

Head Monitoring Persistent Collision Map Multi Table App

Summer 2010 Projects

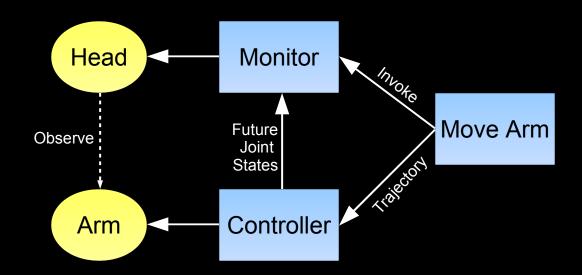
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Head Monitoring

- Laser limited, use stereo vision
- Integrated into move_arm











Head Monitoring

- Location: move_arm_head_monitor
- Usage:
 - pr2_arm_navigation_actions
 - head_monitor_x_arm.launch
 - move_x_arm_active.launch



- Currently amnesic
- Want to remember
- Other desired features



- OcTree structure
- Hierarchical, 8 children
- Octomap package
 - (Uni. Freiburg)





- Advantages:
 - More compact
 - Probabilistic update
 - Query resolution
 - Free & unknown space
 - Can degrade
 - Templated



- Implementation:
 - Replacement for collision_map
 - Volume difference per insertion
 - Increased query speed
- Location:
 - octomap2
 - collision_octomap





- Mobile manipulation
- Build world with Octomap
- Identify tables, objects
- Get manipulation points
- Navigation & grasping
- Head monitoring



- Multi table detector service
- Table detection:
 - Point clouds from collision_octomap
 - Filter z direction
 - Cluster points
 - Fit plane
 - Project inliers



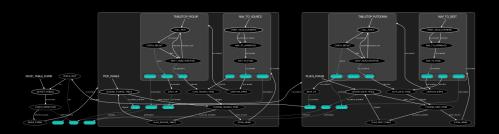
- Manipulation pose generation:
 - Expand table perimeter
 - Check for reachability
- Object detection:
 - Cluster volume over table
 - Find distance to perimeter poses
- Pose ranking







- Implemented in SMACH
 - Table and pose selection
 - Navigation
 - Grasping via wrapping PickAndPlaceManager









Future Work

- Octomap:
 - Make it faster
 - Operations directly on octree?
 - Solve clearing problem
- App:
 - Improve table/object detector
 - Use both arms
 - Make it faster



Package Locations

- move_arm_head_monitor in arm_navigation
- collision_octomap in collision_environment (soon)
- multi_table_detector and multi_table_app location (and name) t.b.d.



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