

# Normal form of your dynamical system

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## Specified dynamical system

$$\dot{x}_1 = s\sigma(-1/2w_2 - 1/2w_1) + \sigma w_1 + \varepsilon(-x_1y_2 - 2x_1y_1)$$

$$\dot{x}_2 = 0$$

$$\dot{y}_1 = s\varepsilon(-x_2y_2 - x_2y_1 - x_2) + \sigma(-w_3 + 1/2w_2 + 1/2w_1) + \varepsilon(-x_2x_1 - y_2^2 - 3y_2y_1 - 2y_1^2) - 2y_1$$

$$\dot{y}_2 = s\varepsilon(x_2y_2 + x_2y_1 + x_2) + \sigma w_3 + \varepsilon x_2x_1 - y_2$$

## Time dependent coordinate transform

$$\begin{aligned} y_1 = & -1/2X_2X_1\varepsilon + X_2s\sigma\varepsilon(e^{-2t}\star e^{-2t}\star w_3 - 1/2e^{-2t}\star e^{-2t}\star w_2 - \\ & 1/2e^{-2t}\star e^{-2t}\star w_1 - e^{-1t}\star w_3 + e^{-2t}\star w_3 - 1/4e^{-2t}\star w_2 - 1/4e^{-2t}\star w_1) + \\ & X_2s\varepsilon(-Y_2 - 1/2) + 1/2X_2\sigma\varepsilon e^{-2t}\star w_1 + \sigma\varepsilon(-2e^{-1t}\star e^{-1t}\star w_3 Y_2 + \\ & 3e^{-1t}\star w_3 Y_2 + 3e^{-1t}\star w_3 Y_1 - 3e^{-2t}\star w_3 Y_2 - 2e^{-2t}\star w_3 Y_1 - 3/2e^{-1t}\star w_2 Y_2 + \\ & 3/2e^{-2t}\star w_2 Y_2 + e^{-2t}\star w_2 Y_1 - 3/2e^{-1t}\star w_1 Y_2 + 3/2e^{-2t}\star w_1 Y_2 + \\ & e^{-2t}\star w_1 Y_1) + \sigma(-e^{-2t}\star w_3 + 1/2e^{-2t}\star w_2 + 1/2e^{-2t}\star w_1) + \varepsilon(3Y_2Y_1 + Y_1^2) + Y_1 \end{aligned}$$

$$\begin{aligned} y_2 = & X_2X_1\varepsilon + X_2s\sigma\varepsilon(e^{-1t}\star e^{-1t}\star w_3 - e^{-1t}\star w_3 + e^{-2t}\star w_3 + e^{-1t}\star w_2 - \\ & 1/2e^{-2t}\star w_2 + e^{-1t}\star w_1 - 1/2e^{-2t}\star w_1) + X_2s\varepsilon(-Y_1 + 1) - \\ & X_2\sigma\varepsilon e^{-1t}\star w_1 + \sigma e^{-1t}\star w_3 + Y_2 \end{aligned}$$

$$x_1 = X_1 \sigma \varepsilon (e^{-1t} \star w_3 - e^{-2t} \star w_3 + 1/2 e^{-2t} \star w_2 + 1/2 e^{-2t} \star w_1) + X_1 \varepsilon (Y_2 + Y_1) + X_1 + s \sigma \varepsilon (-1/2 e^{2t} \star w_2 Y_1 - 1/2 e^t \star w_2 Y_2 - 1/2 e^{2t} \star w_1 Y_1 - 1/2 e^{1t} \star w_1 Y_2) + \sigma \varepsilon (e^{2t} \star w_1 Y_1 + e^t \star w_1 Y_2)$$

$$x_2 = X_2$$

## Result normal form DEs

$$\begin{aligned} \dot{Y}_1 = & X_2^2 s^2 \varepsilon^2 Y_1 - 2X_2 X_1 \varepsilon^2 Y_1 + X_2 s \sigma \varepsilon^2 (-1/4 w_2 Y_1 - 1/4 w_1 Y_1) + \\ & X_2 s \varepsilon^2 (3Y_2^2 - Y_1) - X_2 s \varepsilon Y_1 + 3/2 X_2 \sigma \varepsilon^2 w_1 Y_1 + \sigma^2 \varepsilon^2 (e^{-1t} \star w_3 w_2 Y_1 + \\ & e^{-1t} \star w_3 w_1 Y_1 - e^{-2t} \star w_3 w_2 Y_1 - e^{-2t} \star w_3 w_1 Y_1 + 1/2 e^{-2t} \star w_2 w_2 Y_1 + \\ & 1/2 e^{-2t} \star w_2 w_1 Y_1 + 1/2 e^{-2t} \star w_1 w_2 Y_1 + 1/2 e^{-2t} \star w_1 w_1 Y_1) + \sigma \varepsilon^2 (7/2 w_3 Y_2^2 + \\ & 11/4 w_2 Y_2^2 + 11/4 w_1 Y_2^2) + \sigma \varepsilon (-w_3 Y_1 - w_2 Y_1 - w_1 Y_1) - \varepsilon Y_2^2 - 2Y_1 \end{aligned}$$

$$\begin{aligned} \dot{Y}_2 = & -X_2^2 s^2 \varepsilon^2 Y_2 + X_2 X_1 \varepsilon^2 Y_2 + X_2 s \sigma \varepsilon^2 (-1/2 w_3 Y_2 - 5/4 w_2 Y_2 - \\ & 5/4 w_1 Y_2) + X_2 s \varepsilon Y_2 + X_2 \sigma \varepsilon^2 w_1 Y_2 - Y_2 \end{aligned}$$

$$\begin{aligned} \dot{X}_1 = & X_2 X_1 s \sigma \varepsilon^2 (-1/4 w_2 - 1/4 w_1) + 1/2 X_2 X_1 \sigma \varepsilon^2 w_1 + \\ & X_2 s^2 \sigma^2 \varepsilon^2 (1/2 e^{-1t} \star e^{-1t} \star w_3 w_2 + 1/2 e^{-1t} \star e^{-1t} \star w_3 w_1 + \\ & 1/2 e^{-2t} \star e^{-2t} \star w_3 w_2 + 1/2 e^{-2t} \star e^{-2t} \star w_3 w_1 - 1/4 e^{-2t} \star e^{-2t} \star w_2 w_2 - \\ & 1/4 e^{-2t} \star e^{-2t} \star w_2 w_1 - 1/4 e^{-2t} \star e^{-2t} \star w_1 w_2 - 1/4 e^{-2t} \star e^{-2t} \star w_1 w_1 - \\ & e^{-1t} \star w_3 w_2 - e^{-1t} \star w_3 w_1 + e^{-2t} \star w_3 w_2 + e^{-2t} \star w_3 w_1 + 1/2 e^{-1t} \star w_2 w_2 + \\ & 1/2 e^{-1t} \star w_2 w_1 - 3/8 e^{-2t} \star w_2 w_2 - 3/8 e^{-2t} \star w_2 w_1 + 1/2 e^{-1t} \star w_1 w_2 + \\ & 1/2 e^{-1t} \star w_1 w_1 - 3/8 e^{-2t} \star w_1 w_2 - 3/8 e^{-2t} \star w_1 w_1) + X_2 s \sigma^2 \varepsilon^2 (- \\ & e^{-1t} \star e^{-1t} \star w_3 w_1 - e^{-2t} \star e^{-2t} \star w_3 w_1 + 1/2 e^{-2t} \star e^{-2t} \star w_2 w_1 + \\ & 1/2 e^{-2t} \star e^{-2t} \star w_1 w_1 + 2e^{-1t} \star w_3 w_1 - 2e^{-2t} \star w_3 w_1 - e^{-1t} \star w_2 w_1 + \\ & 3/4 e^{-2t} \star w_2 w_1 - 1/2 e^{-1t} \star w_1 w_2 - 3/2 e^{-1t} \star w_1 w_1 + 1/4 e^{-2t} \star w_1 w_2 + \\ & e^{-2t} \star w_1 w_1) + X_2 \sigma^2 \varepsilon^2 (e^{-1t} \star w_1 w_1 - 1/2 e^{-2t} \star w_1 w_1) + \\ & X_1 \sigma^2 \varepsilon^2 (1/2 e^{-1t} \star w_3 w_2 + 1/2 e^{-1t} \star w_3 w_1 - 1/2 e^{-2t} \star w_3 w_2 - \\ & 1/2 e^{-2t} \star w_3 w_1 + 1/4 e^{-2t} \star w_2 w_2 + 1/4 e^{-2t} \star w_2 w_1 + 1/4 e^{-2t} \star w_1 w_2 + \\ & 1/4 e^{-2t} \star w_1 w_1) + X_1 \sigma \varepsilon (-1/2 w_2 - 1/2 w_1) + s \sigma^2 \varepsilon (1/2 e^{-1t} \star w_3 w_2 + \\ & 1/2 e^{-1t} \star w_3 w_1 - 1/2 e^{-2t} \star w_3 w_2 - 1/2 e^{-2t} \star w_3 w_1 + 1/4 e^{-2t} \star w_2 w_2 + \\ & 1/4 e^{-2t} \star w_2 w_1 + 1/4 e^{-2t} \star w_1 w_2 + 1/4 e^{-2t} \star w_1 w_1) + s \sigma (-1/2 w_2 - 1/2 w_1) + \\ & \sigma^2 \varepsilon (-e^{-1t} \star w_3 w_1 + e^{-2t} \star w_3 w_1 - 1/2 e^{-2t} \star w_2 w_1 - 1/2 e^{-2t} \star w_1 w_1) + \sigma w_1 \end{aligned}$$

$$\dot{X}_2 = 0$$