Centre manifold of your dynamical system

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3:20 P.M., November 15, 2017

Throughout and generally: the lowest order, most important, terms are near the end of each expression.

The specified dynamical system

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\begin{split} \dot{u}_1 &= \varepsilon (-\beta^{-1} u_3^2 + u_2 u_3) + \beta u_3 - u_1 - u_3 \\ \dot{u}_2 &= \varepsilon^2 u_3 \\ \dot{u}_3 &= \varepsilon^2 u_1 \end{split} \qquad \begin{array}{l} \text{ff}_:=\text{tp mat}((\text{u}2*\text{u}3-\text{u}3^2/\text{beta-}(1-\text{beta})*\text{u}3-\text{u}1\\,\text{small*u}3\\,\text{small*u}1\ ));\\ \text{freqm}_:=\text{mat}((0,0));\\ \text{ee}_:=\text{tp mat}((0,1,0),(-1+\text{beta},0,1));\\ \text{zz}_:=\text{tp mat}((0,1,0),(0,0,1)); \\ \text{toosmall}:=5; \end{split}
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Centre subspace basis vectors

$$\vec{e}_1 = \{\{0, 1, 0\}, e^{0i}\}$$

$$\vec{e}_2 = \{\{\beta - 1, 0, 1\}, e^{0i}\}$$

$$\vec{z}_1 = \{\{0, 1, 0\}, e^{0i}\}$$

$$\vec{z}_2 = \{\{0, 0, 1\}, e^{0i}\}$$

The centre manifold These give the location of the centre manifold in terms of parameters s_i .

$$\begin{split} u_1 &= \varepsilon^3 (-3s_2^2\beta^{-1} + 2s_2^2 - 2s_2s_1\beta + 2s_2s_1) + \varepsilon^2 (-s_2\beta^2 + 2s_2\beta - s_2) + \\ \varepsilon (-s_2^2\beta^{-1} + s_2s_1) + s_2\beta - s_2 & \text{Got much of (32)} \\ u_2 &= s_1 \\ u_3 &= s_2 \end{split}$$

Centre manifold ODEs The system evolves on the centre manifold such that the parameters evolve according to these ODEs.

$$\dot{s}_1 = \varepsilon^2 s_2$$

$$\dot{s}_2 = \varepsilon^4 (-s_2 \beta^2 + 2s_2 \beta - s_2) + \varepsilon^3 (-s_2^2 \beta^{-1} + s_2 s_1) + \varepsilon^2 (s_2 \beta - s_2)$$
Half of (33)

Normals to isochrons at the slow manifold Use these vectors: to project initial conditions onto the slow manifold; to project non-autonomous forcing onto the slow evolution; to predict the consequences of modifying the original system; in uncertainty quantification to quantify effects on the model of uncertainties in the original system. The normal vector $\vec{z}_j := (z_{j1}, \ldots, z_{jn})$

$$\begin{aligned} z_{11} &= -\varepsilon^4 \\ z_{12} &= 1 \\ z_{13} &= \varepsilon^4 (\beta - 1) \\ z_{21} &= \varepsilon^4 (-2\beta + 2) + \varepsilon^2 \\ z_{22} &= -\varepsilon^3 s_2 \\ z_{23} &= \varepsilon^4 (3\beta^2 - 6\beta + 3) + \varepsilon^3 (2s_2\beta^{-1} - s_1) + \varepsilon^2 (-\beta + 1) + 1 \end{aligned}$$