

Make It Aesthetic

Anna-Maria Hohmann
Konrad Kring
Meret Lindanis

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About Us

Meret

- computer science
- medical technologies

Anna

- business informatics
- project management

Konrad

- pedagogics
- music



Goals of Our Project

our motivation:

- interested in photography
- opening aesthetic photography to the public
- simplifying the aesthetic photography for the user
- being able to save every moment in beautiful photos
- bringing this knowledge into school

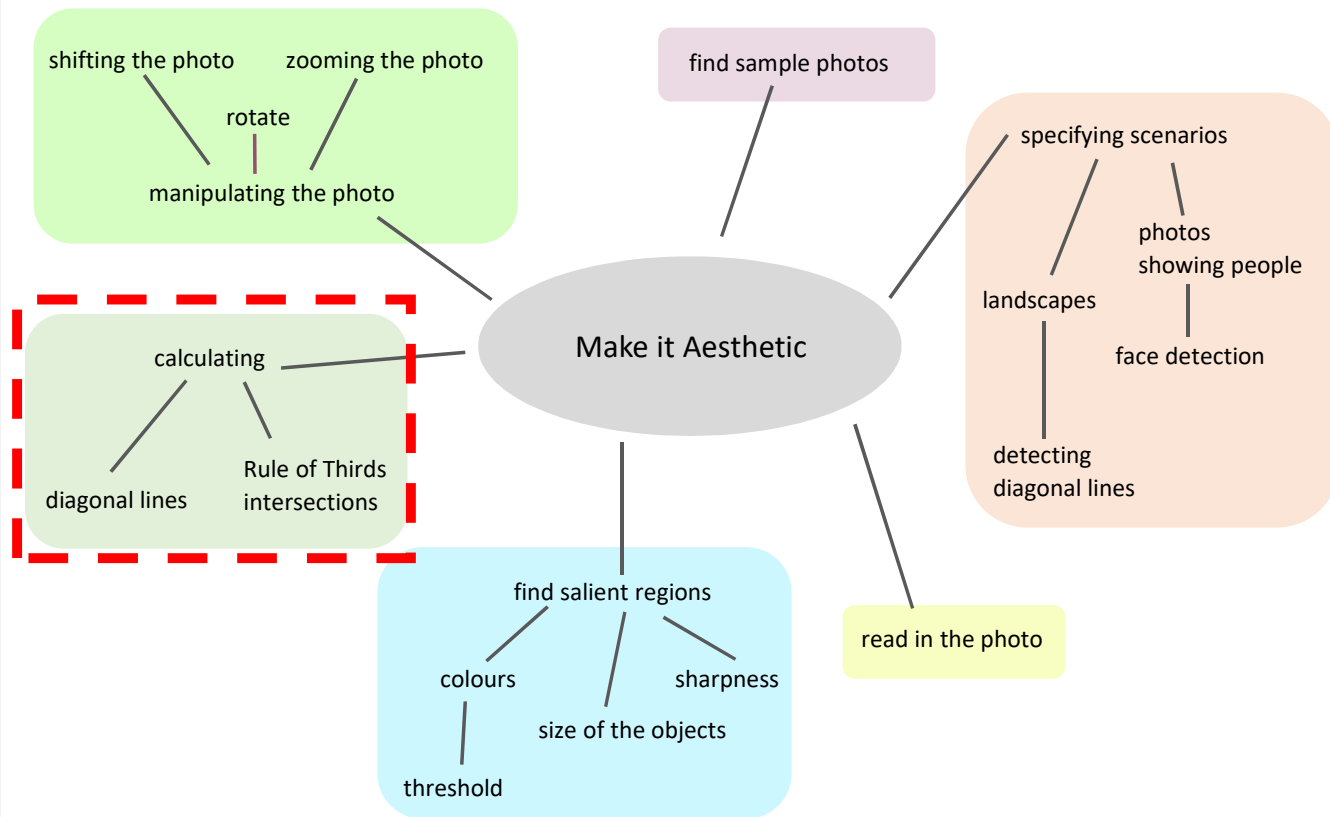


Goals of Our Project

- make given photos aesthetic
- by zooming, rotating or cropping the photo
- selecting the guideline the photo should follow



Milestones





Use-Cases

- make photos more aesthetic for a photo album / website
 - wedding /big events --> people/creature
 - vacation --> landscape, buildings, people
 - art --> all categories
- let the algorithms editing all your photos instead of doing it manually



Scenarios

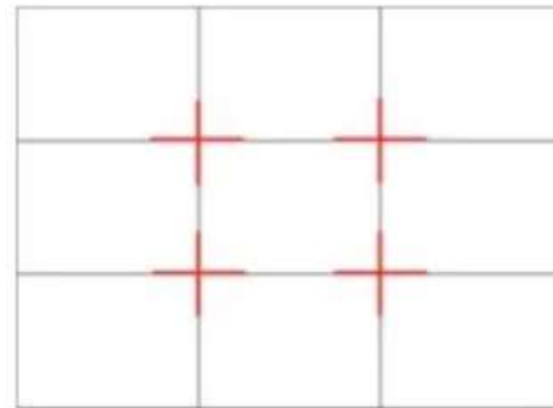
- using clear colour contrast first
 - bright background, dark main object
 - dark background, bright main object
 - only one object
- adding more and more complicated scenarios
 - more objects
 - fewer colour contrasts
 - i.e. bright background, bright main object
 - and vice versa



Focus

Rule of Third (RT):

- breaking image down into thirds
- horizontally / vertically = 9 parts
- gives four important parts for placing points of interest in photo

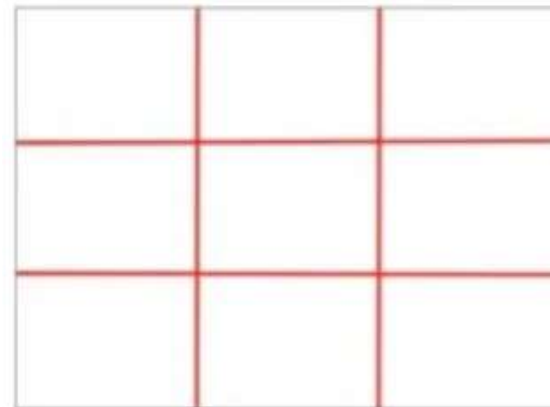




Focus

Rule of Third:

- gives also four important lines
- useful positions for elements in photo





Implementation

Importing image to our notebook

```
! wget -q https://raw.githubusercontent.com/.../snail.JPG  
img_snail = cv2.imread("snail.JPG")  
img_snail = cv2.cvtColor(img_snail, cv2.COLOR_BGR2RGB)  
plt.imshow(img_snail)
```

<matplotlib.image.AxesImage at 0x7fc287d01c18>





Implementation

Function for drawing the RT-lines

```
def draw_rule_of_thirds(img, line_color, line_width):
    size = img.shape
    height = img.shape[0]
    width = img.shape[1]

    #calculating the line for the rule of thirds
    third_of_height_1 = height // 3
    third_of_height_2 = (height // 3) * 2
    third_of_width_1 = width // 3
    third_of_width_2 = (width // 3) * 2

    #drawing the line on the photo calculated above
    #drawing the horizontal lines
    img = cv2.line(img, (0, third_of_height_1), (width, third_of_height_1), line_color, line_width)
    img = cv2.line(img, (0, third_of_height_2), (width, third_of_height_2), line_color, line_width)
    #drawing the vertical lines
    img = cv2.line(img, (third_of_width_1, 0), (third_of_width_1, height), line_color, line_width)
    img = cv2.line(img, (third_of_width_2, 0), (third_of_width_2, height), line_color, line_width)
    return img
```



Implementation

Calculating the height and width of the image

```
height = img.shape[0]  
width = img.shape[1]
```



Implementation

Calculating the position of the lines

```
#calculating the lines for the rule of thirds
third_of_height_1 = height // 3
third_of_height_2 = (height // 3) * 2
third_of_width_1 = width // 3
third_of_width_2 = (width // 3) * 2
```



Implementation

Drawing all lines

```
#drawing the lines on the photo calculated above
#drawing the horizontal lines
img = cv2.line(img, (0, third_of_height_1), (width, third_of_height_1), line_color, line_width)
img = cv2.line(img, (0, third_of_height_2), (width, third_of_height_2), line_color, line_width)
#drawing the vertical lines
img = cv2.line(img, (third_of_width_1, 0), (third_of_width_1, height), line_color, line_width)
img = cv2.line(img, (third_of_width_2, 0), (third_of_width_2, height), line_color, line_width)
return img
```



```
draw_rule_of_thirds(img_snail, (255, 255, 255), 5)
plt.imshow(img_snail)
```



Implementation

Sample 1

```
draw_rule_of_thirds(img_seagull, (255,255,255), 17)  
plt.imshow(img_seagull)
```

<matplotlib.image.AxesImage at 0x7fc285417eb8>



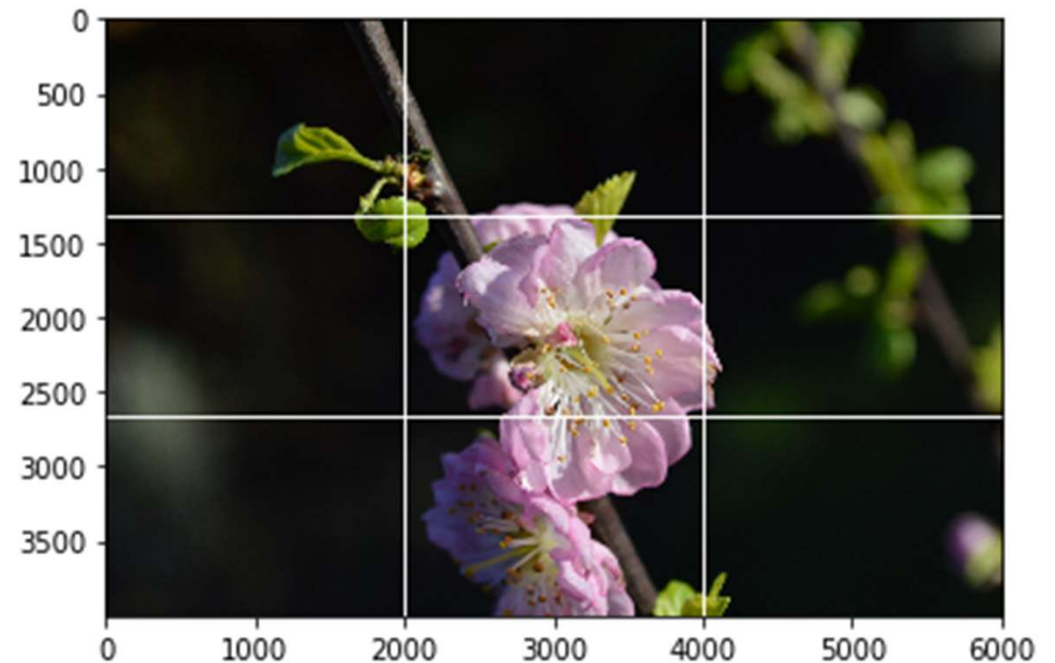


Implementation

Sample 2

```
draw_rule_of_thirds(img_flower, (255, 255, 255), 5)  
plt.imshow(img_flower)
```

<matplotlib.image.AxesImage at 0x7f4af3f42390>





Challenges

- the RT-lines only appear with the right thickness value
- it is difficult to find the right thickness for the lines



Next Steps

- detecting the objects of interest in the photo
- calculating the points of interest respectively the intersections of the RT-lines



Sources

Literature / Internet

[1] <https://digital-photography-school.com/rule-of-thirds/>