

A **unifier** or **solution** to a finite set of type constraints $\{A_1 \stackrel{?}{=} B_1, \dots, A_n \stackrel{?}{=} B_n\}$ is a type substitution σ such that:

$$\forall i \in \{1 \dots n\}. A_i \sigma = B_i \sigma$$

We will write $\mathcal{C} \sigma$ for the application of σ to all the types in \mathcal{C} .

EXAMPLE SOLUTION σ

$$\sigma := \left[\begin{array}{lcl} & a \rightarrow a & / \quad b \\ (a \rightarrow a) \rightarrow a \rightarrow a & / & c \\ & a \rightarrow a & / \quad d \\ & a \rightarrow a & / \quad e \\ & a & / \quad f \end{array} \right]$$

EXAMPLE SOLUTION τ

$$\tau := \left[\begin{array}{l} b \rightarrow b \quad / \quad a \\ (b \rightarrow b) \rightarrow b \rightarrow b \quad / \quad b \\ ((b \rightarrow b) \rightarrow b \rightarrow b) \rightarrow (b \rightarrow b) \rightarrow b \rightarrow b \quad / \quad c \\ (b \rightarrow b) \rightarrow b \rightarrow b \quad / \quad d \\ (b \rightarrow b) \rightarrow b \rightarrow b \quad / \quad e \\ b \rightarrow b \quad / \quad f \end{array} \right]$$

A set of type constraints of the shape $\mathcal{C} = \{a_1 \stackrel{?}{=} A_1, \dots, a_m \stackrel{?}{=} A_m\}$ is in **solved form** just if each of the a_i are pairwise distinct variables none of which occurs in any of the A_i .

In such a case, we define $\llbracket \mathcal{C} \rrbracket := [A_1/a_1, \dots, A_m/a_m]$.

ROBINSON'S ALGORITHM

$$\begin{aligned} \{A \stackrel{?}{=} A\} \uplus \mathcal{C} &\Longrightarrow \mathcal{C} \\ \{A_1 \rightarrow A_2 \stackrel{?}{=} B_1 \rightarrow B_2\} \uplus \mathcal{C} &\Longrightarrow \{A_1 \stackrel{?}{=} A_1, A_2 \stackrel{?}{=} B_2\} \uplus \mathcal{C} \\ \{A \stackrel{?}{=} a\} \uplus \mathcal{C} &\Longrightarrow \{a \stackrel{?}{=} A\} \uplus \mathcal{C} && \text{if } A \notin \mathbb{A} \\ \{a \stackrel{?}{=} A\} \uplus \mathcal{C} &\Longrightarrow \{a \stackrel{?}{=} A\} \uplus \mathcal{C}[A/a] && \text{if } a \notin \text{FTV}(A) \end{aligned}$$

