Proposition: Let T: V > W be a linear transformation and let {v,,..., vn} be a spanning set of V. Then span { To, Ton3 = RCT). Proof: Let we R(T) => 3 vev st. To=w Since {v,..., vng is a spanning set of V, 3 a,..., agir $v = a_1 v_1 + \cdots + a_n v_n$ $w = Tv = T(a_1v_1 + \cdots + a_nv_n) = a_1Tv_1 + \cdots + a_nTv_n$ E span { To, ,..., Ton}

Hence
$$R(T) \subseteq Span \{To_1, ..., Ton\} \subseteq R(T)$$

$$\Rightarrow R(T) = Span \{To_1, ..., Ton\} \longrightarrow$$

Proposition: Let T:V > W be an injective linear transformation. Suppose {v,,...,vn} be a linearly independent set in V. Then the set {Tv,,..., Tvn} is linearly independent.

Peroff: Let $a, Tv, + \cdots + a_n Tv_n = 0$ $\Rightarrow T(a, v, + \cdots + a_n v_n) = 0$

$$= 0$$

=) {To,,..., Tony is linearly independent.

Vs W be finité dimensional vector spaces and let Theorem: Let, T:V -> W be a bijective linear

transformation. Then dim (V) = dim (W).

Proof: Let $B = \{v_1, ..., v_n\}$ be a basis of VSince B is a spanning set, by the proposition above, $\{Tv_1, ..., Tv_n\}$ spans R(T). Since T is surjective, we have R(T)=W. $\Rightarrow \{Tv_1, ..., Tv_n\}$ spans W. By the proposition above, Since T is injective k. B is linearly independent, we have $\{Tv_1, ..., Tv_n\}$ is linearly independent k hence a basis. Therefore dim(W) = n = dim(V). Conversely, it {To,..., Ton } is a basis of W, then {vi,..., vn } is a basis of V.

Theorem: Let V be a finite dimensional vector space and let $\{v_1, \dots, v_n\}$ be a basis of V. Let $\{w_1, \dots, w_n\}$ be a subset of W (a vector space). Then there exists a unique linear transformation $T: V \to W$ s.t $Tv_j = w_j$ for $j = 1, \dots, n$.

Uniqueness_ Proof: If S and T be two linear transformations $g + Sv_j = w_j = Tv_j$ for j=1,2,...,nLet v E V. => 7 an..., an s.+ v= and, t... + andn. Then So = $S(a_1v_1 + \cdots + a_nv_n) = a_1Sv_1 + \cdots + a_nSv_n$ $= a_1 \omega_1 + \cdots + a_n \omega_n$ lily To = a, To, t. . + anTon $= a_1 w_1 + \cdots + a_n w_n = S v$

Existence:

Let veV and ai,...,aneir best

 $19 = a_1 \vartheta_1 + \cdots + a_n \vartheta_n$

We define Tre := a, w, + ... + anwn.

Well-definedness follows from the fact that every vector of V can be written as a unique linear combination of basis vectors.

Let $v, v' \in V$ and $v = a_1v_1 + \cdots + a_nv_n + v' = b_1v_1 + \cdots + b_nv_n$

Goal: T(v+v') = Tv+Tv' $v+v' = (a_1+b_1)v_1+\cdots+(a_n+b_n)v_n$ $T(v+v') = (a_1+b_1)w_1+\cdots+(a_n+b_n)w_n$ $Tv = a_1w_1+\cdots+a_nw_n$ $Tv' = b_1w_1+\cdots+b_nw_n$ $Tv' = (a_1+b_1)w_1+\cdots+(a_n+b_n)w_n = T(v+v')$ Check that $T(v) = cTv + v \in V \in CeR$.

2

Example: We know that the

erotation by Omaps (1,0) to (coso, sino) 2

 $(011) \longrightarrow (-8100, \cos 0).$

Our notation can be defined

$$R(x_1y) = xR(1,0) + yR(0,1)$$

$$R\left(\frac{x}{y}\right) = \frac{\cos\theta - \sin\theta}{\sin\theta} \left(\frac{x}{y}\right).$$



