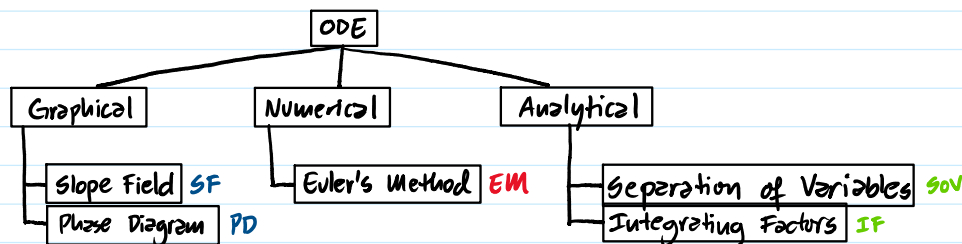


Objectives:

1. Summarize concepts on solving 1st-order ODEs.
 2. Review 1st-order ODEs that model physical systems and how to interpret them.
- Ways to solve an ODE we have presented so far.



→ Note that you can use multiple methods simultaneously to analyze an ODE.

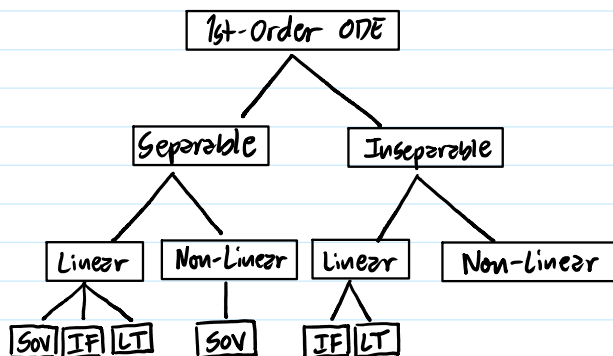
- Analytical Methods and the class of ODEs.

• Forms:

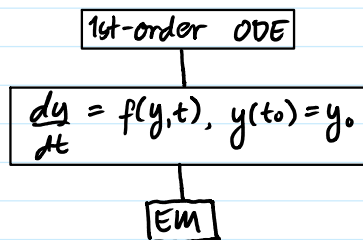
→ Separable: $\frac{dy}{dt} = f(y)g(t)$

→ 1st-order linear: $\frac{dy}{dt} + P(t)y = Q(t)$

- If $P(t)$ is a constant, then LT is "easy" to apply.



- Numerical Methods and the form of ODEs.



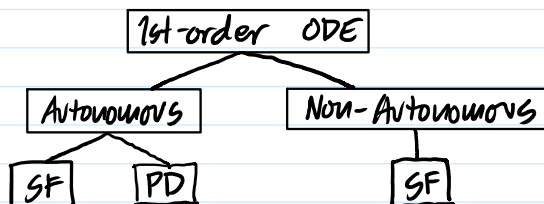
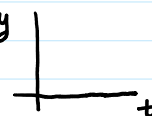
- Graphical methods and the class of ODEs

• Forms:

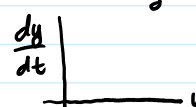
→ Autonomous: $\frac{dy}{dt} = f(y)$

→ Non-Autonomous: $\frac{dy}{dt} = f(y,t)$

- Axes of SF:



• Axes of PD: in 1D: y
in 2D: $\frac{dy}{dt}$



• Modeling Physical Systems

→ Exponential growth: $\frac{dy}{dt} = Ky$ with parameter K , $y(0) = y_0$

If $K > 0$, then
increasing

If $K < 0$, then
decreasing

initial condition

→ Logistic growth: $\frac{dy}{dt} = Ky(N-y) + \beta$ with parameter K and β , $y(0) = y_0$

↓
Bifurcation parameter

If $K > 0$, then
increasing for $0 < y < N$
& decreasing for $y < 0$ & $y > N$

If $K < 0$, then
decreasing for $0 < y < N$
increasing for $y < 0$ & $y > N$

initial condition

→ Mixing model:

$\frac{dS}{dt} = \mu - \left(\frac{\beta S}{V_0 + Mt} \right)$ with parameter μ, β , and M , $S(0) = S_0$, $V_0 \leftarrow$ initial volume

↑ flow-in rate

↑ flow-out rate with changing or changing volume

rate of change salt amount

initial condition