

Lecture 6

Complex Integrals(複素積分)

What you will learn in Lecture 6

*6.1 Review of Real Line Integral (実·線積分)

6.2 Complex Integral (複素積分)

Real Line Integral

(実·線積分)

in the Cartesian Plane



Complex Integral

(複素積分)

in the Complex Plane

*6.1 Review of Real Line Integral

(実·線積分)

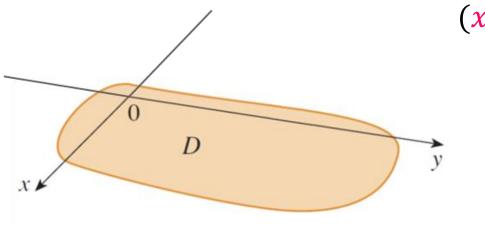






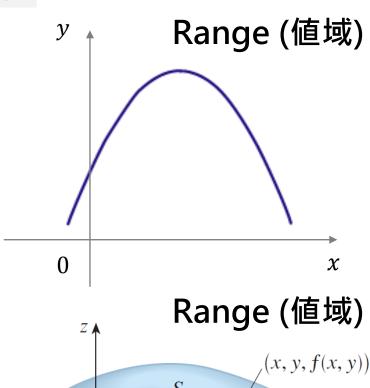


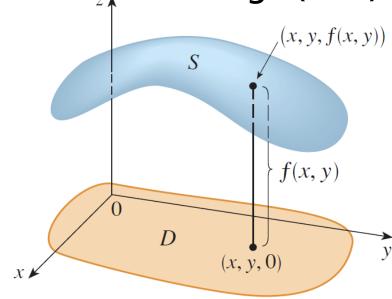
Domain (定義域) $(x, y) \in \mathbf{D}$



(x, y, f(x, y))







One-Variable Calculus -- Definite integral (定積分) of f

$$\int_{a}^{b} f(x)dx = \lim_{\|\Delta x\| \to 0} \sum_{k=1}^{n} f(x_{k}^{*}) \Delta x = \lim_{\|\Delta x\| \to 0} [f(x_{k}^{*}) \Delta x + f(x_{2}^{*}) \Delta x + \dots + f(x_{n}^{*}) \Delta x]$$
One-Variable Function
$$y = f(x)$$

$$Area(面積) = \int_{a}^{b} f(x) dx$$

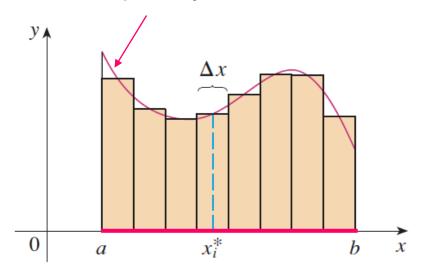
relationship, called **function**

$$\mathbf{y} = f(x)$$

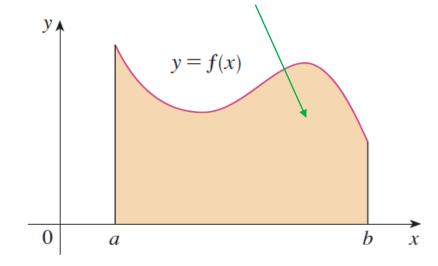
Independent variable

dependent variable

$$y = f(x)$$

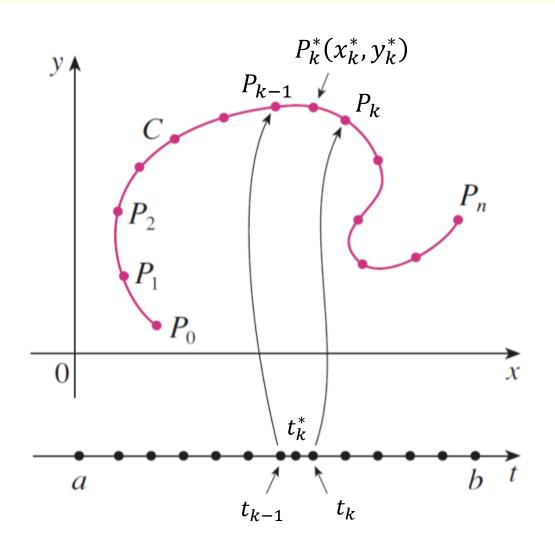


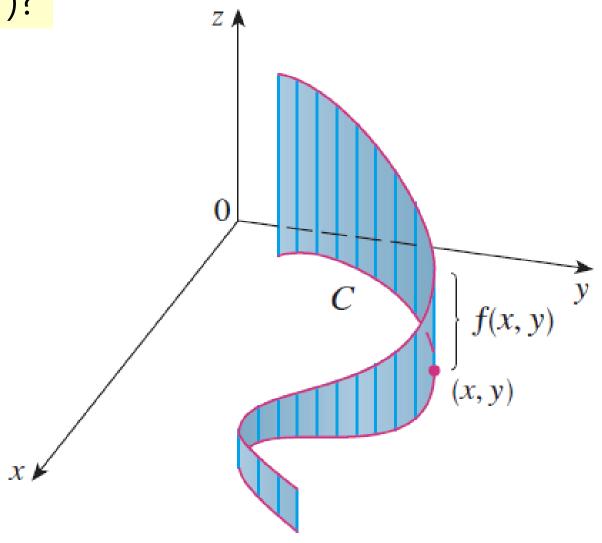
$$Area($$
面積 $) = \int_{a}^{b} f(x)dx$



$$\Delta x_1 = \Delta x_2 = \cdots = \Delta x_n = \Delta x$$
, i.e. equal interval (等間隔)

Recall: what is Line integral (線積分)?





Line Integral (線積分)

If f is defined on a smooth (滑らか) or piecewise-smooth (区分的滑らか) curve C, then **the line integral of** f **along** C is

$$\int_{C} f(x,y)ds = \lim_{\|\Delta s_{max}\| \to 0} \sum_{k=1}^{n} f(x_{k}^{*}, y_{k}^{*}) \Delta s_{k}$$

if this limits exists. (Here the norm $\|\Delta s_{max}\|$ defines the length of the longest subinterval (部分区間))

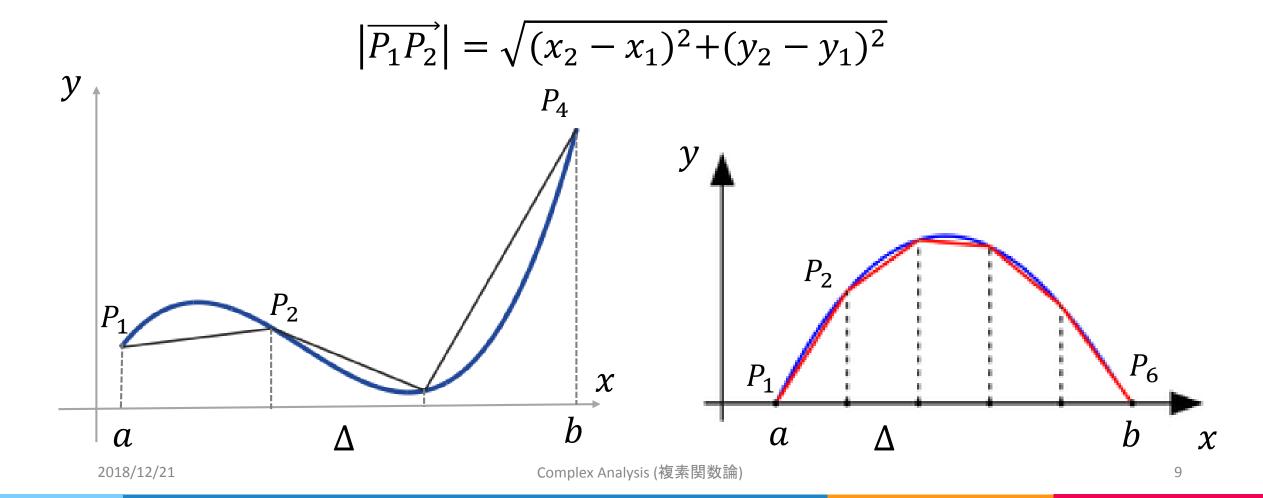
How to compute Line Integral?

By introducing **Arc length (弧長)** $L = \int_a^b \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} dt$, we have

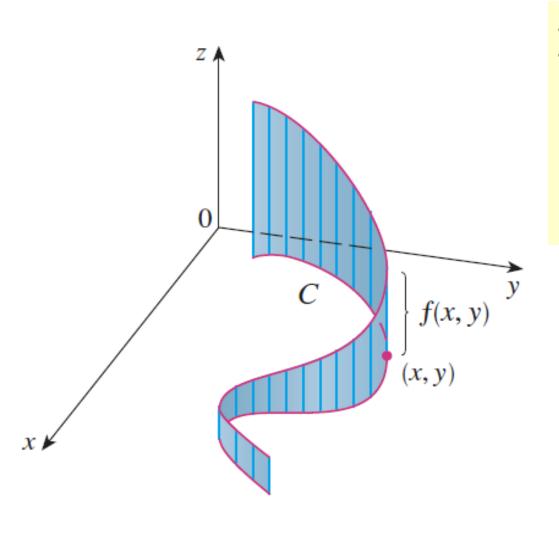
$$\int_{C} f(x,y)ds = \int_{C} f(x(t),y(t)) \sqrt{\left(\frac{dx}{dt}\right)^{2} + \left(\frac{dy}{dt}\right)^{2}} dt$$

Arc Length (弧長)

$$L = \int_{a}^{b} \sqrt{\left(\frac{dx}{dt}\right)^{2} + \left(\frac{dy}{dt}\right)^{2}} dt$$



Insight (洞察) of Line Integrals



In fact, if f(x, y) > 0,

 $\int_c f(x,y)ds$ represents the area (面積) of one side of the "curtain".



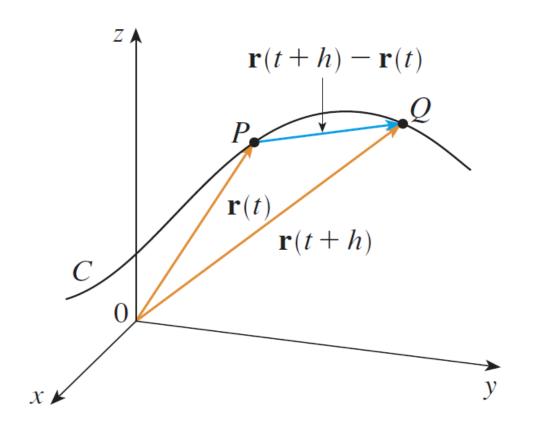
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Complex Analysis (複素関数論)



Q: How to represent curves in the complex plane?

Parametrization (パラメータ表示) of Real curve (実・曲線)



Parametrization (パラメータ表示) of Complex curve (複素・曲線)

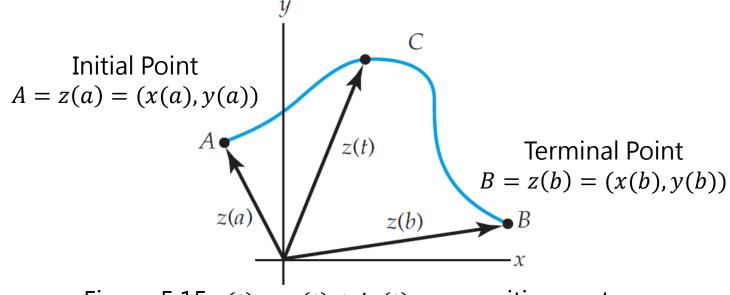
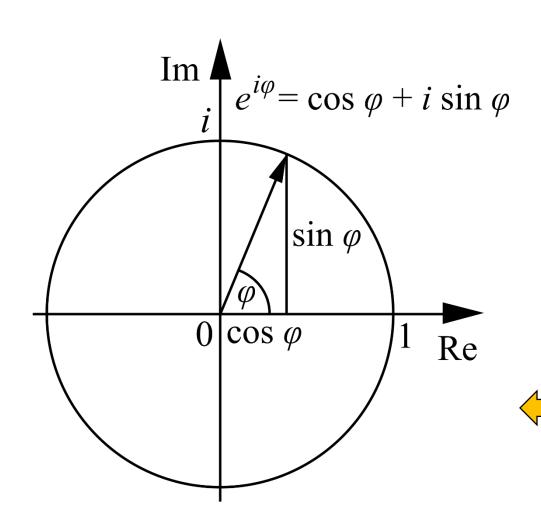


Figure 5.15 z(t) = x(t) + iy(t) as a position vector

$$z(t) = x(t) + iy(t), a \le t \le b$$
 (5.2.1)

The points z on the curve C is expressed by a complex-valued function of a real variable t. This is called a parametrization of C.



Parametrization (パラメータ表示) of Complex curve (複素・曲線)

$$z(t) = x(t) + iy(t)$$
, $a \le t \le b$

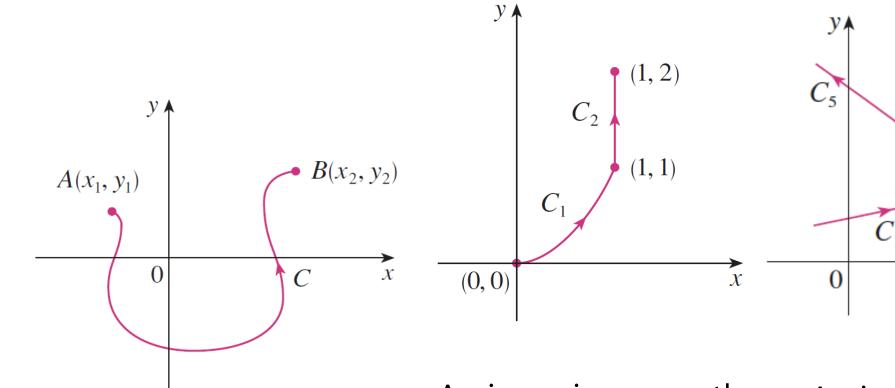
For example,

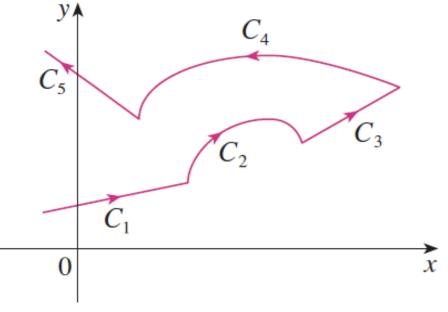
if
$$x(t) = \cos t$$
, $y(t) = \sin t$, $0 \le t \le 2\pi$
we will have

$$z(t) = \cos t + i \sin t, 0 \le t \le 2\pi$$

which is a parametrization of the circle C.

Piecewise-smooth (区分的滑らか) curve





A smooth curve C

A piecewise-smooth curve $C = C_1 \cup C_2$

A piecewise-smooth curve
$$C = C_1 \cup C_2 \cup \cdots \cup C_5$$

Suppose the derivative of

$$z(t) = x(t) + iy(t), a \le t \le b$$
 (5.2.1)

is

$$z'(t) = x'(t) + iy'(t)$$

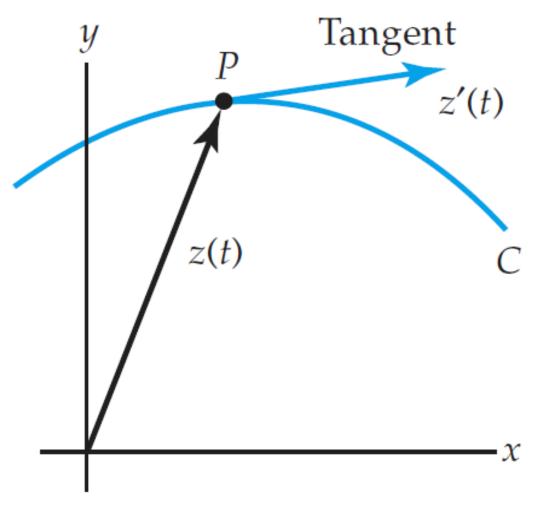


Figure 5.16 z'(t) = x'(t) + iy'(t) as a tangent vector (接べクトル)

Smooth (滑らか) Curve

A curve C in the complex plane is called smooth if z'(t) is continuous and NEVER zero in the interval $a \le t \le b$.

In other words, a smooth curve have NO sharp corners or Cusps (尖点).

Piecewise-smooth (区分的滑らか) Curve

A piecewise smooth curve C is continuous EXCEPT possibly at the points where the component smooth curves C_1, C_2, \ldots, C_n are joined together.

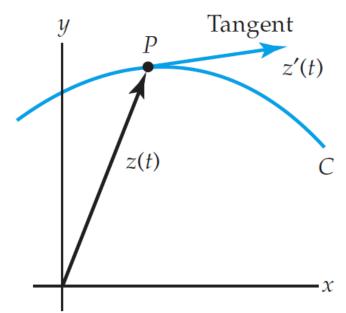


Figure 5.16 z'(t) = x'(t) + iy'(t) as a tangent vector (接ベクトル)

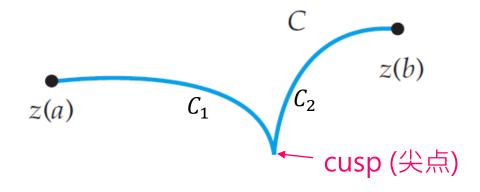


Figure 5.17 Curve C is not smooth because it has a cusp

Simple (単一) Curve

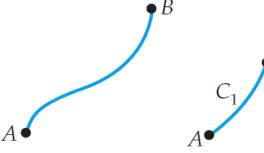
A curve C in the complex plane is said to be a simple if $z(t_1) \neq z(t_2)$ for $t_1 \neq t_2$, except possibly for initial point t = a and terminal point t = b.

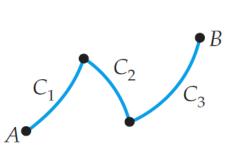
Closed (閉) Curve

C is a closed curve if z(a) = z(b).

Simple Closed Curve (単一閉曲線)

C is a simple closed curve if $z(t_1) \neq z(t_2)$ for $t_1 \neq t_2$ and z(a) = z(b).

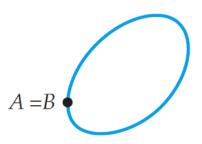




Smooth, simple, not closed

Piecewise smooth, simple, not closed





Smooth, closed, not simple

Smooth, simple, closed

Contour

A piecewise smooth curve C is called a Contour or Path.

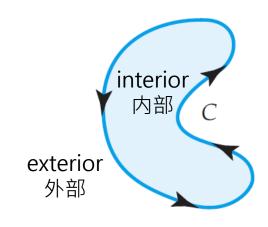
Direction (向き) on a Contour

- We define the **positive direction** on a contour *C* corresponding to increasing values of the parameter *t*.
- Roughly, for a simple closed curve C, the positive direction is the counterclockwise (左回りの) direction or the direction that a person must walk on C and keep the interior (内部) of C at the left hand.
- The negative direction on a contour C is the direction opposite (反対の) the positive direction.
- Notice: If C has positive direction, then its opposite curve can be denoted by -C.





(a) Positive direction



(b) Positive direction

Figure 5.18 Interior of each curve is at the left hand

Note: Find more explanations in Page 247 ~ 250 of the textbook.

Definition 5.3 Complex Integral (複素積分)

An integral of a function f(z) defined by

$$\int_{C} f(z) dz = \lim_{\|\Delta z_{max}\| \to 0} \sum_{k=1}^{n} f(z_{k}^{*}) \Delta z_{k}$$
 (5.2.2)

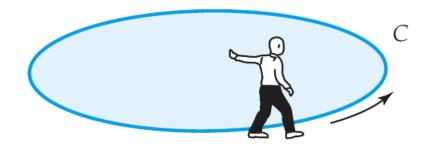
is called a **complex integral**, where z is a complex number, and f(z) is defined on a **contour** C (積分路). (Here the norm $\|\Delta z_{max}\|$ defines the length of the longest subinterval (部分区間))

- If the limit in (5.2.2) exists, then f(z) is said to be integrable (可積分の) on C.
- The limit exists whenever if f(z) is continuous at all points on C, where C is either smooth or piecewise smooth.
- The Complex Integral $\int_C f(z)dz$ has a more common name: Contour Integral.

Specially, we will use the notation

$$\oint_C f(z)dz$$

as a complex integral around a positively oriented closed curve C.



Closed curve C with Positive direction

Integral for Complex-Valued Function of a Real Variable

Example

If t represents a real variable, then the output of the function $f(t) = (2t + i)^2$ is a complex number. For t = 2,

$$f(2) = (2 \cdot 2 + i)^2 = 16 + 8i + i2 = 15 + 8i.$$

In general, if f_1 and f_2 are real-valued functions of a real variable t (that is, real functions), then $f(t) = f_1(t) + if_2(t)$ is a complex-valued function of a real variable t.

When we consider the interval $0 \le t \le 1$,

$$\int_0^1 (2t+i)^2 dt = \int_0^1 (4t^2 - 1 + i4t) dt = \int_0^1 (4t^2 - 1) dt + i \int_0^1 4t dt = \left(\frac{4}{3} \cdot t^3 - t\right) \Big|_0^1 + i \cdot 2t^2 \Big|_0^1 = \frac{1}{3} + 2i$$

Then we can define the integral of the complex-valued function $f(t) = f_1(t) + if_2(t)$ on interval $a \le t \le b$ as

$$\int_{a}^{b} f(t) dt = \int_{a}^{b} f_{1}(t) dt + i \int_{a}^{b} f_{2}(t) dt$$
 (5.2.4)

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Theorem 5.1 How to Compute a Complex Integral (i.e. Complex Integral)

If f is continuous on a smooth curve C given by the parametrization $(パラメータ表示) z(t) = x(t) + iy(t), a \le t \le b$, then

$$\int_C f(z) dz = \int_a^b f(z(t))z'(t) dt$$
 (5.2.11)

where

$$f(z(t))z'(t) = f(z(t))[x'(t) + iy'(t)] = [u(x(t), y(t)) + iv(x(t), y(t))][x'(t) + iy'(t)]$$

Recall z(t) in Equation (5.2.1)

EXAMPLE (例題) 5.2.1 Evaluating a Contour Integral

Evaluate $\int_C \bar{z} dz$, where C is given by z(t) = x(t) + iy(t), x(t) = 3t, $y(t) = t^2$, $-1 \le t \le 4$.

Solution (解答):

$$z(t) = x(t) + iy(t) = 3t + it^2$$

$$f(z(t)) = \overline{z(t)} = x(t) - iy(t) = 3t - it^2$$
 and $z'(t) = x'(t) + iy'(t) = 3 + i2t$

Then by Equation (5.2.11)

$$\int_{C} \bar{z} dz = \int_{-1}^{4} f(z(t))z'(t)dt = \int_{-1}^{4} (3t - it^{2})(3 + i2t)dt = \int_{-1}^{4} (2t^{3} + 9t + 3t^{2}i)dt$$

By using Equation (5.2.4) in this Lecture, we have

$$\int_{C} \bar{z} dz = \int_{-1}^{4} (2t^{3} + 9t) dt + i \int_{-1}^{4} 3t^{2} dt = \left(2 \cdot \frac{1}{4} \cdot t^{4} + 9 \cdot \frac{1}{2} \cdot t^{2}\right) \Big|_{-1}^{1} + i \cdot t^{3} \Big|_{-1}^{4} = 195 + 65i$$

$$\int_{-1}^{2018/12/21} |z|_{-1}^{4} (2t^{3} + 9t) dt + i \int_{-1}^{4} 3t^{2} dt = \left(2 \cdot \frac{1}{4} \cdot t^{4} + 9 \cdot \frac{1}{2} \cdot t^{2}\right) \Big|_{-1}^{1} + i \cdot t^{3} \Big|_{-1}^{4} = 195 + 65i$$

EXAMPLE (例題) 5.2.2 Evaluating a Contour Integral

Evaluate $\oint_C \frac{1}{z} dz$, where C is the circle $x(t) = \cos t$, $y(t) = \sin t$, $0 \le t \le 2\pi$.

Solution (解答):

$$z(t) = \cos t + i \sin t = e^{it}$$

$$\therefore f(z(t)) = \frac{1}{z(t)} = \frac{1}{e^{it}} = e^{-it} \quad \text{and} \quad z'(t) = ie^{it}$$

Then by Equation (5.2.11)

$$\oint_C \frac{1}{z} dz = \int_0^{2\pi} f(z(t))z'(t)dt = \int_0^{2\pi} (e^{-it})ie^{it}dt$$

$$= i \int_0^{2\pi} e^{-it+it}dt = i \int_0^{2\pi} e^0 dt = i \int_0^{2\pi} dt = i \cdot t \Big|_0^{2\pi} = 2\pi i$$

Theorem 5.2 Properties of Contour Integrals

Suppose the functions f and g are continuous in a domain D, and C is a smooth or piecewise smooth curve in D. Then

- (i) $\int_C qf(z) dz = q \int_C f(z) dz$, where q is a complex constant.
- (ii) $\int_{C} [f(z) + g(z)] dz = \int_{C} f(z) dz + \int_{C} g(z) dz$
- (iii) $\int_C f(z) dz = \int_{C_1} f(z) dz + \int_{C_2} f(z) dz$, where C consists of the smooth curves C_1 and C_2 joined end to end.
- (iv) $\int_{-C} f(z) dz = -\int_{C} f(z) dz$, where -C denotes the curve having the opposite Orientation (向き) of C.

EXAMPLE (例題) 5.2.3 C is a Piecewise Smooth Curve

Evaluate $\int_C (x^2 + iy^2) dz$, where C is the contour shown in Figure 5.20.

Solution (解答):

 $f(z) = x^2 + iy^2$ From Theorem 5.2(iii), we have

$$\int_{C} (x^2 + iy^2) dz = \int_{C_1} (x^2 + iy^2) dz + \int_{C_2} (x^2 + iy^2) dz$$

From the Figure 5.20, we know the curves

① C_1 is y = x, when $0 \le x < 1$

Therefore, (x(t), y(t)) becomes (x(t), x(t)), it makes sense that we can directly use x as parameter, then

$$z(x) = x + ix z'(x) = 1 + i$$

$$f(z(x)) = x^2 + ix^2$$

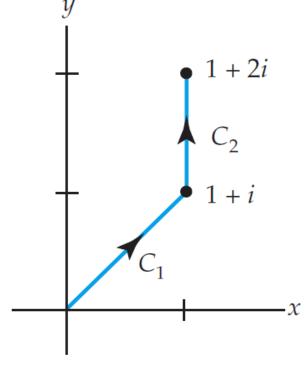


Figure 5.20 Contour $C = C_1 \cup C_2$ is piecewise-smooth

Solution (解答)(cont.):

Then by Equation (5.2.11)

$$\int_{C_1} (x^2 + iy^2) dz = \int_0^1 f(z(x))z'(x) dx = \int_0^1 (x^2 + ix^2)(1 + i) dx$$
$$= (1 + i)^2 \int_0^1 x^2 dx = (1 + i)^2 \cdot \frac{1}{3} \cdot t^3 \Big|_0^1 = \frac{2}{3}i$$

(2) C_2 is x = 1, when $1 \le y \le 2$

Therefore, (x(t), y(t)) becomes (1, y(t)), it makes sense that we can directly use y as parameter, then

$$z(y) = 1 + iy$$
 $z'(y) = 0 + i = i$ $f(z(y)) = 1 + iy^2$

Then by Equation (5.2.11)

$$\int_{C} (x^{2} + iy^{2}) dz = \int_{1}^{2} f(z(y))z'(y) dy = \int_{1}^{2} (1 + iy^{2})i dy = -\int_{1}^{2} y^{2} dy + i \int_{1}^{2} 1 dy = -\frac{7}{3} + i$$

by Equation (5.2.4)

Combining the results of ① and ②, we have $\int_C (x^2 + iy^2) dz = \frac{2}{3}i + \left(-\frac{7}{3} + i\right) = -\frac{7}{3} + \frac{5}{3}i$

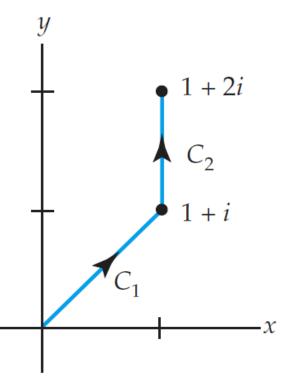


Figure 5.20 Contour $C = C_1 \cup C_2$ is piecewise-smooth

*Theorem 5.3 A Bounding (界) Theorem

If f is continuous on a smooth curve C and if modulus $|f(z)| \le M$

for all z on C, Then
$$\left| \int_C f(z) dz \right| \le ML$$
, where L is the length of C.

*EXAMPLE (例題) 5.2.4 A Bound for a Contour Integral

Find an upper bound (上界) for the absolute value of $\oint_C \frac{e^z}{z+1} dz$, where Cis the circle |z|=4.

Solution (解答):

First, the length L (circumference (円周)) of the circle with radius (半径) r=4 is $L=2\pi r=8\pi$. Recall the inequality (1.2.7) $|z_1 + z_2| \ge |z_1| - |z_2|$ in Page 35 of the Lecture 1 Slides, all points z on the circle that $|z + 1| \ge |z| - 1 = 4 - 1 = 3$

$$\left|\frac{e^z}{z+1}\right| \le \frac{|e^z|}{|z|-1} = \frac{|e^z|}{3}$$

Because $|e^z| = |e^x(\cos y + i\sin y)| = \sqrt{(e^x\cos y)^2 + (e^x\sin y)^2} = \sqrt{(e^x)^2(\cos^2 x + \sin^2 x)} = e^x$ Then for points on the circle |z| = 4, the maximum that x = Re(z) can be is 4, therefore

$$\left|\frac{e^z}{z+1}\right| \le \frac{e^4}{3}$$

$$\left|\frac{e^z}{z+1}\right| \le \frac{e^4}{3}$$
From the Theorem 5.3, we have
$$\left|\int_C \frac{e^z}{z+1} dz\right| \le M \cdot L = \frac{e^4}{3} \cdot 8\pi = \frac{8\pi e^4}{3}$$

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Review for Lecture 6

- Real Line Integral
- Piecewise Smooth Curve
- Simple, Closed Curve
- Complex Integral (Contour Integral)
- How to Compute Complex Integral

Assignment

Please Check https://github.com/uoaworks/ComplexAnalysisAY2018

Reading Materials: The Section 5.1 and 5.2 of Textbook

References

- [1] A first course in Complex Analysis with application, Dennis G. Zill and Patrick D. Shanahan, Jones and Bartlett Publishers, Inc. 2003
- [2] Calculus, 6th Edition, James Stewart, Thomas Brooks/Cole, 2009
- [3] Wikipedia

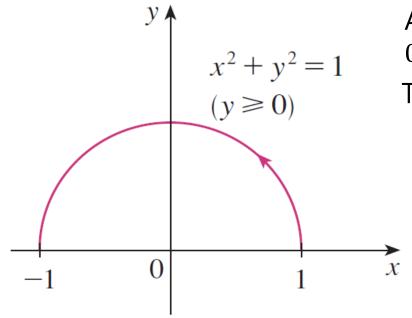
Appendix (付録)

*6.1 Review of Real Line Integral (実·線積分)

EXAMPLE (例題) Recall Real Line Integral in Calculus II (微積分 II)

Evaluate $\int_C (2 + x^2 y) ds$, where C is the upper half of the unit circle $x^2 + y^2 = 1$

Solution (解答):



Recall that the unit circle can be parametrized by

$$x = \cos t$$
, $y = \sin t$

And the upper half of the circle is described by the parameter interval

 $0 \le t \le \pi$

Therefore, from the formula in Page 14 of this lecture note, we have

$$\int_{C} (2+x^{2}y)ds = \int_{0}^{\pi} (2+\cos^{2}t\sin t) \sqrt{\left(\frac{dx}{dt}\right)^{2} + \left(\frac{dy}{dt}\right)^{2}} dt$$

$$= \int_{0}^{\pi} (2+\cos^{2}t\sin t) \sqrt{(-\sin t)^{2} + \cos^{2}t} dt$$

$$= \int_{0}^{\pi} (2+\cos^{2}t\sin t) = \left[2t - \frac{\cos^{3}t}{3}\right]_{0}^{\pi} = 2\pi + \frac{2}{3}$$

EXAMPLE (例題) Recall Real Line Integral in Calculus II (微積分 II)

Evaluate $\int_C 2x \, ds$, where C consists of the arc C_1 of the parabola $y = x^2$ from (0,0) to (1,1) followed by the vertical line segment C_2 from (1,1) to (1,2).

Solution (解答):

① Because from C_1 we know y is a function of x, i.e. the domain (x,y) becomes (x,x^2) , so we can use x as the parameter, then

$$x = x, \quad y = x^2, \quad 0 \le x \le 1$$

Therefore

$$\int_{C_1} 2x ds = \int_0^1 2x \sqrt{\left(\frac{dx}{dx}\right)^2 + \left(\frac{dy}{dx}\right)^2} dx = \int_0^1 2x \sqrt{1 + (2x)^2} dx$$

$$= \left[\frac{1}{4} \cdot \frac{2}{3} (1 + 4x^2)^{\frac{3}{2}}\right]_0^1 = \frac{5\sqrt{5} - 1}{6}$$

(0, 0)

Appendix (付録)

*6.1 Review of Real Line Integral (実·線積分)

Solution (解答)(cont.):

② Because from C_2 we see a vertical line segment, so we can use y as the parameter, then

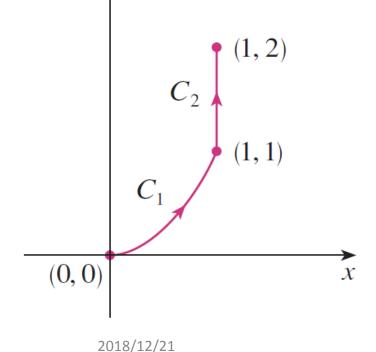
$$x = 1$$
, $y = y$, $1 \le y \le 2$

Therefore

$$\int_{C_2} 2xds = \int_1^2 2 \cdot 1 \cdot \sqrt{\left(\frac{dx}{dy}\right)^2 + \left(\frac{dy}{dy}\right)^2} dy$$

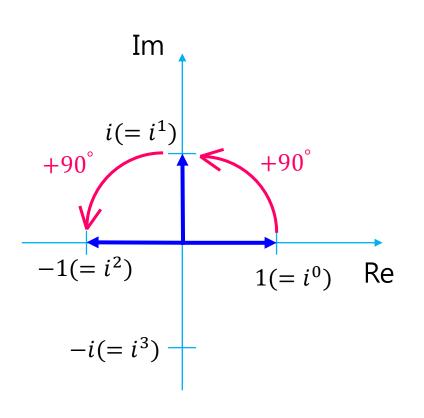
$$= \int_1^2 2\sqrt{0 + 1} dy = \int_1^2 2dy = 2$$

$$\int_C 2xds = \int_{C_1} 2xds + \int_{C_2} 2xds = \frac{5\sqrt{5} - 1}{6} + 2$$



Application 2 of Complex Number:

Rotation











Application 2 of Complex Number: Rotation

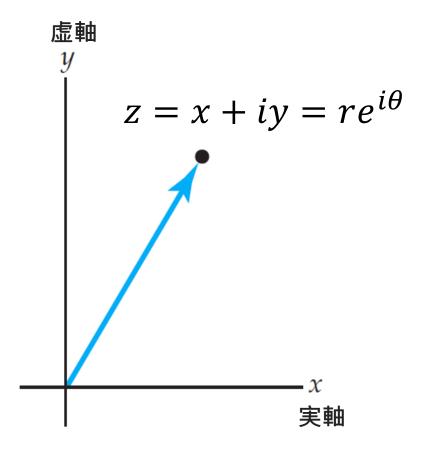


Figure 1.2 A vector *z*

