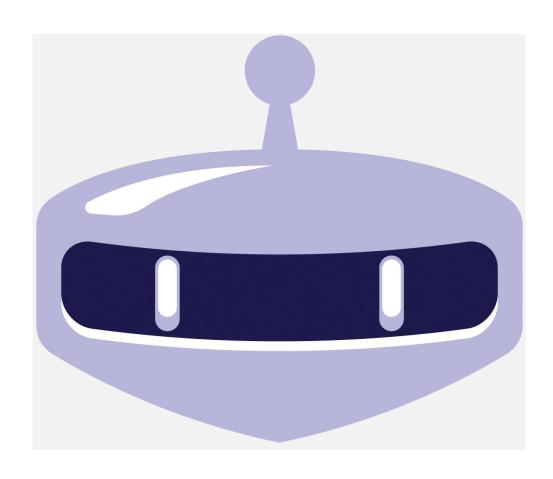
UP Competitive Robotics Club

# Workshop 1: Intro to Competitive Robotics

Slides by: Pio Mendoza and Alfred Abanto



**ABOUT US** 

### Who we are

The UP Competitive Robotics Club is an organization established to pursue and facilitate competitive robotics.





### What do we do?



#### Pursue competitive robotics

Introducing and popularizing competitive robotics to universities and schools in the Philippines



#### Host robotics tournaments

Pushing for people to get creative and be better at robotics



## Develop robotics-based solutions

Helping communities and localities through robotics research

# Speaker





## Alfred Jason Abanto

- UP CRC Chief Executive Officer
- Synergy: Revolutionary Robotics 2019 Head
- Synergy: Revolutionary Robotics 2018 Head
- Revolutionary Robotics workshop speaker 2019
- Revolutionary Robotics workshop speaker 2018
- Dagitab 2019: Day 4 Guest speaker
- Smartfox Data solutions Inc. Developer

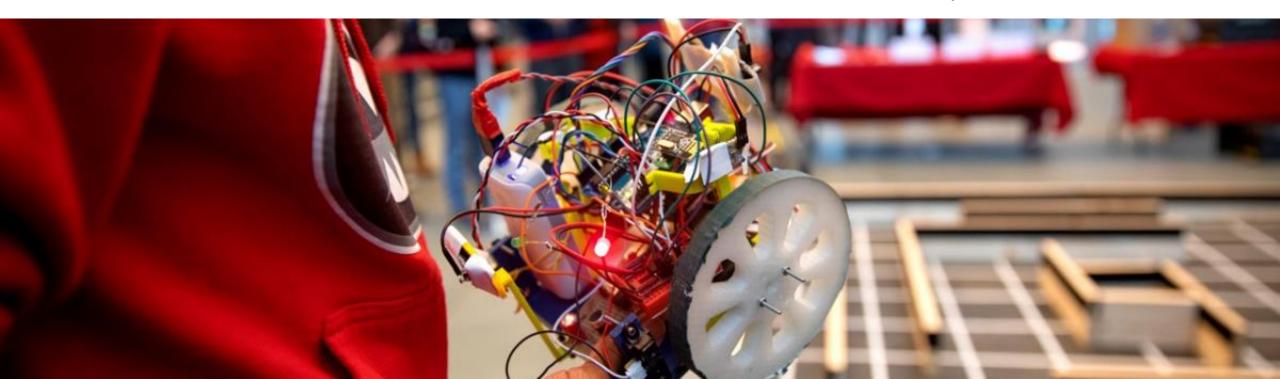
# Questions

Go to menti.com and type in the code –here-

**UP Competitive Robotics Club** 

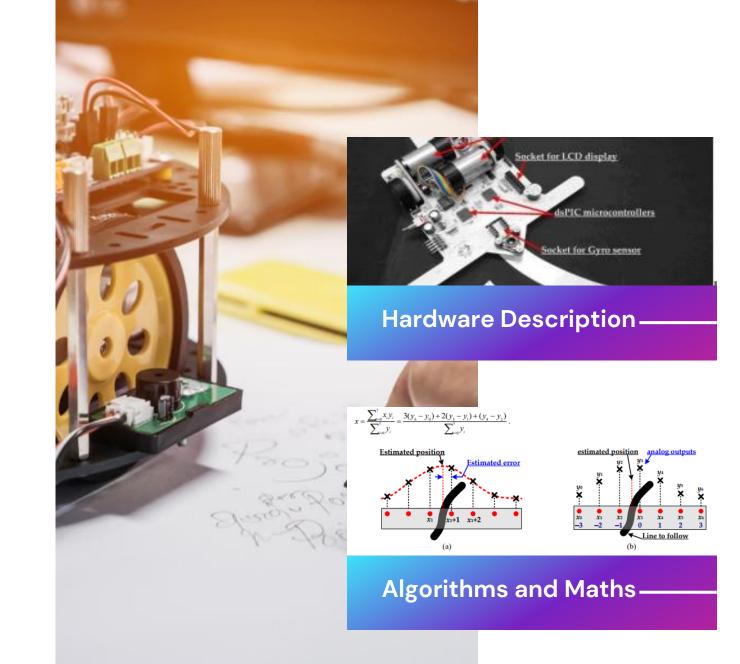
## Why competitive robotics?

Besides being really cool; It allows anyone to practice robotics and provides an opportunity for anyone to learn and develop new skills that might eventually lead to better opportunities. It's a way forward for not only students and enthusiasts, but also for small businesses and the local industry.



# How do I start? - with research

 An intelligent line-following robot project for introductory robot courses by: Juing-Huei Su, Chyi-Shyong Lee, Hsin-Hsiung Huang, Sheng-Hsiung Chuang
 & Chih-Yuan Lin Lunghwa University of Science and Technology Taoyuan County, Taiwan



## Building a maze solving robot



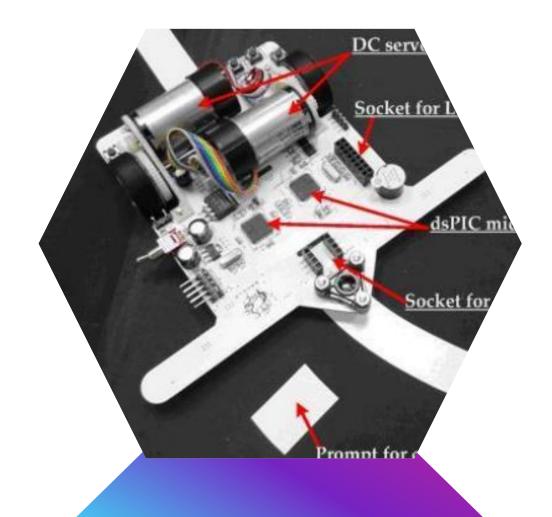
#### Microcontroller

- Small footprint
- Convenient to use



#### **Geared Motors**

- Low current draw
  - High torque





#### Sensors

- Easy to source
  - Low-cost



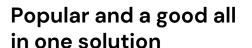
## Drivers and power circuits

- Low-cost
- Easy to source

#### **UP CRC**







Arduinos are open source so clones are very common and easy to source. It also comes with its own power circuits



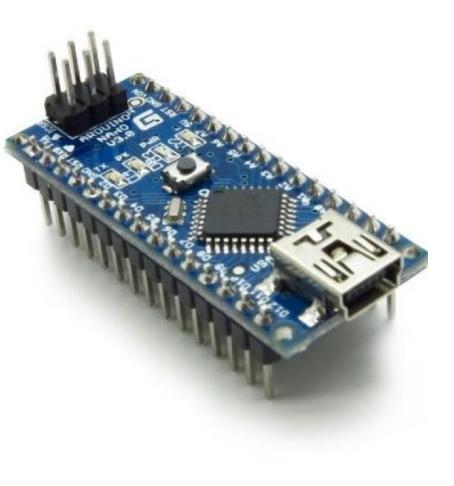
#### Easy to program

Arduinos also have onboard communication chips and a USB connector which makes it easy to program. You can also transfer your program to other boards easily

# Microcontroller - Arduino



#### **UP CRC**



### Crash course Arduino

Functions you need

#### digitalRead()

Returns 1 or 0 if the pin measures 5V and 0V respectively.

#### digitalWrite()

Applies 5V of 0V to the pin.

#### analogRead()

Returns a value between 0-1023 which represents the measured voltage measured at the pin (from 0V to 5V)

#### analogWrite()

Applies a voltage from 0V to 5V based on the input value ranging from 0 to 255 respectively

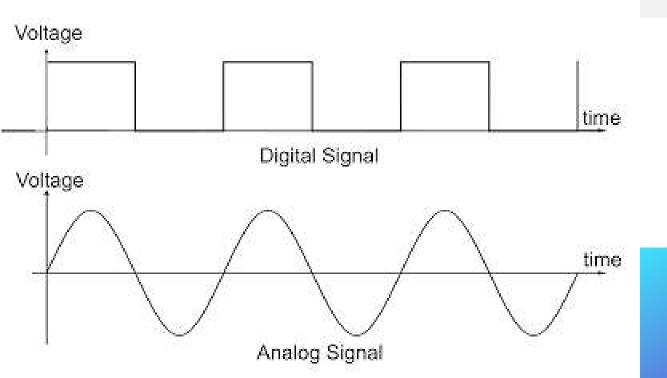
#### pinMode()

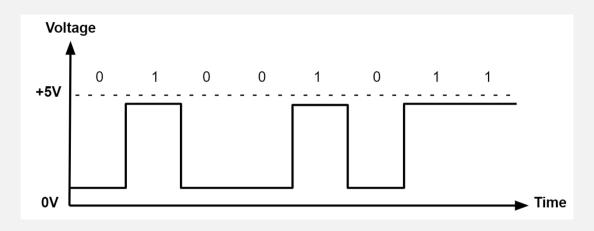
Sets the pin as an output or and input



## **Analog vs Digital**

And why it matters to you





Analog signals have a more continuous range of values

(ex. 0V, 3.3V, 2.5V) while **Digital signals** only have a high or low value (ex. 0V and 5V for low and high respectively)

Powered by Google



Analog

### **Geared DC motors**

Old reliable





**Brushed DC motors** are simple to control and can be salvaged from almost everywhere. You can easily control 2 motors using a single **L293D** motor driver

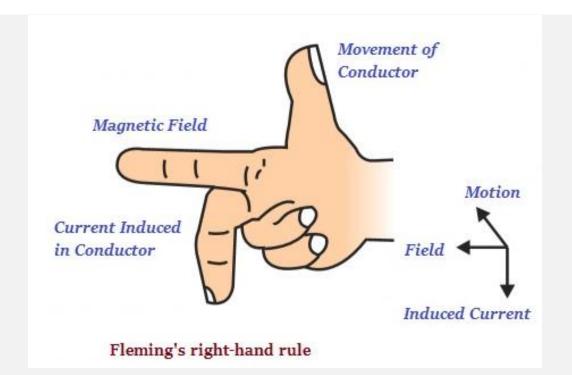
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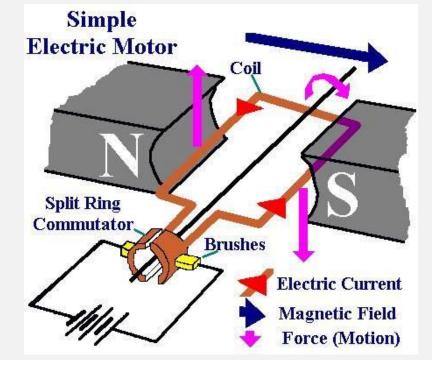


How do motors work?

## How do they work?

Black magic

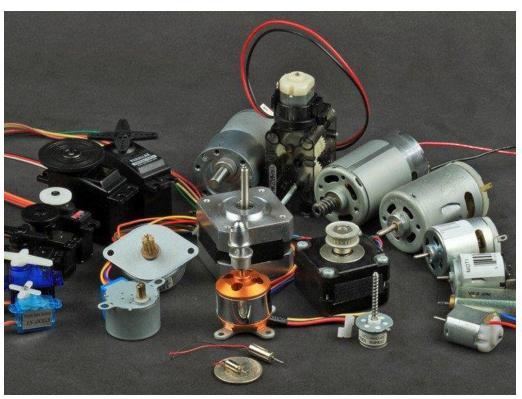




For brushed DC motors, the dc voltage at the terminals causes current to flow through the coils. The magnets inside the motor produce the electric field that turns the coil. Thus, if more voltage is supplied, more current will flow and the motor will turn faster

Voltage make motor go brr





How do I pick?









#### Parts Help

## Picking a motor

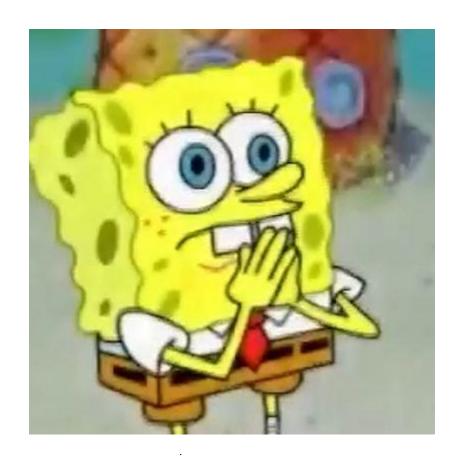
## Generic plastic geared motor (upper left)

- Low-cost
- Needs high current
- Power hungry
- Low-torque

## N20 geared motor (upper right)

- Costly
- Low current consumption
- High-torque

Geared motors are encouraged since they allow you to be able to control your speed and position much easier. They also enable you to move much more weight for the same amount of current. This is important since current output will dictate your motor driver options.



But how do you control them?

#### **UP CRC**







#### Very affordable

Perhaps the easiest driver to source here locally per piece.

Note: take account current limitation



#### Convenient

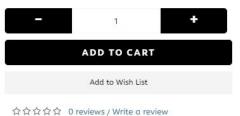
Straight forward control, small footprint and does not need any supporting circuitry.



Dual H-Bridge Motor Driver for DC or Steppers 600mA L293D

Product Code: AK005 Availability: 60

₹45



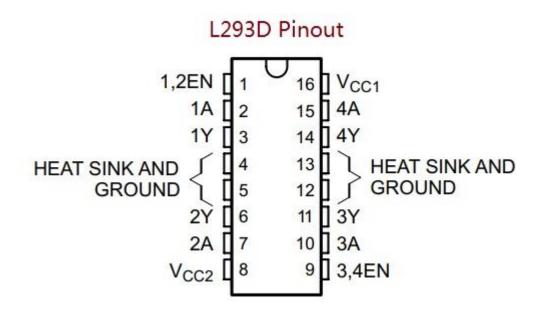


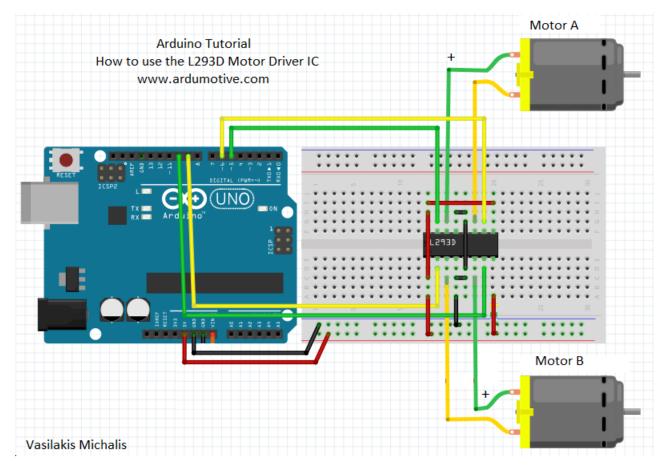


# Other motor driver options - L298N



But how EXACTLY do you use them?





## you'll find out in our hands-on activity



Go to menti.com and type in the code –here-

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# **Closing Remarks**



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