

Invariant manifold of your dynamical system

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Throughout and generally: the lowest order, most important, terms are near the end of each expression.

The specified dynamical system

$$\dot{u}_1 = -\varepsilon^2 u_1^2 u_2 - 1/2 u_1 - u_2$$

$$\dot{u}_2 = \varepsilon^2 \epsilon u_2 - \varepsilon u_2^2 - u_1 - 2u_2$$

Invariant subspace basis vectors

$$\vec{e}_1 = \left\{ \{1, 2\}, e^{(-5t/2)} \right\}$$

$$\vec{z}_1 = \left\{ \{1/5, 2/5\}, e^{(-5t/2)} \right\}$$

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The invariant manifold These give the location of the invariant manifold in terms of parameters s_j .

$$u_1 = \varepsilon^3 (53152/140625 e^{-10t} s_1^4 + 88/625 e^{-5t} s_1^2 \epsilon) + \varepsilon^2 (838/1875 e^{(-15t/2)} s_1^3 + 8/25 e^{(-5t/2)} s_1 \epsilon) + 8/25 \varepsilon e^{-5t} s_1^2 + e^{(-5t/2)} s_1$$

$$u_2 = \varepsilon^3(122444/140625 e^{-10t} s_1^4 + 76/625 e^{-5t} s_1^2 \epsilon) + \varepsilon^2(2116/1875 e^{(-15t/2)} s_1^3 - 4/25 e^{(-5t/2)} s_1 \epsilon) + 36/25 \varepsilon e^{-5t} s_1^2 + 2 e^{(-5t/2)} s_1$$

Invariant manifold ODEs The system evolves on the invariant manifold such that the parameters evolve according to these ODEs.

$$\dot{s}_1 = -8/125 \varepsilon^4 s_1 \epsilon^2 + 4/5 \varepsilon^2 s_1 \epsilon$$