

## Dimension

### Objectives

1. Define homogeneous and non-homogeneous systems.
2. Define "dimensions" of a vector space.
3. Define the "dimensions" of a solution set.

### Recall: Matrix-Vector Form of Linear Equations

A linear system of  $m$  equations and  $n$  variables,

$$a_{11}x_1 + a_{12}x_2 + \cdots + a_{1n}x_n = b_1$$

$$a_{21}x_1 + a_{22}x_2 + \cdots + a_{2n}x_n = b_2$$

$$\vdots$$

$$a_{m1}x_1 + a_{m2}x_2 + \cdots + a_{mn}x_n = b_m$$

can be written in matrix-vector form:

$$\underbrace{\begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix}}_A \underbrace{\begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}}_{\vec{x}} = \underbrace{\begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix}}_{\vec{b}}$$

or  $A\vec{x} = \vec{b}$ .

- $A$  is size  $m \times n$
- $\vec{x}$  is size  $n \times 1$
- $\vec{b}$  is size  $m \times 1$

### Homogeneous vs Non-homogeneous Equations

Given a linear equation  $A\vec{x} = \vec{b}$ ,

- if  $\vec{b} = \vec{0}$ , then  $A\vec{x} = \vec{0}$  is a homogeneous system.
- if  $\vec{b} \neq \vec{0}$ , then  $A\vec{x} = \vec{b}$  is a non-homogeneous system.

\* Example: Given the linear system in  $\mathbb{R}^4$ ,

$$\underbrace{\begin{bmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & 1 & -1 \\ 1 & 0 & 1 & 1 \\ 0 & 1 & 1 & -1 \end{bmatrix}}_{A \substack{\uparrow \\ 4 \times 4}} \underbrace{\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}}_{\substack{\downarrow \\ \vec{x} \\ 4 \times 1}} = \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}}_{\substack{\downarrow \\ \vec{b} \\ 4 \times 1}}$$

Here,  $\vec{b} = \vec{0}$ , so, a homogeneous system.

Solution set:

$$\xrightarrow{\text{RREF}} \begin{bmatrix} 1 & 0 & 1 & 1 & 0 \\ 0 & 1 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$x_3$  &  $x_4$  are free variables

Let  $x_3 = s$  and  $x_4 = t$ .

$$\left. \begin{array}{l} x_1 + s + t = 0 \\ x_2 + s - t = 0 \\ x_3 = s \\ x_4 = t \end{array} \right\} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} + s \begin{bmatrix} -1 \\ -1 \\ 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} 1 \\ -1 \\ 0 \\ 1 \end{bmatrix}$$

the  $\vec{0}$  vector (always for homo equations)

parametric equation for a plane

So, the basis of the solution set is which is also in the subspace of  $\mathbb{R}^4$  since it passes through the origin.

$$\left\{ \begin{bmatrix} -1 \\ -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \\ 0 \\ 1 \end{bmatrix} \right\},$$

The dimension of this solution set is 2, since there are two vectors in the solution set basis.

## Vector Space Dimensions

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The dimension of a vector space is the number of vectors in its basis.

- \* Examples:
1.  $\mathbb{R}^1$  has one dimension, only one vector in its basis
  2.  $\mathbb{R}^2$  has two dimension, only two vectors in its basis
  3.  $\mathbb{R}^3$  has three dimension, only three vectors in its basis

## Solution Set Dimensions

The dimensions of a solution set is the number of vectors in its basis, which is always less than the dimension of the linear system.

- \* Example: Given a linear system  $A\vec{x} = \vec{b}$  in  $\mathbb{R}^3$  and its solution set with 2 basis vectors, then the dimension of the solution set is 2.