

Guiding Neural Entity Alignment with Compatibility

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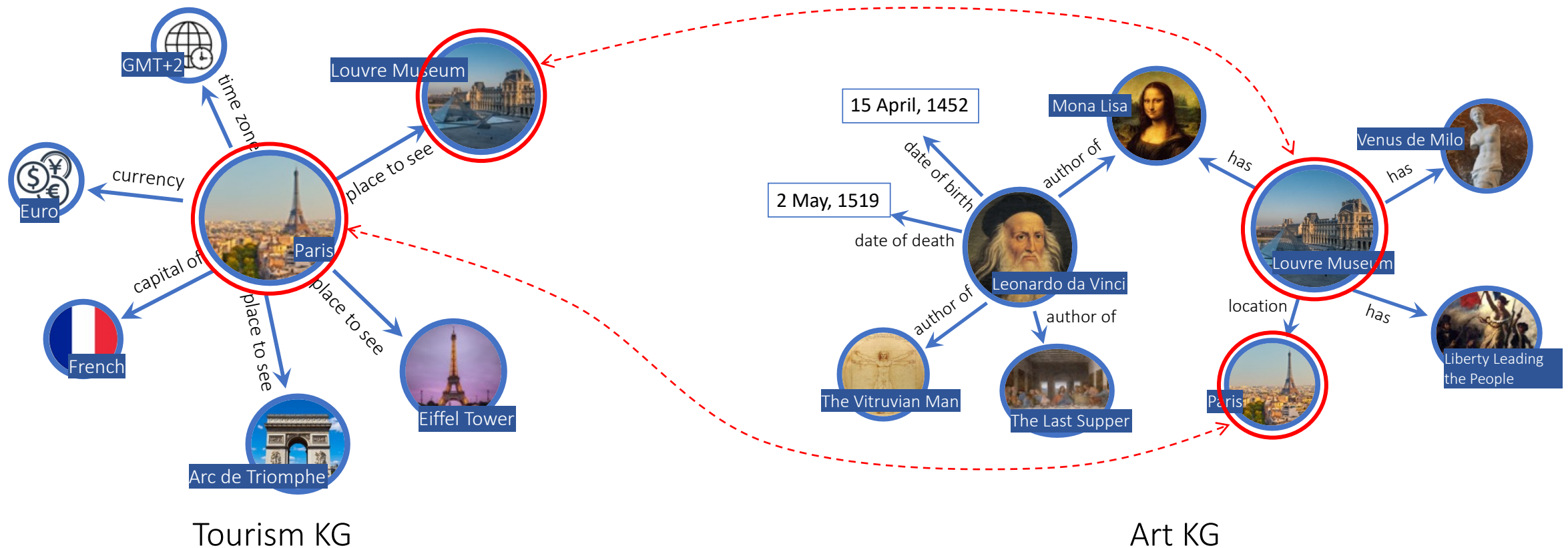
🌐 <https://uqbingliu.github.io/>

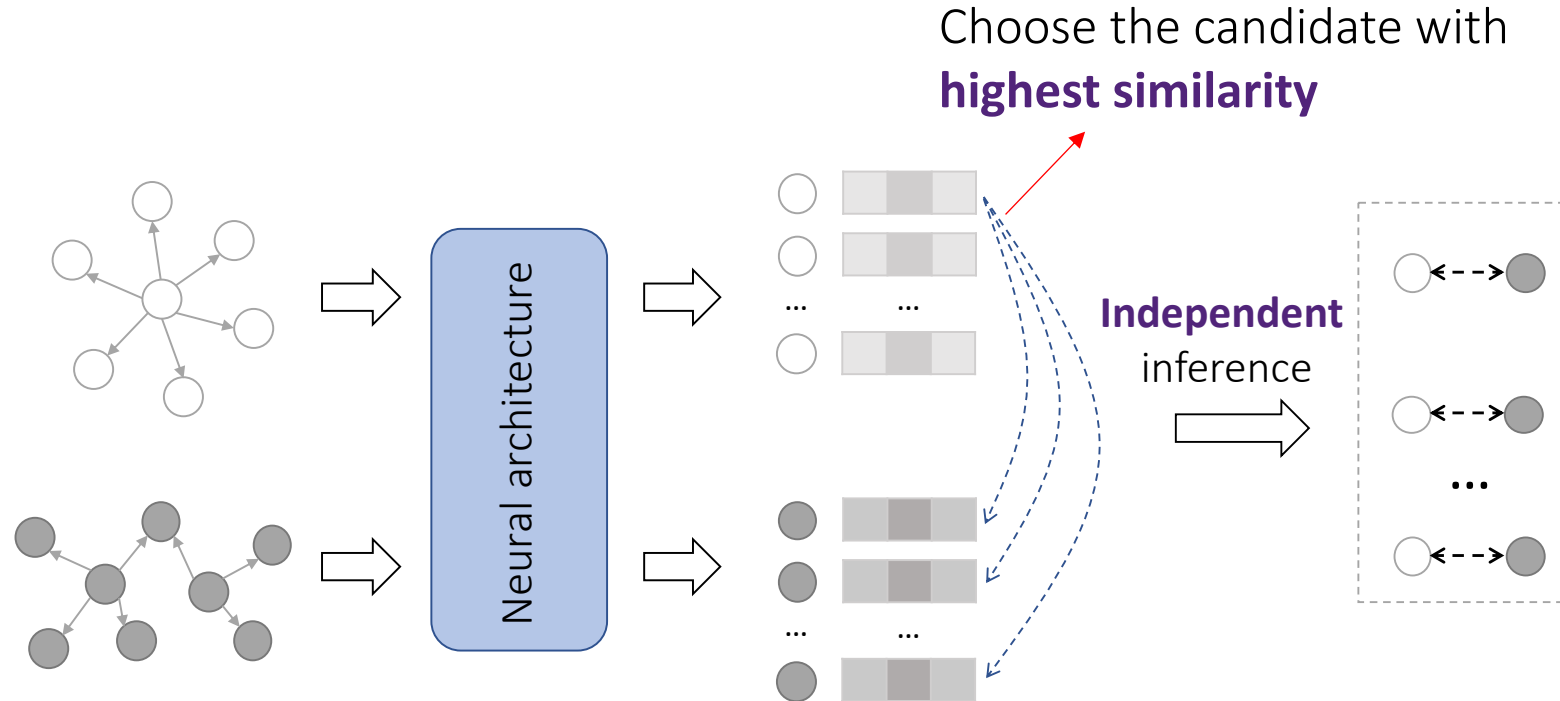
🐦 @BingLiu1011

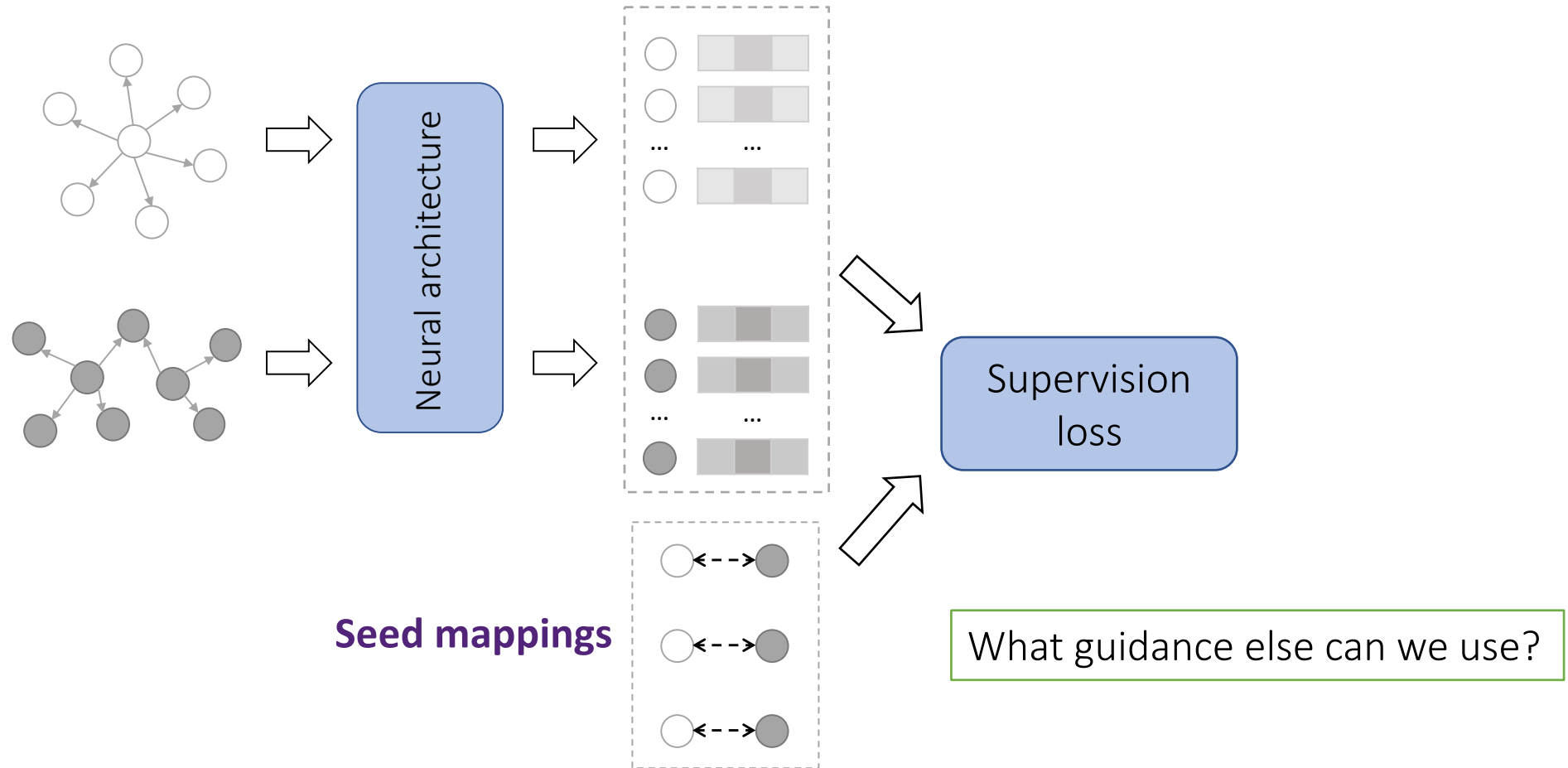


Establish **mappings** between **equivalent entities** in different Knowledge Graphs (KGs).

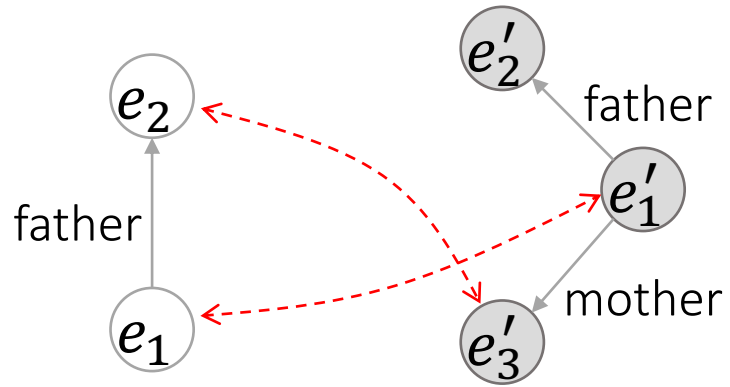
- Challenge: **Heterogeneity** of different KGs







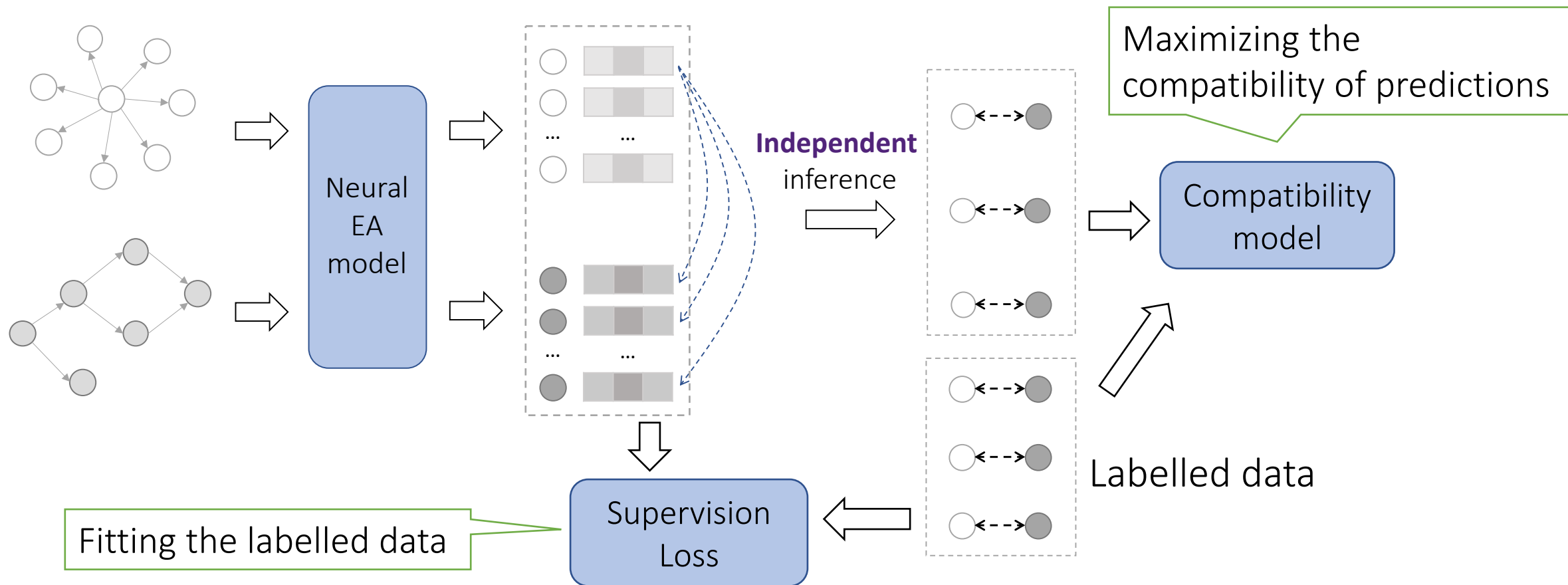
Compatibility of Mappings



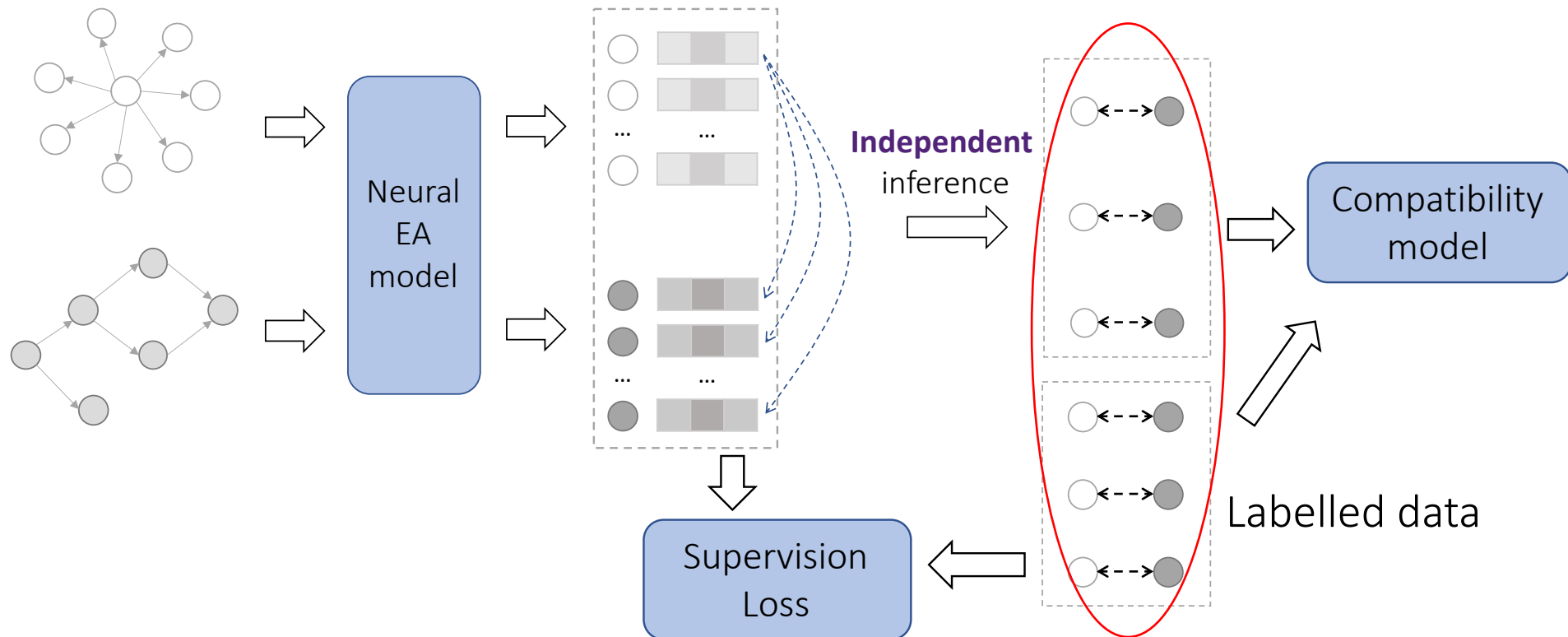
Incompatible

Another Objective: Making Compatible Predictions

Learning objectives:

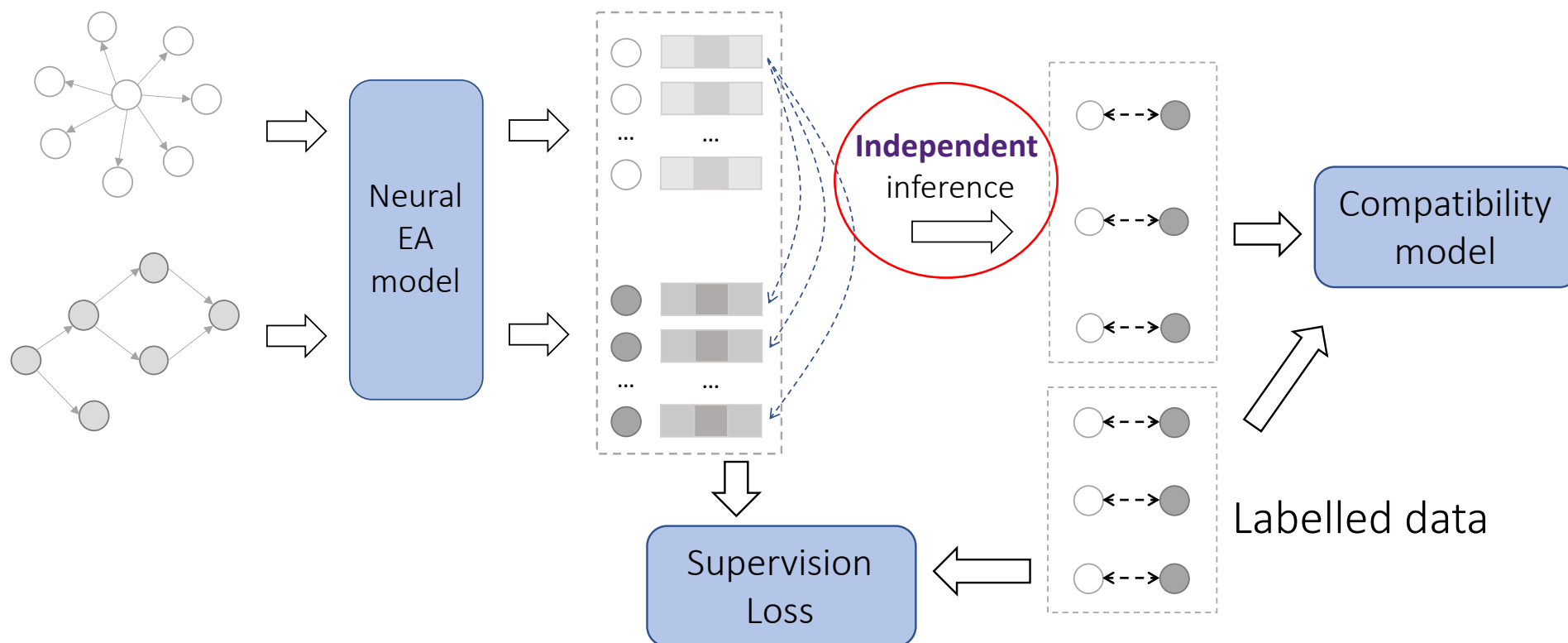


Challenge 1: How to measure the overall compatibility of a large number of mappings?

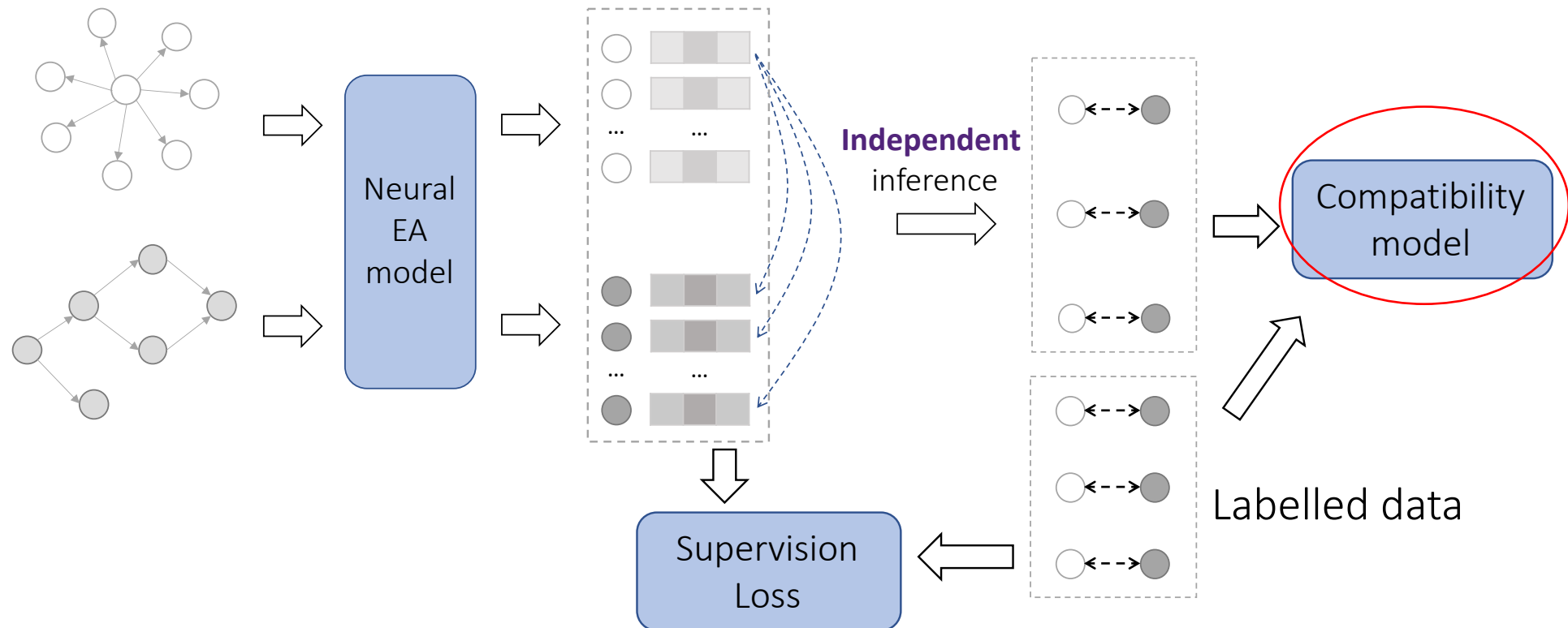


Challenge 2: How to exploit the compatibility to train the EA models ?

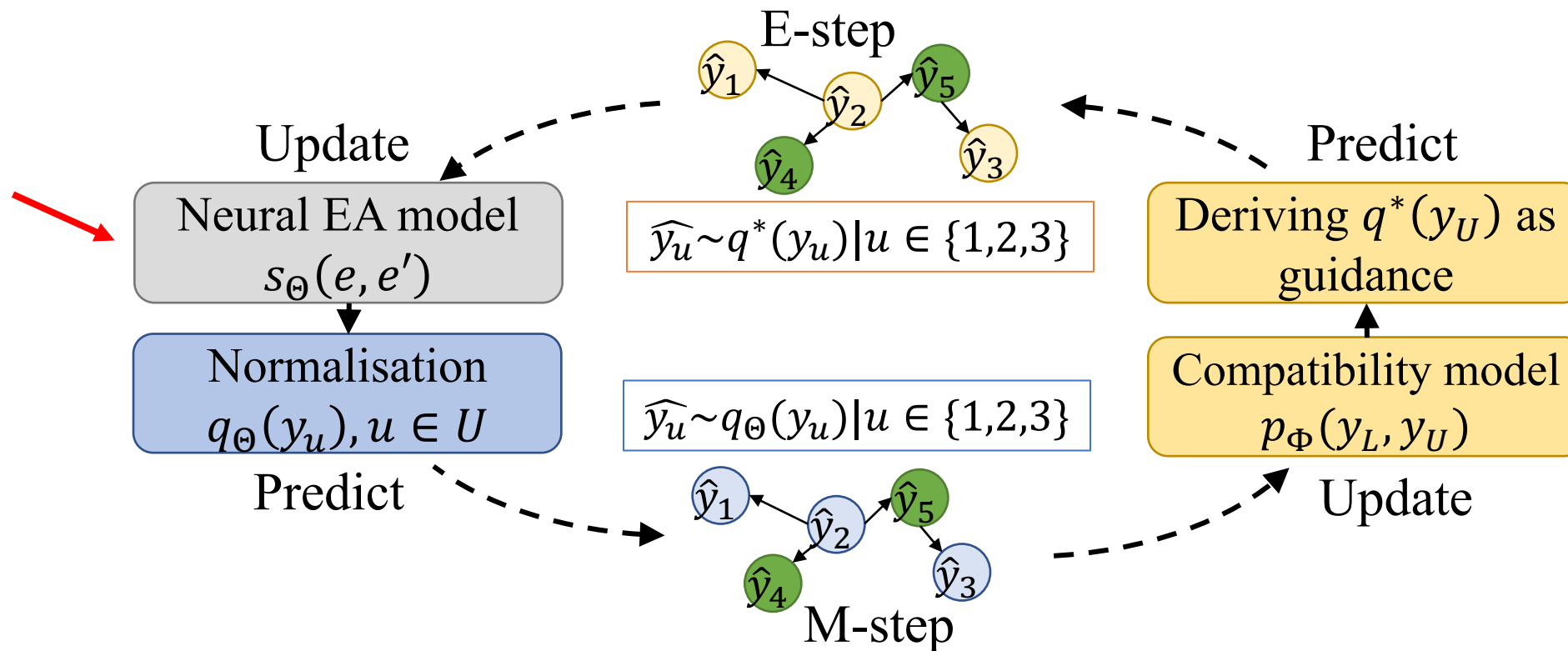
- The inference processing is not derivable.

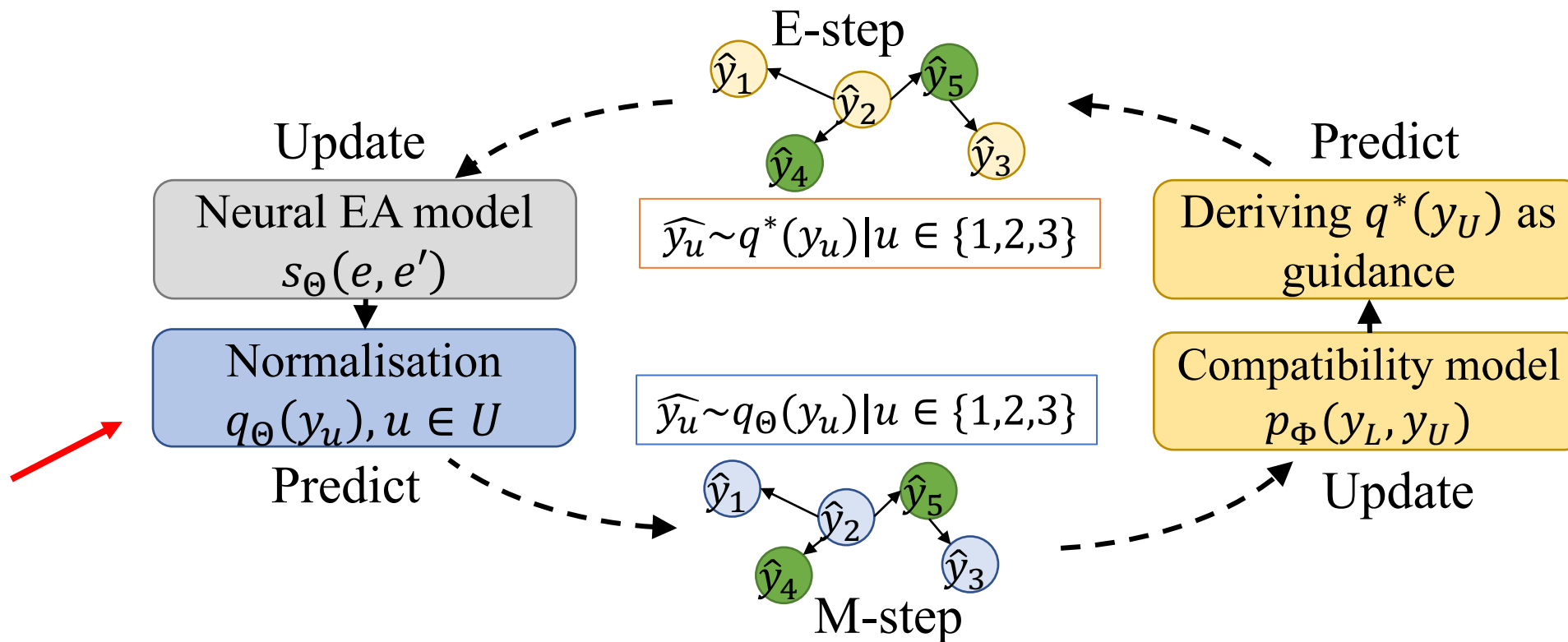


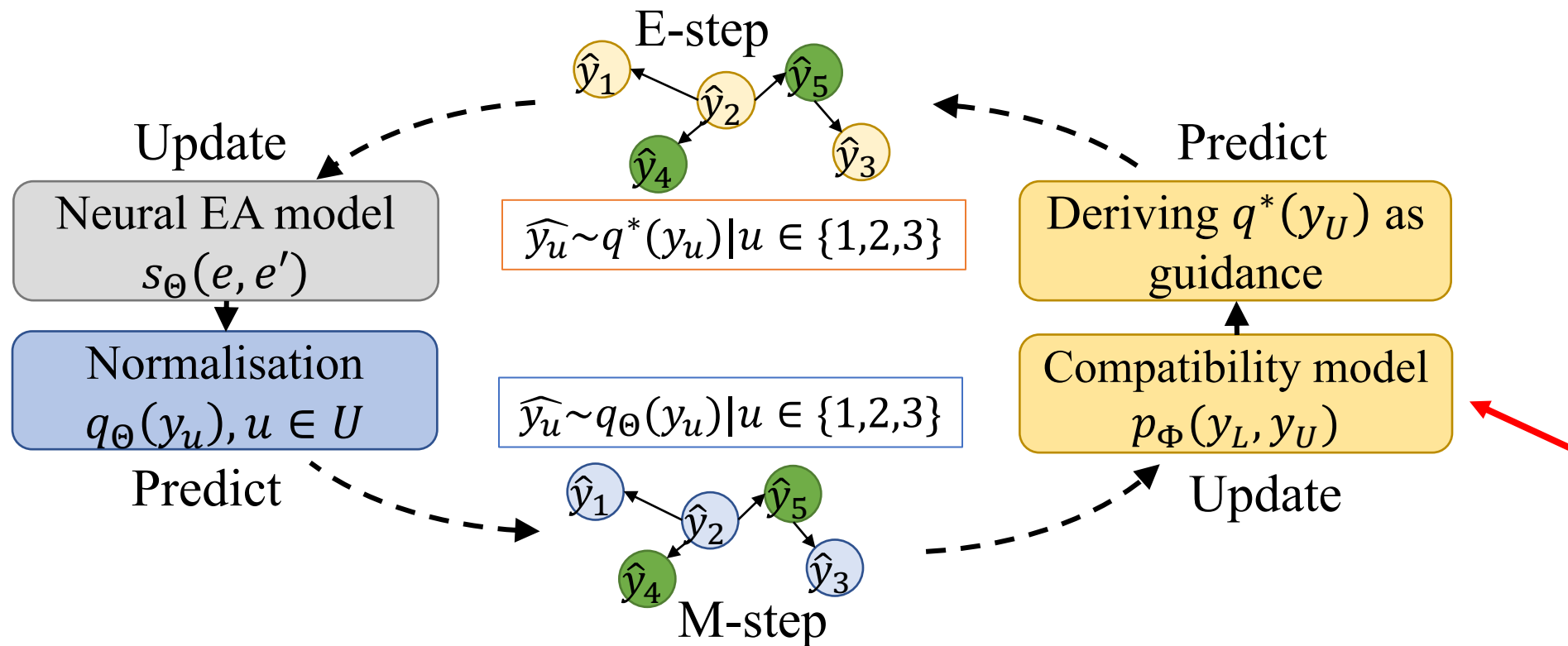
Challenge 3: How to optimize the compatibility model?

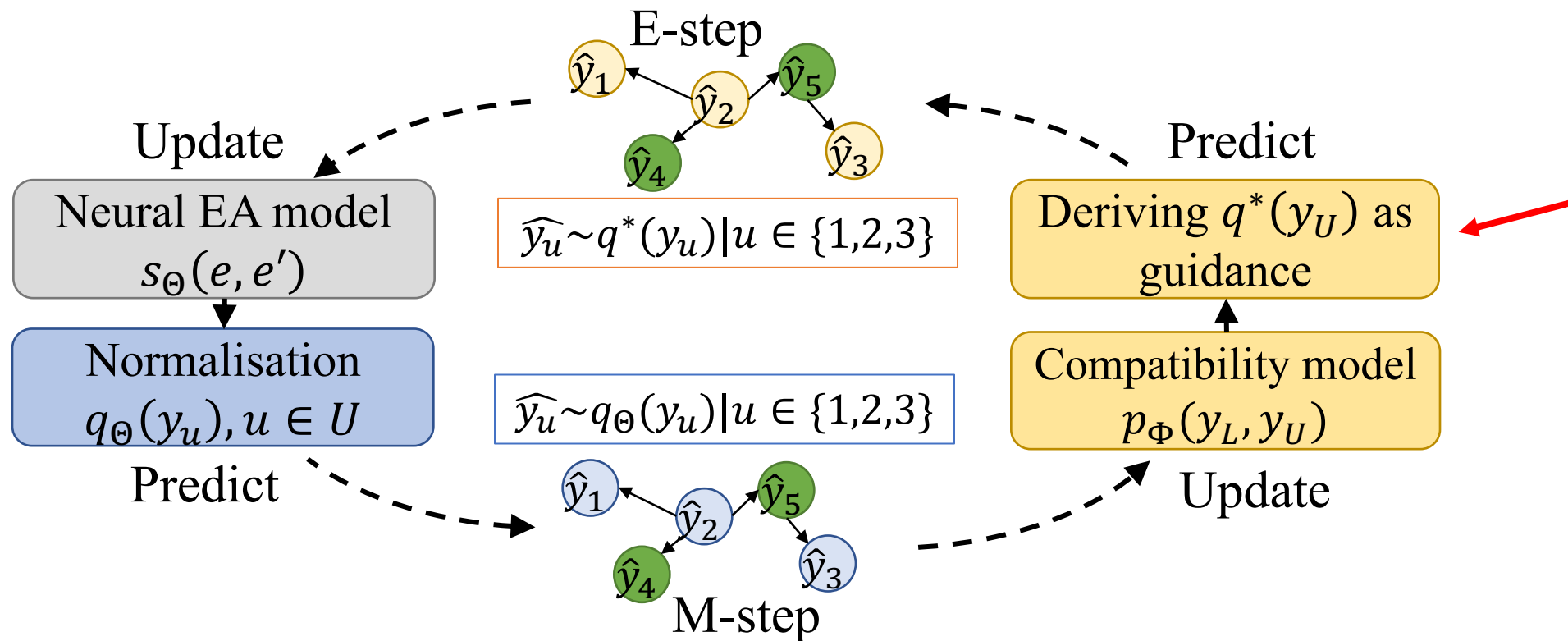


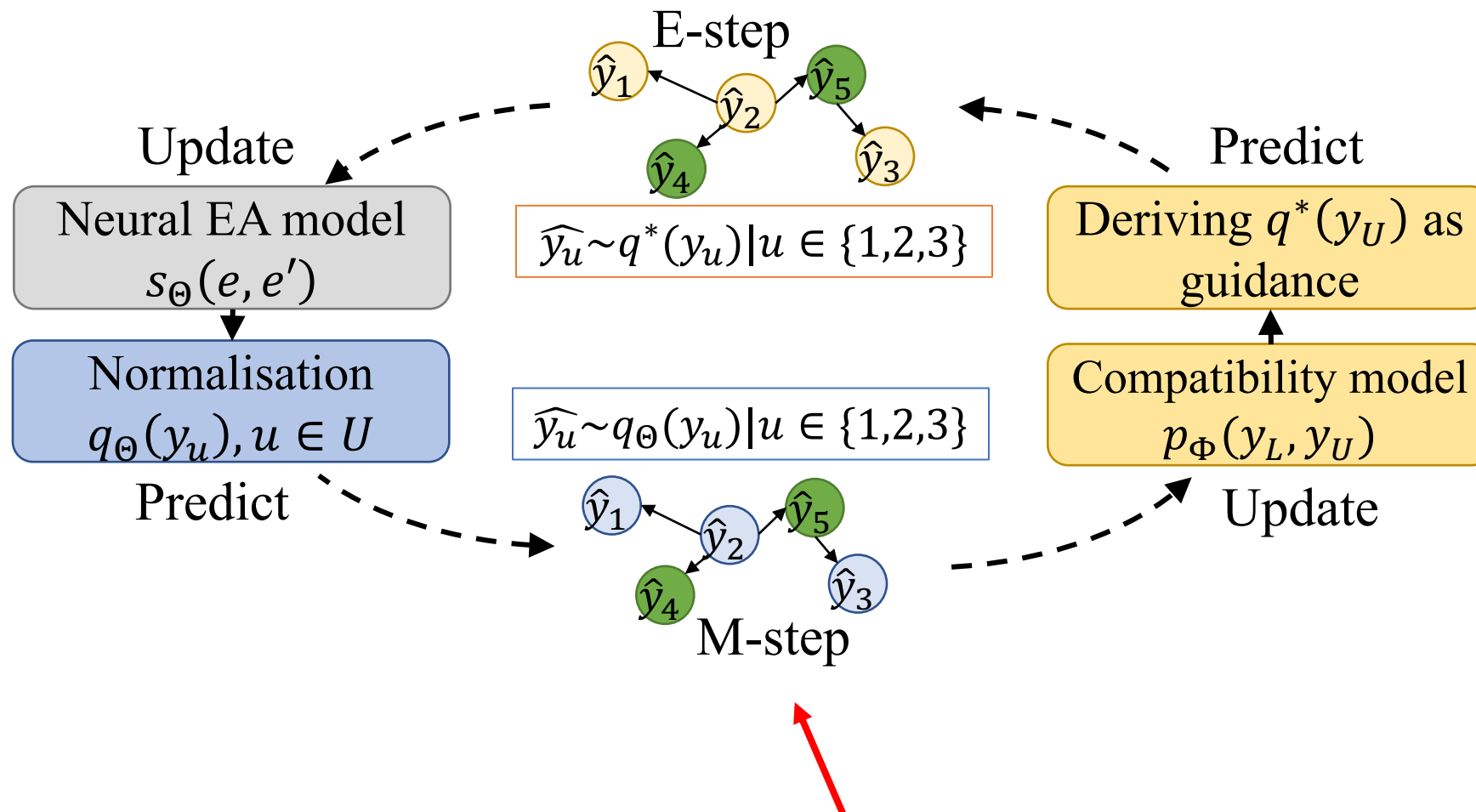
The EMEA Framework

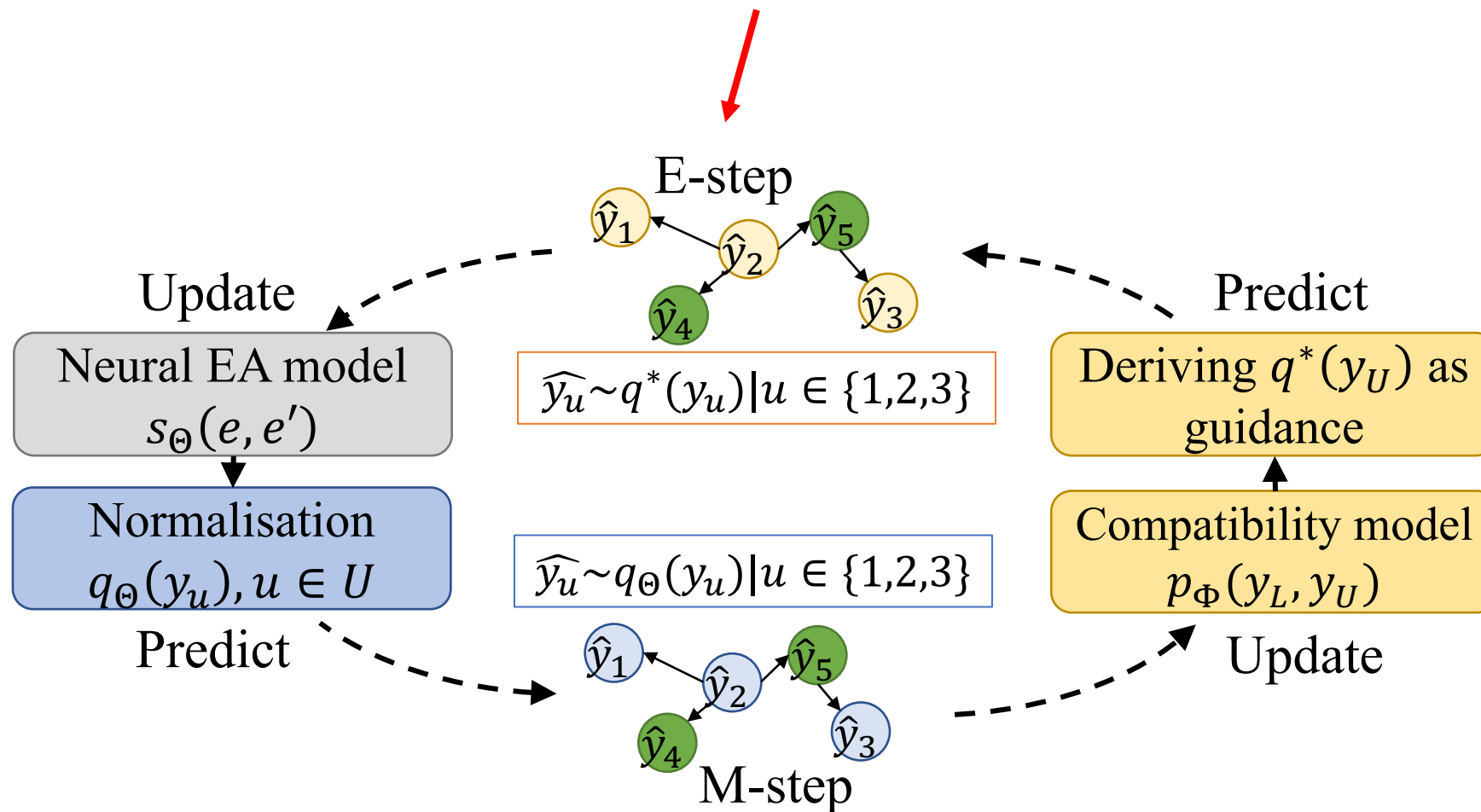




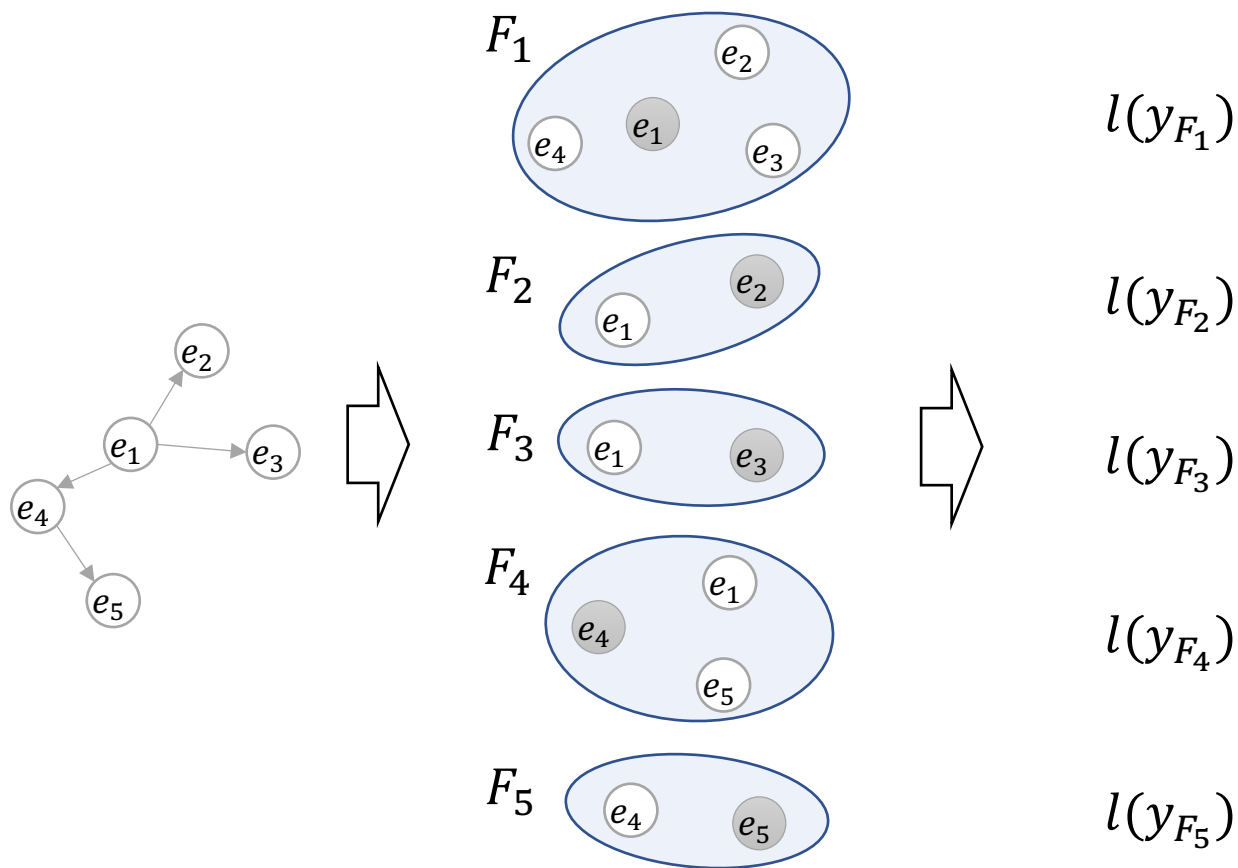








Model the **overall compatibility** with a **Probabilistic Graphical Model**



Source KG

Factor subsets

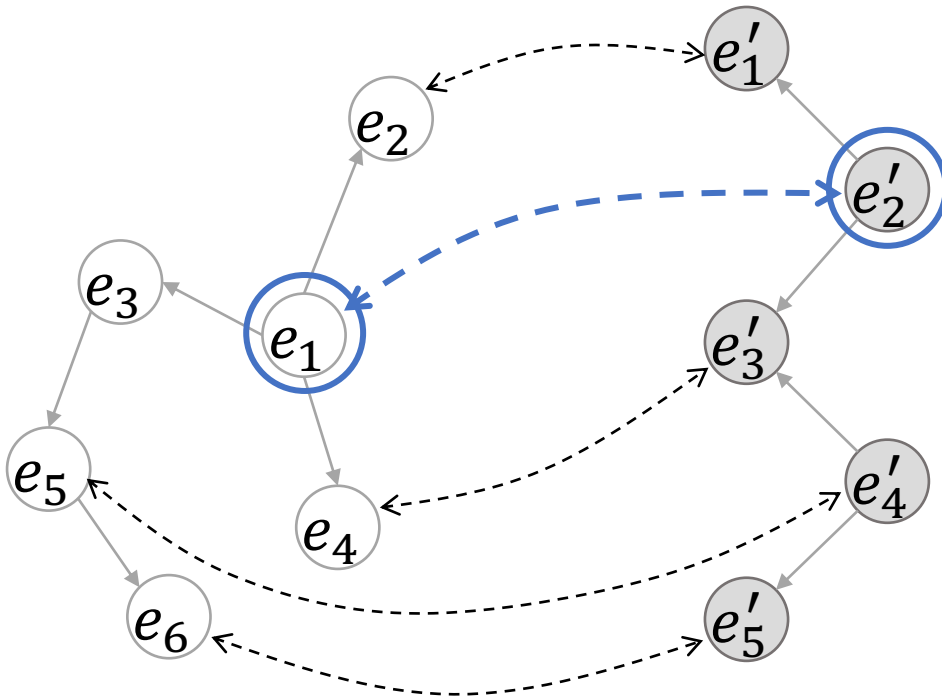
Local compatibilities

Reuse **PARIS^[1] rule** to check compatibility:

- Estimate the equivalence of two entities according to other mappings between their neighbours.

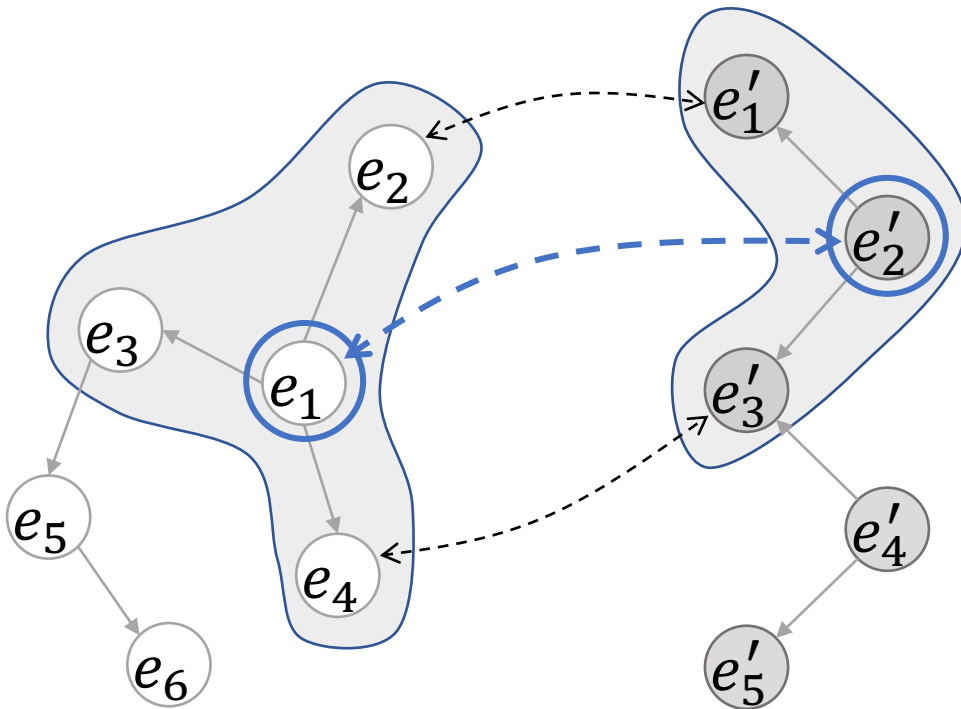
Reuse **PARIS rule** to check compatibility:

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Reuse **PARIS rule** to check compatibility:

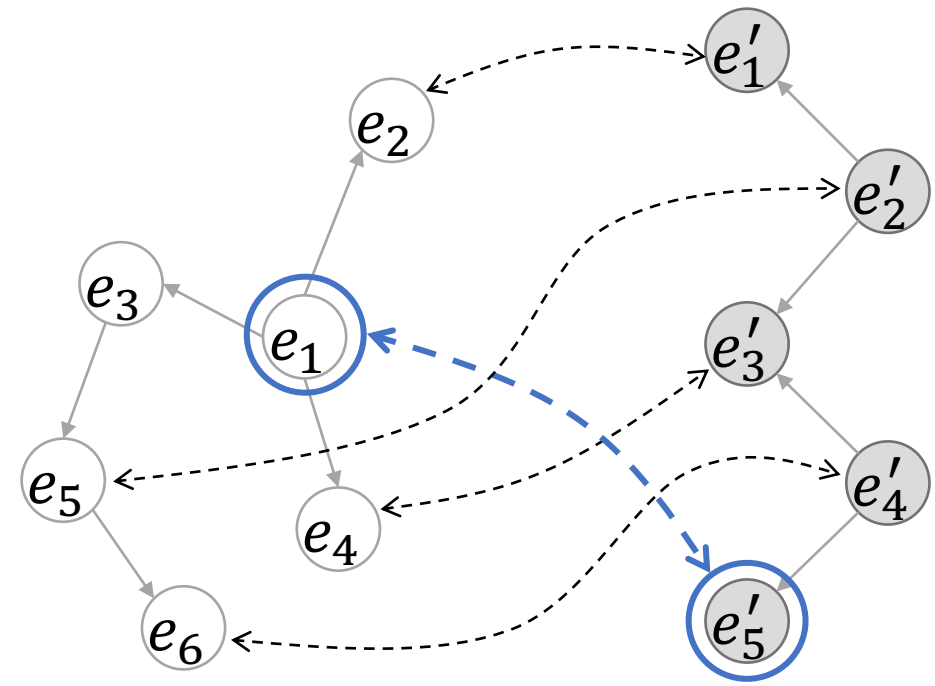
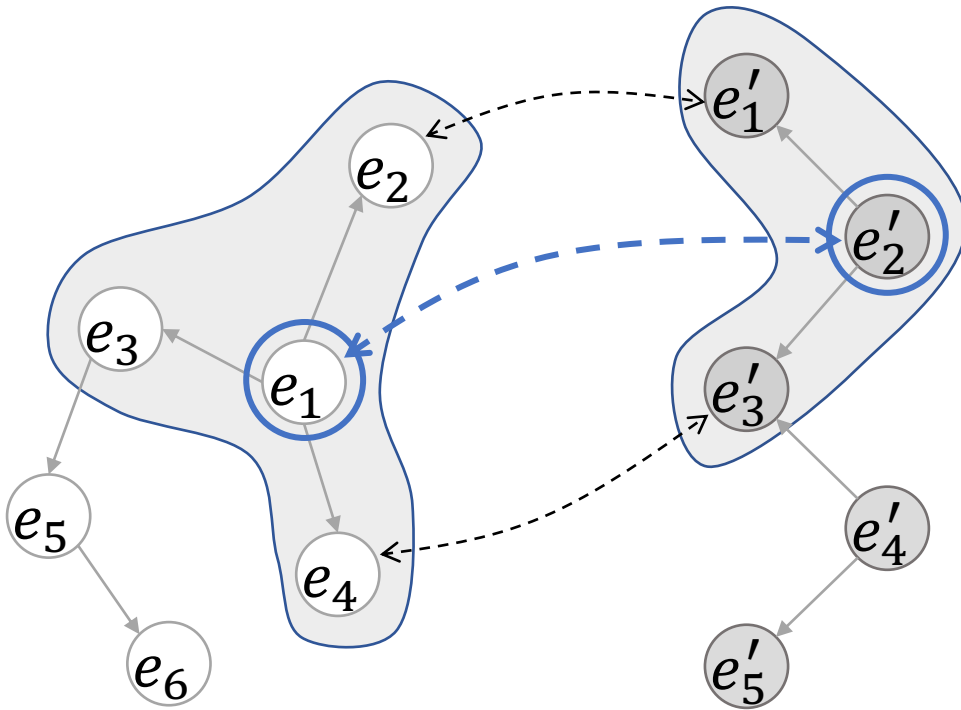
- Estimate the equivalence of two entities according to other mappings between their neighbours.



Two supporting mappings

Reuse **PARIS rule** to check compatibility:

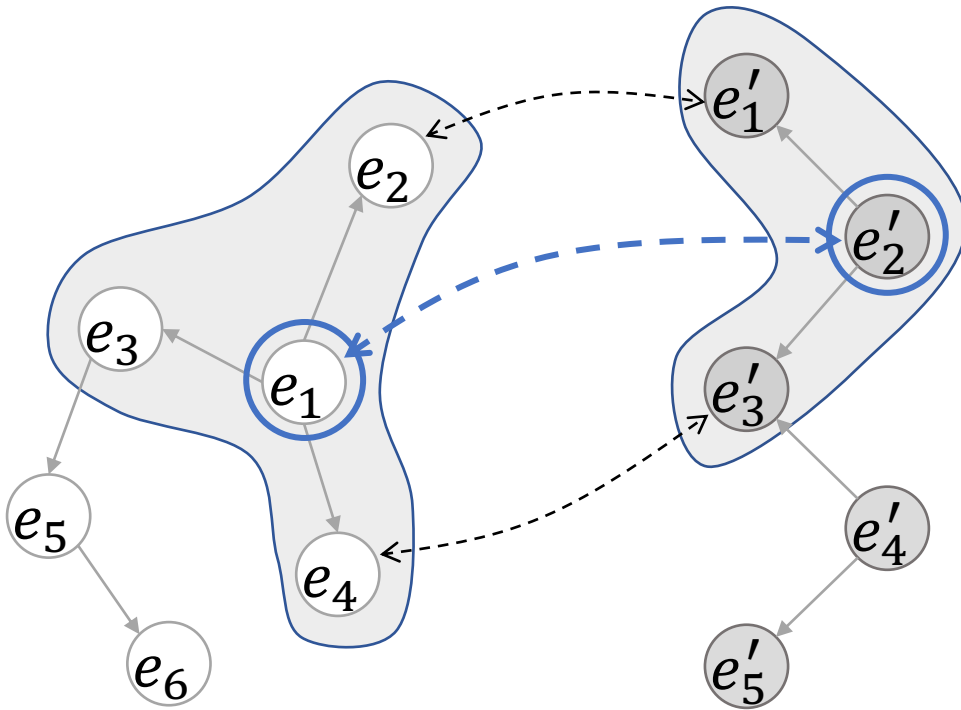
- Estimate the equivalence of two entities according to other mappings between their neighbours.



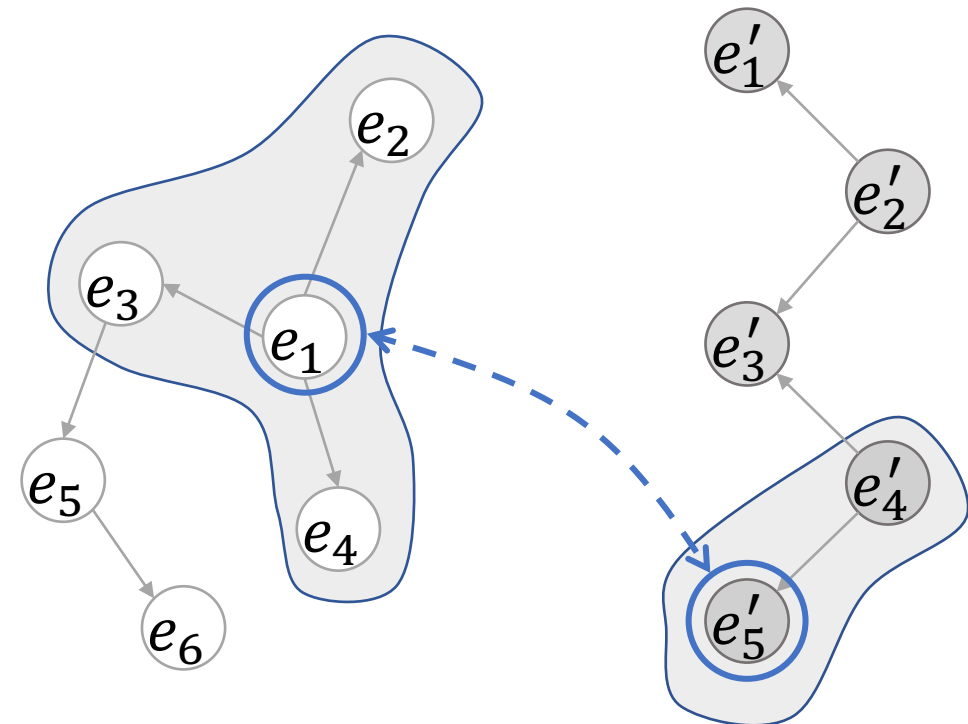
Two supporting mappings

Reuse **PARIS rule** to check compatibility:

- Estimate the equivalence of two entities according to other mappings between their neighbours.

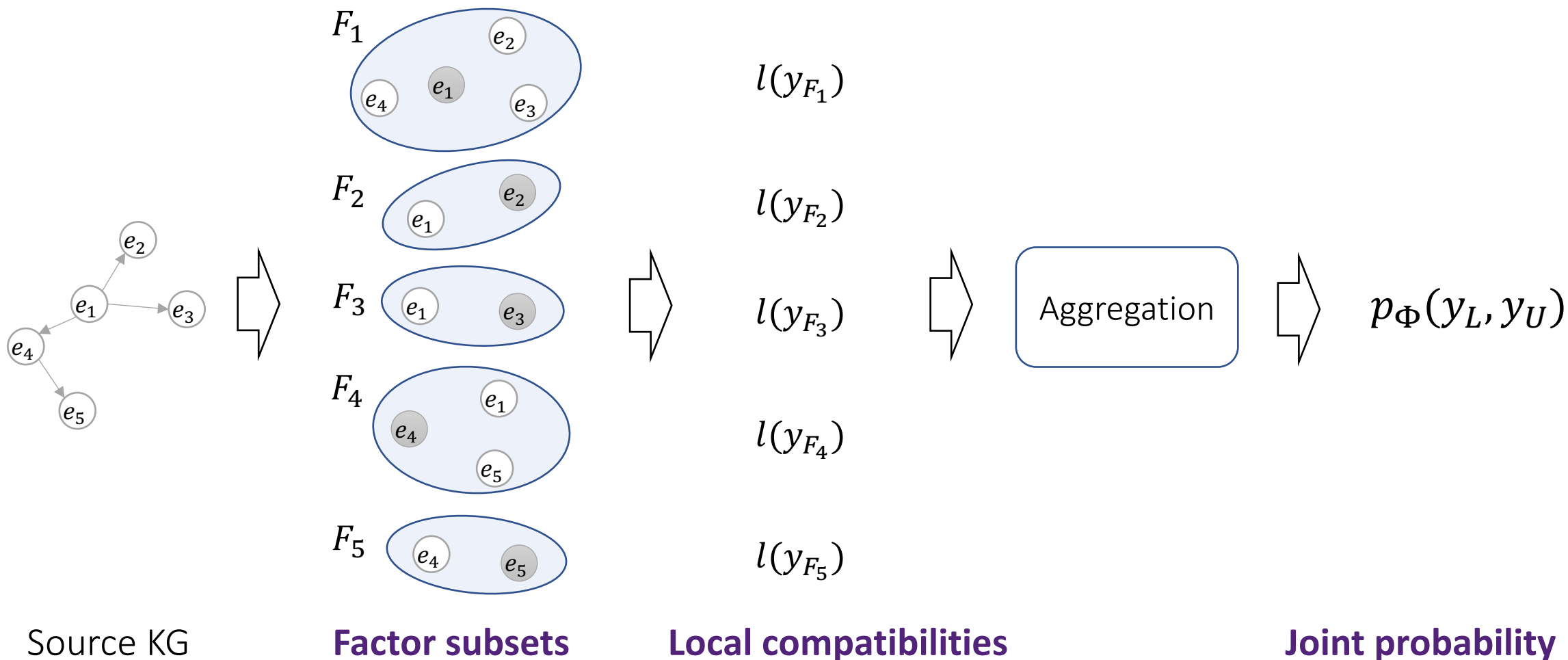


Two supporting mappings

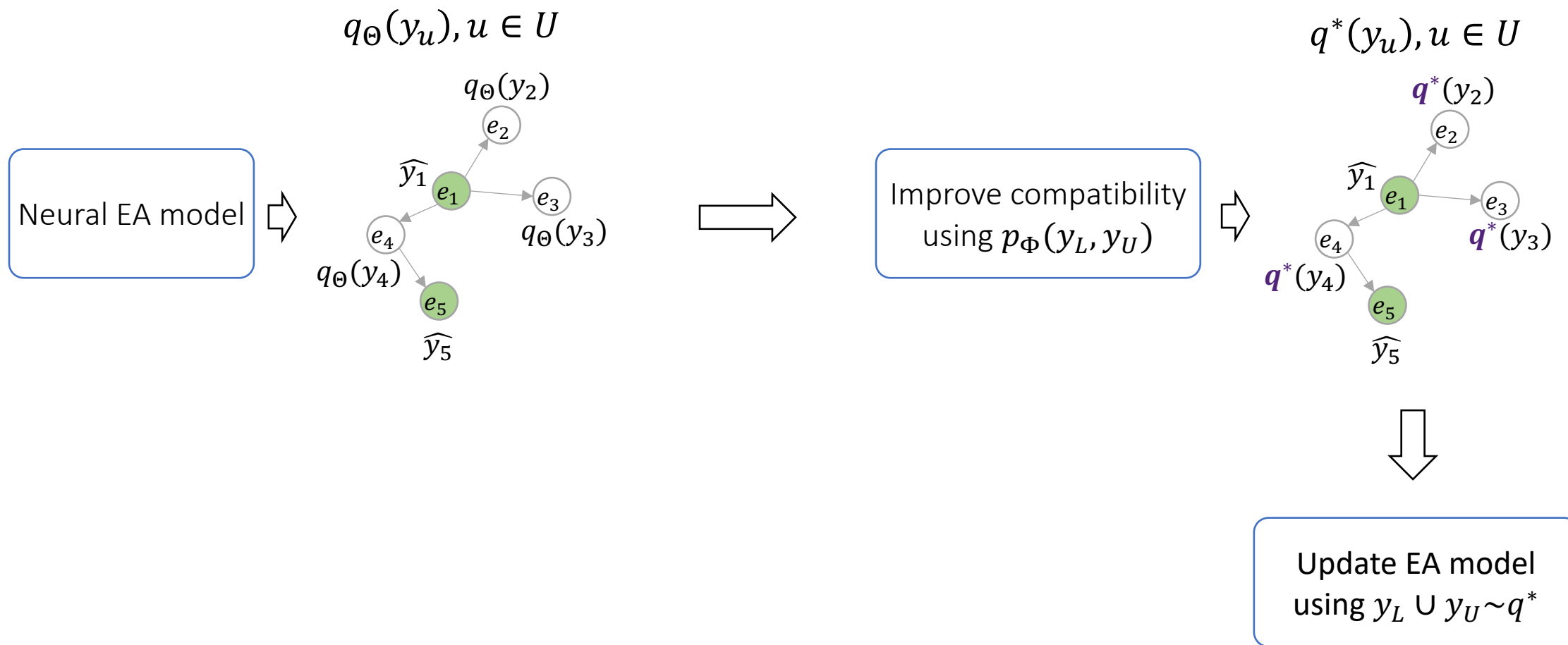


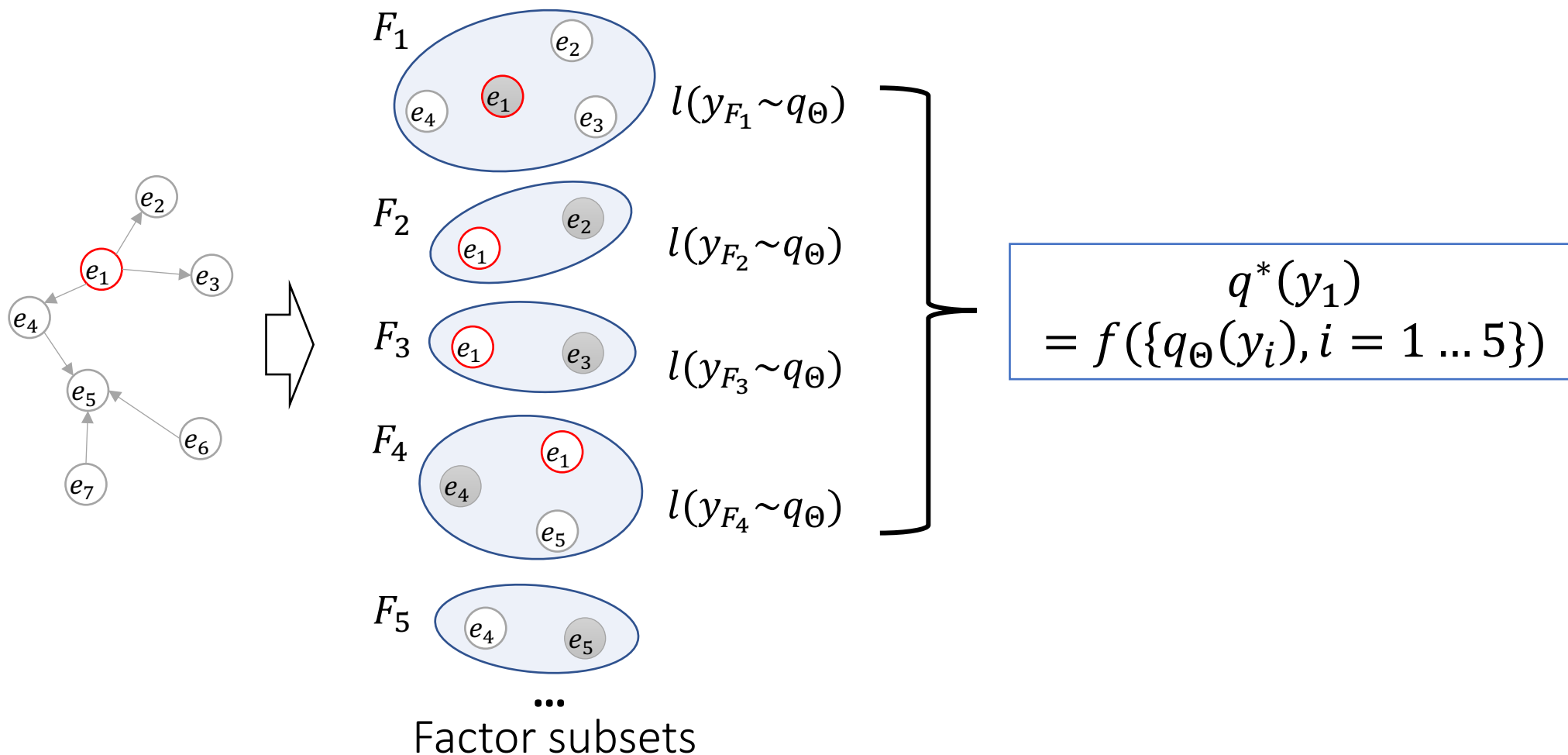
No supporting mapping

Model the **overall compatibility** with a **Probabilistic Graphical Model**



Improve Neural Predictions

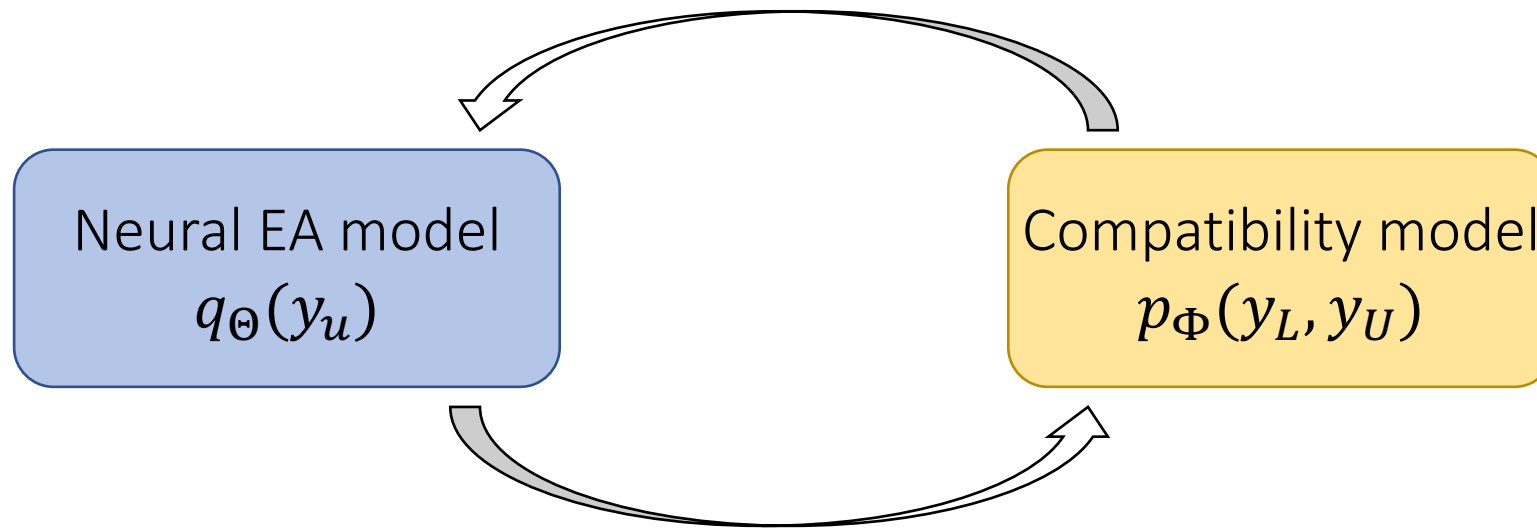




$q^*(y_e)$ involves the neural distributions of entities depending on e .

Expectation step:

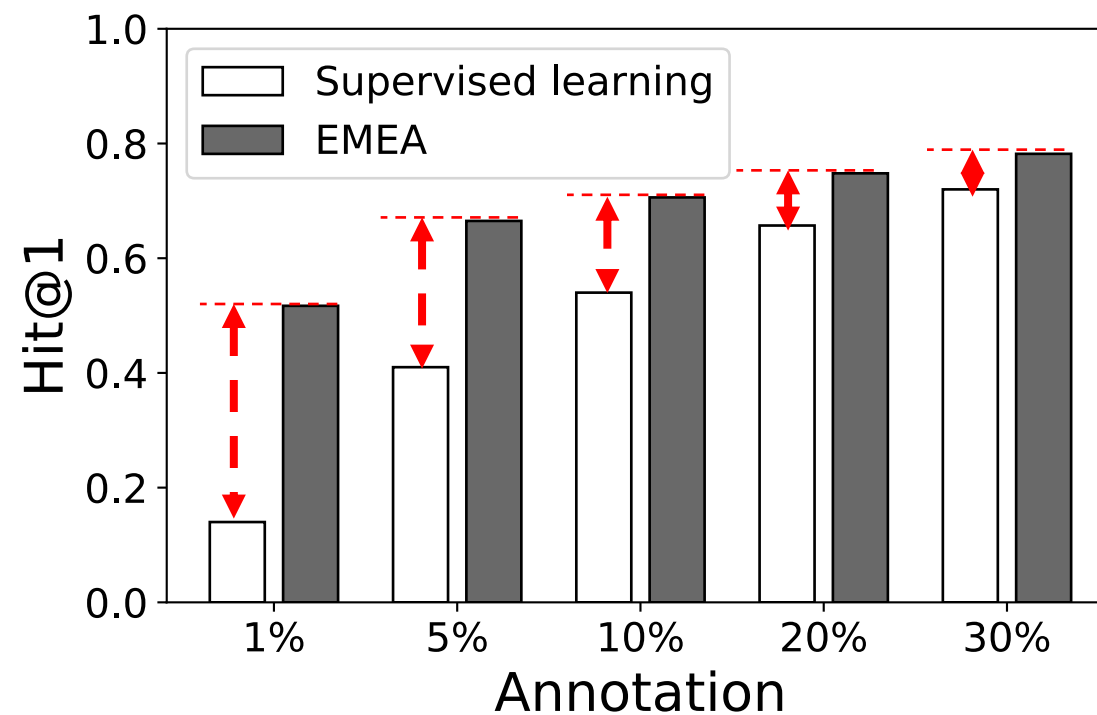
- Derive $q^*(y_u), u \in U$
- Update Θ using $\{y_u \sim q^*(y_u), u \in U\}$ and y_L



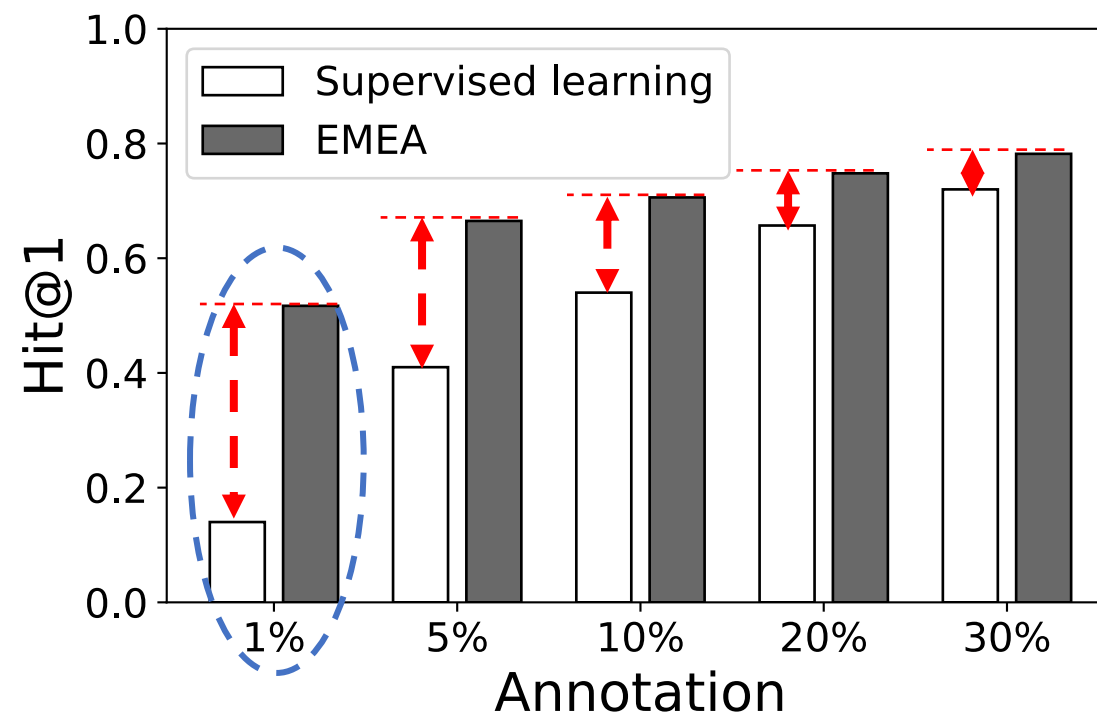
Maximization step:

- Sample $\hat{y}_U \sim q_{\Theta}(y_U)$
- Update Φ to maximize the $p_{\Phi}(y_L, y_U)$

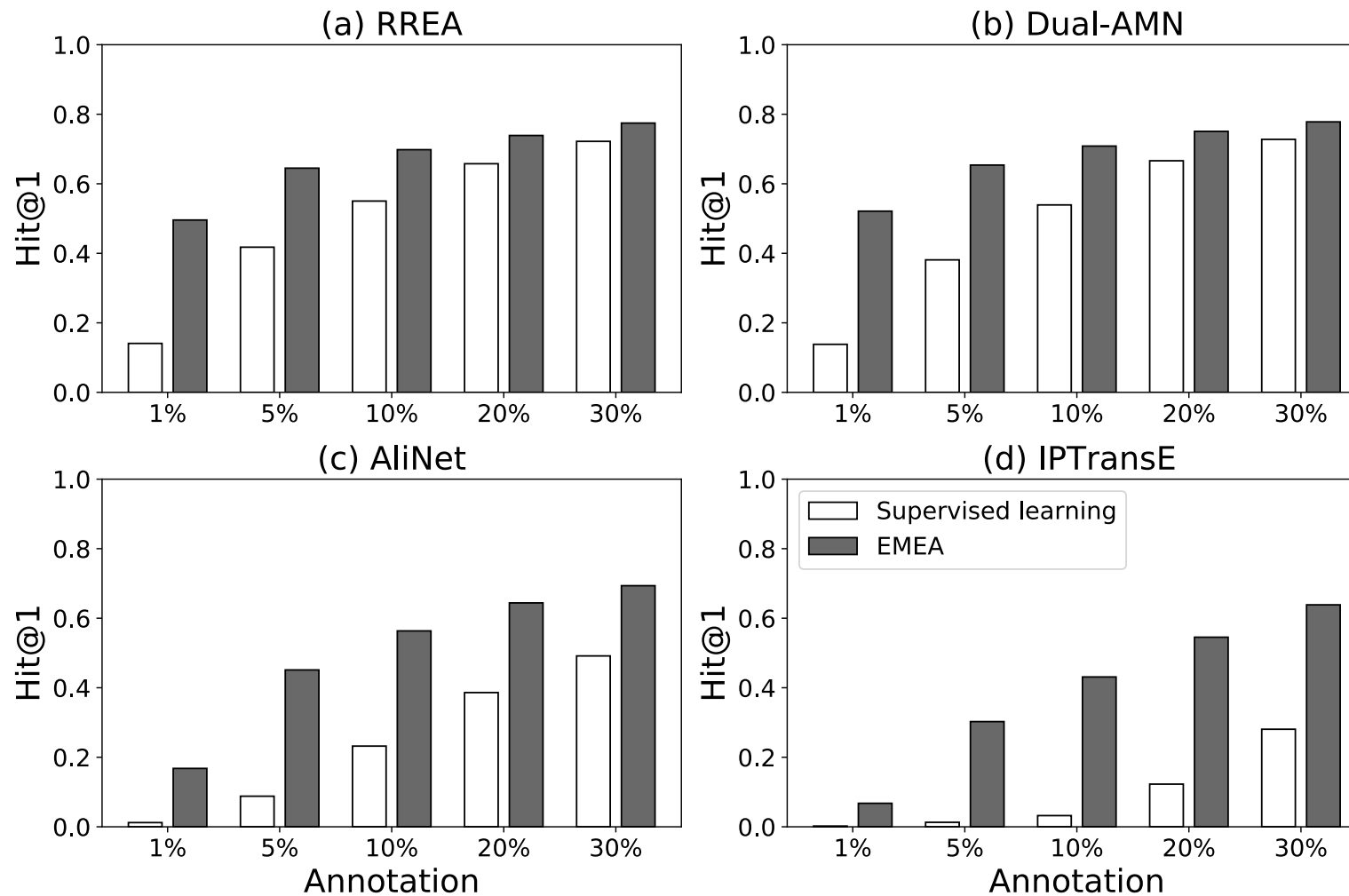
Experimental Results



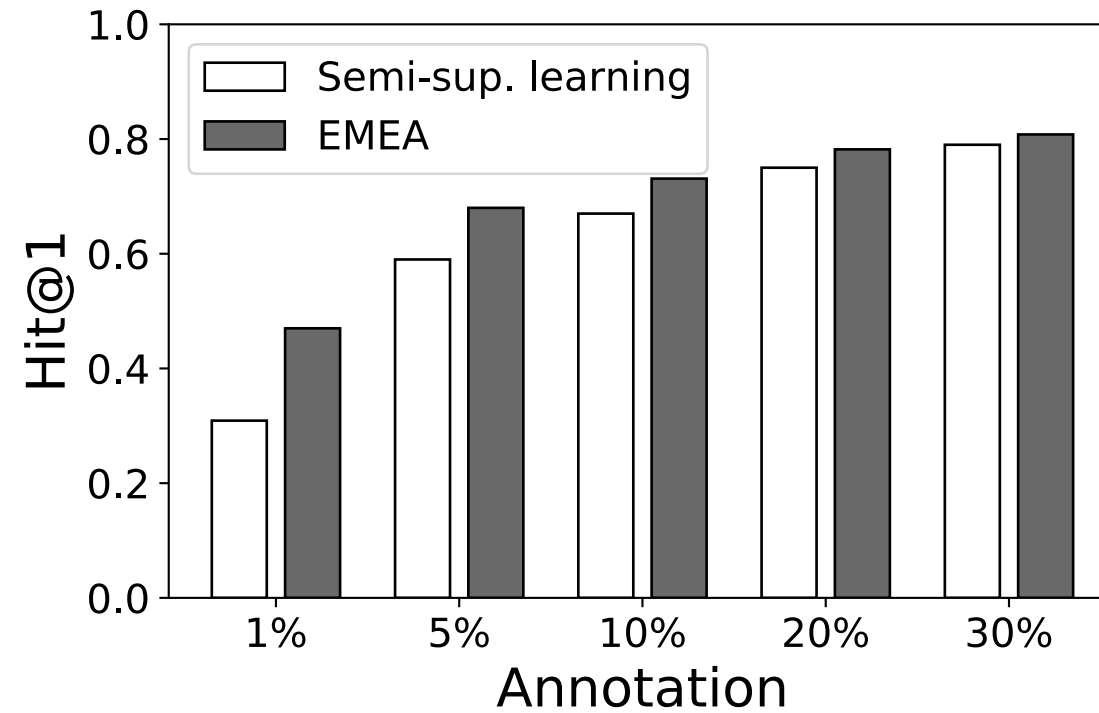
Settings: neural model: RREA, dataset: zh_en



Settings: neural model: RREA, dataset: zh_en



Settings: dataset: zh_en



EMEA: a more effective training framework of neural EA models

- Incorporate compatibility as an extra guidance of training.
- Bridge the gap between neural and reasoning-based EA methods.
- Generic across different settings.

Code & data: <https://github.com/uqbingliu/EMEA>

Thank you for listening!

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