

Our background



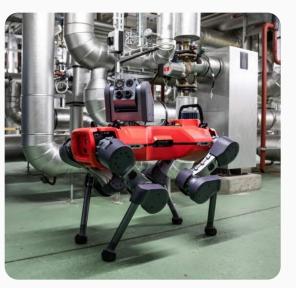
Robotics market - Segmentation















1 Industrial Robots

2 Professional Service Robots

Robotics market - Current state of OTA

- Extremely fragmented
- Often 'hacky'
- Often an afterthought
- Poor fleet visibility
- Often insecure



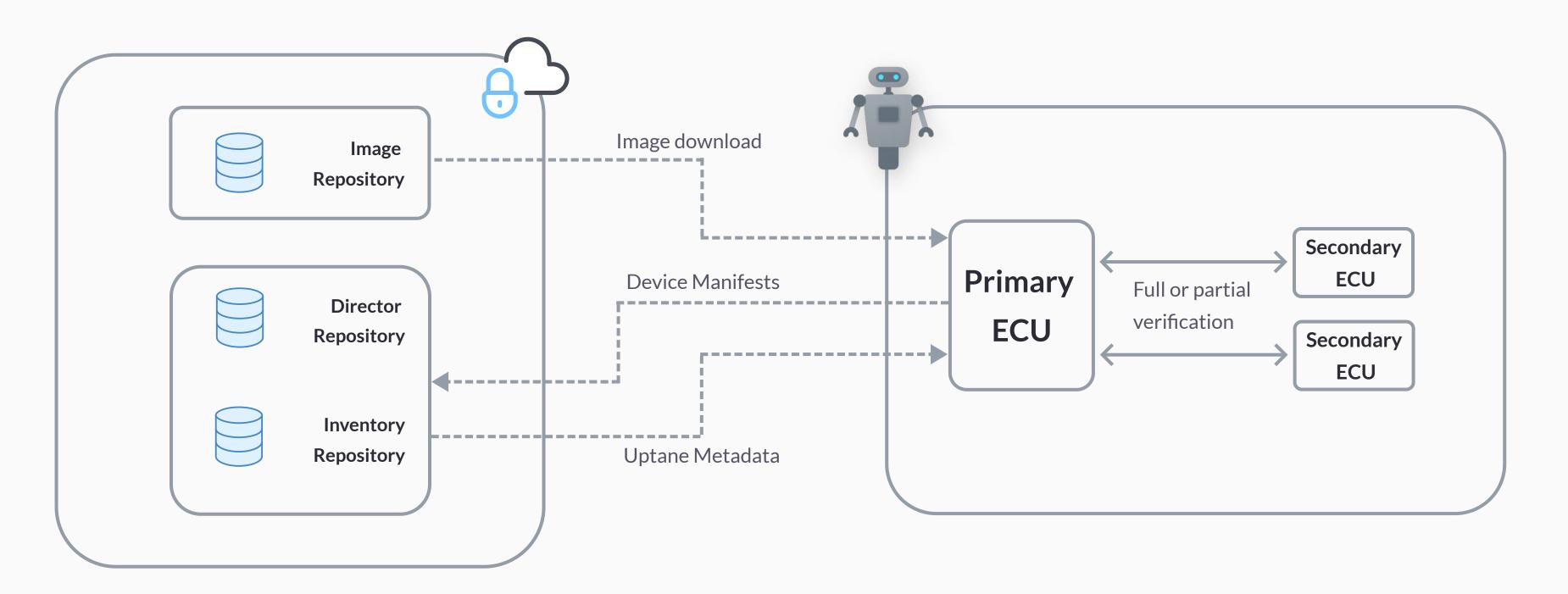


Why Uptane?

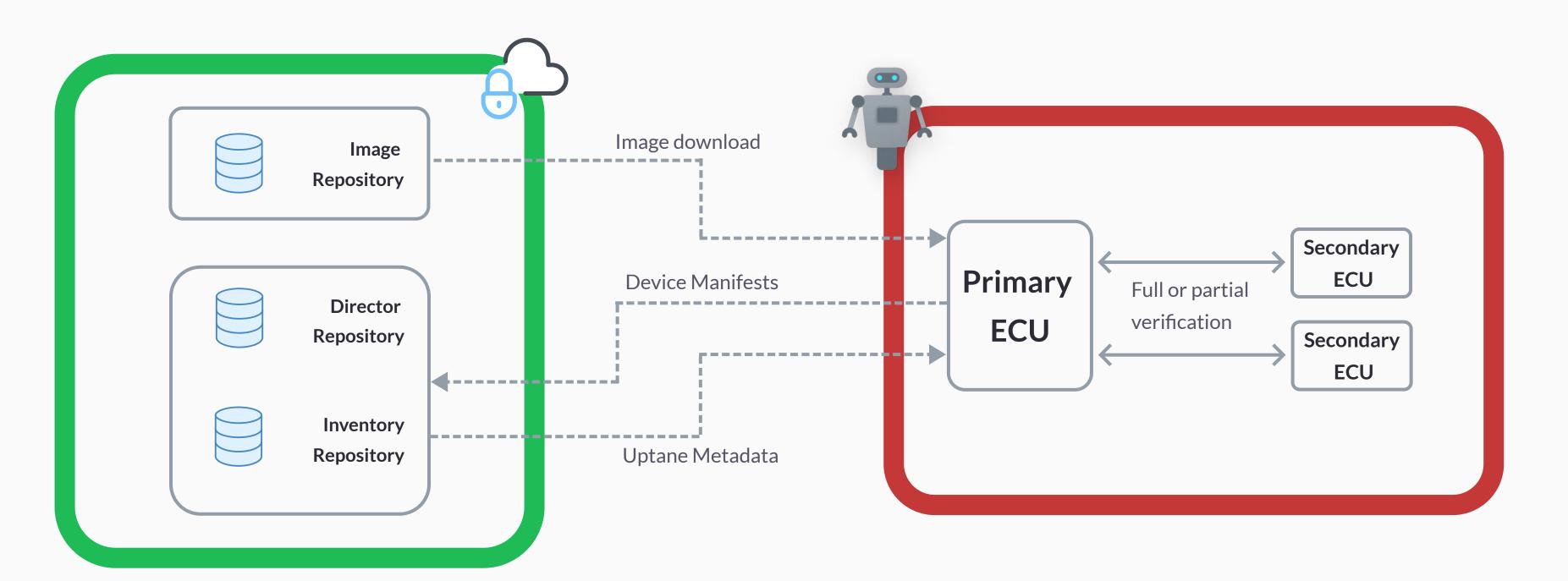
- Robots exhibit many of the same attributes as automobiles
 - Multiple ECUs
 - Large physical devices that work alongside humans
 - Often require regular software updates
 - Often operate in constrained network envirnoments
- Security is of paramount importence
 - A compromised fleet of robots could be catostrophic
 - Uptane provides the most protection from potential attack vectors we've seen from any framework



Uptane Inital thoughts



Implementation Decisions





Implementation - Prep

The Update Framework Specification

Version: 1.0.32

Last modified: 2 March 2023

https://theupdateframework.github.io/specification/latest/



Uptane Standard for Design and Implementation 2.0.0

uptane-standard-design

https://uptane.github.io/papers/uptane-standard.2.0.0.html



Implementation - Prep



The Update Framework (TUF)

A framework for securing software update systems

A 52 followers NYU Tandon School of Engineering...

https://github.com/theupdateframework



Uptane

Secure Over-The-Air Updates for Ground Vehicles

https://github.com/uptane





https://github.com/simao/ota-lith

Implementation - Image Repo

1 Initialisation



Generate key pairs for 4 roles



Generate TUF metadata for 4 roles, Root, Targets, Snapshot & Timestamp



Store the keypairs, in dev we simply write them to disk



Other app specific init, like team inititisation etc.

2 Operations



Handle new target being uploaded



Handle fetching of metadata files



Handle delegations

3 Extras



Handle the resigning of metadata



Handle deletion of repos

Implementation - Inventory Repo

1 Provisioning



Generate keypair for robot



Use keypair to issue x509 cert for robot



Associate each ECU with the robot,

2 Operations



DB schema to represent robot and associated ECUs



Most the endpoints associated with managment side, eg list devices, add device to group, get device ECUs



Implementation - Director Repo

1 Initialisation



Generate TUF metadata for 3 roles, Targets,
Snapshot & Timestamp



Store the ECUs public key so we can verify manifest reports later

2 Operations



Validate robot manifest



Handle fetching of metadata files



Creation of new metadata

3 Extras



Handling rollouts



Handle the resigning of metadata

Implementation - Challenges

- Testing can be difficult without a reference implementation
- Managing key pairs and certs is challenging
- Quite a few moving parts
- A lot of helper classes required to serialize, de-serialize, canonicalize and manipulate data.
- Some actions require a lot of operations, especially initialisations, it is hard to ensure these are always atomic



Recommendations

To other implementors

- Start with TUF and reference implementations
- Make use of the open source implementations
- Reach out to the Uptane community or other implementers for help

To the Uptane community

- A reference implementation for Uptane like python_tuf would be very useful
- Standard nomenclature for "official" Uptane sources.



Closing Thoughts

- Huge thanks to the Uptane community for being so welcoming and helpful.
- Open source repos from ATS/HERE and a special thanks to Simão Mata and Phil Wise for their time.



Questions?

