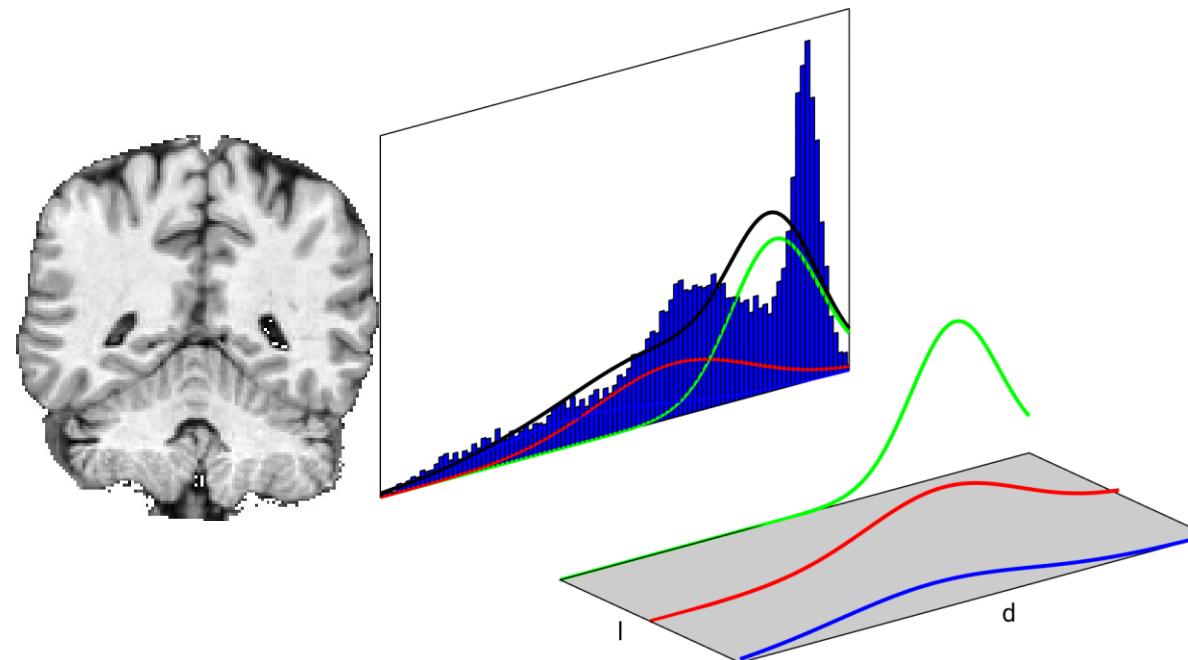
- Idea: model the joint distribution $p(d, l)$ instead



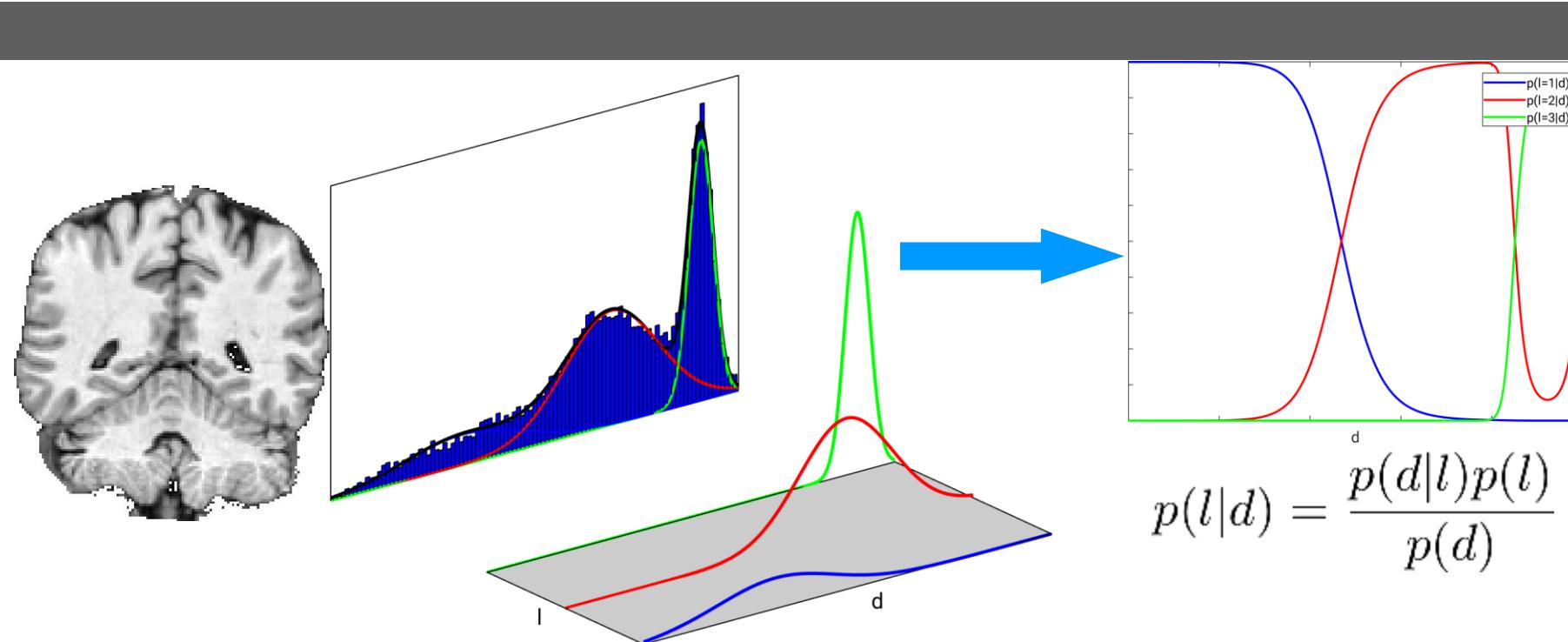
Generative methods: Gaussian mixture model



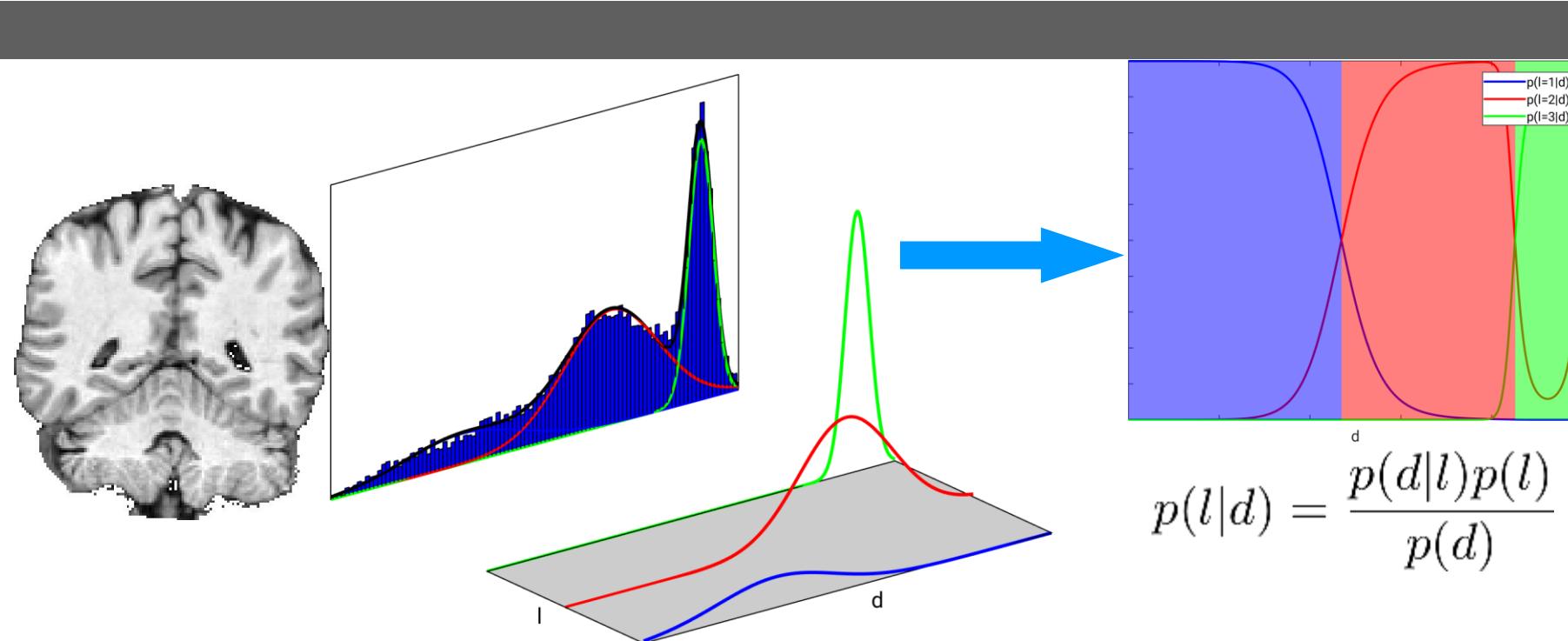
Generative methods: Gaussian mixture model



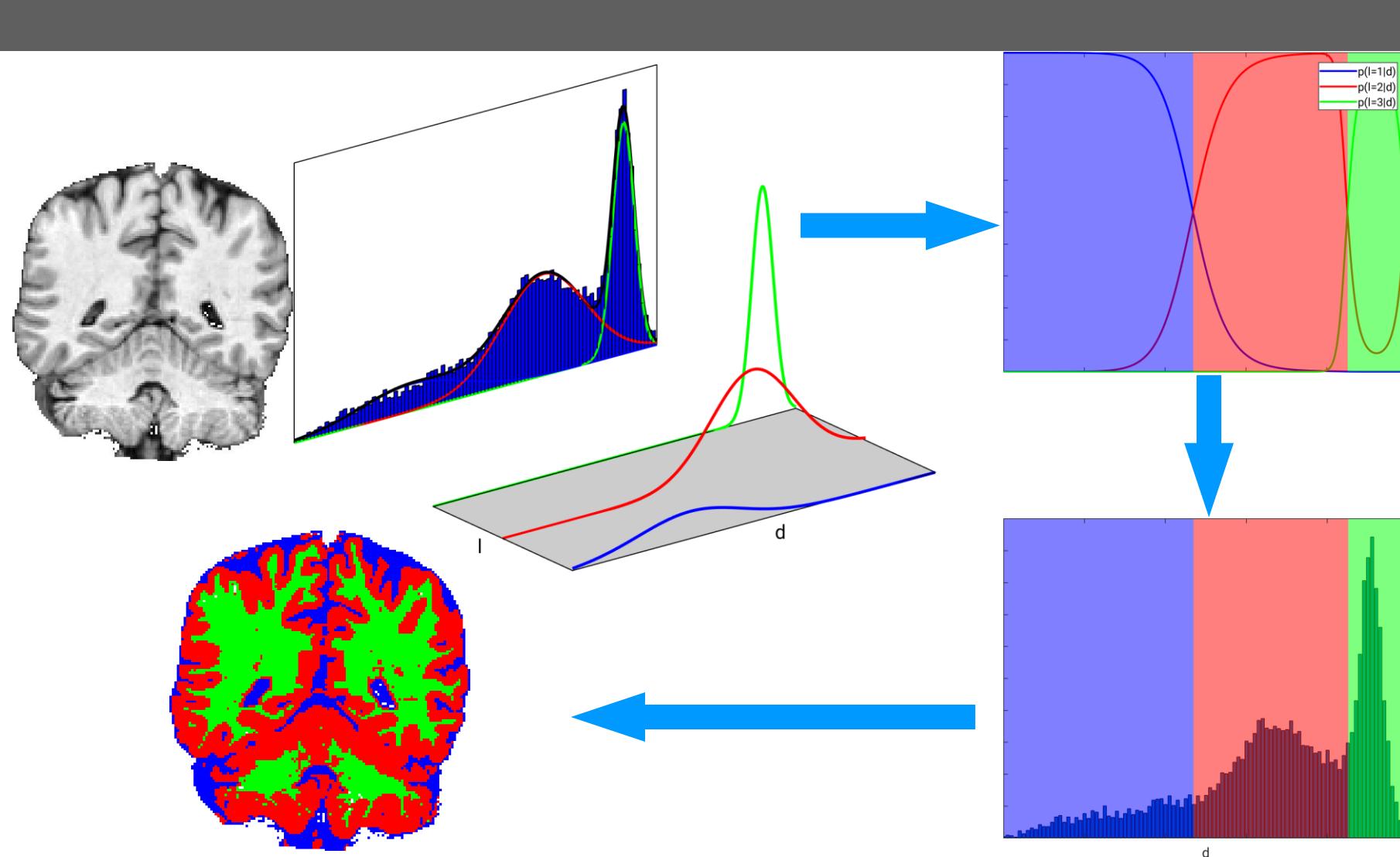
Generative methods: Gaussian mixture model



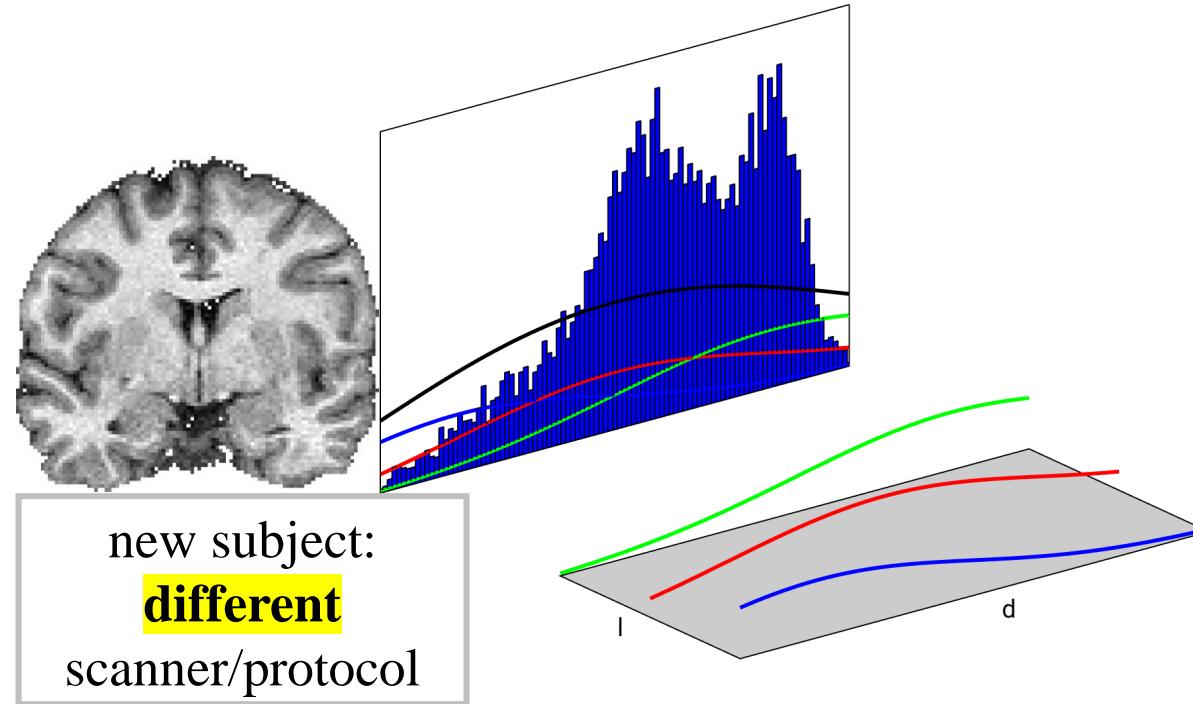
Generative methods: Gaussian mixture model



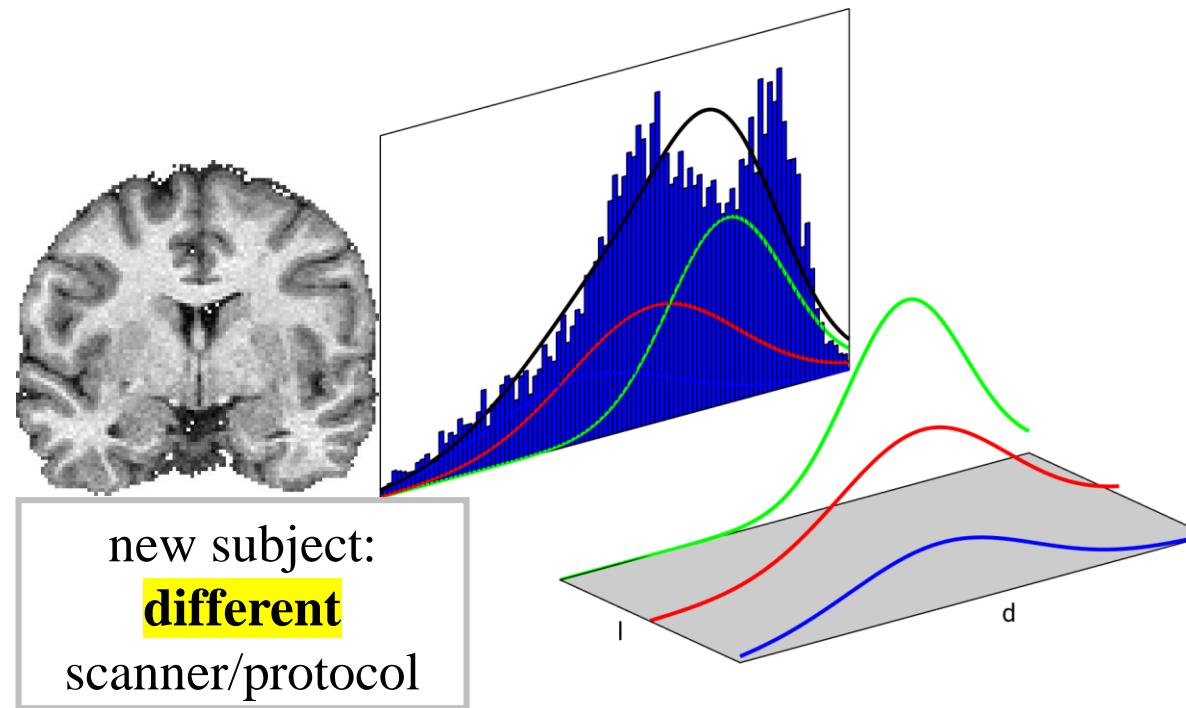
Generative methods: Gaussian mixture model



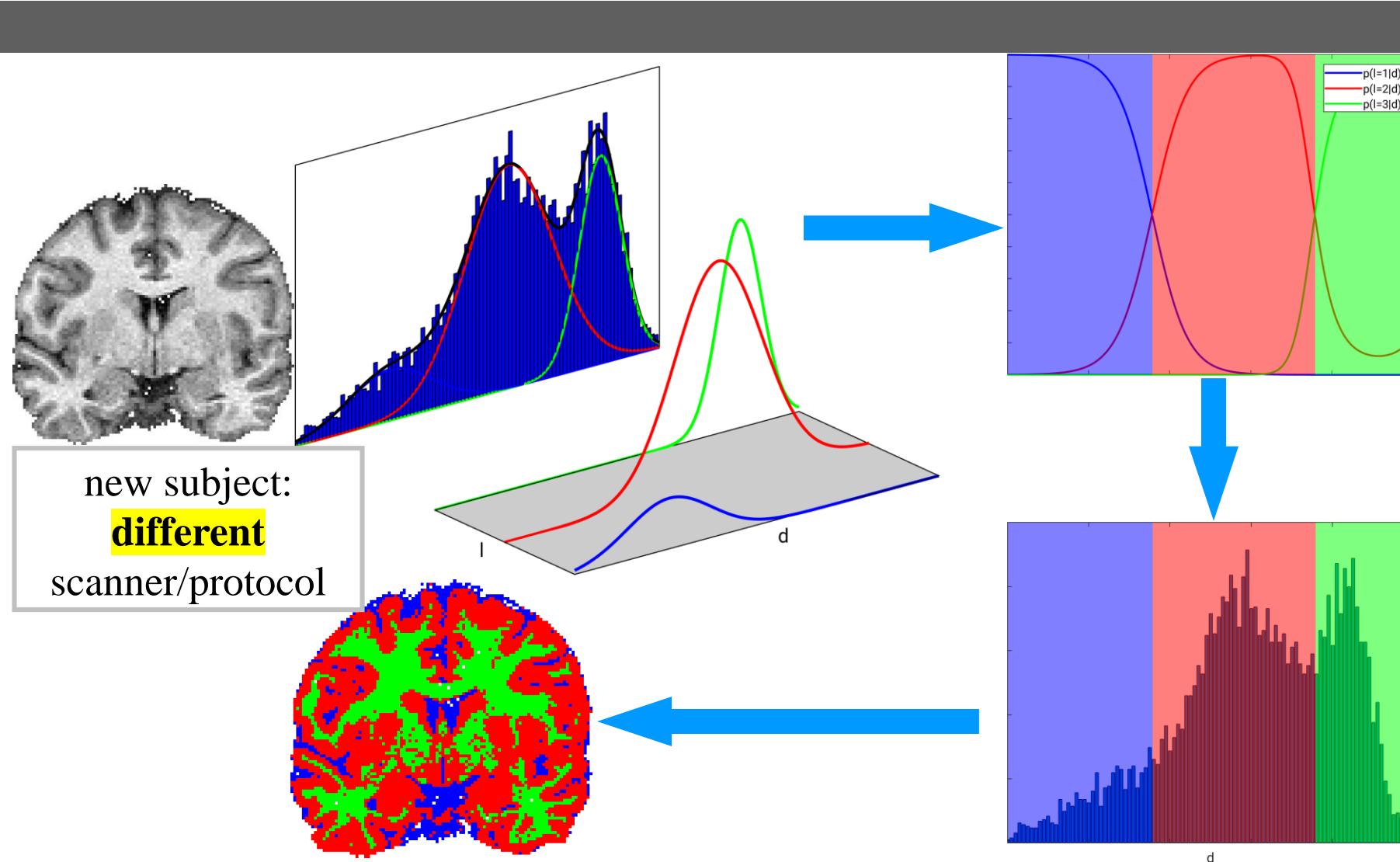
Generative methods: Gaussian mixture model



Generative methods: Gaussian mixture model



Generative methods: Gaussian mixture model

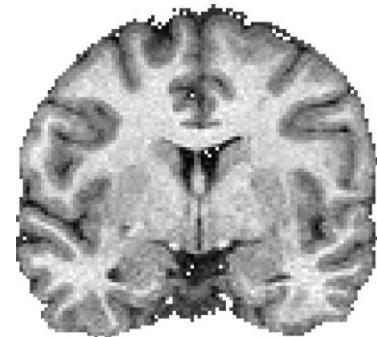




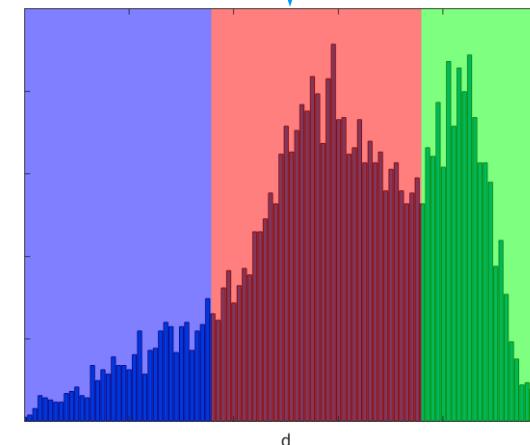
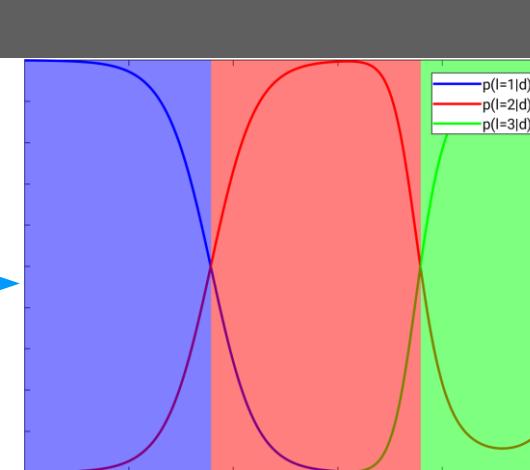
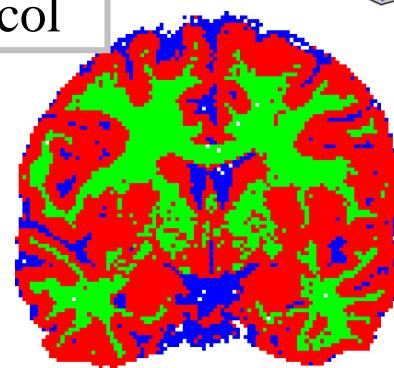
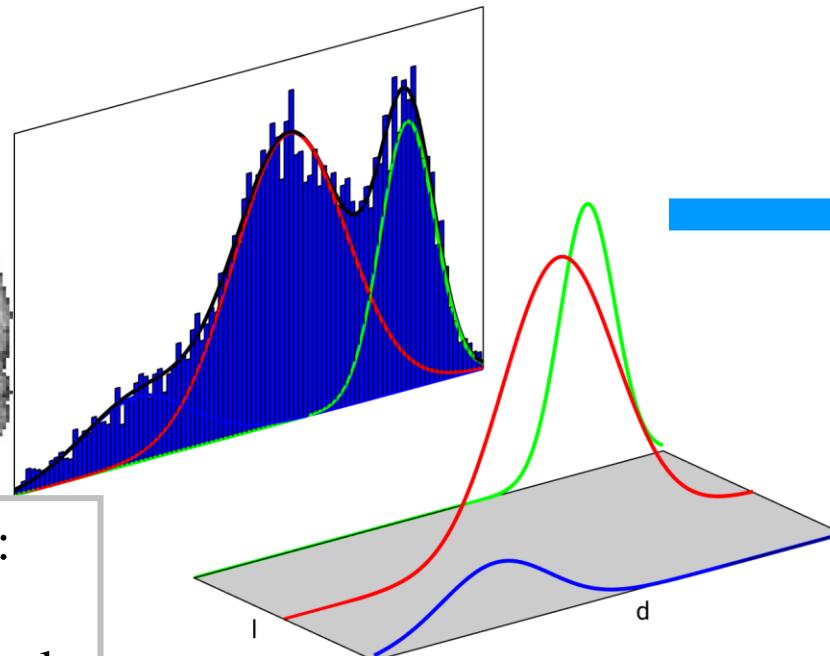
Adaptive!
No matching training data needed!



Slow because of image-specific optimization

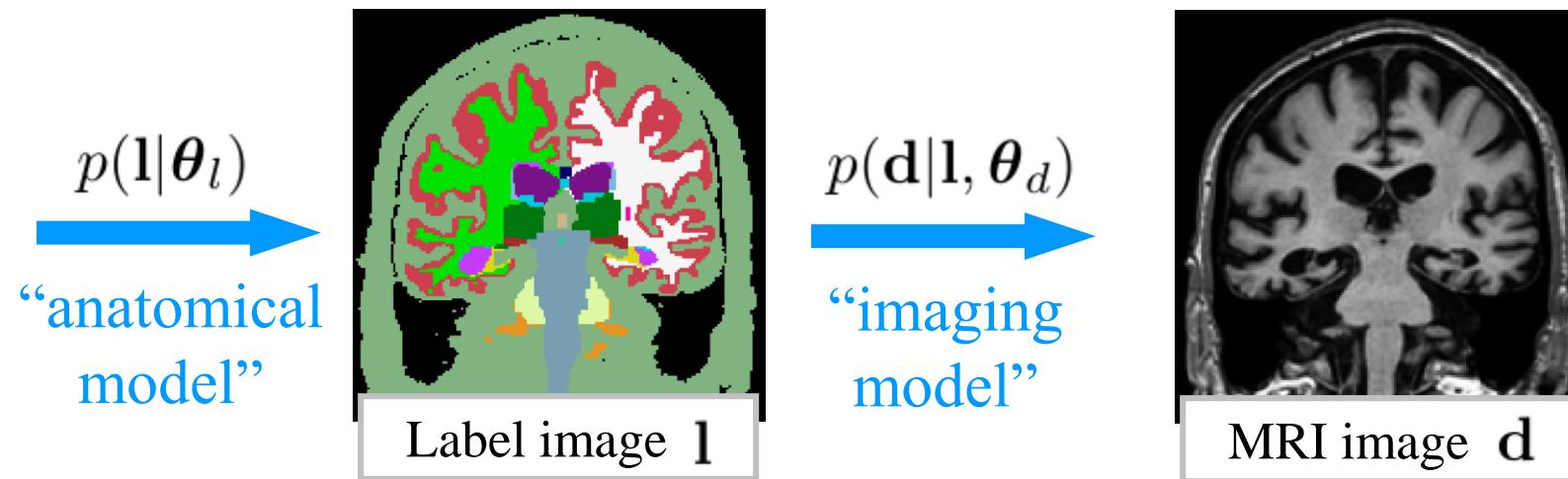


new subject:
different
scanner/protocol



Generative models

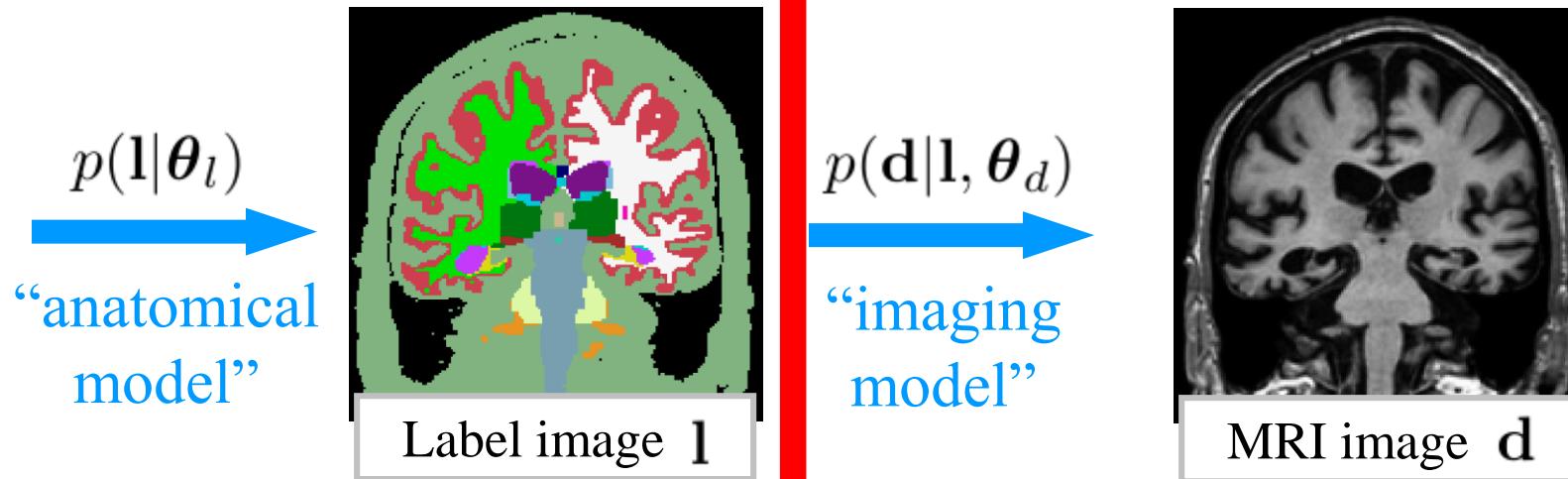
- A probabilistic model of how an MRI image is formed



- The model depends on some parameters $\boldsymbol{\theta} = (\boldsymbol{\theta}_l^T, \boldsymbol{\theta}_d^T)^T$
- Appropriate values $\hat{\boldsymbol{\theta}}$ can be estimated

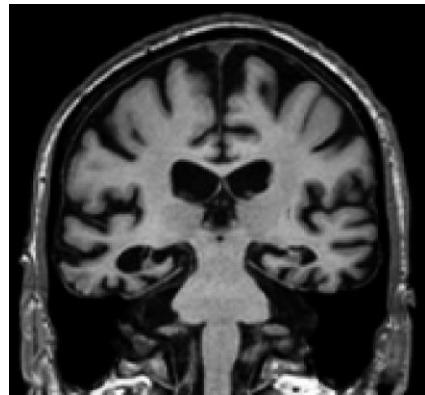
Generative models

- A probabilistic model of how an MRI image is formed

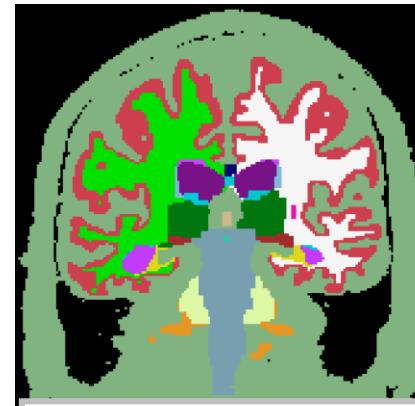
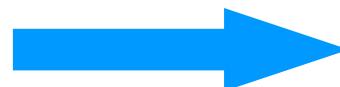


- The model depends on some parameters $\boldsymbol{\theta} = (\boldsymbol{\theta}_l^T, \boldsymbol{\theta}_d^T)^T$
- Appropriate values $\hat{\boldsymbol{\theta}}$ can be estimated

Segmentation = inverse problem



MRI image \mathbf{d}



Label image \mathbf{l}

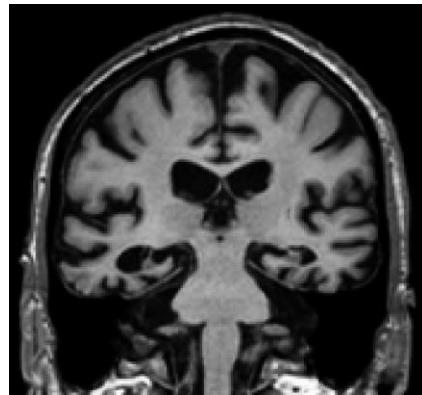


$$\hat{\mathbf{l}} = \arg \max_{\mathbf{l}} p(\mathbf{l}|\mathbf{d}, \hat{\theta})$$

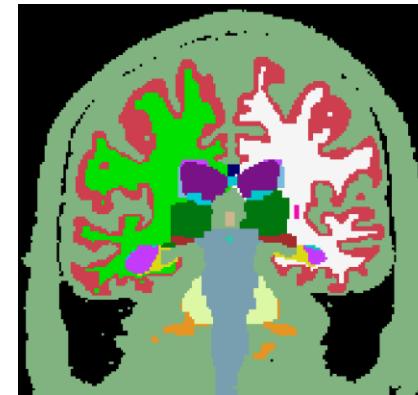
The posterior distribution $p(\mathbf{l}|\mathbf{d}, \hat{\theta})$ is given by Bayes rule:

$$p(\mathbf{l}|\mathbf{d}, \hat{\theta}) = \frac{p(\mathbf{d}|\mathbf{l}, \hat{\theta}_d)p(\mathbf{l}|\hat{\theta}_l)}{p(\mathbf{d}|\hat{\theta})}$$

Segmentation = inverse problem



MRI image \mathbf{d}



Label image \mathbf{l}

$$\hat{\mathbf{l}} = \arg \max_{\mathbf{l}} p(\mathbf{l}|\mathbf{d}, \hat{\theta})$$

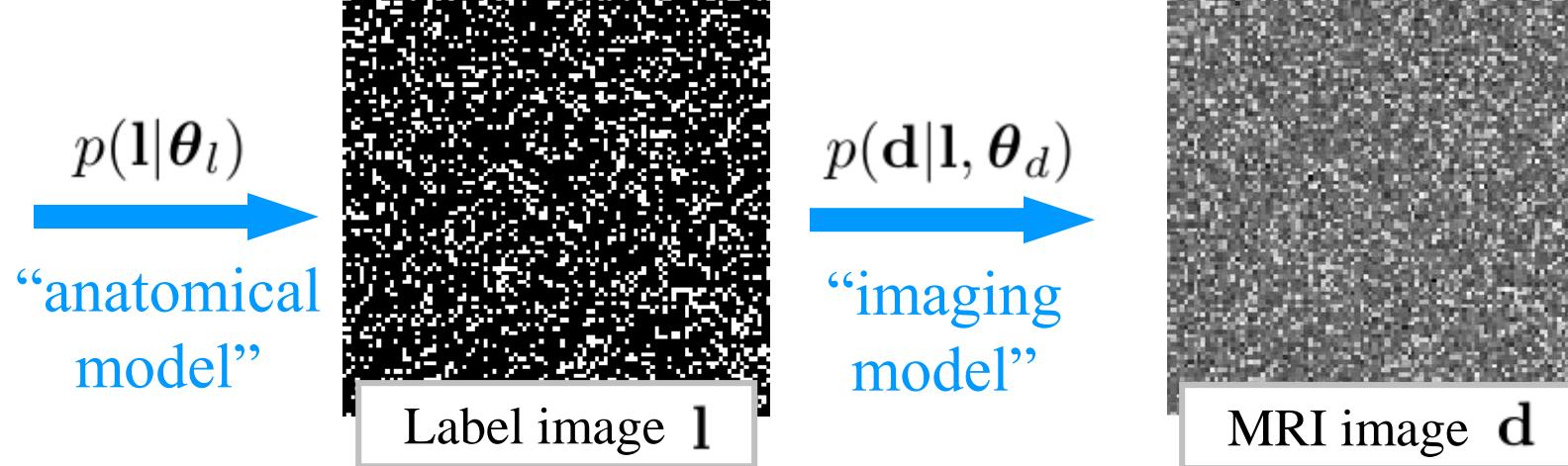
The posterior distribution $p(\mathbf{l}|\mathbf{d}, \hat{\theta})$ is given by Bayes rule:

imaging model

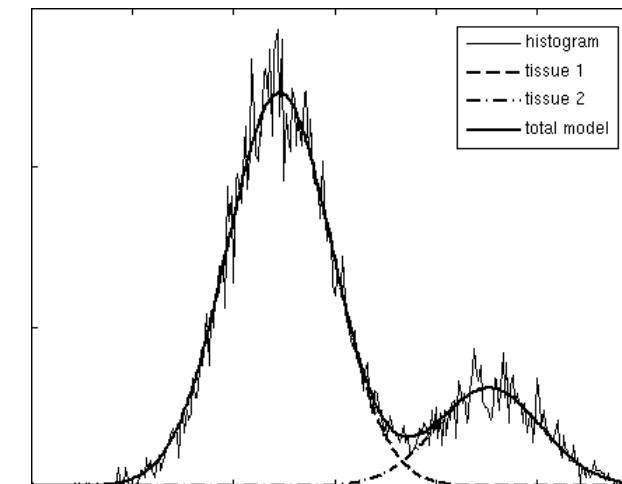
$$p(\mathbf{l}|\mathbf{d}, \hat{\theta}) = \frac{p(\mathbf{d}|\mathbf{l}, \hat{\theta}_d)p(\mathbf{l}|\hat{\theta}_l)}{p(\mathbf{d}|\hat{\theta})}$$

anatomical
model

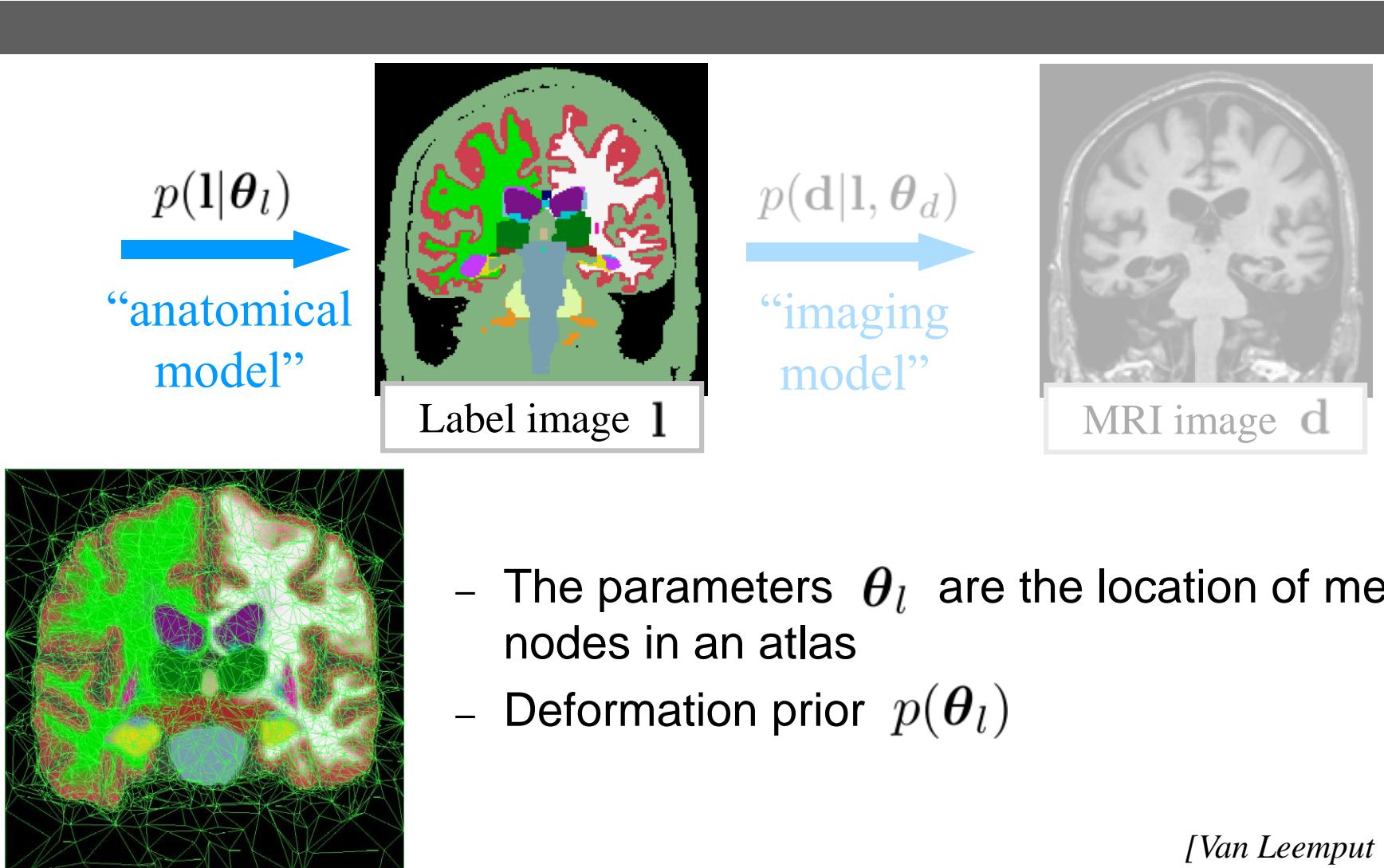
Gaussian mixture model



*You can't segment 40+ brain
structures with this...*

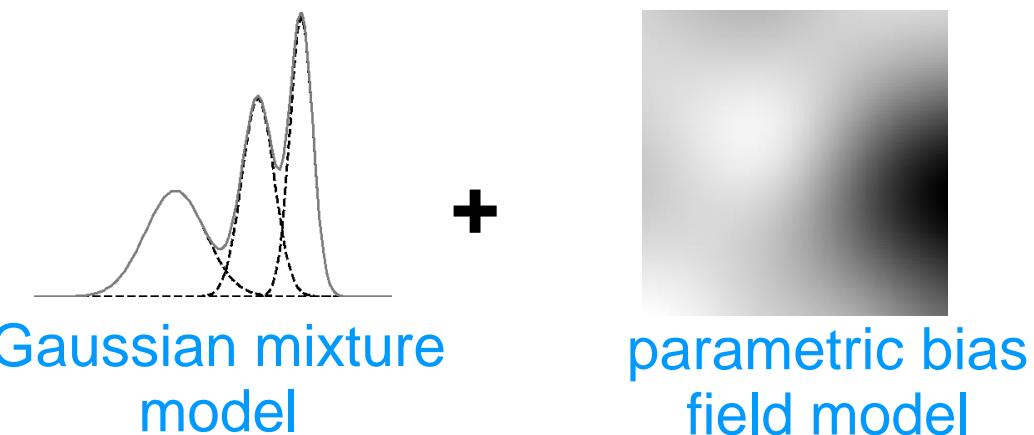
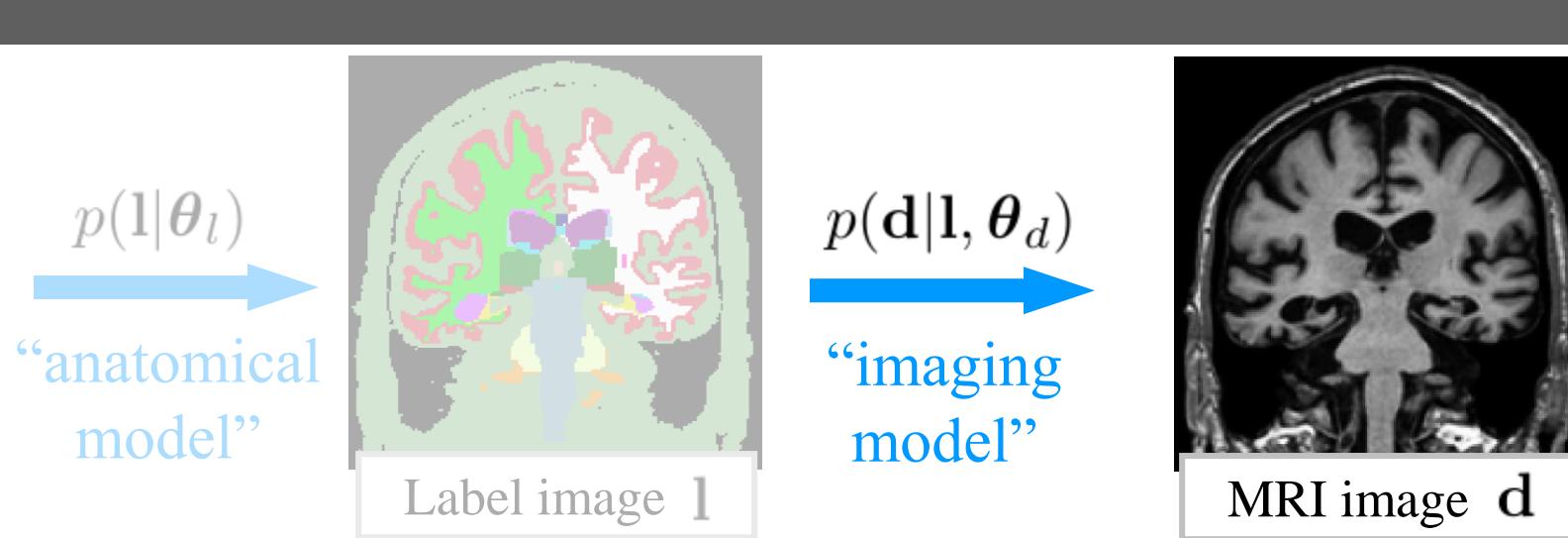


Anatomical model



[Van Leemput TMI 2009]

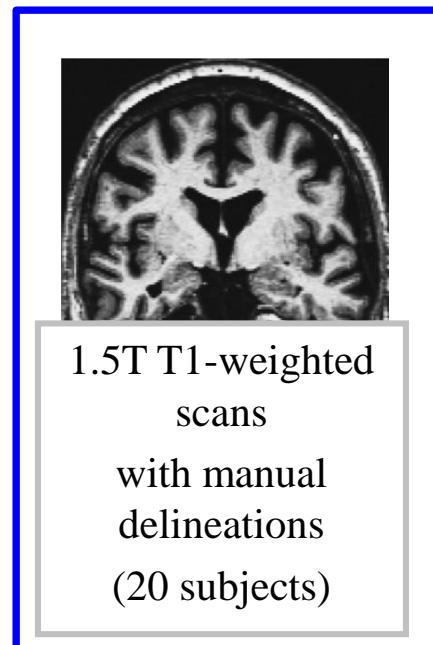
Imaging model



<http://freesurfer.net/>

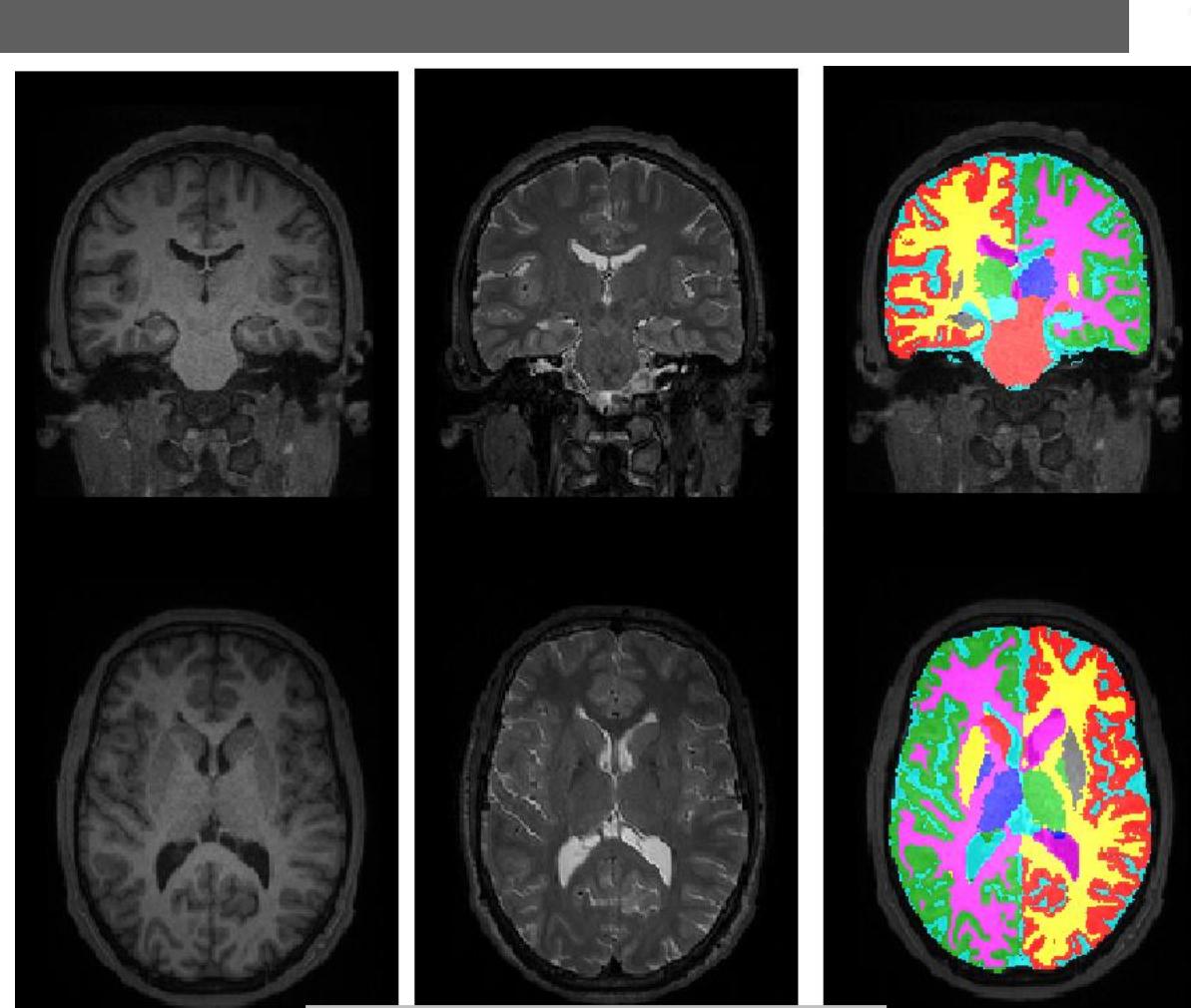


“Inverting” the model



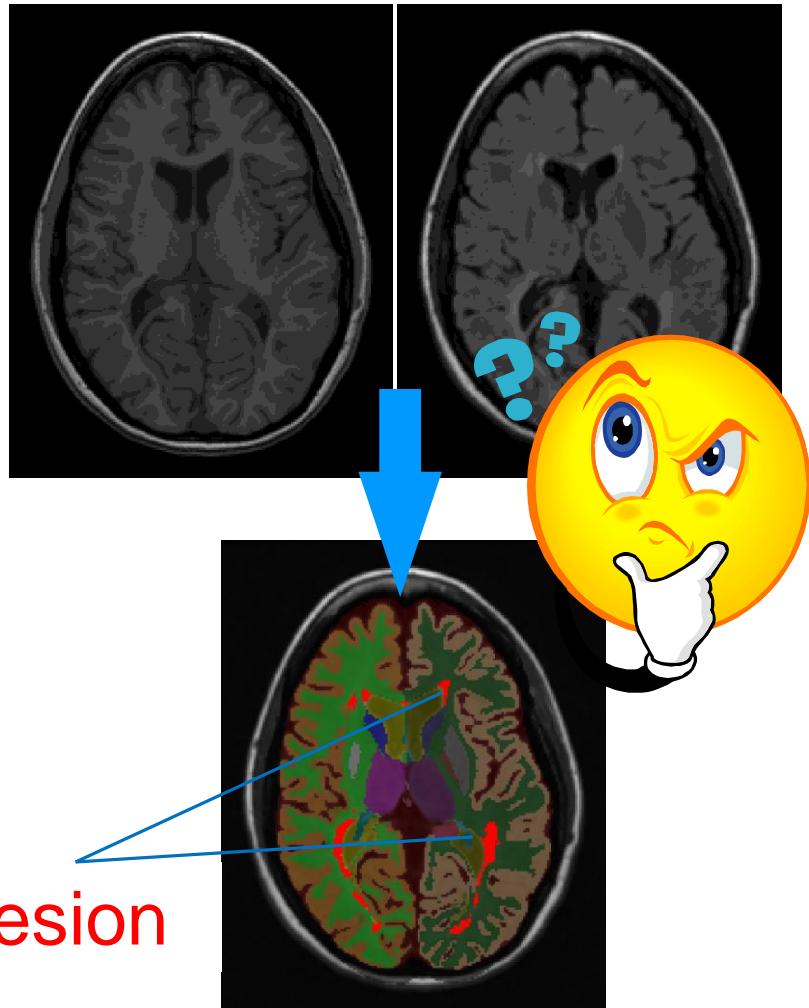
~10min
(CPU)

Training data



3T multi-contrast scan

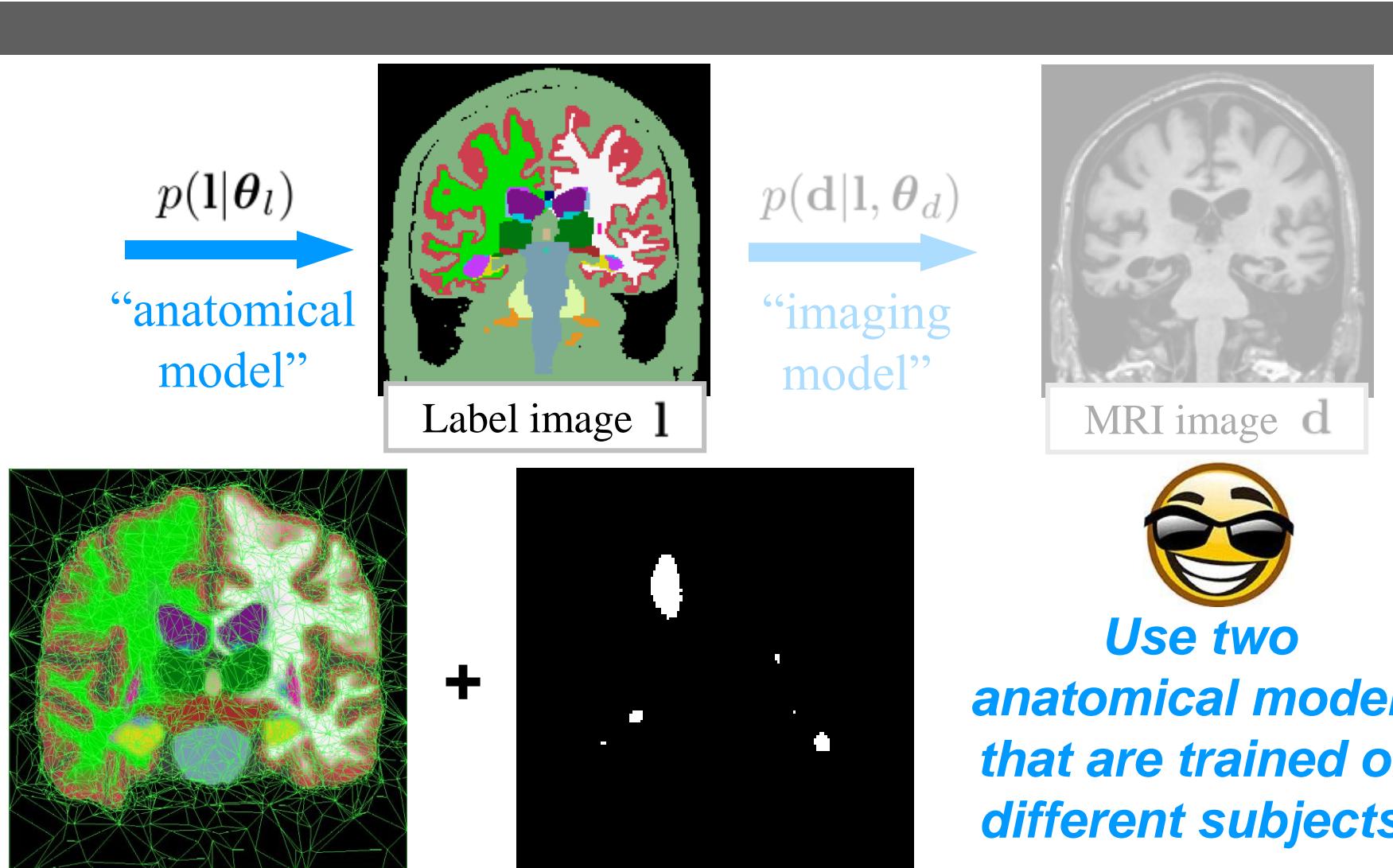
Adding pathology into the mix...



- Tissue contrast depends on hardware and pulse sequence
- No standard protocol for clinical imaging (multimodal)
- **Additional difficulty:**
Disease-specific lesions!

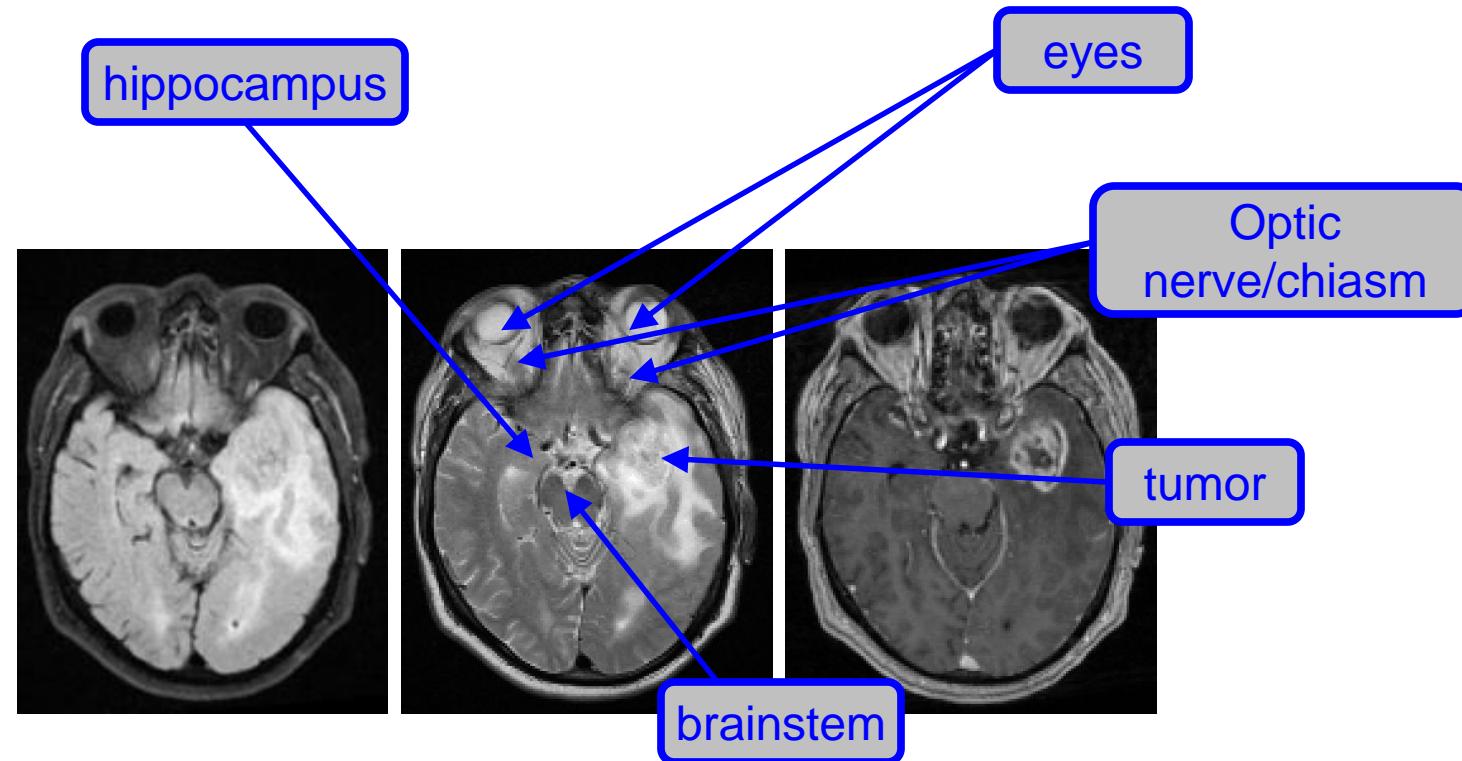


Idea: alter the generative model

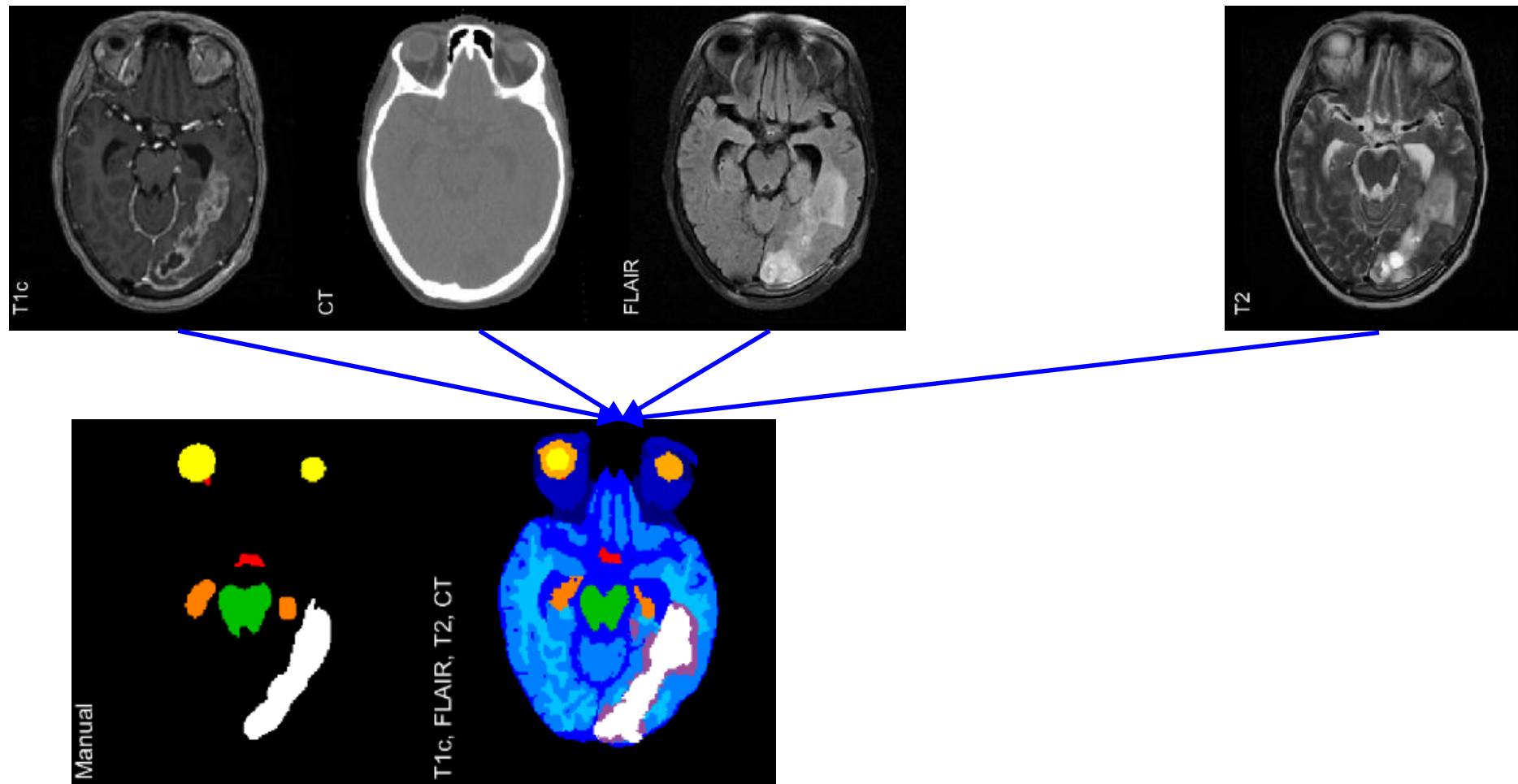


Radiation therapy planning

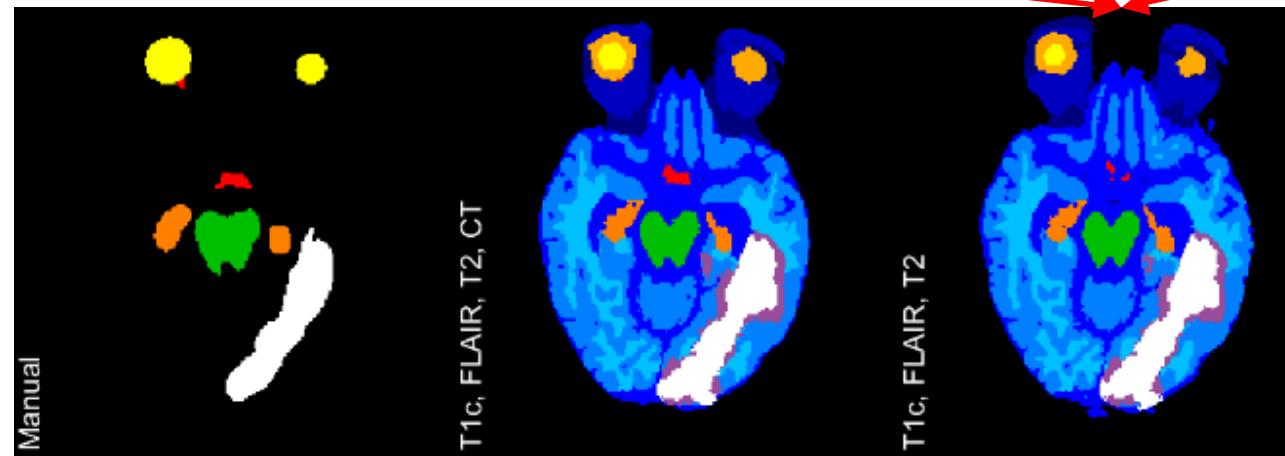
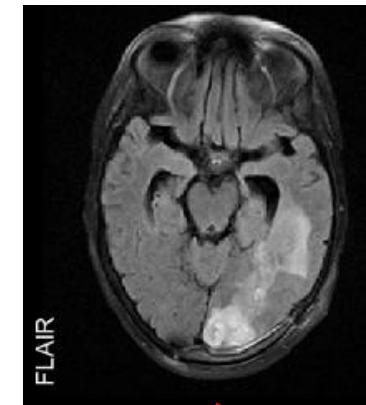
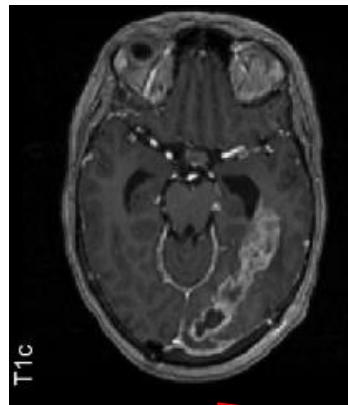
- Radiate a brain tumor while sparing organs-at-risk
- Need to know where these structures are



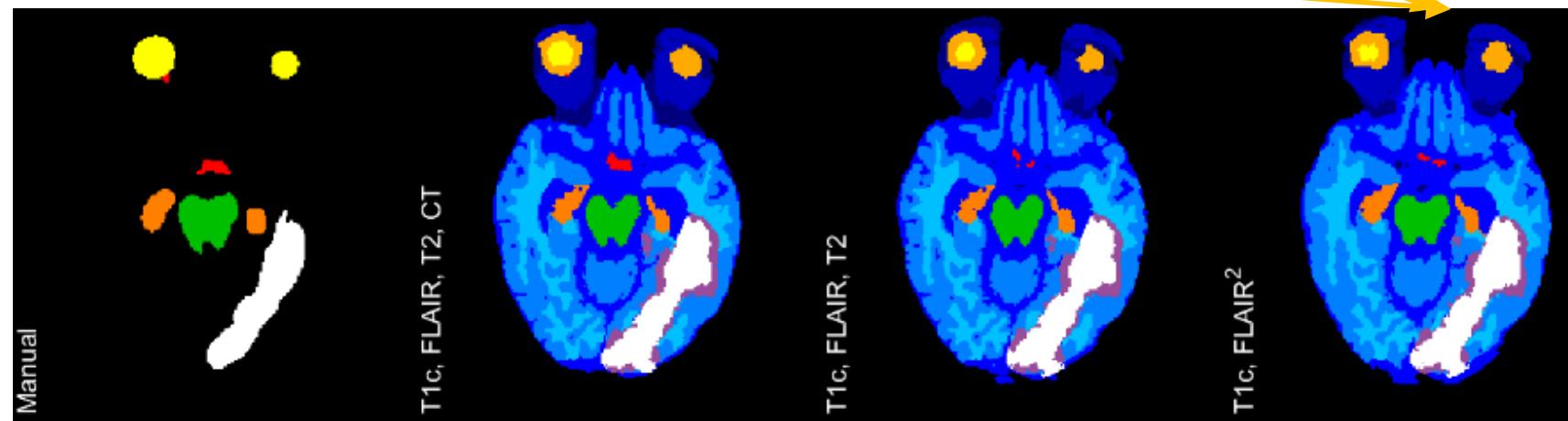
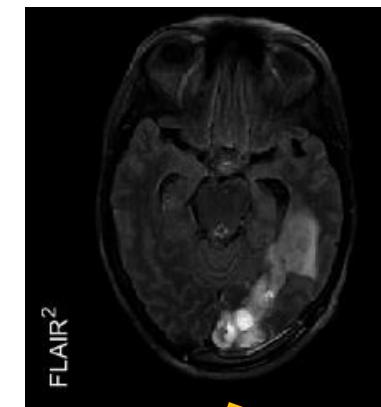
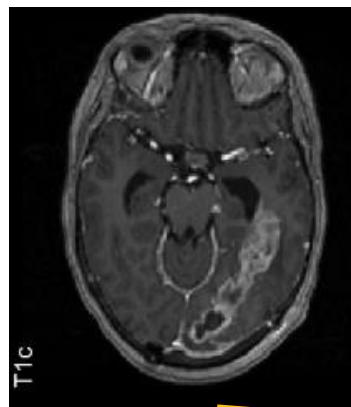
Radiation therapy planning



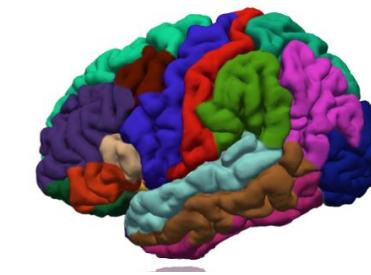
Radiation therapy planning



Radiation therapy planning



Tiny brain structures

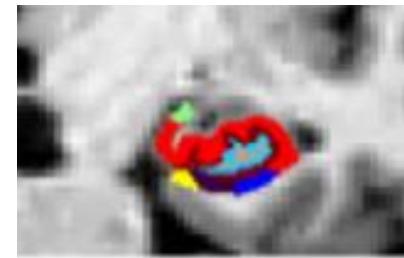


<http://freesurfer.net/>



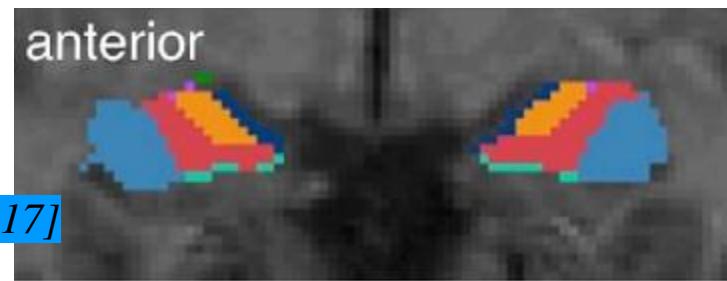
hippocampus

[Iglesias NeuroImage 2015]



amygdala

[Saygin NeuroImage 2017]

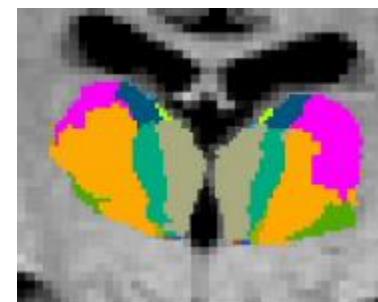


anterior

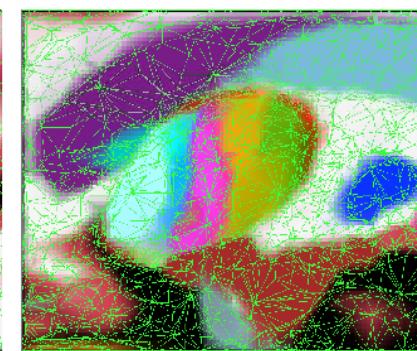
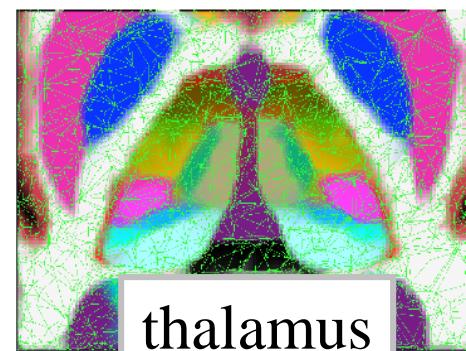
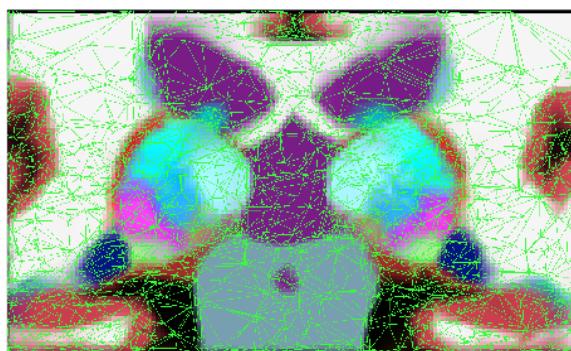
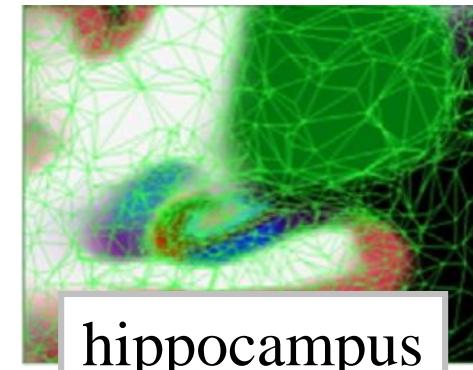
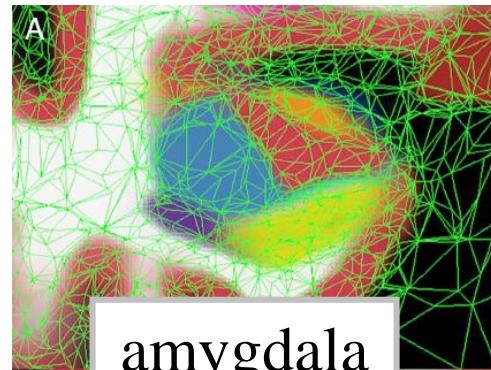


thalamus

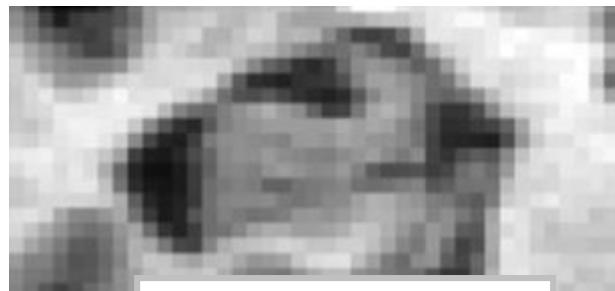
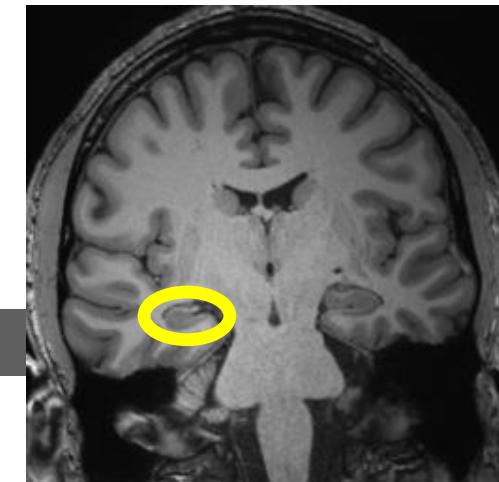
[Iglesias NeuroImage 2018]



Segmentation method same as before



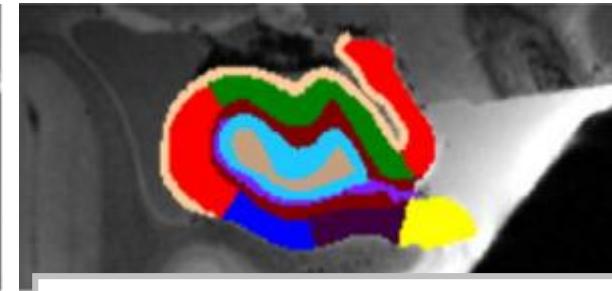
Discriminative methods?



in vivo
1mm isotropic



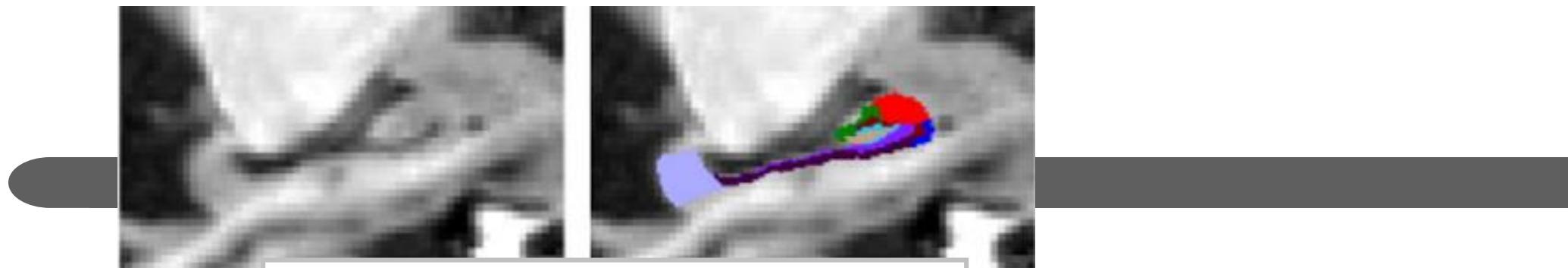
ex vivo
0.13mm isotropic



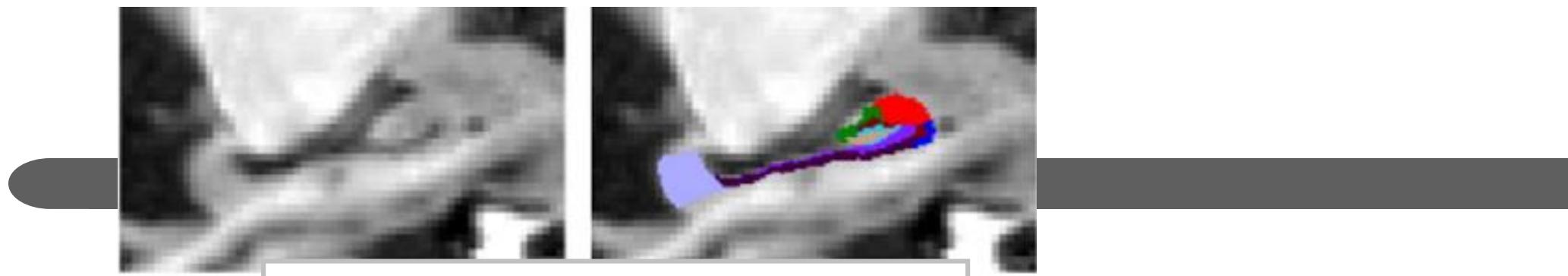
ex vivo
expert segmentation

Manual delineations on high-resolution *ex vivo* scans:

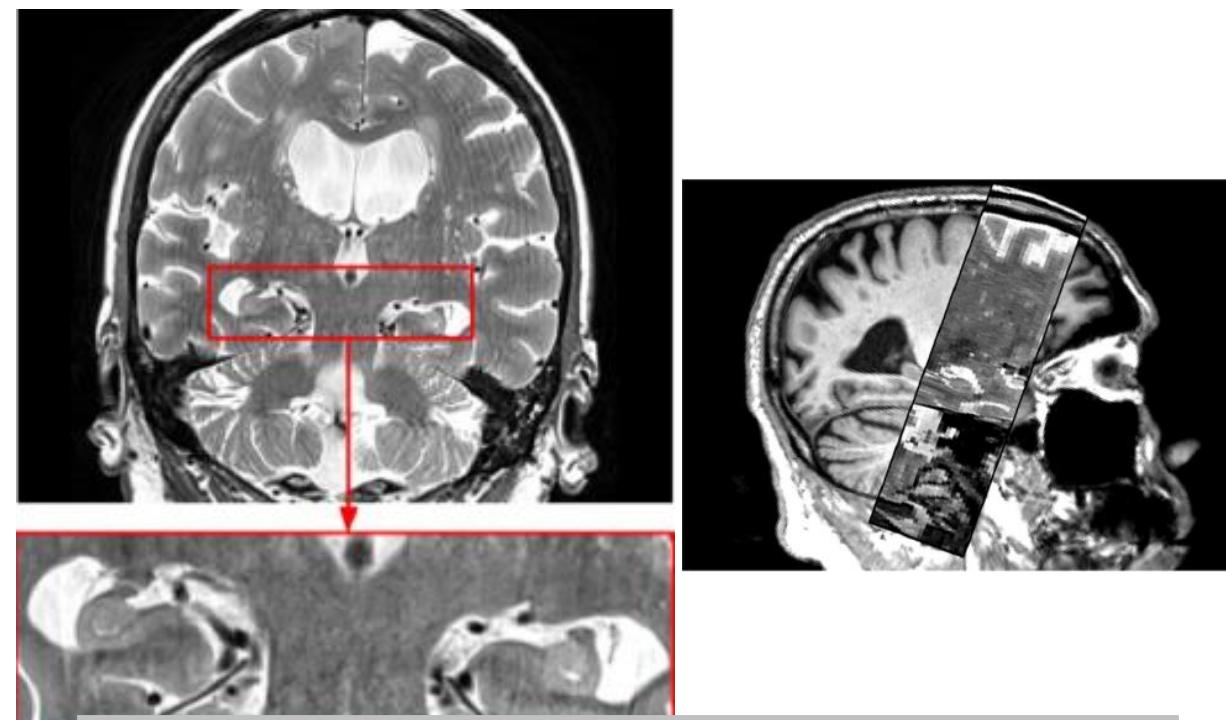
- Intrinsic MRI contrast changes
- Only ~10 training subjects



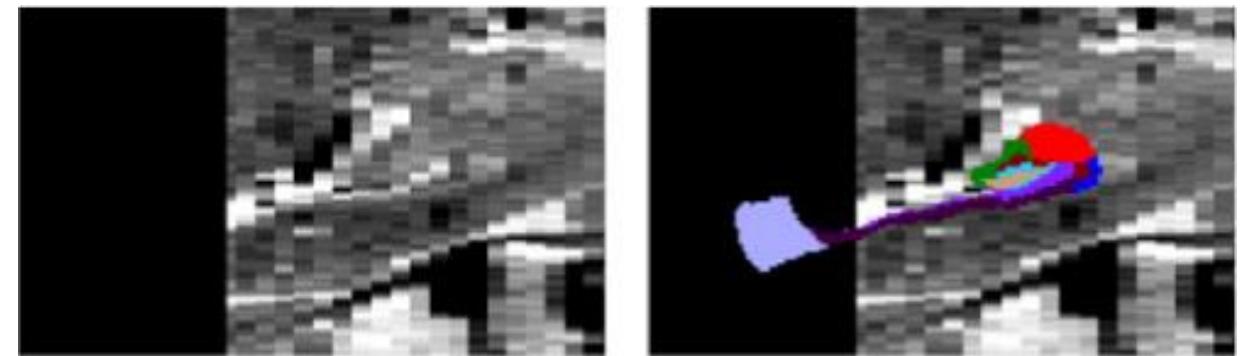
T1w only (1mm isotropic)



T1w only (1mm isotropic)



Additional T2w (0.38 x 0.38 x 0.8 mm)



Overview



Uncertainty on input using generative models

Uncertainty on output using Monte Carlo sampling

Discussion and conclusion

Uncertainty papers from me/my group...

variational approximation

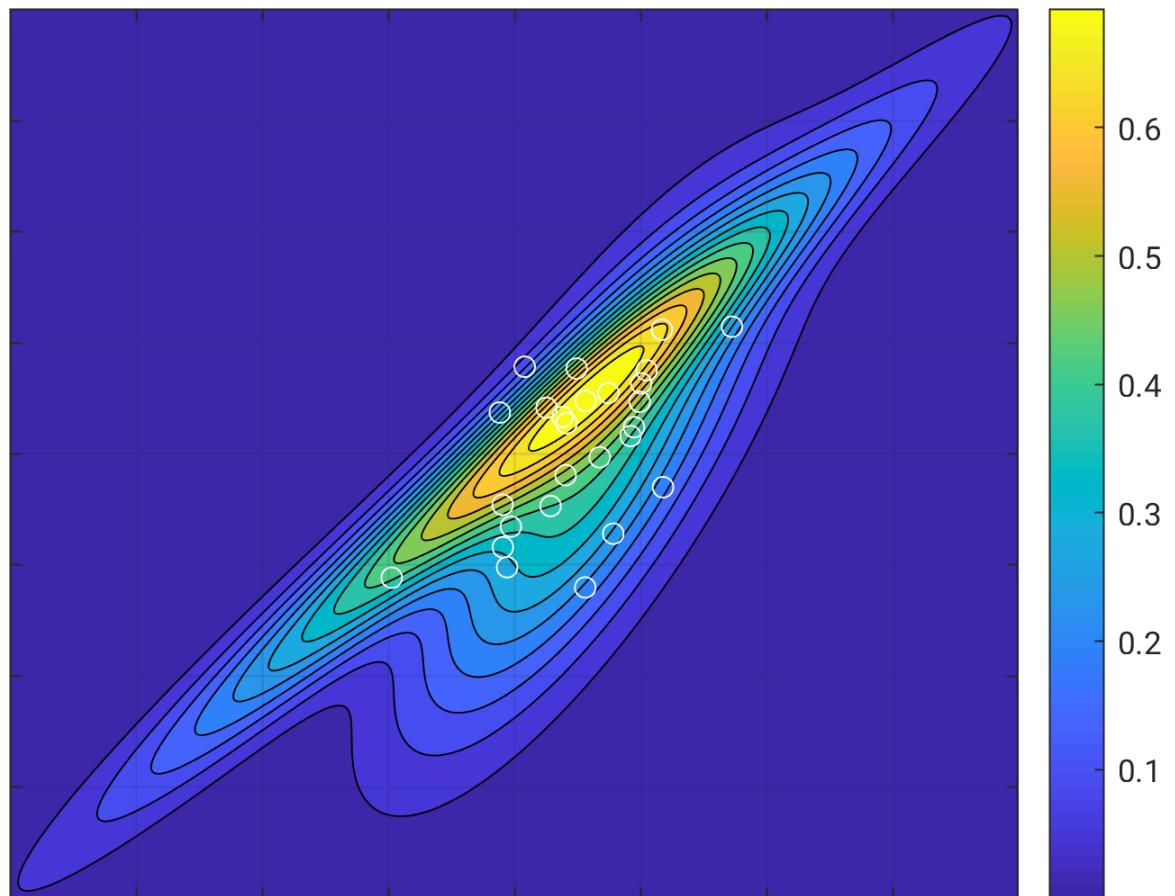
- Mean-field approximation of MRFs (TMI 1999)
- Metropolis sampling for partial volume models (TMI 2003)
- HMC for visualizing atlas warp priors (TMI 2009)
- HMC + Gibbs sampling for segmentation uncertainty (MEDIA 2013)
- Gibbs sampling for analyzing STAPLE (MICCAI 2014)
- HMC for PET reconstruction uncertainty (MICCAI 2015)
- Gibbs sampling for radiotherapy segmentations (MEDIA 2019)
- Gibbs sampling for MI-based registration uncertainty (UNSURE 2019)

Monte Carlo sampling

Monte Carlo (MC) sampling

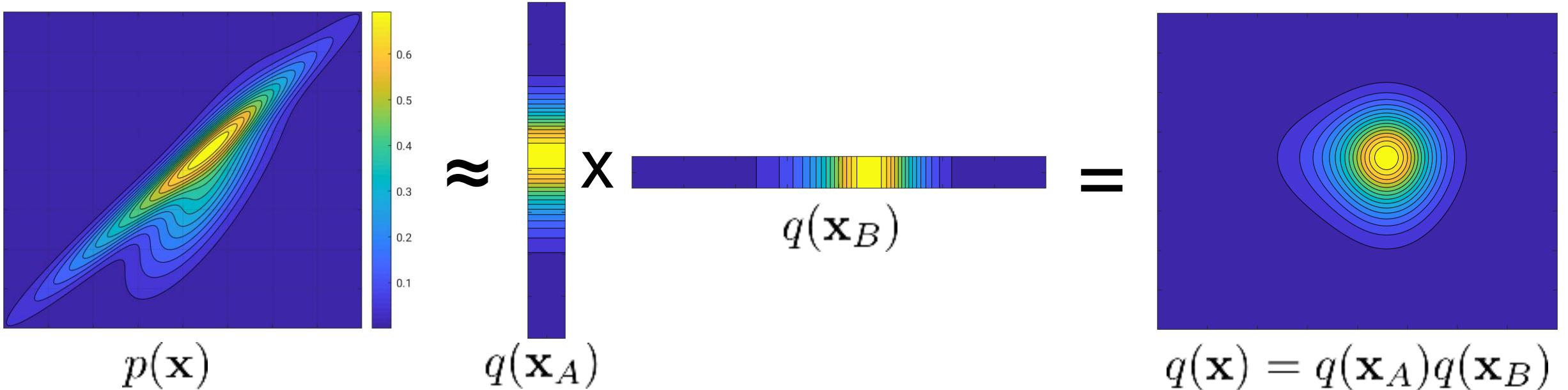
- Obtain samples of $p(\mathbf{x})$: $\{\mathbf{x}^{(s)}\}_{s=1}^S$
 - Samples from marginal distributions are obtained automatically
 - Integrals over nuisance variables automagically “disappear”!
- Approximate expectations:

$$\begin{aligned}\mathbb{E} [\phi(\mathbf{x})] &= \int_{\mathbf{x}} \phi(\mathbf{x}) p(\mathbf{x}) d\mathbf{x} \\ &\simeq \frac{1}{S} \sum_{s=1}^S \phi(\mathbf{x}^{(s)})\end{aligned}$$



Why Monte Carlo sampling?

- Variational methods (mean-field approximation): $\mathbf{x} = (\mathbf{x}_A^T, \mathbf{x}_B^T)^T$

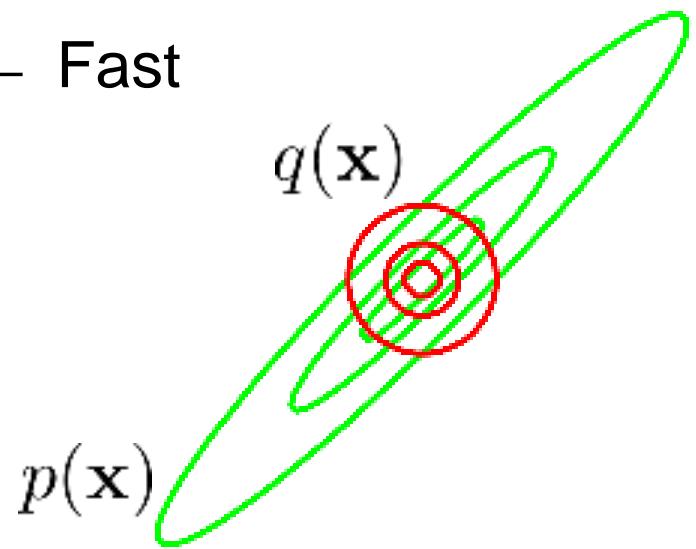


- Minimize the Kullback-Leibler divergence between $q(\mathbf{x})$ and $p(\mathbf{x})$

Variational approximations (mean-field)?



- Fast

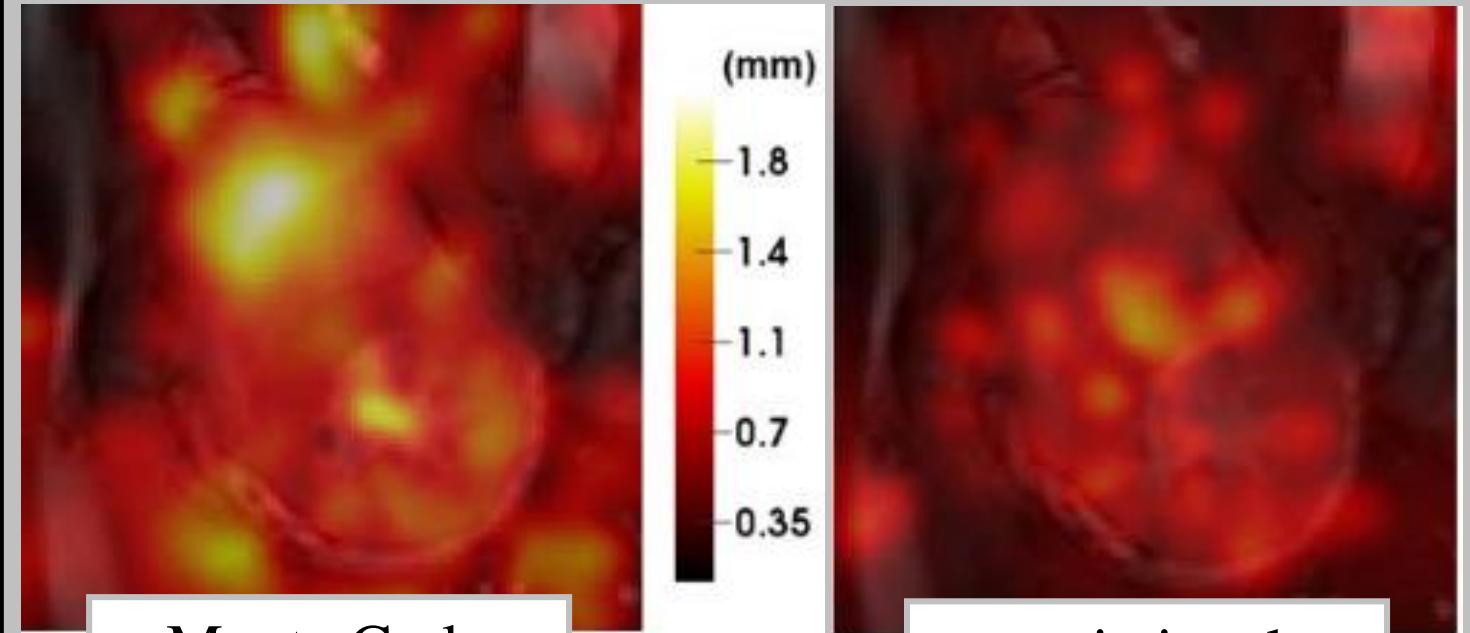


[Bishop PRML 2016]



- Can be hugely inaccurate (for strong dependencies)
- No red flags raised

Registration uncertainty [Le Folgoc TMI 2017]



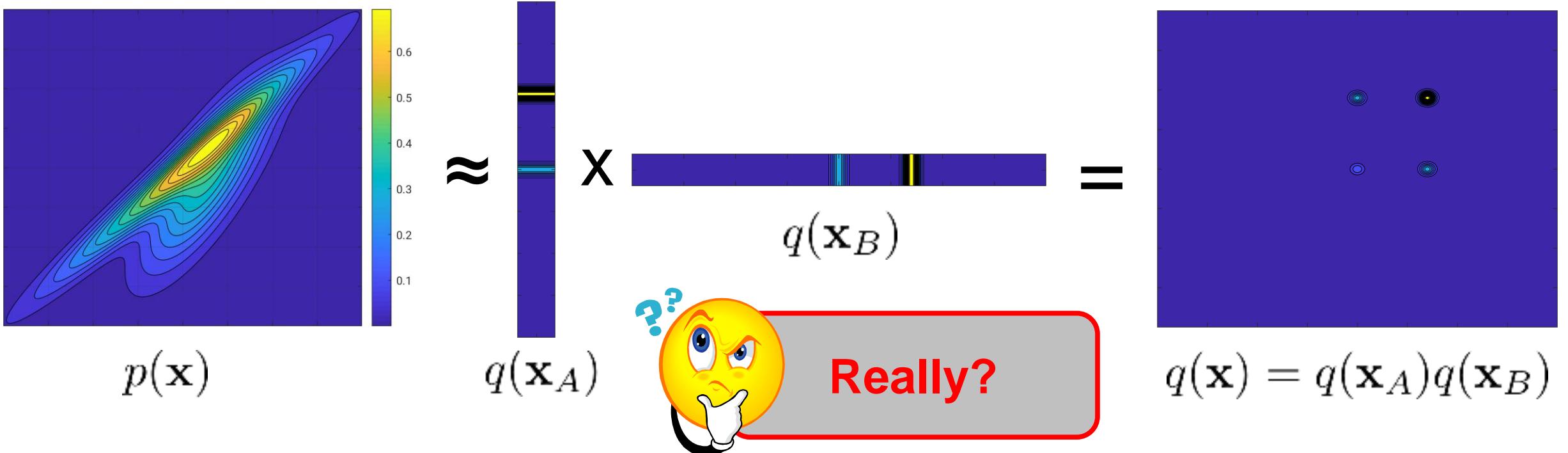
Monte Carlo

variational

- *OK for increasing e.g., Dice scores*
- *Dubious for anything else*

BTW: dropout at test time?

- Randomly remove some units in a neural network [Gal & Ghahramani ICML 2016]
- Popular in medical image analysis



Monte Carlo sampling in high dimensions

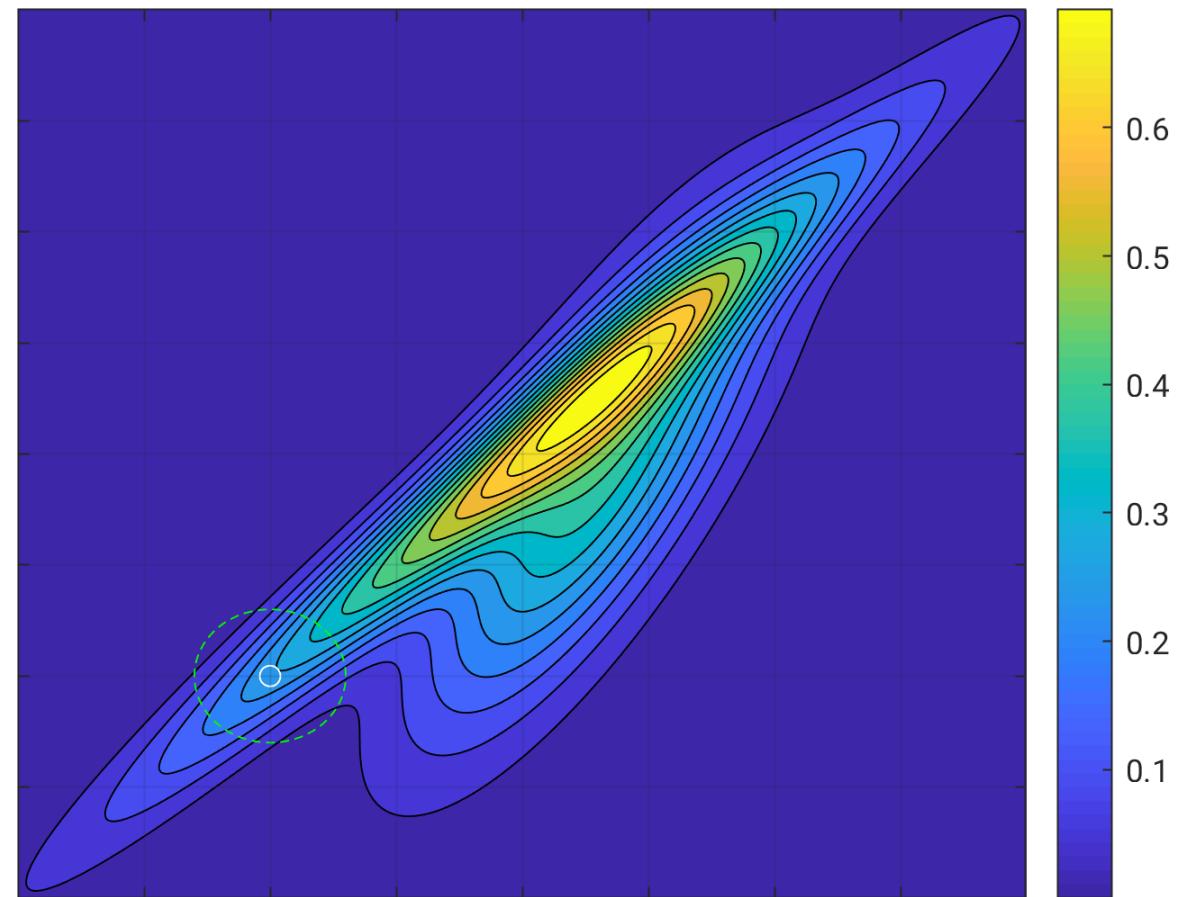
Markov chain Monte Carlo (MCMC):

- Propose a perturbation \mathbf{x}^* of a current state $\mathbf{x}^{(\tau)}$ using a proposal distribution $q(\mathbf{x}^* | \mathbf{x}^{(\tau)})$

- Accept \mathbf{x}^* with probability

$$\min \left(1, \frac{p(\mathbf{x}^*) q(\mathbf{x}^{(\tau)} | \mathbf{x}^*)}{p(\mathbf{x}^{(\tau)}) q(\mathbf{x}^* | \mathbf{x}^{(\tau)})} \right)$$

[Metropolis-Hastings]



Monte Carlo sampling in high dimensions

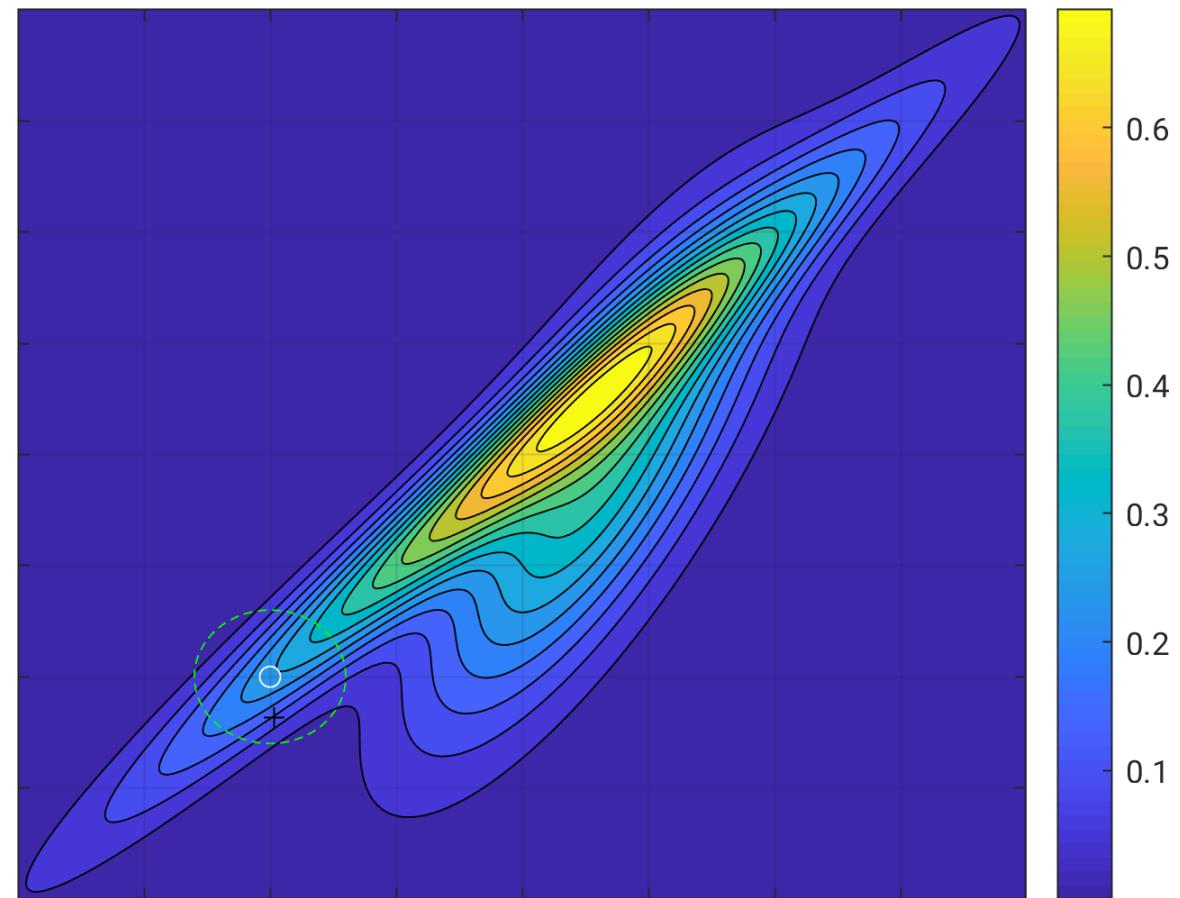
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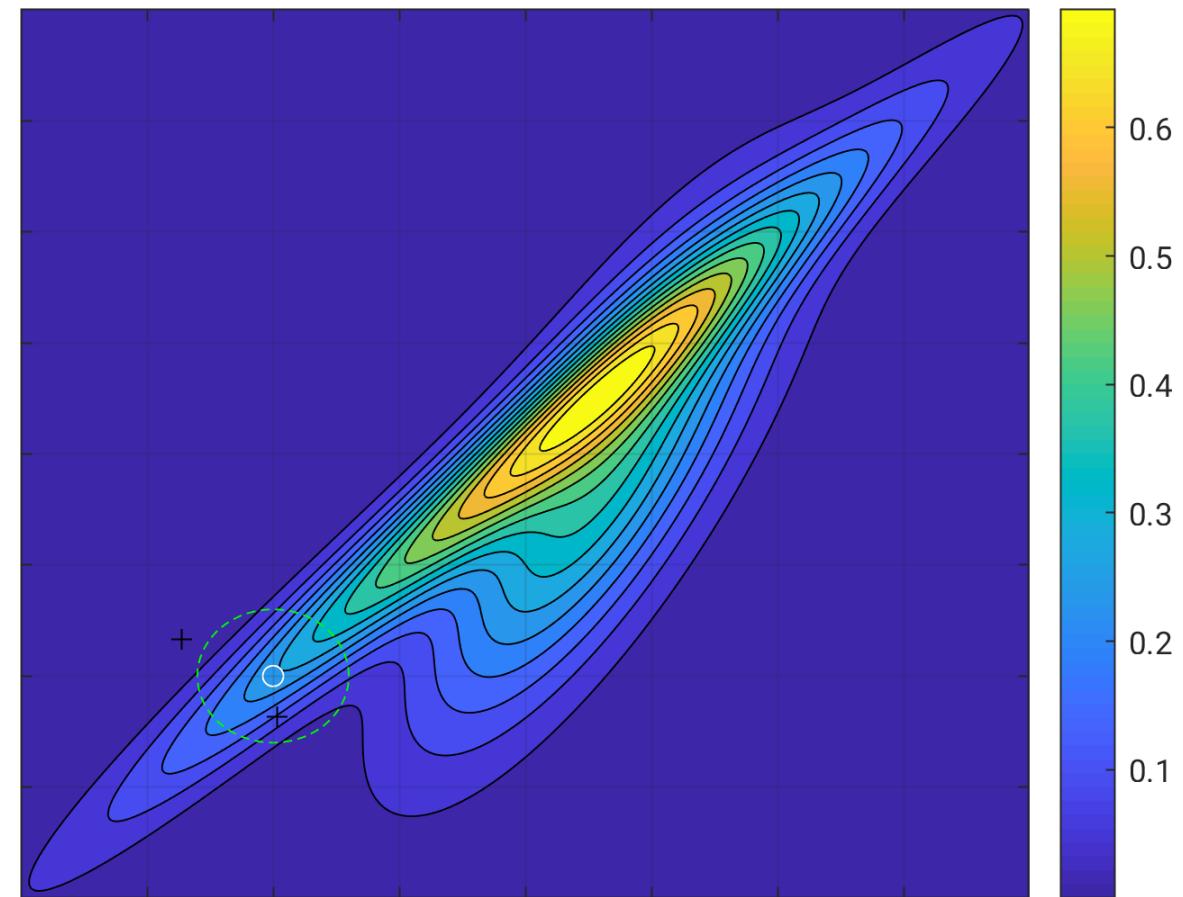
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[Metropolis-Hastings]



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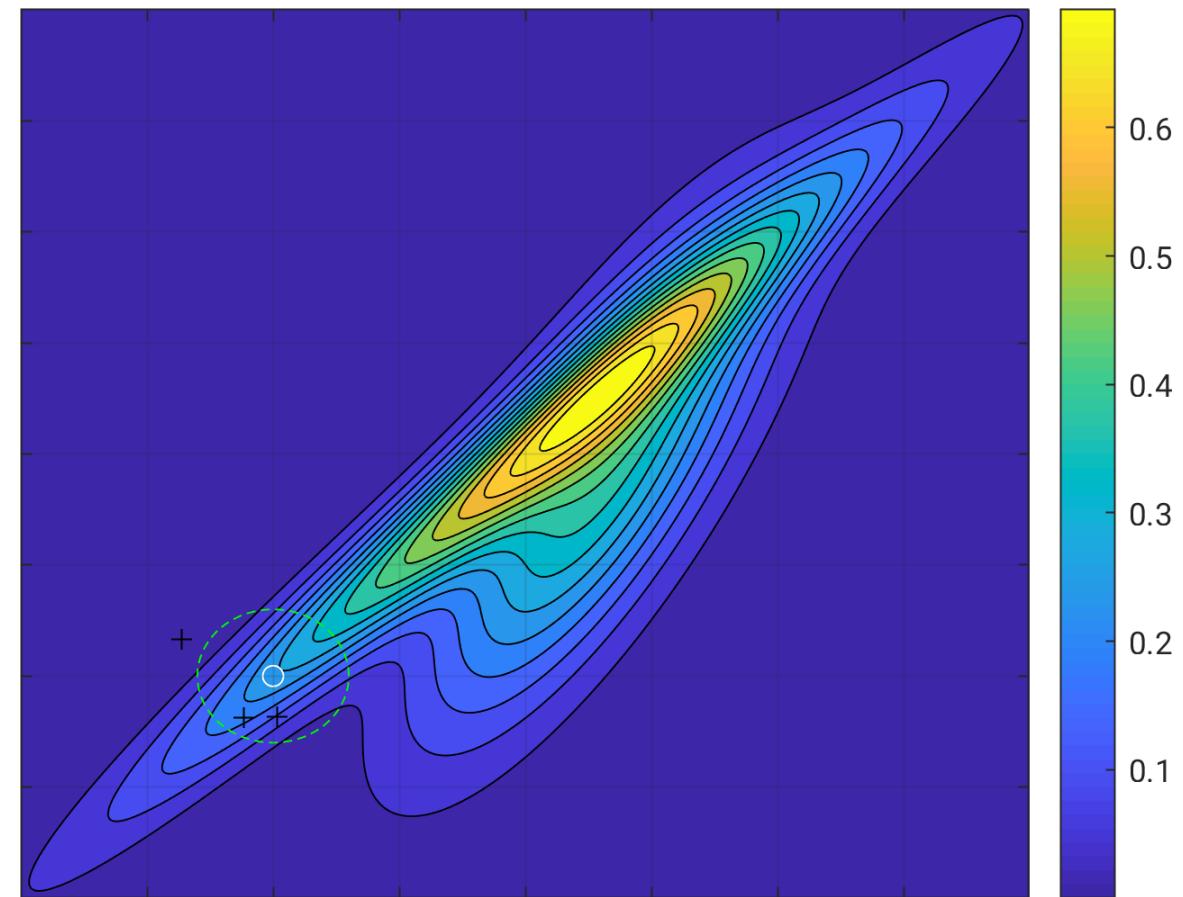
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[Metropolis-Hastings]



Monte Carlo sampling in high dimensions

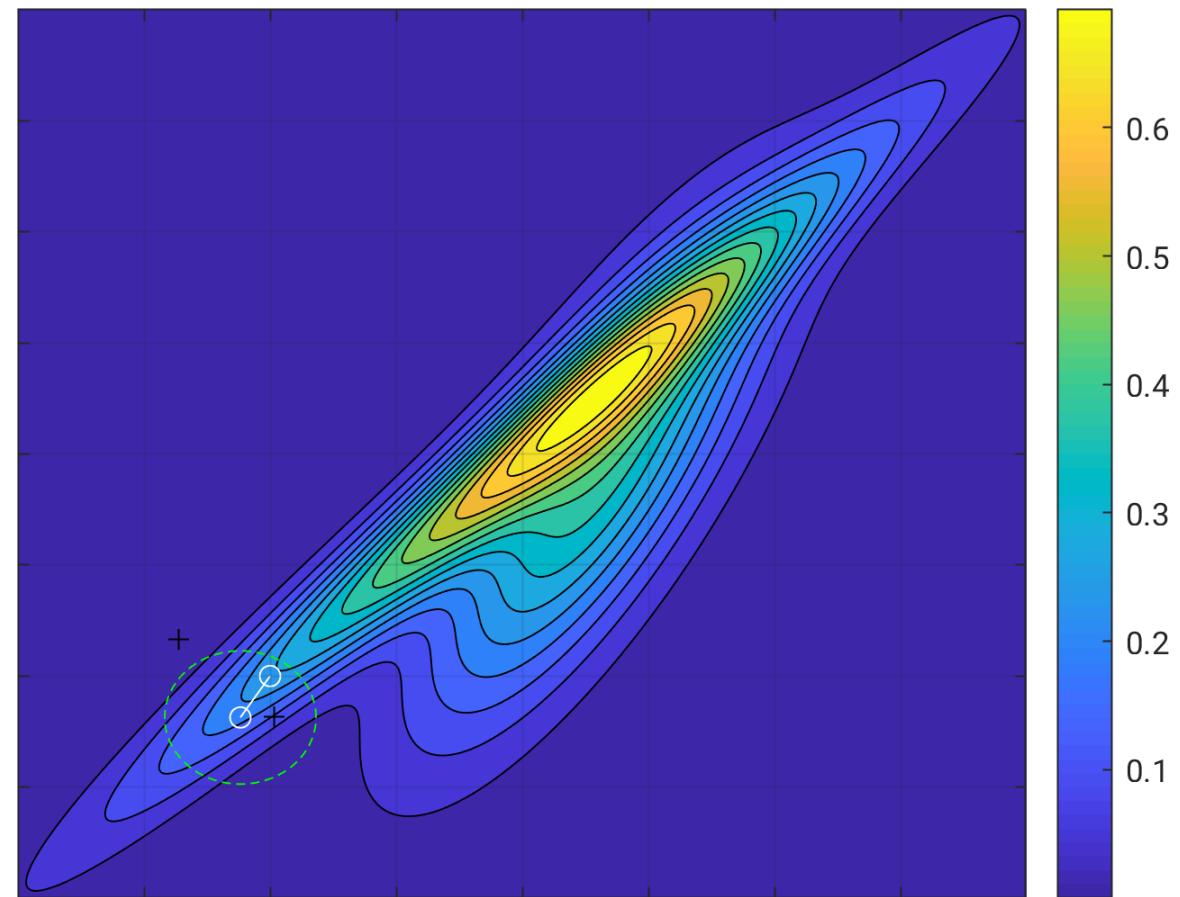
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Monte Carlo sampling in high dimensions

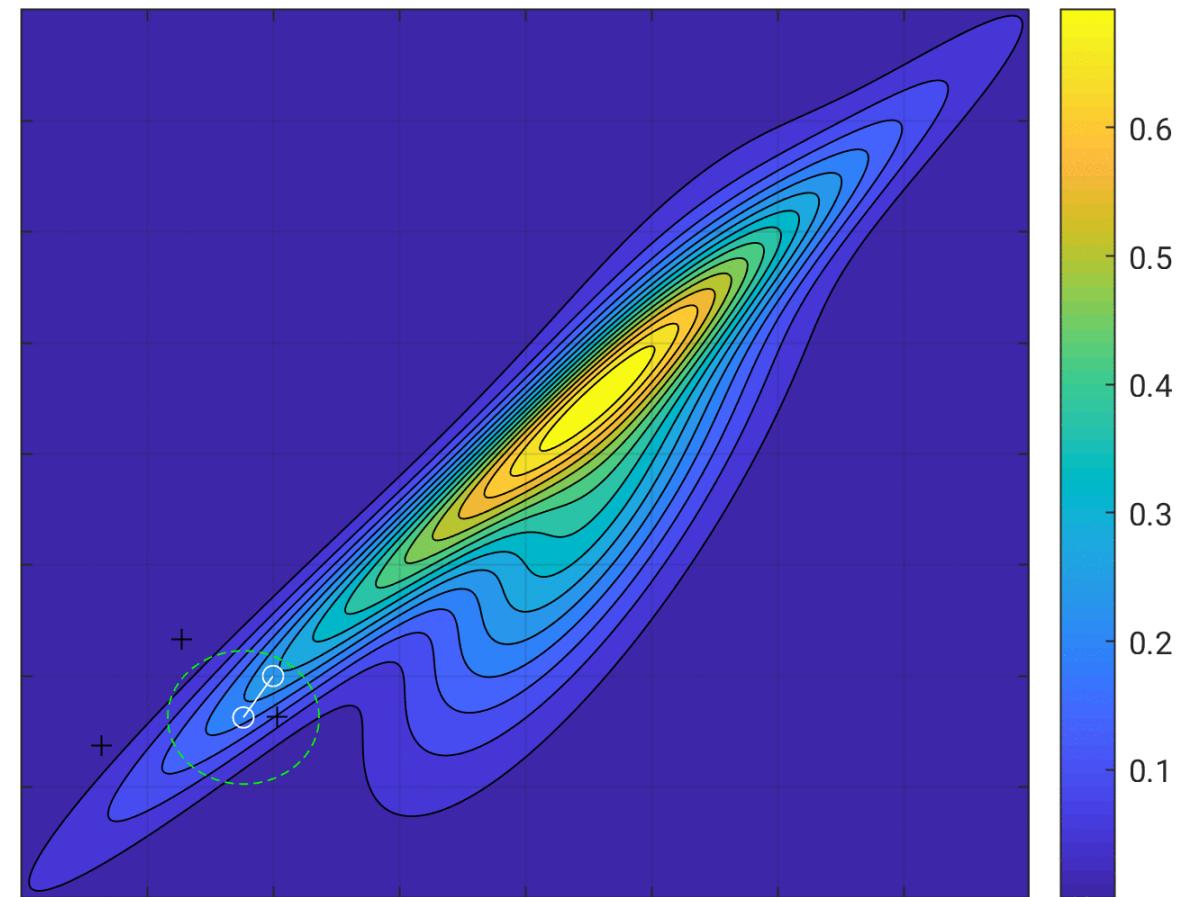
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[Metropolis-Hastings]



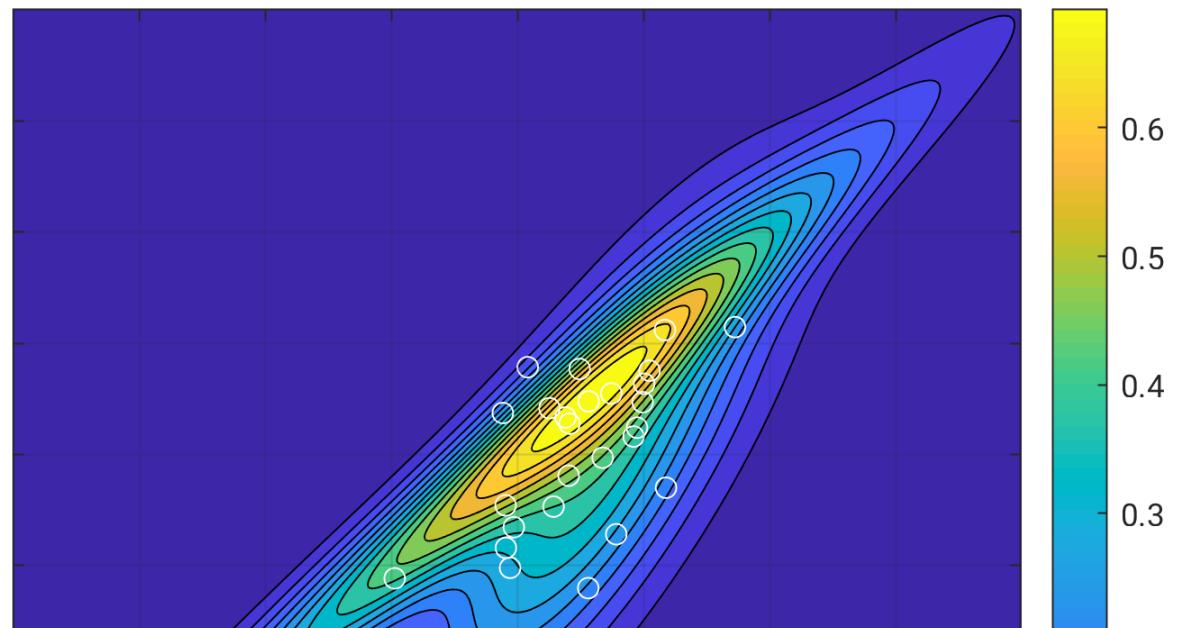
Monte Carlo sampling in high dimensions

Markov chain Monte Carlo (MCMC):

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- Accept \mathbf{x}^* with probability

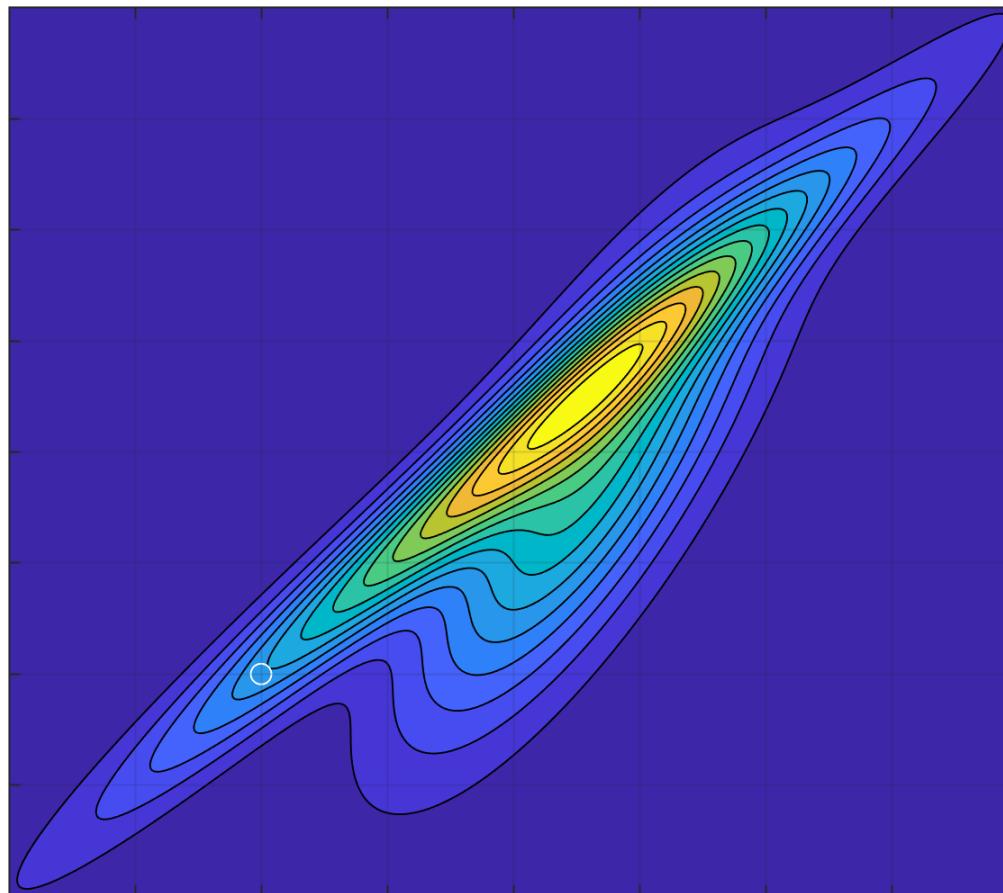
$$\min \left(1, \frac{p(\mathbf{x}^*) q(\mathbf{x}^{(\tau)} | \mathbf{x}^*)}{p(\mathbf{x}^{(\tau)}) q(\mathbf{x}^* | \mathbf{x}^{(\tau)})} \right)$$

[Metropolis-Hastings]



- Great approximations
- Dependencies can make things super slow
- Burn-in period?

Gibbs sampling



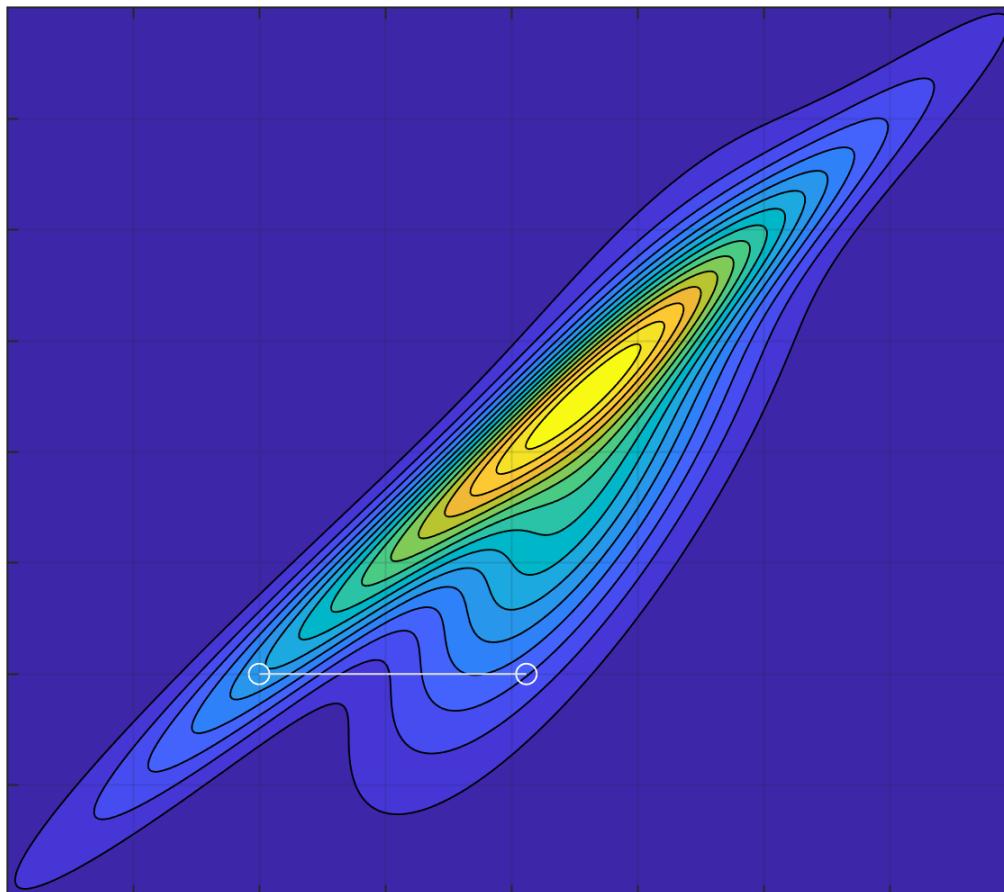
- Proposal distributions are conditional distributions:

$$\mathbf{x}_A^{(\tau+1)} \sim p(\mathbf{x}_A | \mathbf{x}_B^{(\tau)})$$

$$\mathbf{x}_B^{(\tau+1)} \sim p(\mathbf{x}_B | \mathbf{x}_A^{(\tau+1)})$$

- Proposals always accepted
- No tuning needed!
- Cf. optimization:
 - Coordinate descent
 - EM algorithm (95% same code!)

Gibbs sampling



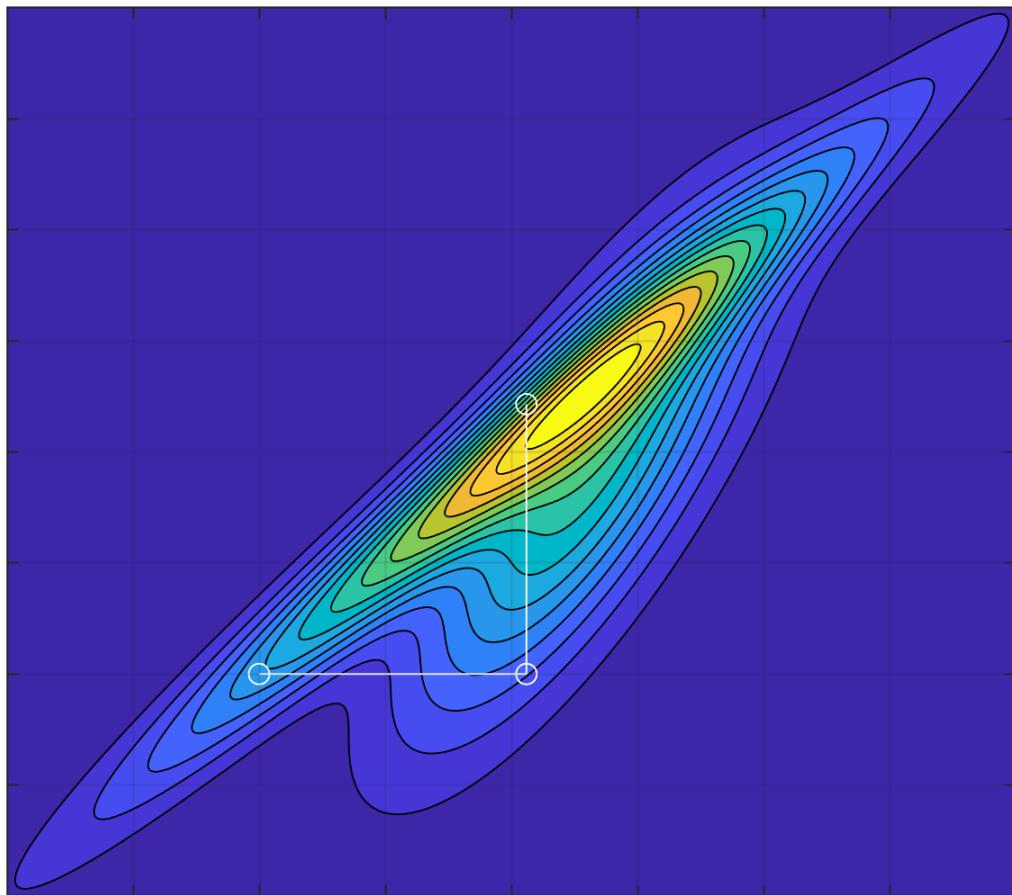
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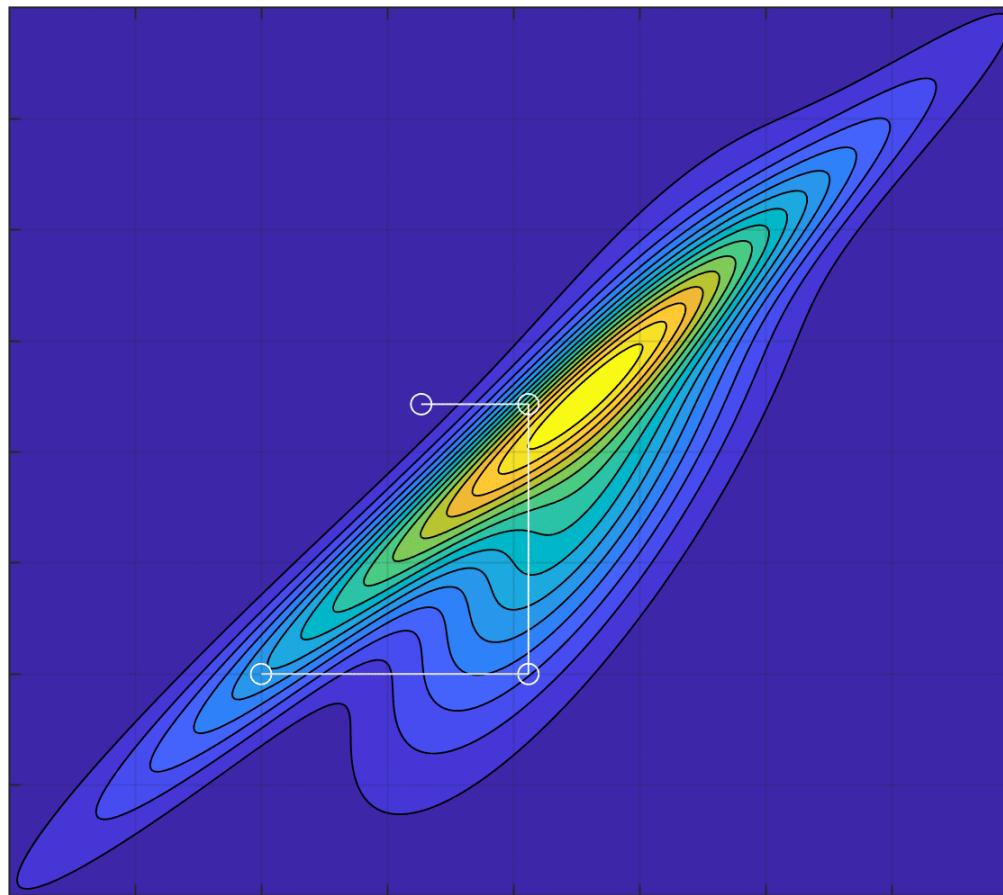
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Gibbs sampling



- Proposal distributions are conditional distributions:

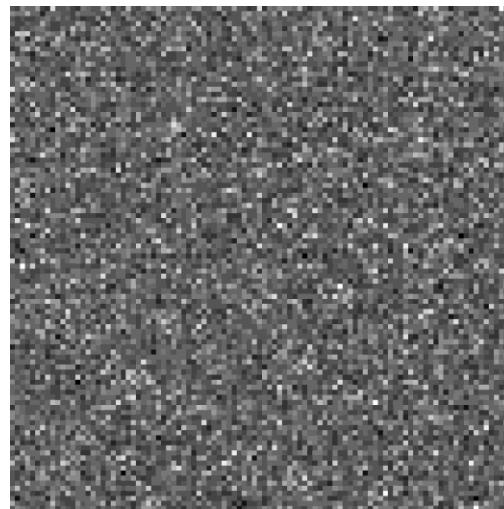
$$\mathbf{x}_A^{(\tau+1)} \sim p(\mathbf{x}_A | \mathbf{x}_B^{(\tau)})$$

$$\mathbf{x}_B^{(\tau+1)} \sim p(\mathbf{x}_B | \mathbf{x}_A^{(\tau+1)})$$

- Proposals always accepted
- No tuning needed!
- Cf. optimization:
 - Coordinate descent
 - EM algorithm (95% same code!)

Gibbs sampling: Gaussian mixture model

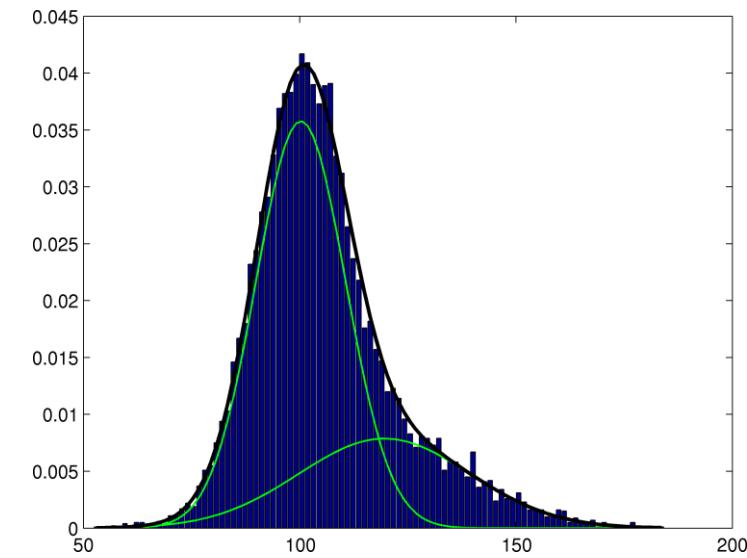
Sampling from $p(\mathbf{l}|\mathbf{d}) = \int_{\boldsymbol{\theta}} p(\mathbf{l}, \boldsymbol{\theta}|\mathbf{d}) d\boldsymbol{\theta}$



\mathbf{d}



$\mathbf{l}^{(\tau+1)} \sim p(\mathbf{l}|\mathbf{d}, \boldsymbol{\theta}^{(\tau)})$

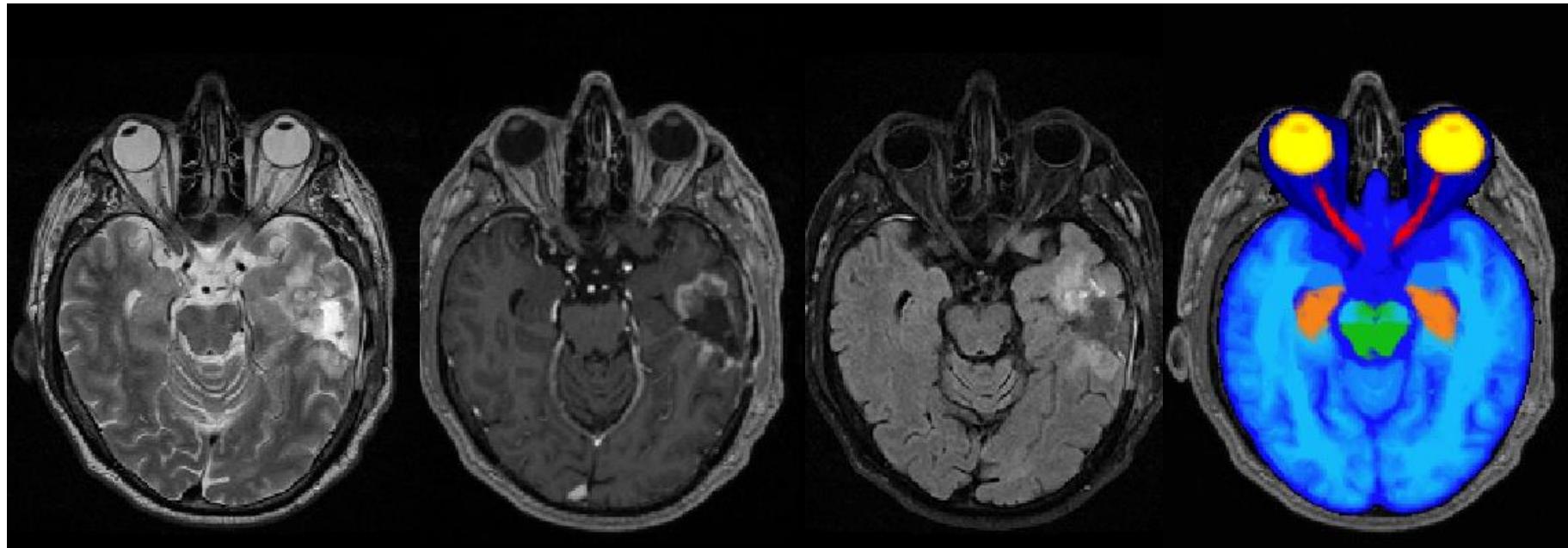


$\boldsymbol{\theta}^{(\tau+1)} \sim p(\boldsymbol{\theta}|\mathbf{d}, \mathbf{l}^{(\tau+1)})$

sample from $p(\mathbf{l}, \boldsymbol{\theta}|\mathbf{d})$ but only keep samples of \mathbf{l}

Gibbs sampling: radiation therapy application

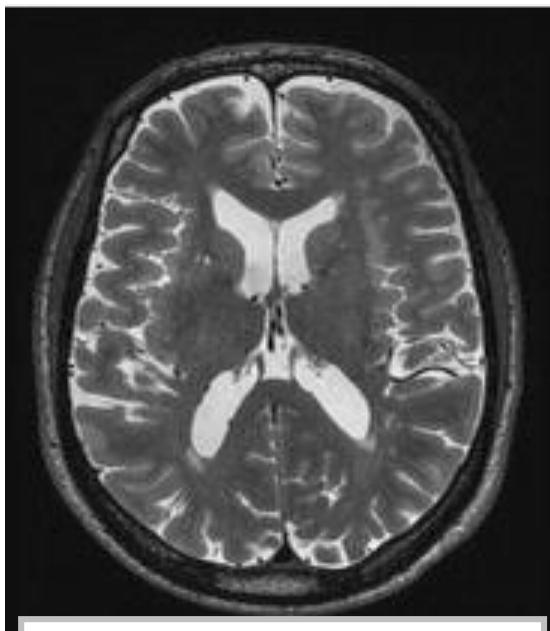
- Optimization as initialization
- Then Gibbs sampling from everything except atlas warp
(segmentation – bias field – Gaussian mixture parameters – latent shape model parameters)



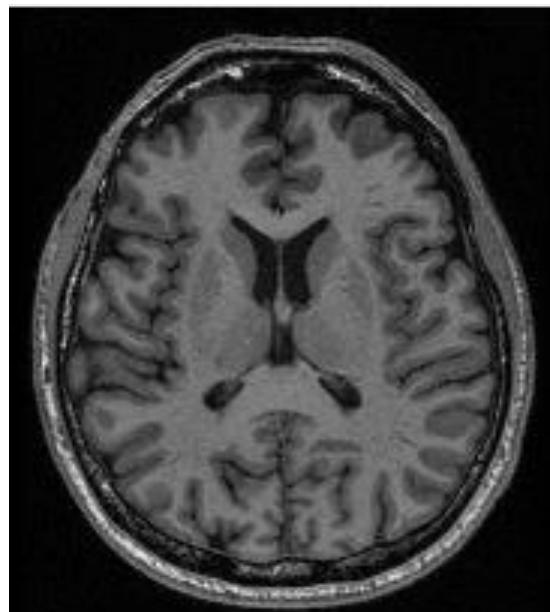
[Agn et al., Medical Image Analysis 2019]

Gibbs sampling: MI-based registration

- Mutual Information (MI) rephrased as a generative model
- EM optimization as initialization, then Gibbs sampling (code re-use!)

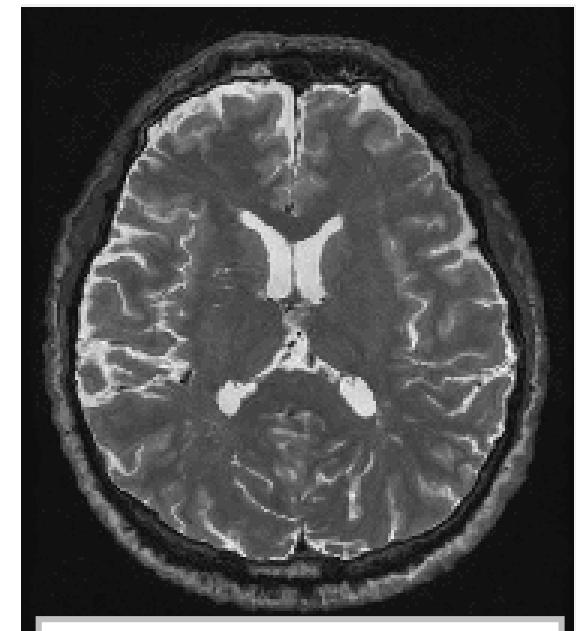


T2w



T1w different subject

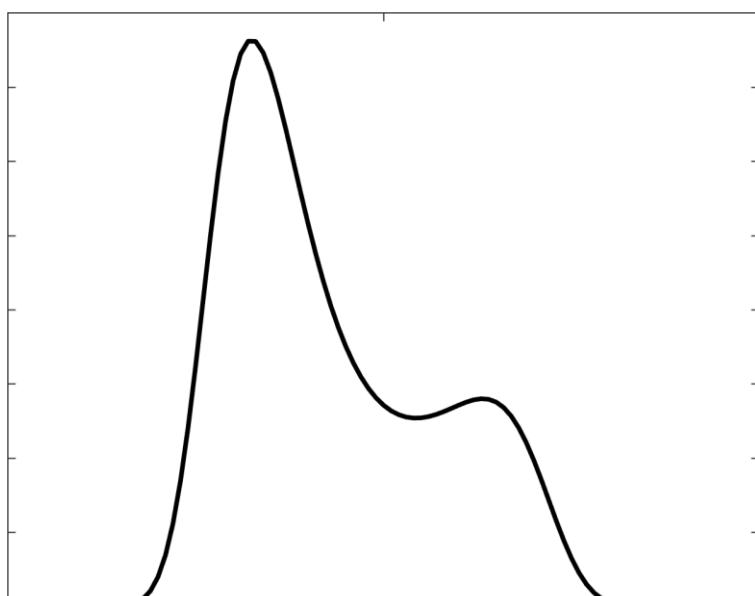
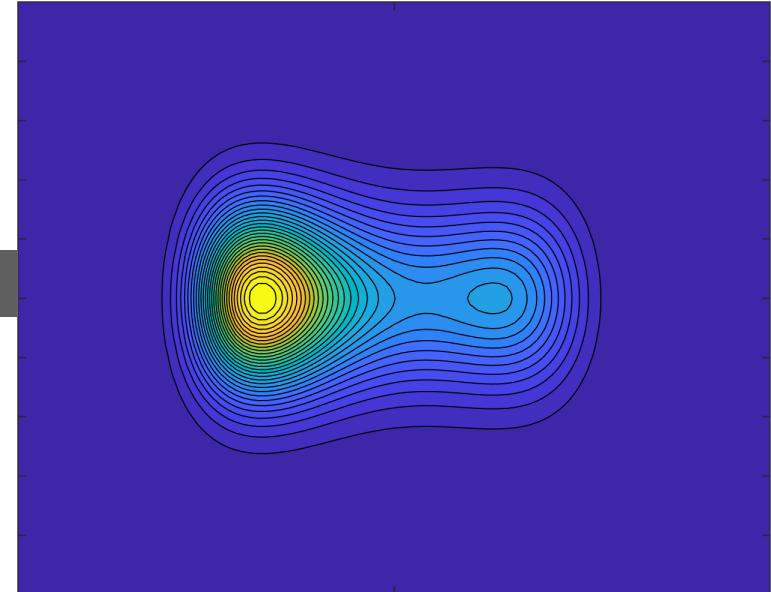
[Agn and Van Leemput, UNSURE 2019]



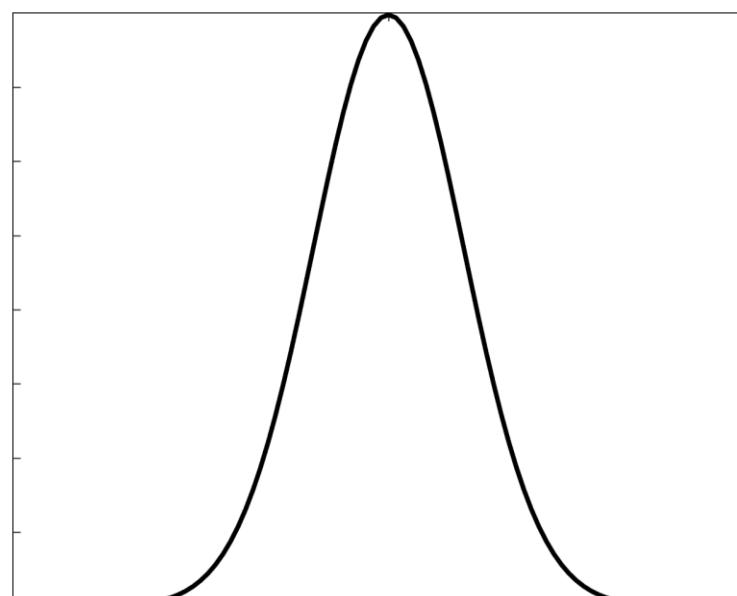
*deformed T2w
(samples)*

Hamiltonian Monte Carlo (HMC)

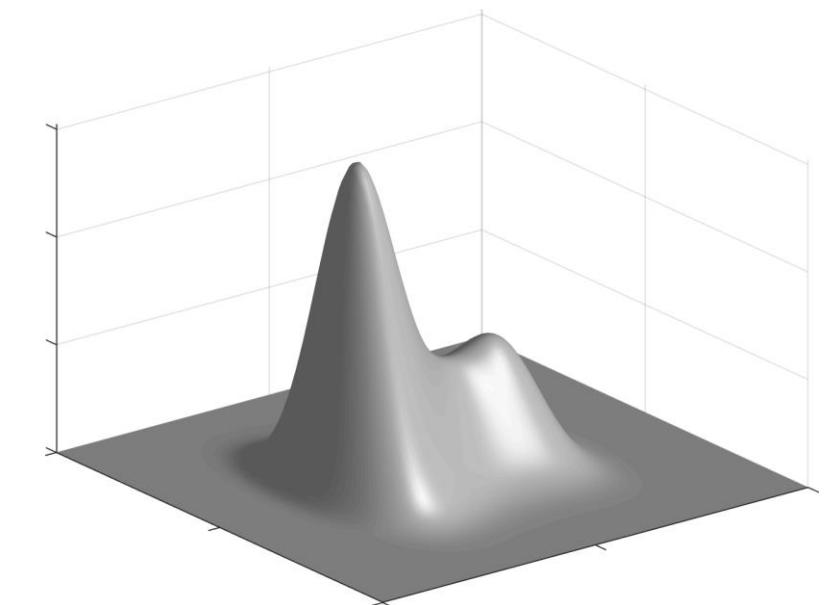
- Introduce virtual “momentum” variables \mathbf{m}
- Sample from $p(\mathbf{x}, \mathbf{m}) = p(\mathbf{x}) \cdot \mathcal{N}(\mathbf{m}|\mathbf{0}, \Sigma)$, and ignore momentum samples



$p(\mathbf{x})$



$\mathcal{N}(\mathbf{m}|\mathbf{0}, \Sigma)$

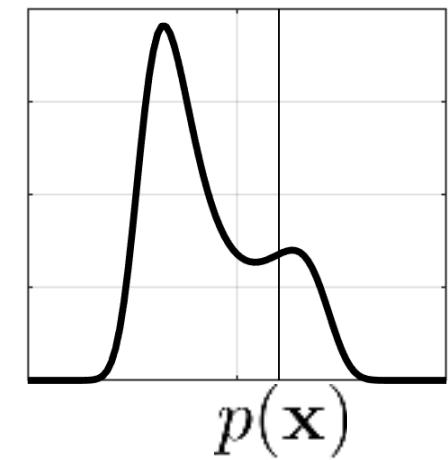
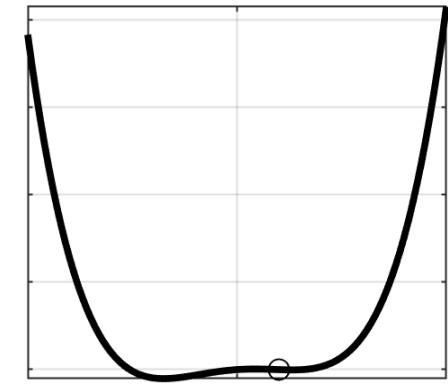
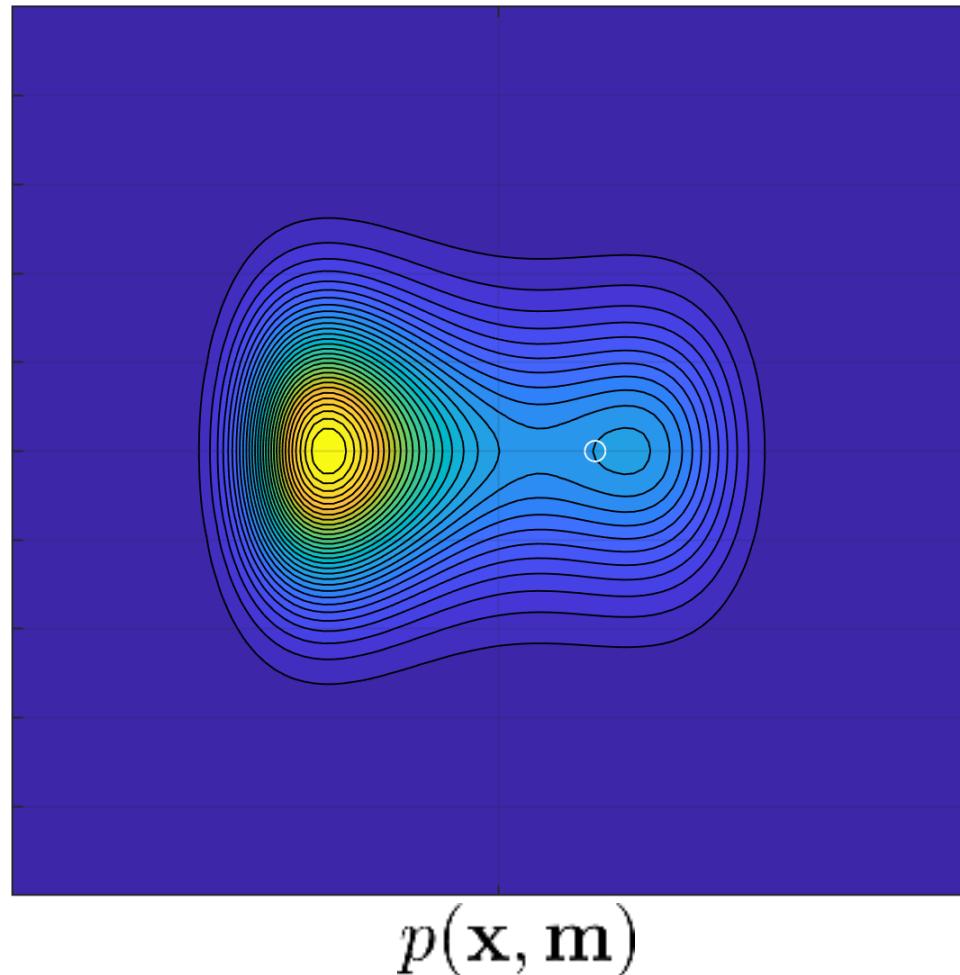


$p(\mathbf{x}, \mathbf{m}) = p(\mathbf{x}) \cdot \mathcal{N}(\mathbf{m}|\mathbf{0}, \Sigma)$

Hamiltonian Monte Carlo (HMC)

- (1) Sample momentum from $\mathcal{N}(\mathbf{m}|\mathbf{0}, \Sigma)$
- (2) Follow isocontour of $p(\mathbf{x}, \mathbf{m})$
- (3) Repeat (1) and (2)

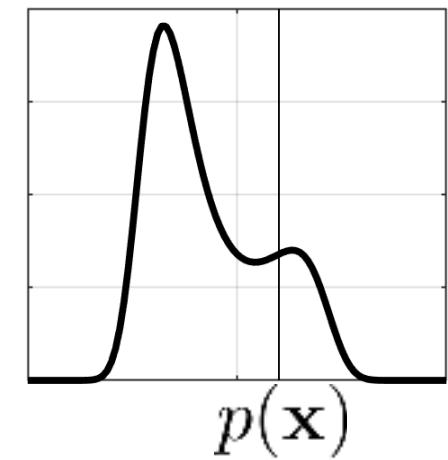
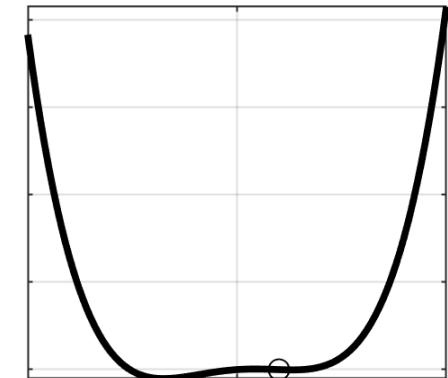
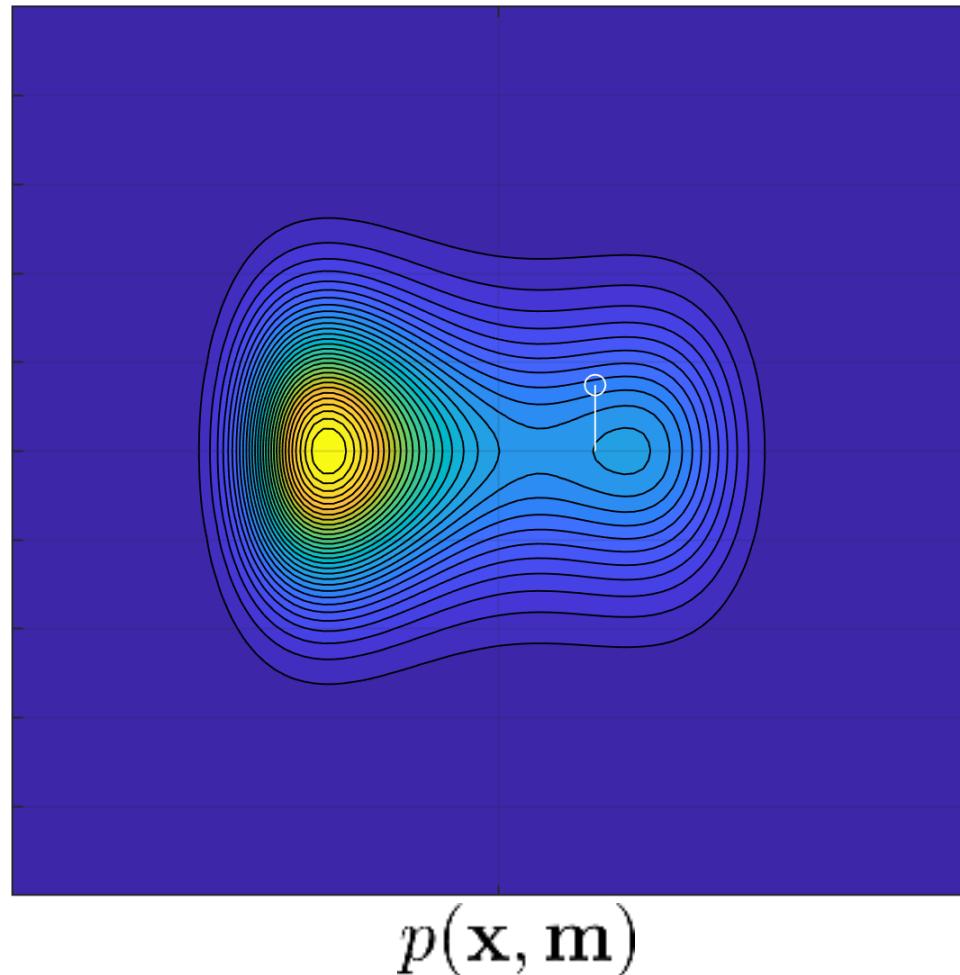
- *Efficiency by using gradient information*
 $\nabla \log p(\mathbf{x})$
- *Cf. optimization*



Hamiltonian Monte Carlo (HMC)

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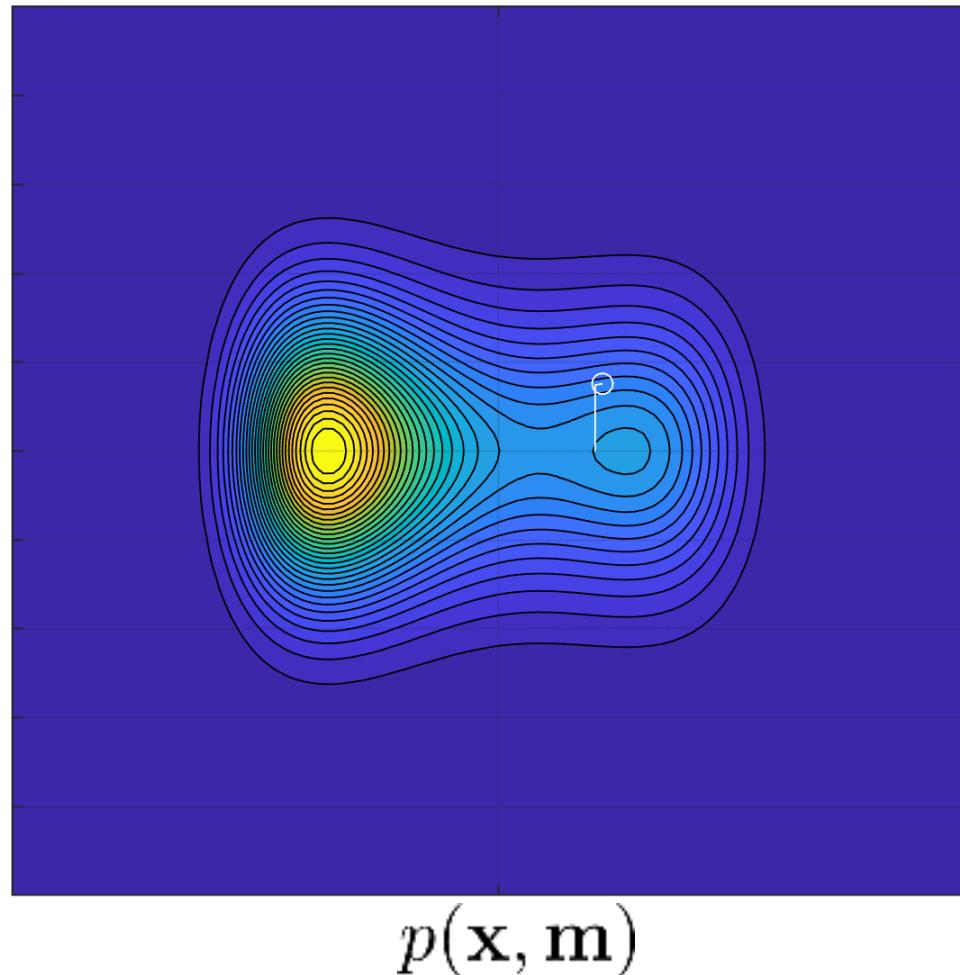
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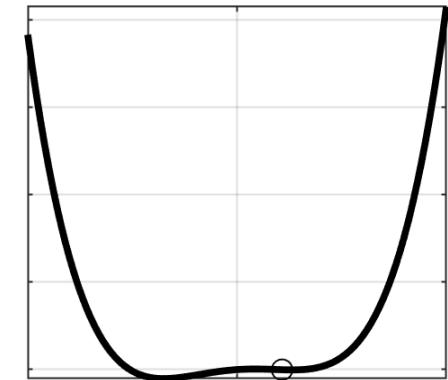
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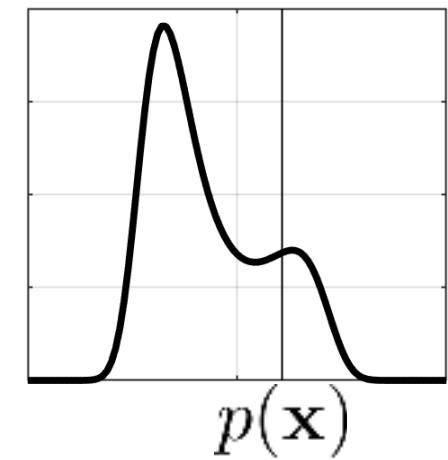
- *Efficiency by using gradient information*
 $\nabla \log p(\mathbf{x})$
- *Cf. optimization*



$p(\mathbf{x}, \mathbf{m})$



$-\log p(\mathbf{x})$

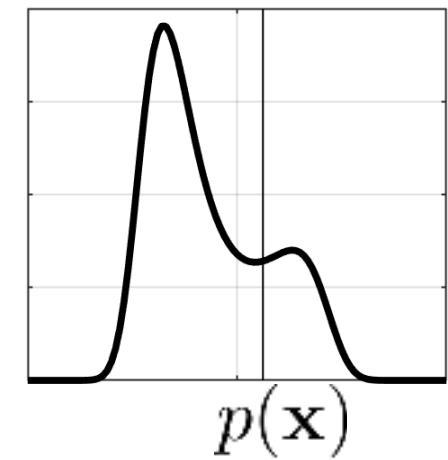
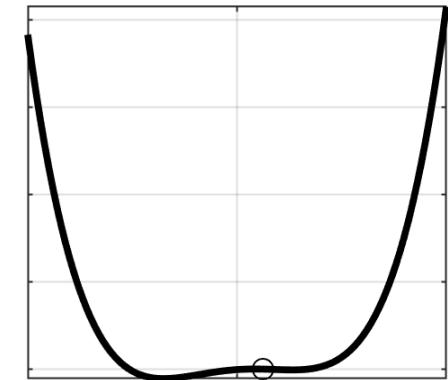
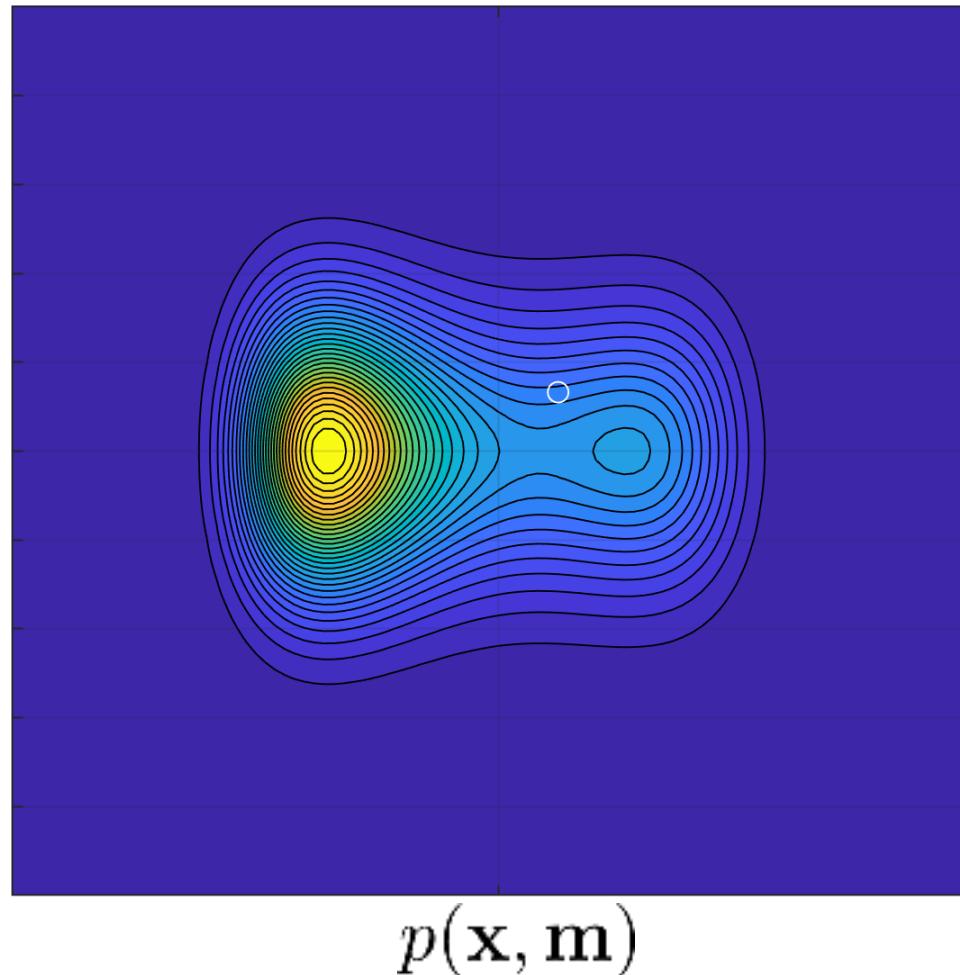


$p(\mathbf{x})$

Hamiltonian Monte Carlo (HMC)

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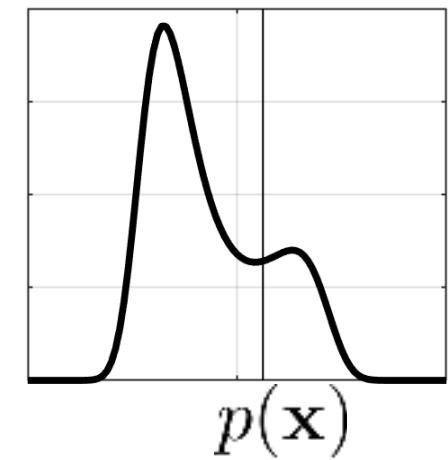
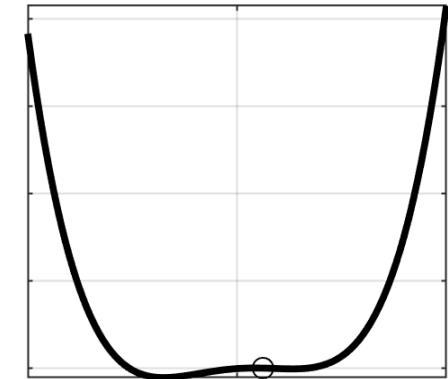
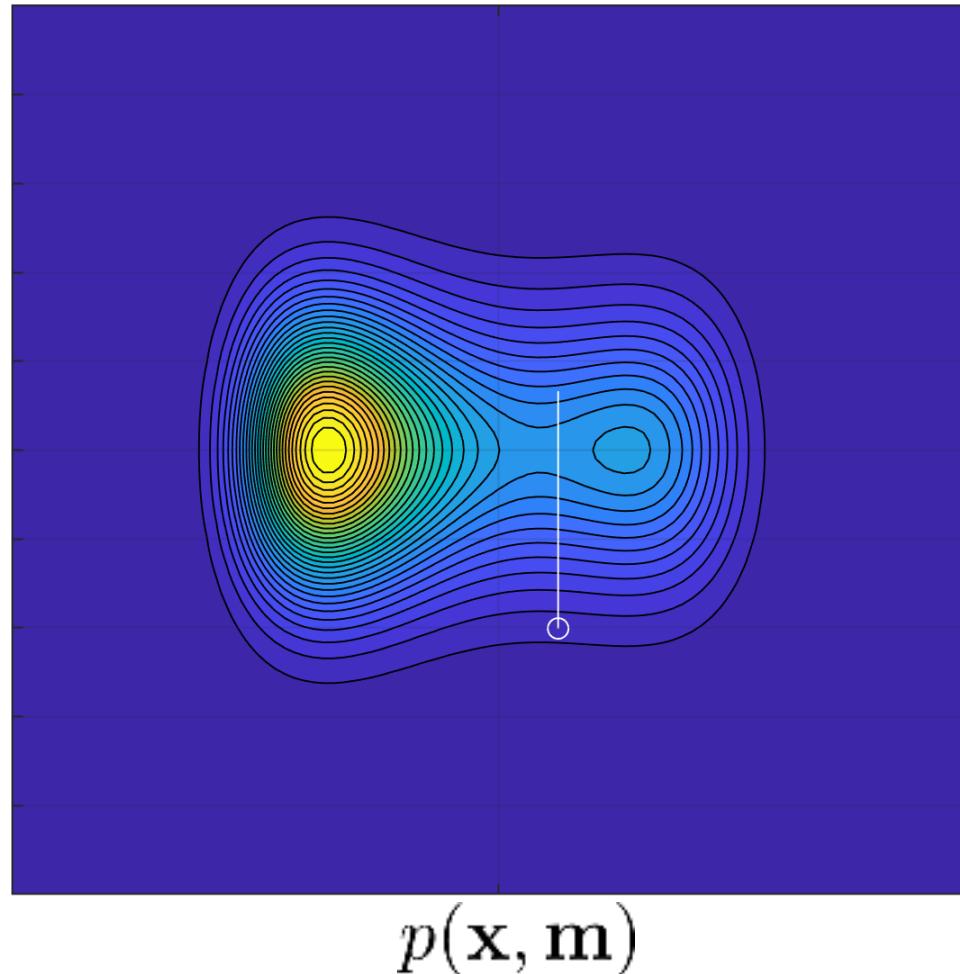
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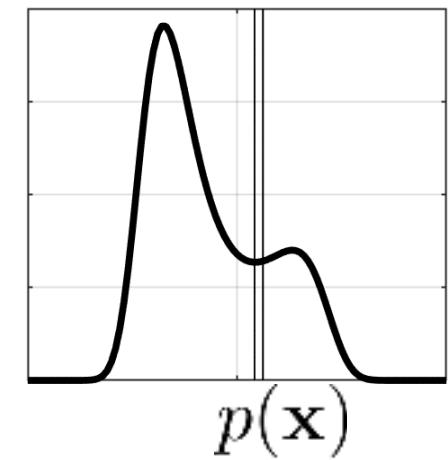
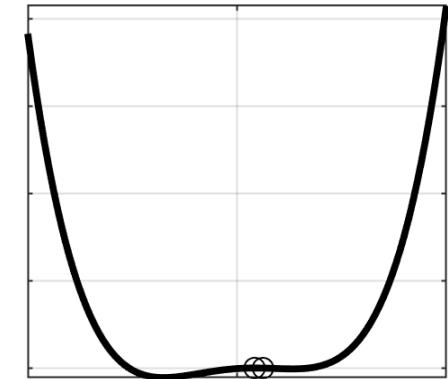
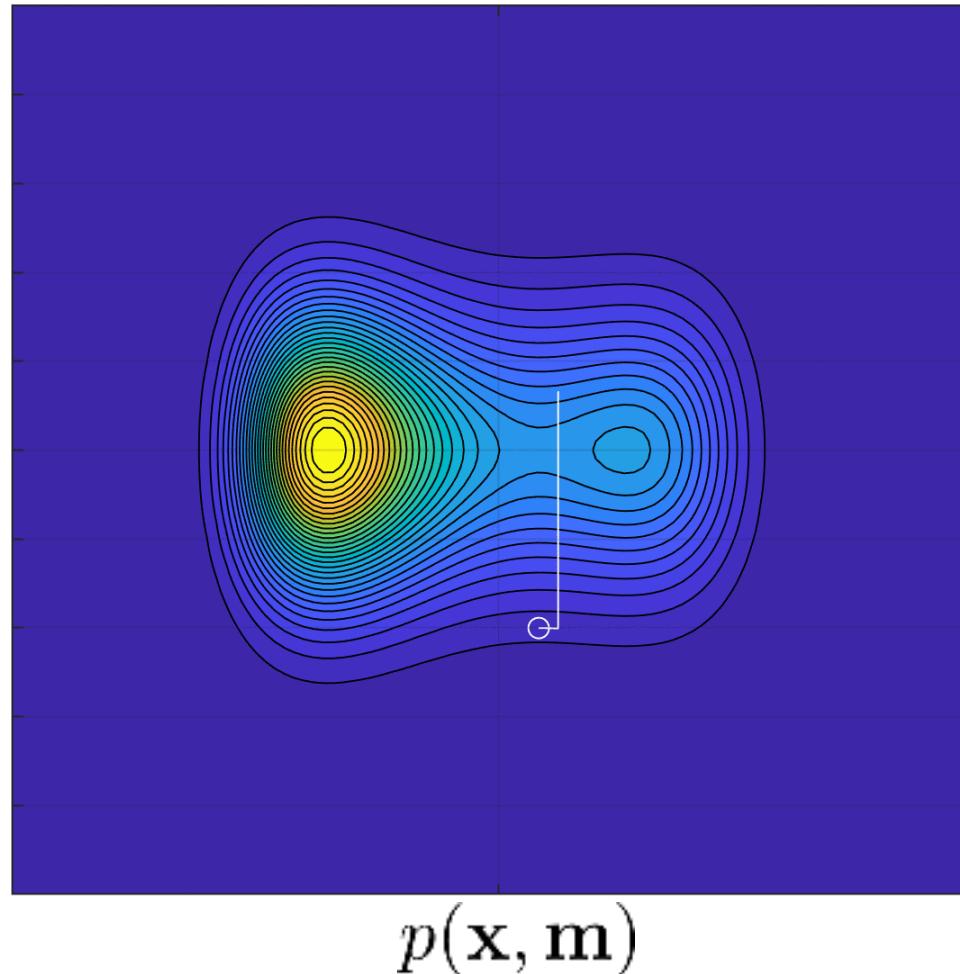
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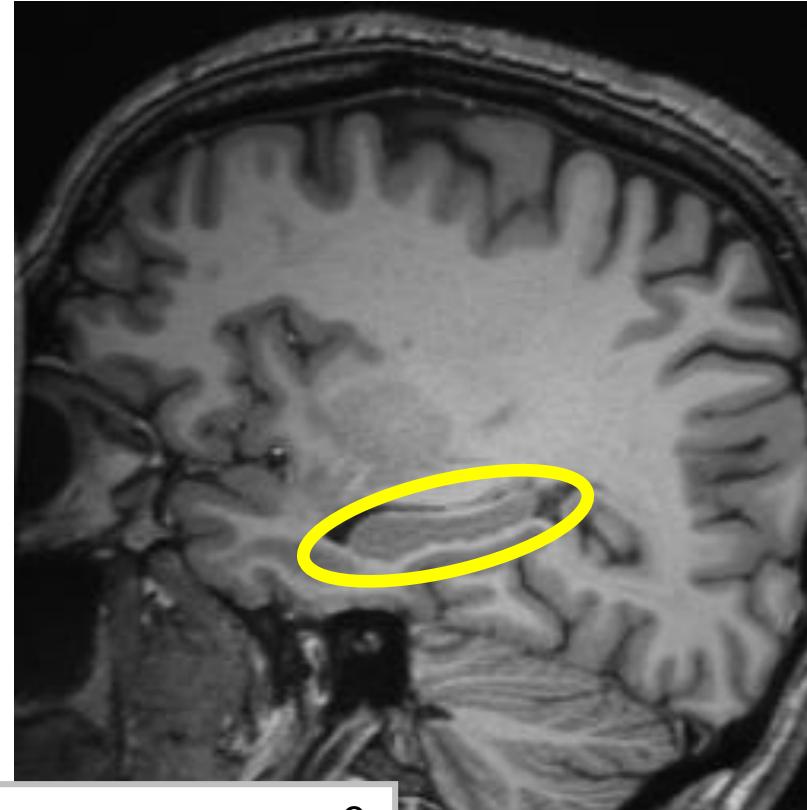
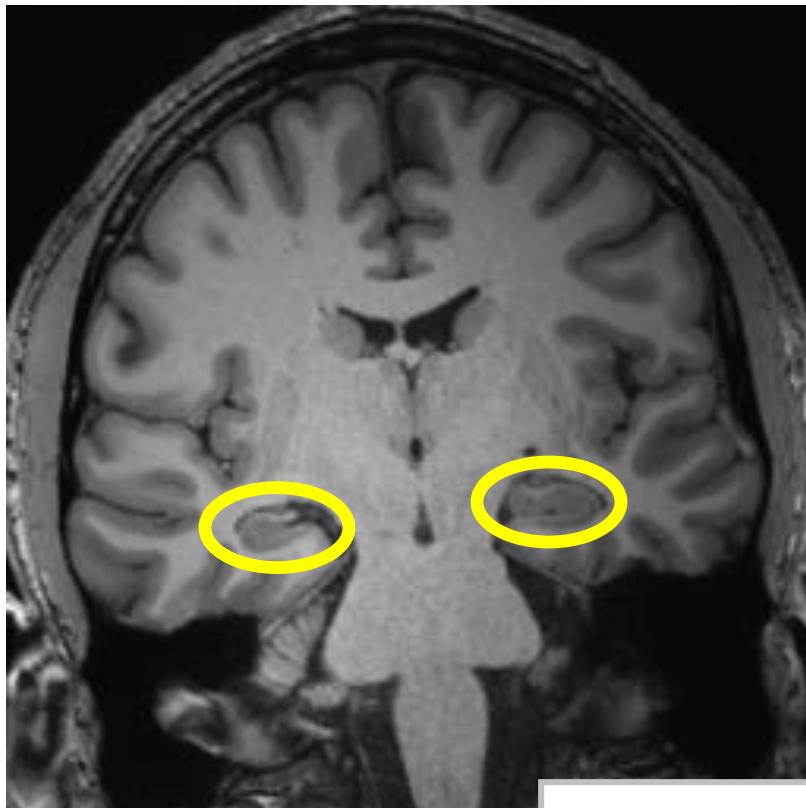
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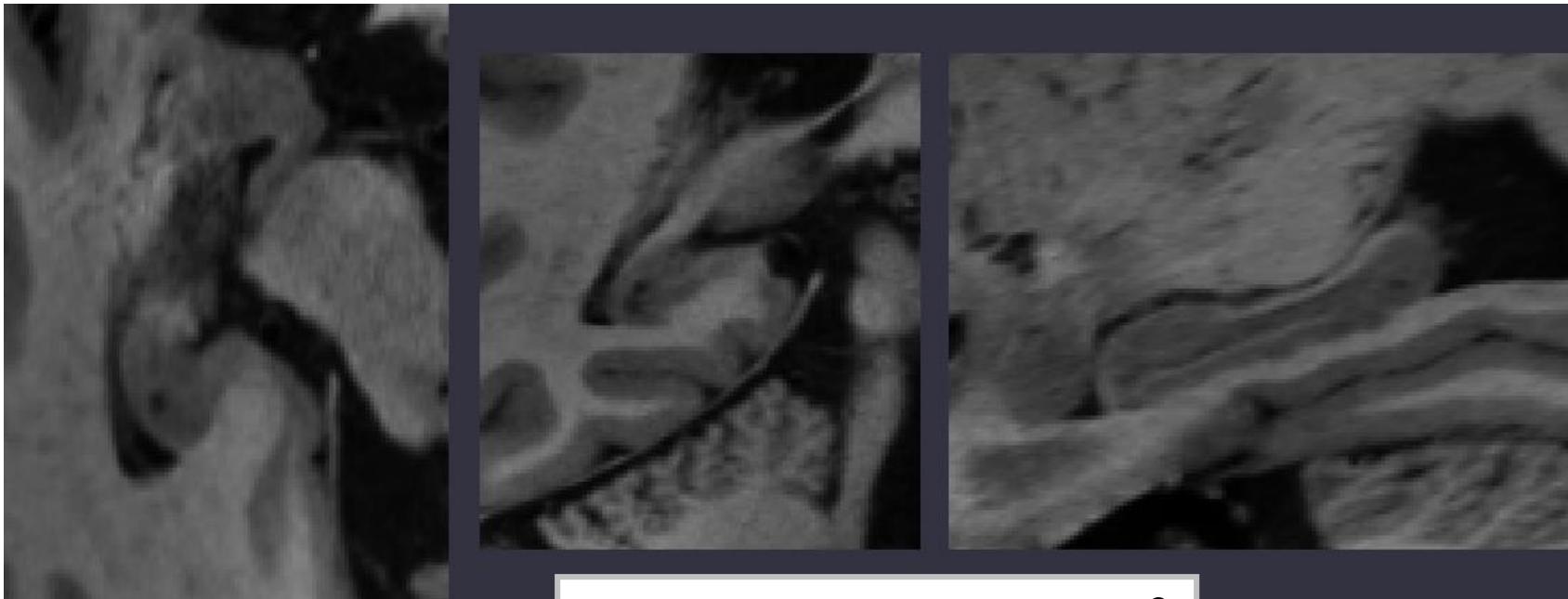


HMC: hippocampal subfield segmentation



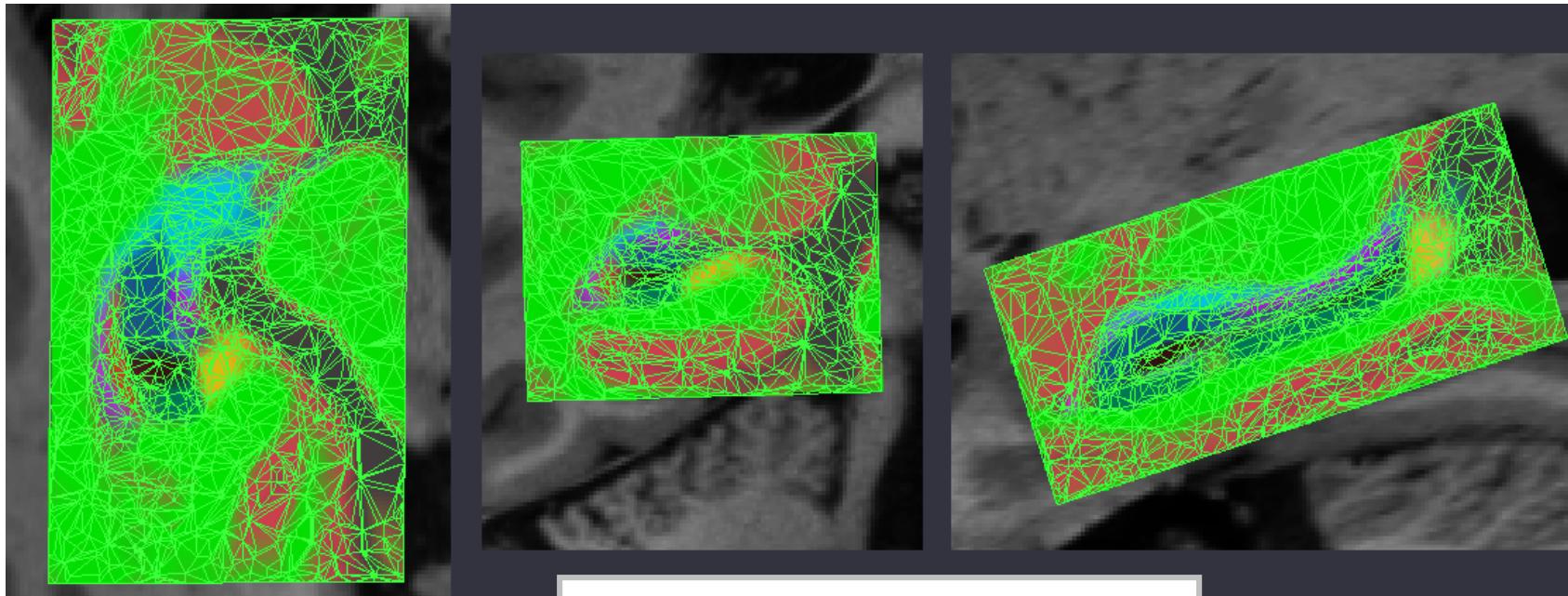
$0.38 \times 0.38 \times 0.8 \text{ mm}^3$

HMC: hippocampal subfield segmentation



$0.38 \times 0.38 \times 0.8 \text{ mm}^3$

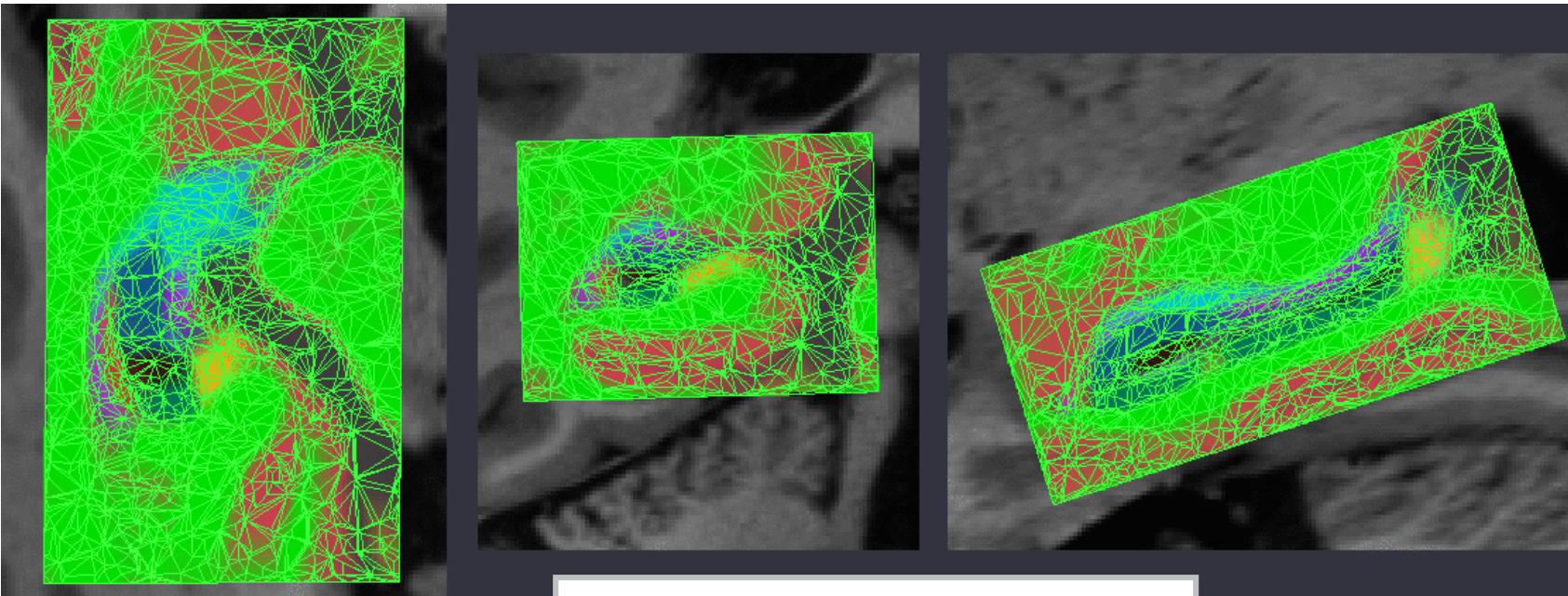
HMC: hippocampal subfield segmentation



$$\hat{\theta} = \arg \max_{\theta} p(\underline{\theta} | \mathbf{d})$$

mesh node positions;
Gaussian means and variances

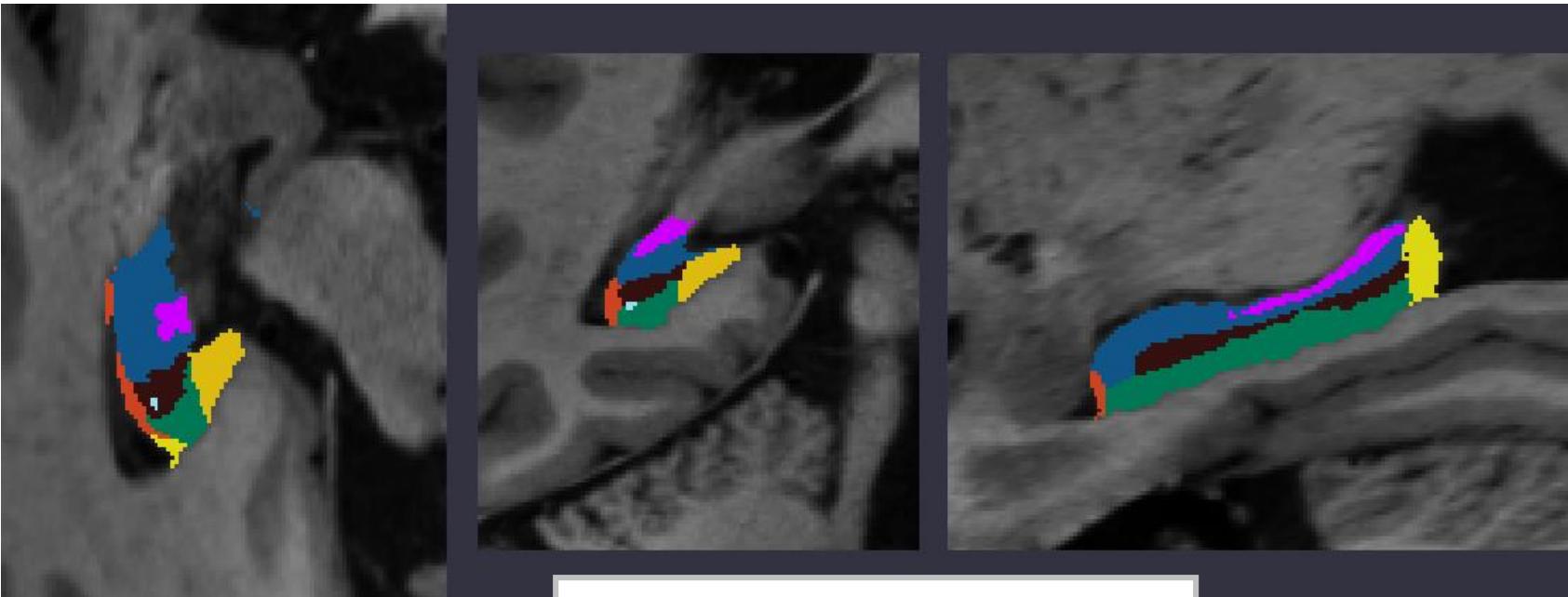
HMC: hippocampal subfield segmentation



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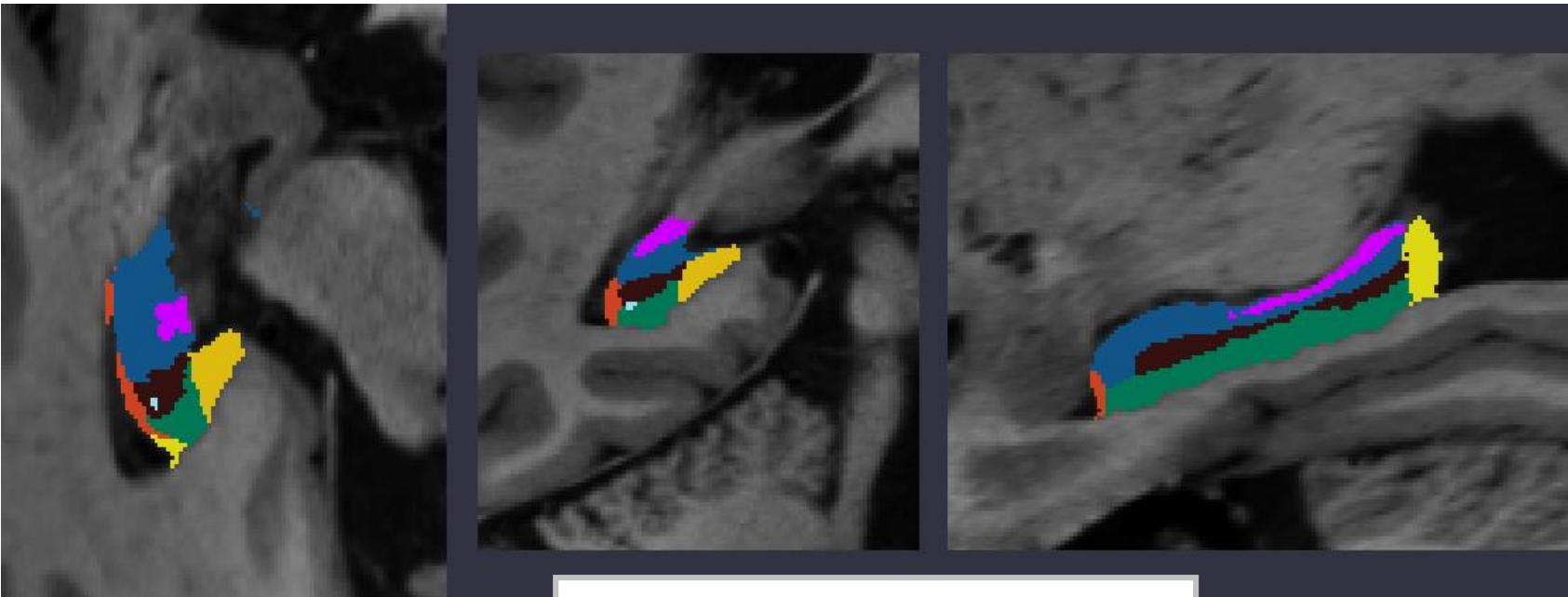
HMC: hippocampal subfield segmentation



$0.38 \times 0.38 \times 0.8 \text{ mm}^3$

$$\hat{\mathbf{l}} = \arg \max_{\mathbf{l}} p(\mathbf{l} | \mathbf{d}, \hat{\theta})$$

HMC: hippocampal subfield segmentation



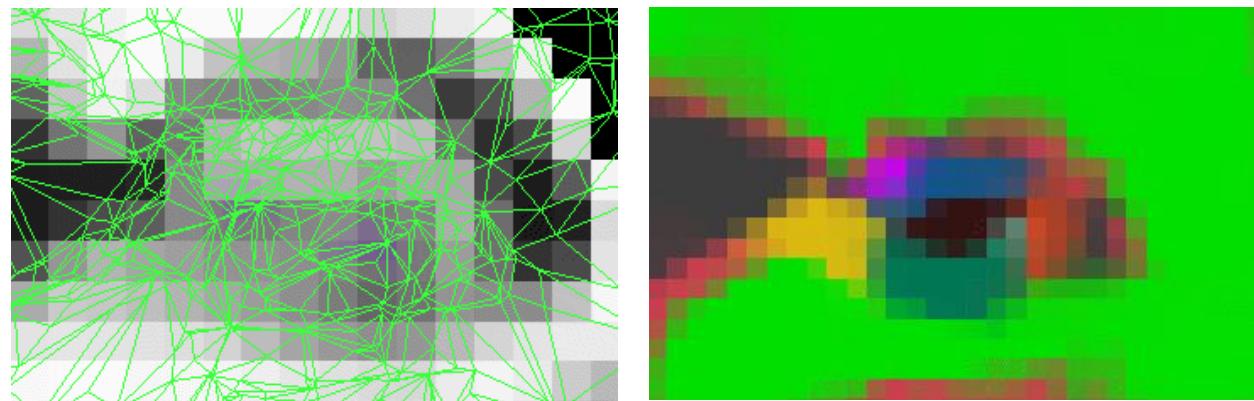
$$\hat{\mathbf{l}} = \arg \max_{\mathbf{l}} p(\mathbf{l}|\mathbf{d}, \hat{\boldsymbol{\theta}})$$



$$p(\mathbf{l}|\mathbf{d}) = \int_{\boldsymbol{\theta}} p(\mathbf{l}, \boldsymbol{\theta}|\mathbf{d}) d\boldsymbol{\theta}$$

HMC: hippocampal subfield segmentation

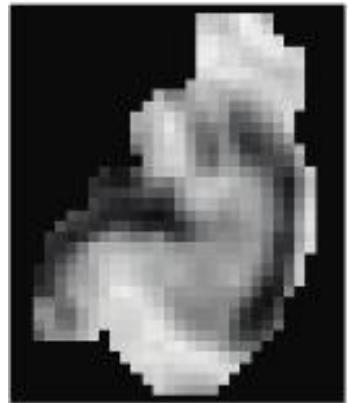
- Sample from $p(\mathbf{l}|\mathbf{d}) = \int_{\boldsymbol{\theta}} p(\mathbf{l}, \boldsymbol{\theta}|\mathbf{d}) d\boldsymbol{\theta}$ by sampling from $p(\mathbf{l}, \boldsymbol{\theta}|\mathbf{d})$
- HMC for atlas deformation; Gibbs sampling for the rest



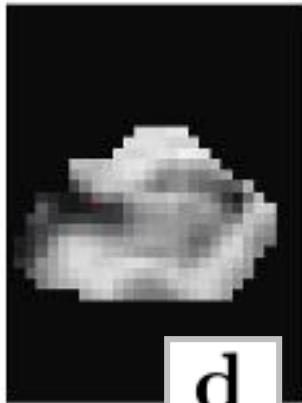
1x1x1 mm³

[Iglesias et al., Medical Image Analysis 2013]

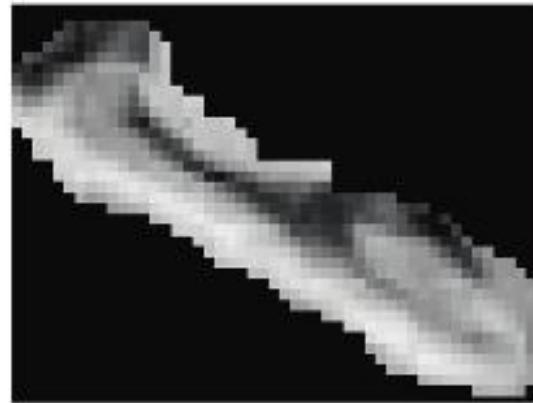
AXIAL



CORONAL



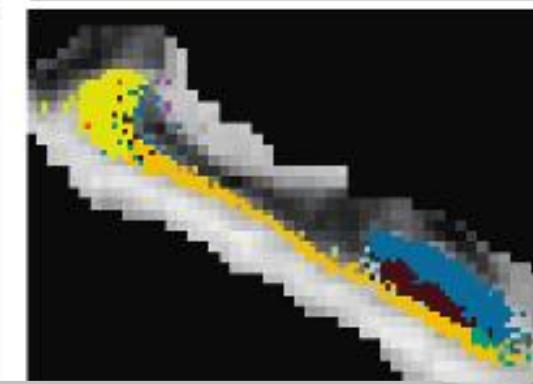
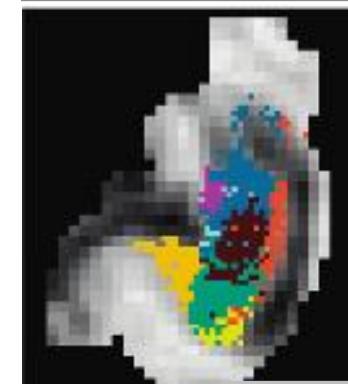
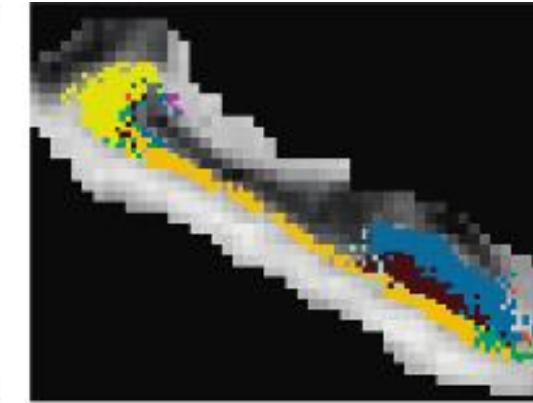
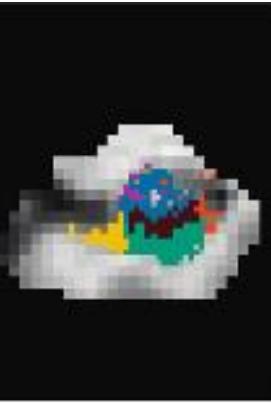
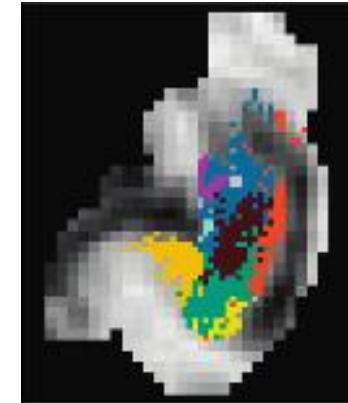
SAGITTAL



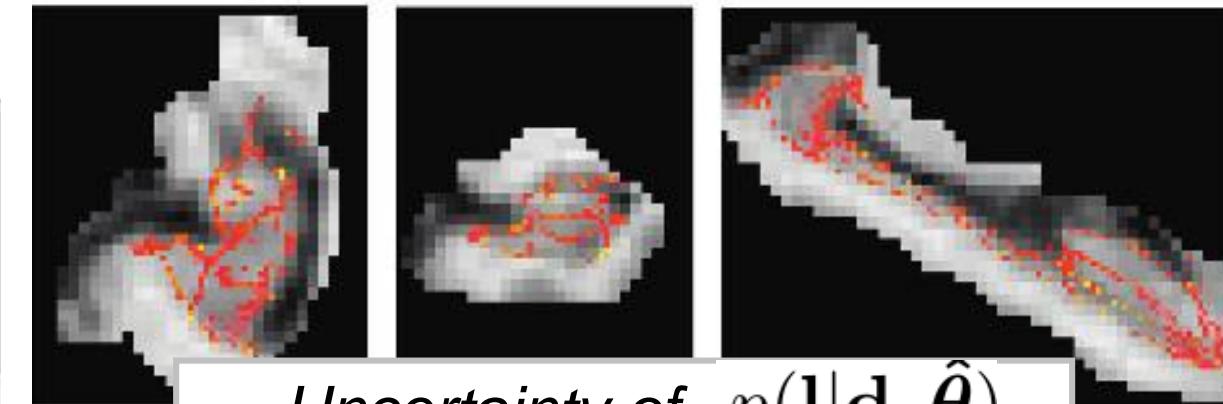
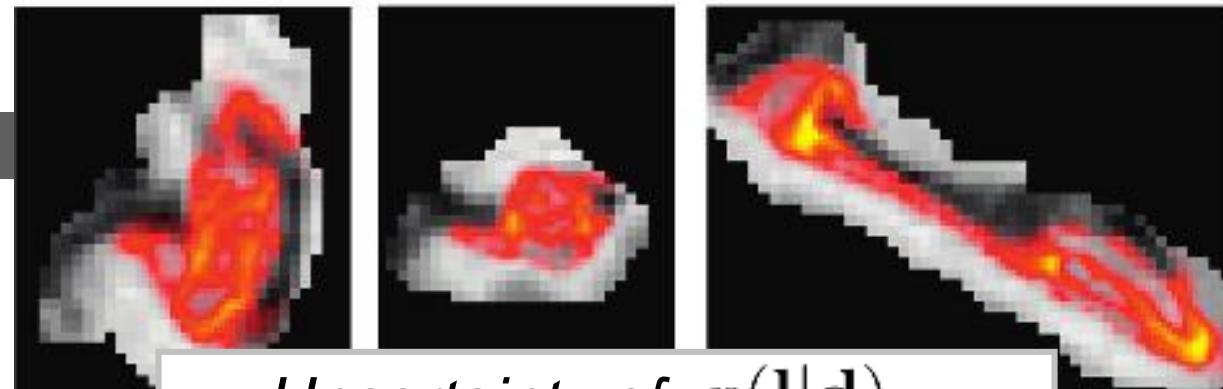
d

Samples from $p(\mathbf{l}|\mathbf{d})$

AXIAL



Uncertainty of $p(\mathbf{l}|\mathbf{d}, \hat{\theta})$



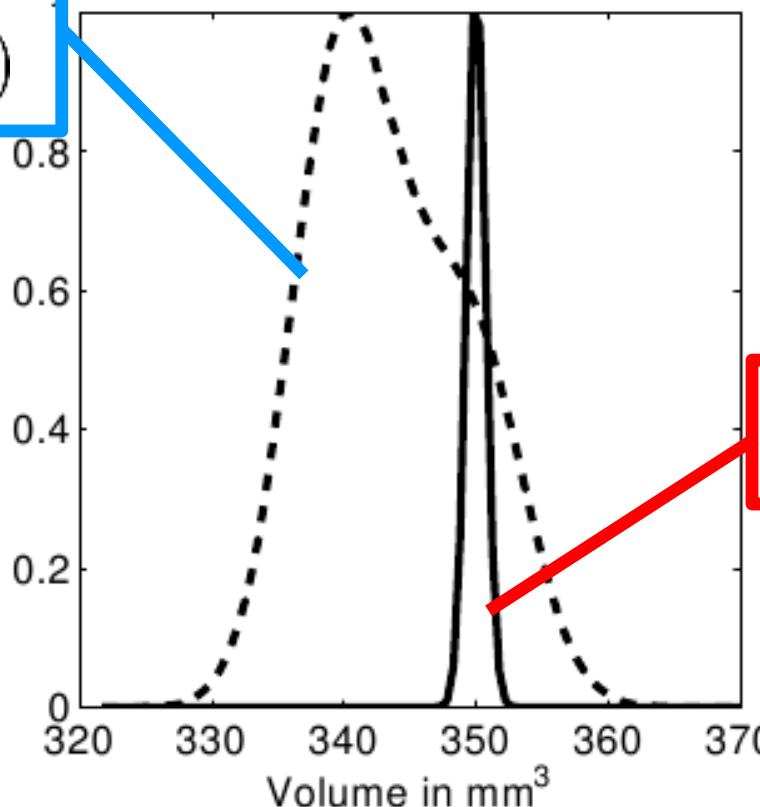
HMC: hippocampal subfield segmentation

Volumes of the subfields:

- Better “error bars”
- 2% boost in classification accuracy AD vs. controls

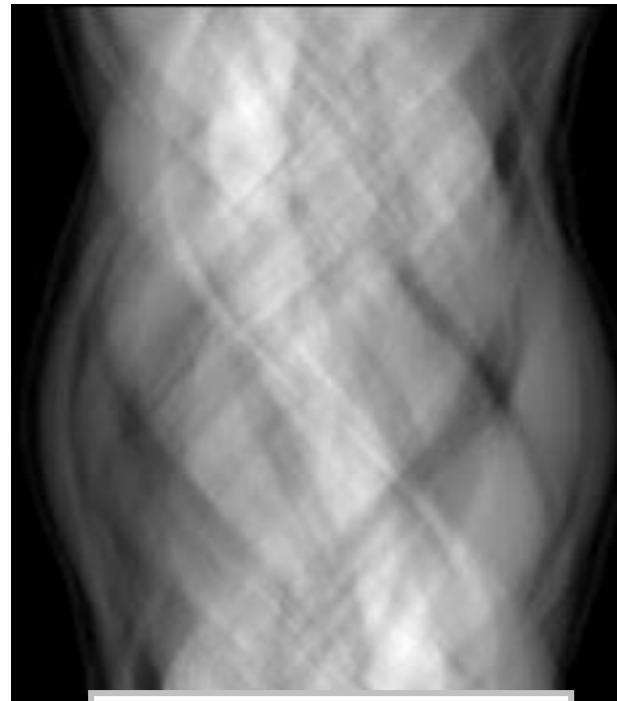
$$p(\text{volume}|\mathbf{d})$$

Distribution of volume of CA1

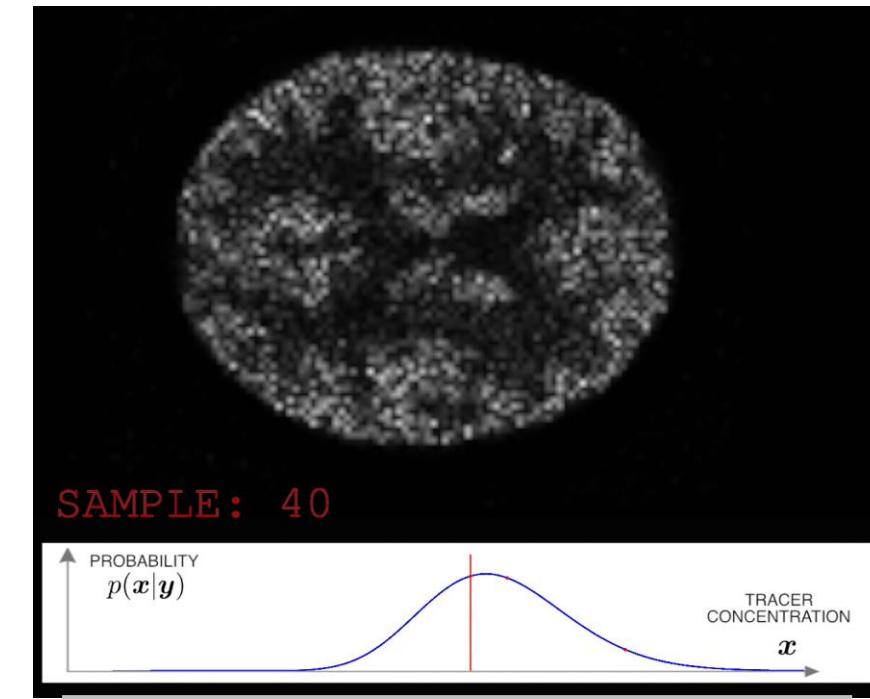


HMC: PET reconstruction

- Reconstruction = inverting a generative model
- HMC: $p(\mathbf{x}, \mathbf{m}) = p(\mathbf{x}) \cdot \mathcal{N}(\mathbf{m} | \mathbf{0}, \Sigma)$



projection data

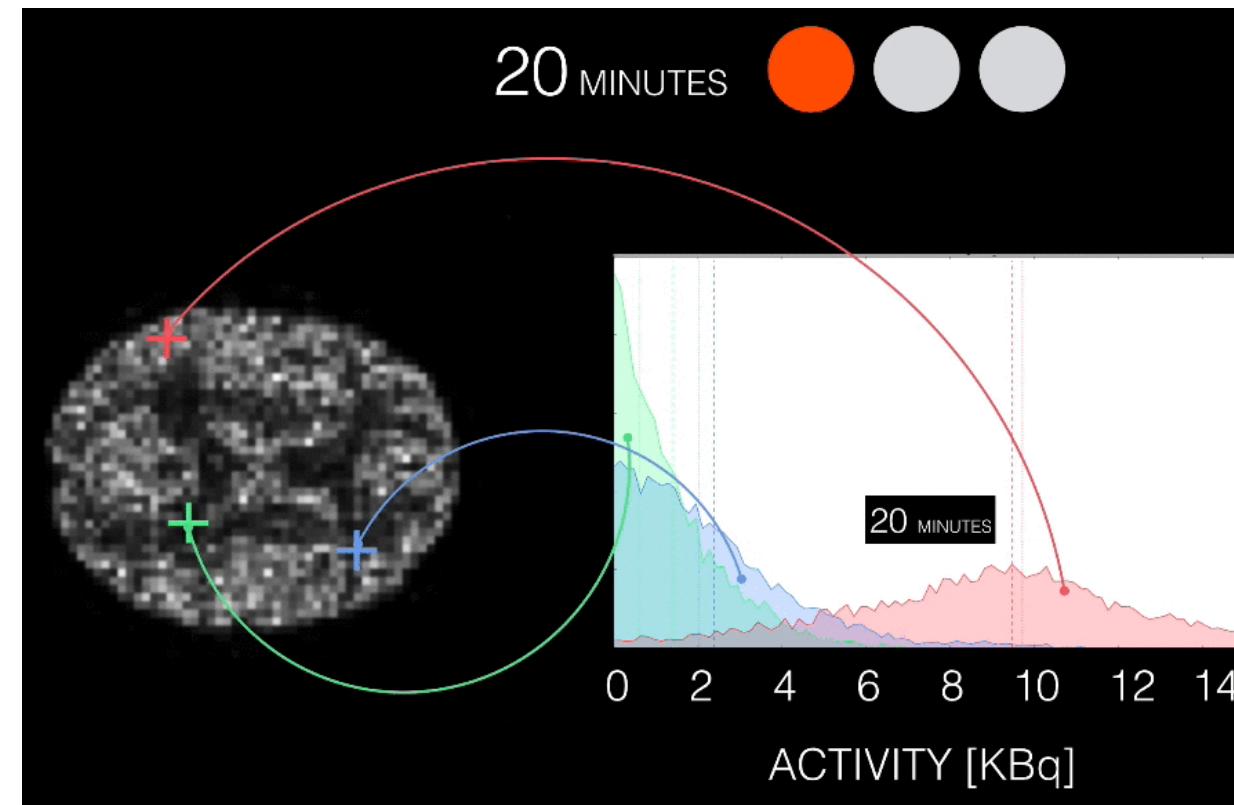


reconstruction samples

HMC: PET reconstruction

- Reconstruction = inverting a generative model
- HMC: $p(\mathbf{x}, \mathbf{m}) = p(\mathbf{x}) \cdot \mathcal{N}(\mathbf{m} | \mathbf{0}, \Sigma)$

chosen “wisely” (using FFTs)



Overview

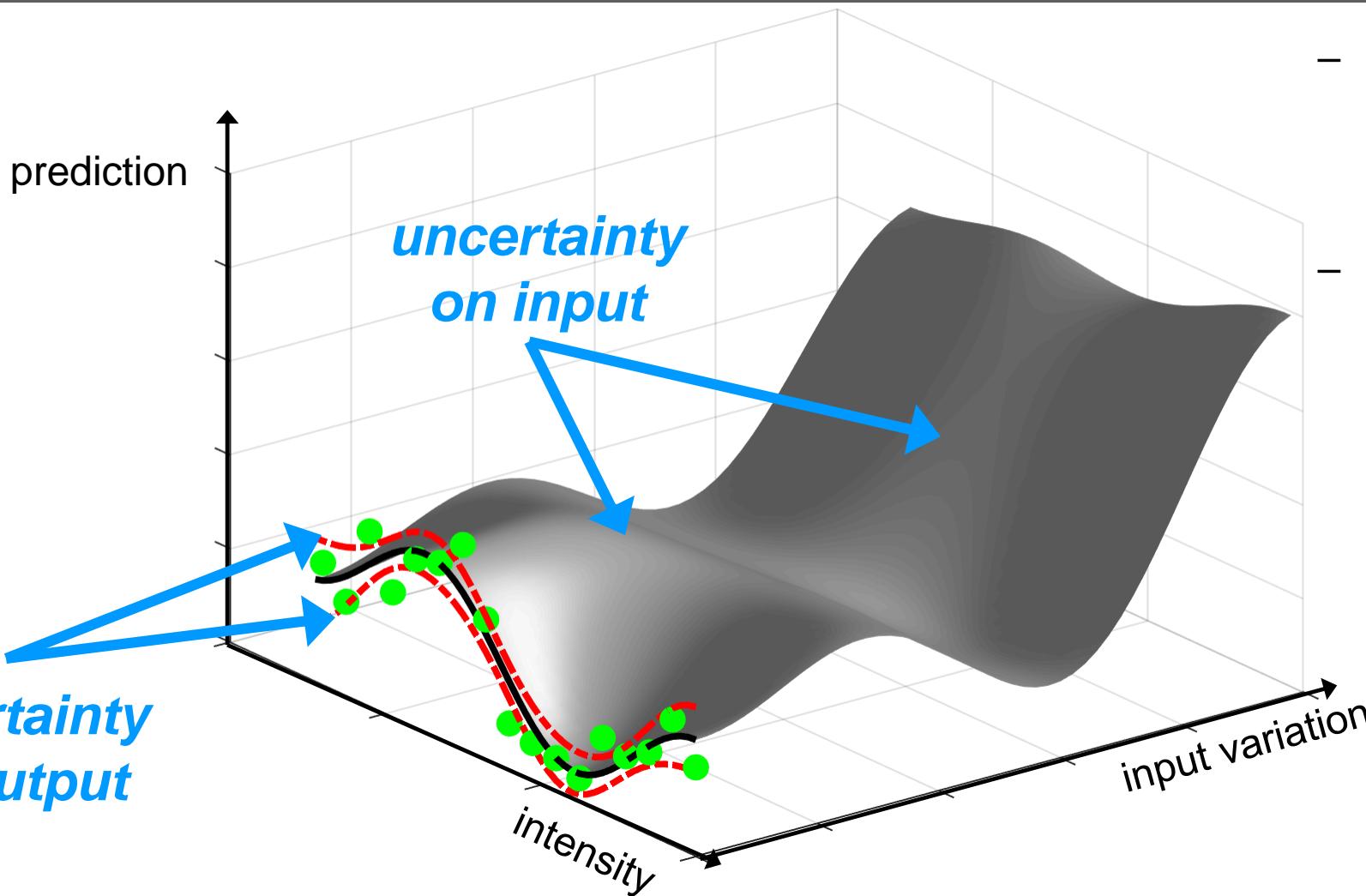


Uncertainty on input using generative models

Uncertainty on output using Monte Carlo sampling

Discussion and conclusion

Discussion and Conclusion



- Generative models *in addition to* discriminative models
- Monte Carlo sampling *in addition to* variational approximations

Main drawback is computational speed, but sometimes it's worth it

Acknowledgements



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We're hiring!
(postdoc in
Boston)



Eugenio Iglesias



Oula Puonti



Mikael Agn



Stefano Pedemonte