

# Centre manifold of your dynamical system

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Throughout and generally: the lowest order, most important, terms are near the end of each expression.

## The specified dynamical system

$$\dot{u}_1 = \varepsilon u_2 u_3$$

$$\dot{u}_2 = \varepsilon u_1 u_3 - u_1 u_4$$

$$\dot{u}_3 = 0$$

$$\dot{u}_4 = u_5$$

$$\dot{u}_5 = -u_4$$

## Centre subspace basis vectors

$$\vec{e}_1 = \{ \{1, 0, 0, 0, 0\}, e^{0i} \}$$

$$\vec{e}_2 = \{ \{0, 1, 0, 0, 0\}, e^{0i} \}$$

$$\vec{e}_3 = \{ \{0, 0, 1, 0, 0\}, e^{0i} \}$$

$$\vec{e}_4 = \{ \{0, 0, 0, 1, i\}, e^{ti} \}$$

$$\vec{e}_5 = \{ \{0, 0, 0, 1, -i\}, e^{-ti} \}$$

$$\vec{z}_1 = \{ \{1, 0, 0, 0, 0\}, e^{0i} \}$$

$$\vec{z}_2 = \{ \{0, 1, 0, 0, 0\}, e^{0i} \}$$

$$\vec{z}_3 = \{\{0, 0, 1, 0, 0\}, e^{0i}\}$$

$$\vec{z}_4 = \{\{0, 0, 0, 1/2, 1/2i\}, e^{ti}\}$$

$$\vec{z}_5 = \{\{0, 0, 0, 1/2, -1/2i\}, e^{-ti}\}$$

**The centre manifold** These give the location of the centre manifold in terms of parameters  $s_j$ .

$$\begin{aligned} u_1 = & s_3^3 \varepsilon^3 (1/36 e^{-3ti} s_5^3 s_1 - 3/4 e^{-2ti} s_5^2 s_2 i + 25/4 e^{-ti} s_5^2 s_4 s_1 - 4 e^{-ti} s_5 s_1 + \\ & 1/36 e^{3ti} s_4^3 s_1 + 3/4 e^{2ti} s_4^2 s_2 i + 25/4 e^{ti} s_5 s_4^2 s_1 - 4 e^{ti} s_4 s_1) + \\ & s_3^2 \varepsilon^2 (1/4 e^{-2ti} s_5^2 s_1 - 2 e^{-ti} s_5 s_2 i + 1/4 e^{2ti} s_4^2 s_1 + 2 e^{ti} s_4 s_2 i) + \\ & s_3 \varepsilon (e^{-ti} s_5 s_1 + e^{ti} s_4 s_1) + s_1 \end{aligned}$$

$$\begin{aligned} u_2 = & s_3^3 \varepsilon^3 (-1/144 e^{-4ti} s_5^4 s_1 i - 5/18 e^{-3ti} s_5^3 s_2 - 79/18 e^{-2ti} s_5^3 s_4 s_1 i + \\ & 11/4 e^{-2ti} s_5^2 s_1 i - 3 e^{-ti} s_5^2 s_4 s_2 + 4 e^{-ti} s_5 s_2 + 1/144 e^{4ti} s_4^4 s_1 i - \\ & 5/18 e^{3ti} s_4^3 s_2 + 79/18 e^{2ti} s_5 s_4^3 s_1 i - 11/4 e^{2ti} s_4^2 s_1 i - 3 e^{ti} s_5 s_4^2 s_2 + 4 e^{ti} s_4 s_2) + \\ & s_3^2 \varepsilon^2 (-1/12 e^{-3ti} s_5^3 s_1 i - 5/4 e^{-2ti} s_5^2 s_2 - 9/4 e^{-ti} s_5^2 s_4 s_1 i + 2 e^{-ti} s_5 s_1 i + \\ & 1/12 e^{3ti} s_4^3 s_1 i - 5/4 e^{2ti} s_4^2 s_2 + 9/4 e^{ti} s_5 s_4^2 s_1 i - 2 e^{ti} s_4 s_1 i) + s_3 \varepsilon (- \\ & 1/2 e^{-2ti} s_5^2 s_1 i - e^{-ti} s_5 s_2 + 1/2 e^{2ti} s_4^2 s_1 i - e^{ti} s_4 s_2) - e^{-ti} s_5 s_1 i + e^{ti} s_4 s_1 i + s_2 \end{aligned}$$

$$u_3 = s_3$$

$$u_4 = e^{-ti} s_5 + e^{ti} s_4$$

$$u_5 = -e^{-ti} s_5 i + e^{ti} s_4 i$$

**Centre manifold ODEs** The system evolves on the centre manifold such that the parameters evolve according to these ODEs.

$$\dot{s}_1 = s_3 \varepsilon s_2$$

$$\dot{s}_2 = s_3^3 \varepsilon^3 (-25/2 s_5^2 s_4^2 s_1 + 8 s_5 s_4 s_1) + s_3 \varepsilon (-2 s_5 s_4 s_1 + s_1)$$

$$\dot{s}_3 = 0$$

$$\dot{s}_4 = 0$$

$$\dot{s}_5 = 0$$