COMS21202: Symbols, Patterns and Signals Probabilistic Data Models

[modified from Dima Damen lecture notes]

Rui Ponte Costa & Dima Damen

rui.costa@bristol.ac.uk

Department of Computer Science, University of Bristol Bristol BS8 1UB, UK

March 9, 2020

Data Modelling

- Deterministic models do not explicitly model uncertainties or 'randomness' in data
- Inference variability from the data is not included
- In many tasks, we benefit from modelling uncertainty
- ► This is explicit in **Probabilistic Models**

Back to Fish - Discrete case

Discrete variable:

Example

A fisherman returns with the daily catch of fish. If we select a fish at random from the hold, what species will it be? $fish \in \{salmon, seabass, cod, ...\}$

```
A deterministic model would give one value, the most likely
```

- A probabilistic model quantifies the chance/probability of the selected fish being one of the possible species.
- ▶ Model the probability $P(x_i = q_i)$ where $q_i \in \{salmon, seabass, cod, \cdots\}$

Back to Fish - Continuous case

Continuous variable:

Example

Predict the weight of fish from its length

Let us assume that we think the weight of fish is directly proportional to its length, i.e. $weight = b \times length + a$ (linear regression)

A **probabilistic approach** would model weight as a **random variable** and hypothesize that

$$weight = b \times length + a + \epsilon$$

where ϵ is a random variable, with mean usually close to zero

Back to Fish - Continuous case

$$weight = b \times length + a + \epsilon$$

- ▶ Modelled using a probability distribution for ϵ ,
 - by a uniform distribution
 - by a normal distribution
 - **•** ...
- ► In the next slides, we will simplify things by setting weight = 0 when length = 0
- As a consequence, the y-intercept can be set to zero (i.e. a=0), and

$$weight = b \times length + \epsilon$$

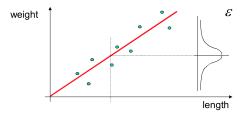
Back to Fish - Probabilistic

$$weight = b \times length + \epsilon$$

We can assume, for example, that ϵ is given by $\mathcal{N}(0, \sigma^2)$

$$p(\epsilon) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{\epsilon^2}{2\sigma^2}}$$

This model has two parameters: the slope b and uncertainty σ (with $\mu = 0$)



Maximum Likelihood Estimation

- Similar to building deterministic models, probabilistic model parameters need to be tuned/trained
- Maximum-likelihood estimation (MLE) is a method of estimating the parameters of a probabilistic model.
- Assume θ is a vector of all parameters of the probabilistic model. (e.g. $\theta = \{b, \sigma\}$).
- ▶ MLE is an extremum estimator¹ obtained by maximising an objective function of θ

¹"Extremum estimators are a wide class of estimators for parametric models that are calculated through maximization (or minimization) of a certain objective function, which depends on the data." wikipedia.org

Maximum Likelihood Estimation

Definition

Assume $f(\theta)$ is an objective function to be optimised (e.g. maximised), the *arg max* corresponds to the value of θ that attains the maximum value of the objective function f

$$\hat{\theta} = arg \max_{\theta} f(\theta)$$

Tuning the parameter is then equal to finding the maximum argument arg max

Maximum Likelihood Estimation - General

 Maximum Likelihood Estimation (MLE) is a common method for solving such problems

```
	heta_{MLE} = arg \max_{\theta} p(D|\theta)
= arg \max_{\theta} \ln p(D|\theta)
= arg \min_{\theta} - \ln p(D|\theta)
```

MLE Recipe

- 1. Determine θ , D and expression for likelihood $p(D|\theta)$
- Take the natural logarithm of the likelihood
- 3. Take the derivative of $\ln p(D|\theta)$ w.r.t. θ . If θ is a multi-dimensional vector, take partial derivatives
- 4. Set derivative(s) to 0 and solve for θ

MLE: 1. Define likelihood

Given a set of N data points - x_i is length and y_i is weight in our *fishy* example

$$D = \{(x_1, y_1), (x_2, y_2), \cdots, (x_N, y_N)\}\$$

- The probabilistic approach would:
 - derive expression for conditional probability of observing data D given parameters $\theta = \{b, \sigma\}$

$$p(D|\theta)$$

MLE: 1. Define likelihood

Given a set of N data points

$$D = \{(x_1, y_1), (x_2, y_2), \cdots, (x_N, y_N)\}\$$

Assume that observations are independent - a common assumption often referred to as **i.i.d. independent and identically distributed** - then :

$$p(D|\theta) = \prod_{i=1}^{N} p(y_i|x_i,\theta)$$

Given $y_i = b x_i + \epsilon$, and ϵ is $\mathcal{N}(0, \sigma^2)$, then

$$p(y_i|x_i,\theta) \sim \mathcal{N}(bx_i,\sigma^2)$$

For a large sample:

- The average of y_i value will be b x_i
- ▶ The 'spread' or variance will be the same as for ϵ , defined by σ^2

MLE: 1. Define likelihood

The conditional probability (for all data) is thus formulated as

$$p(D|\theta) = \prod_{i=1}^{N} p(y_i|x_i,\theta)$$
$$= \prod_{i=1}^{N} \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{1}{2} \frac{(y_i - bx_i)^2}{\sigma^2}}$$

MLE: 2. Take natural logarithm

We will focus on parameter *b* for the next steps,

$$\begin{split} b_{ML} &= arg \ max_b \ p(D|\theta) \\ &= arg \ max_b \prod_{i=1}^N \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{1}{2}\frac{(y_i - bx_i)^2}{\sigma^2}} \\ &= arg \ max_b \ln \Big(\prod_{i=1}^N \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{1}{2}\frac{(y_i - bx_i)^2}{\sigma^2}}\Big) \qquad \text{(use In trick)} \\ &= arg \ max_b \sum_{i=1}^N \ln \Big(\frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{1}{2}\frac{(y_i - bx_i)^2}{\sigma^2}}\Big) \qquad \text{(In prop. 1)} \\ &= arg \ max_b \sum_{i=1}^N \ln \frac{1}{\sqrt{2\pi}\sigma} - \frac{(y_i - bx_i)^2}{2\sigma^2} \qquad \text{(In prop. 2)} \\ &= arg \ max_b \sum_{i=1}^N -\frac{1}{2\sigma^2} (y_i - bx_i)^2 \qquad \text{(discard no-b terms In } \frac{1}{\sqrt{2\pi}\sigma}) \\ &= arg \ min_b \sum_{i=1}^N \frac{1}{2\sigma^2} (y_i - bx_i)^2 \qquad \text{(switch to minimisation form.)} \end{split}$$

Data Modelling - Deterministic vs Probabilistic

Deterministic Least Squares [Lecture 3]:

$$b_{LS} = arg \min_b R(b, a = 0) = arg \min_b \sum_i (y_i - b x_i)^2$$

Probabilistic Maximum Likelihood:

$$b_{ML} = arg min_b \sum_{i} \frac{1}{2\sigma^2} (y_i - b x_i)^2$$

▶ probabilistic model explicit considers uncertainty, σ^2 .

MLE: 3. Take derivatives and 4. Find solution

To simplify the calculations here we assume $\sigma = 1$,

$$b_{ML} = arg min_b \sum_{i} \frac{1}{2} (y_i - b x_i)^2$$

To find the minimum, calculate the derivative

$$\frac{d}{db}\sum_{i}\frac{1}{2}(y_{i}-bx_{i})^{2}=-\sum_{i}x_{i}(y_{i}-bx_{i})$$

and equate it to zero

$$-\sum_{i} x_i (y_i - b_{ML} x_i) = 0$$

$$\sum_{i} x_i y_i - b_{ML} \sum_{i} x_i^2 = 0$$

$$b_{ML} = \frac{\sum_{i} y_i x_i}{\sum_{i} x_i^2}$$

MLE: summary

Example: normal distribution (parameter b)

1. Determine θ , D and expression for likelihood $p(D|\theta)$

$$p(D|b) = \prod_{i=1}^{N} \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{1}{2} \frac{(y_i - bx_i)^2}{\sigma^2}}$$

2. Take the natural logarithm of the likelihood

$$b_{ML} = arg min_b \sum_i \frac{1}{2\sigma^2} (y_i - b x_i)^2$$

3. Take the derivative of $\ln p(D|\theta)$ w.r.t. θ . If θ is a multi-dimensional vector, take partial derivatives ²

$$\frac{d}{db}\sum_{i}\frac{1}{2}(y_{i}-bx_{i})^{2}=-\sum_{i}x_{i}(y_{i}-bx_{i})$$

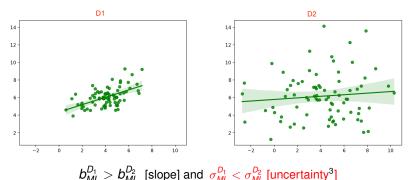
4. Set derivative(s) to 0 and solve for b

$$b_{ML} = \frac{\sum_{i} y_{i} x_{i}}{\sum_{i} x_{i}^{2}}$$

²For simplicity we set $\sigma = 1$

Data Modelling - Deterministic vs Probabilistic

- Probabilistic Models can tell us more
- ▶ We could use the same MLE recipe to find σ_{ML} . This would tell us how uncertainty our model is about the data D.
- For example: if we apply this method to two datasets (D_1 and D_2) what would the parameters $\theta = \{b, \sigma\}$ be?



³The uncertainty (σ) is represented by the light green bar in the plots. Test it your self.

Example

Given a coin, you were assigned the task of figuring out whether the coin will land on its head or tails. You were asked to build a probabilistic model (i.e. with confidence)

- Data: head/tail binary attempts (of size N)
- ► Model: Binomial distribution
- ▶ Model Parameters: head probability α

Definition

The **binomial distribution** gives the probability distribution for a discrete variable to obtain exactly D successes out of N trials, where the probability of the success is α and the probability of failure is $(1 - \alpha)$ and $0 \le \alpha \le 1$

The binomial distribution probability density function is given by

$$P(D|N) = {N \choose D} \alpha^{D} (1 - \alpha)^{N-D}$$
$$= \frac{N!}{D!(N-D)!} \alpha^{D} (1 - \alpha)^{N-D}$$

Accordingly, using the binomial probability distribution where D is the number of heads in N coin tosses and θ is the probability of getting heads in a single toss,

$$P(D|\theta) = \binom{N}{D} \theta^{D} (1-\theta)^{N-D}$$

Maximum Likelihood Estimation (MLE) would then be looking for

$$\theta_{ML} = arg \max_{\theta} p(D|\theta)$$

Take the natural logarithm

$$P(D|\theta) = \binom{N}{D} \theta^{D} (1-\theta)^{N-D}$$

$$\ln P(D|\theta) = \ln \binom{N}{D} + D \ln \theta + (N-D) \ln(1-\theta)$$

ightharpoonup Take the derivative w.r.t θ

$$\frac{d}{d\theta} \ln P(D|\theta) = D\frac{1}{\theta} + (N - D)\frac{1}{1 - \theta}(-1)$$
$$= \frac{D}{\theta} - \frac{N - D}{1 - \theta}$$

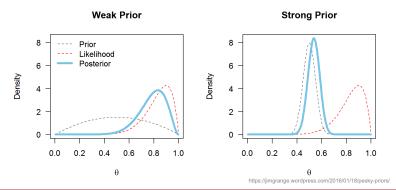
 \blacktriangleright Set the derivative to 0 and solve for θ

$$\begin{split} \frac{D}{\theta_{ML}} - \frac{N - D}{1 - \theta_{ML}} &= 0\\ \frac{D(1 - \theta_{ML}) - (N - D)\theta_{ML}}{\theta_{ML}(1 - \theta_{ML})} &= 0\\ D - N\theta_{ML} &= 0\\ \theta_{ML} &= \frac{D}{N} \end{split}$$

► In conclusion, the probability of heads is the relative frequency (D over the number of samples N).

Probabilistic Model - Using prior information

- ▶ MLE ignores any prior knowledge we may have about θ
- If we have prior knowledge about values what θ is likely to have, then we can use Bayesian inference, which combines prior and likelihood probabilities as $p(\theta|D) = p(D|\theta)p(\theta)/Z$, where $p(\theta|D)$ is the posterior, $p(D|\theta)$ the likelihood of the data, $p(\theta)$ the prior over the parameters and Z is the normalization term (p(D)).



Probabilistic Model - Using prior information

The MLE method can be expanded to consider prior information as

$$\theta_{ML} = arg \max_{\theta} p(D|\theta) p(\theta)$$

► This is known as Maximum a Posteriori (MAP) estimation ⁴

⁴You are going to learn more Posterior distributions next year in Machine Learning!

Example

Given a coin, you were assigned the task of figuring out whether the coin will land on its head or tails. You were asked to build a probabilistic model (i.e. with confidence)

- Suppose we want to utilise our prior belief that coins are typically fair
- \triangleright $p(\theta)$ would peak around $\theta = 0.5$
- Let's use

$$p(\theta) = b\theta(1-\theta)$$

where b is a normalising factor so the area under the curve is equal to 1

Likelihood:

$$p(D|\theta) = \binom{N}{D} \theta^D (1-\theta)^{N-D}$$

Prior:

$$p(\theta) = b\theta(1-\theta)$$

▶ Posterior:

$$p(\theta|D) = p(D|\theta) p(\theta) = \binom{N}{D} \theta^{D} (1-\theta)^{N-D} b \theta (1-\theta)$$

Take the natural logarithm and derivate [same recipe as in MLE]

$$p(D|\theta) p(\theta) = \binom{N}{D} \theta^{D} (1-\theta)^{N-D} b \theta (1-\theta)$$

$$\ln p(D|\theta) p(\theta) = \ln \binom{N}{D} + D \ln \theta + (N-D) \ln(1-\theta) + \ln b + \ln \theta + \ln(1-\theta)$$

$$\frac{d}{d\theta}\ln p(D|\theta)\,p(\theta) = D\frac{1}{\theta} - (N-D)\frac{1}{1-\theta} + \frac{1}{\theta} - \frac{1}{(1-\theta)}$$

▶ Set the derivative to 0 and solve for θ_{MAP}

$$D\frac{1}{\theta_{MAP}} - (N - D)\frac{1}{1 - \theta_{MAP}} + \frac{1}{\theta_{MAP}} - \frac{1}{(1 - \theta_{MAP})} = 0$$

$$\frac{D + 1}{\theta_{MAP}} - (N - D + 1)\frac{1}{1 - \theta_{MAP}} = 0$$

$$\frac{(D + 1)(1 - \theta_{MAP}) - (N - D + 1)\theta_{MAP}}{\theta_{MAP}(1 - \theta_{MAP})} = 0$$

$$\theta_{MAP} = \frac{D + 1}{N + 2}$$

The prior added two 'virtual' coin tosses, one with heads and one with tails. Note that for D = N = 0, it defaults to our prior knowledge, i.e. $\theta_{MAP} = \frac{1}{2}$.

Conclusion

- Probabilistic models encode randomness in the data
- They provide model uncertainty
- Parameters of the model are tuned using estimators
- Maximum Likelihood Estimation (MLE) is a recipe used for training model parameters
- MLE does not encode our prior knowledge of possible parameters
- Maximum a Posteriori (MAP) maximises likelihood along with prior

Further Reading

- Probability and Statistics for Engineers and Scientists Walpole et al (2007)
 - Section 3.1
 - Section 3.2
 - Section 4.1
 - Section 4.2
- Statistical Learning Methods Russell and Norvig (2003)
 - Chapter 20 (p. 712 720)