

AI in Built Environment

DCP4300

Lec09: Computer Vision

Part A

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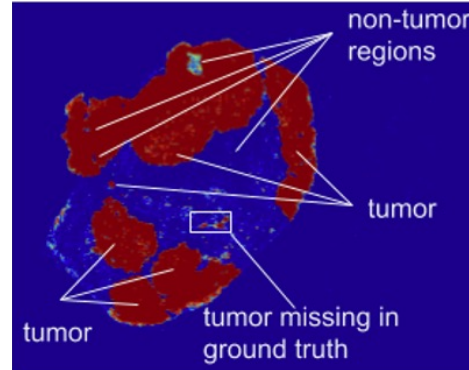
Applications of Computer Vision



Face recognition



Autonomous driving



Disease diagnosis



3D reconstruction

...

Applications of Computer Vision

Classification



Applications of Computer Vision

Segmentation



Images

What we see



What the computer sees

1	5	10	5
6	4	12	4
10	5	12	11
5	11	23	9

A 256x256 RGB image is a 256x256x3 matrix

Images



Visual Illusion: <https://www.youtube.com/watch?v=9Gw23ayxY-I>

Images



Vision



It started from the research on cat's vision system

Vision



simple features



complex features



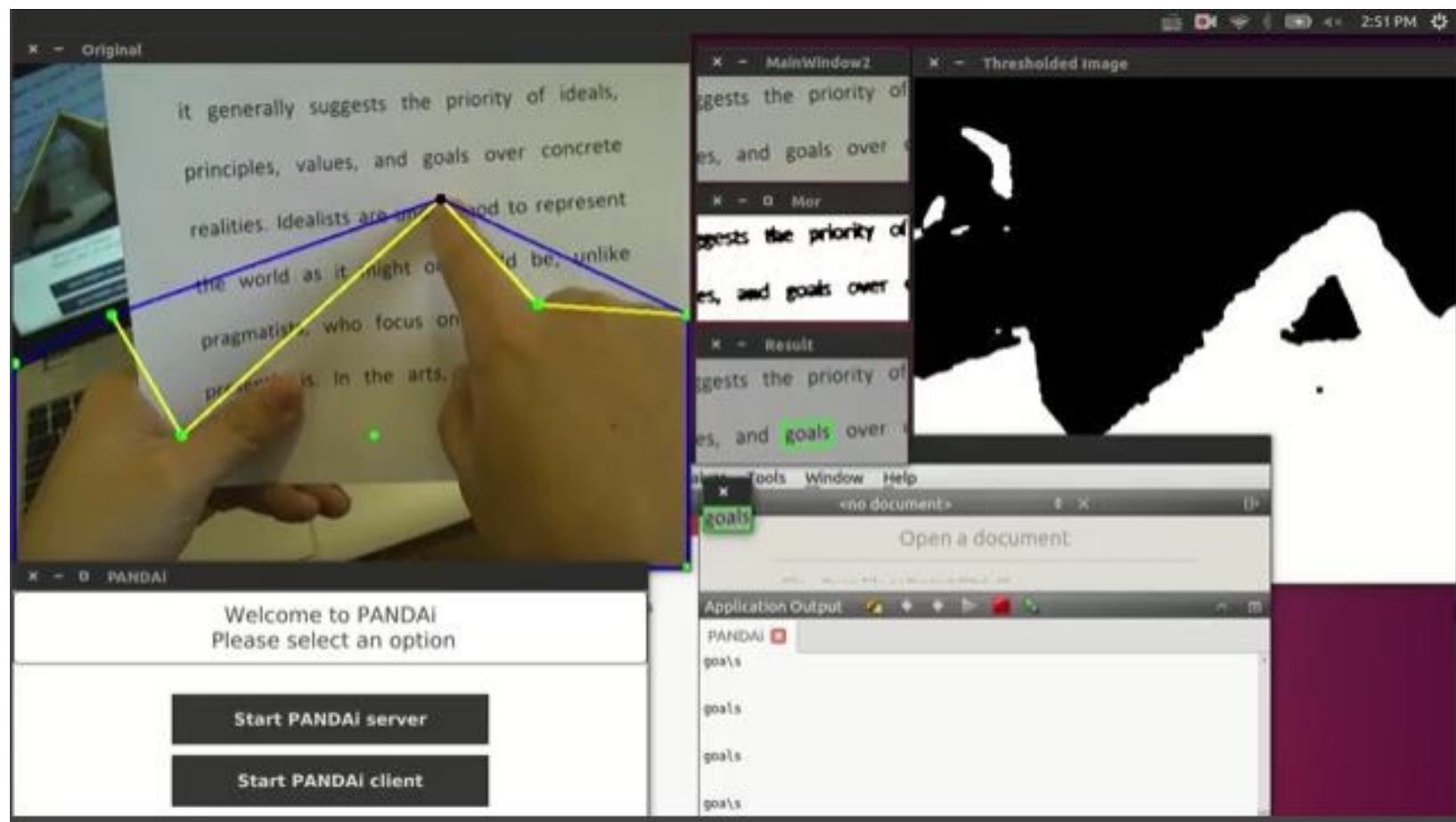
The early-stage computer vision

- Edge Detection
- Dilation, Erosion
- Perspective Transformation
- Cropping
- Scaling, Interpolations, And Re-Sizing
- Thresholding
- Sharpening
- Blurring
- Contours
- Line Detection
- Blob Detection
- ...



<https://opencv.org/>

The early-stage computer vision



My first computer vision project

Key points in the history of computer vision

1950

1960

1970

1980

1990

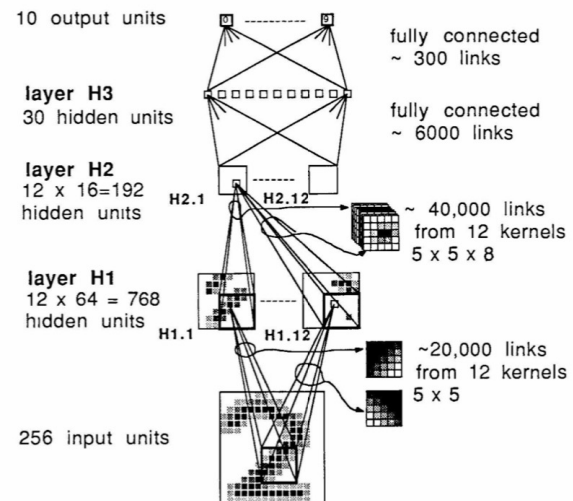
2000

2010

2020

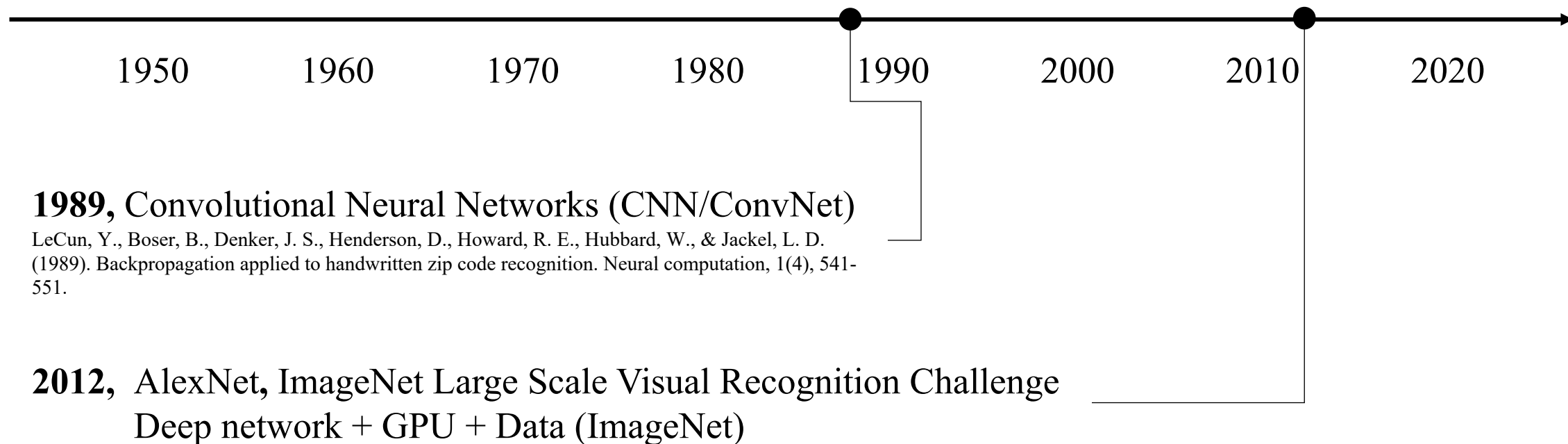
1989, Convolutional Neural Networks (CNN/ConvNet)

LeCun, Y., Boser, B., Denker, J. S., Henderson, D., Howard, R. E., Hubbard, W., & Jackel, L. D. (1989). Backpropagation applied to handwritten zip code recognition. *Neural computation*, 1(4), 541-551.

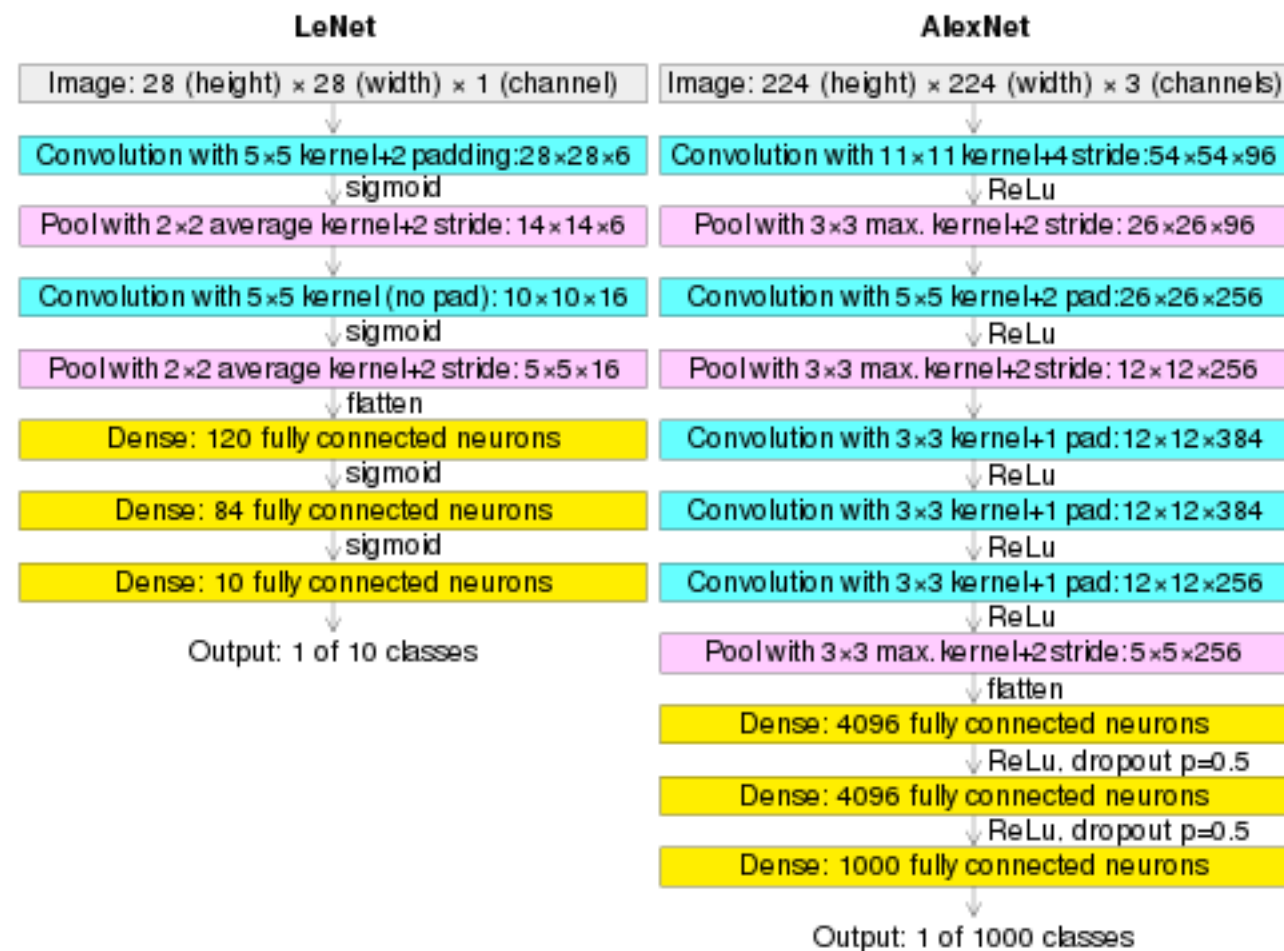


Yann LeCun demonstrating LeNet 1, 1993

Key points in the history of computer vision



Key points in the history of computer vision

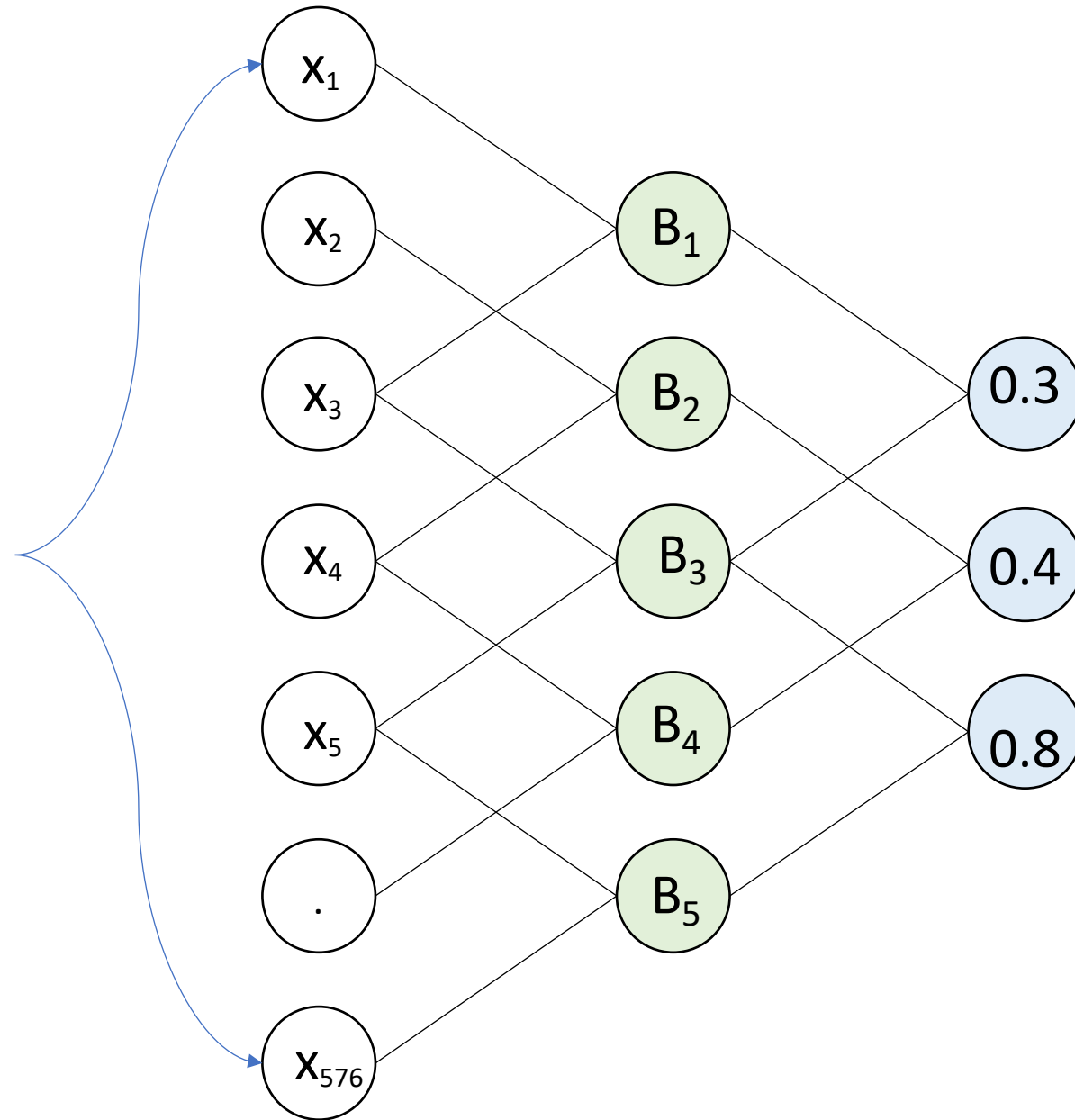


<https://en.wikipedia.org/wiki/AlexNet>

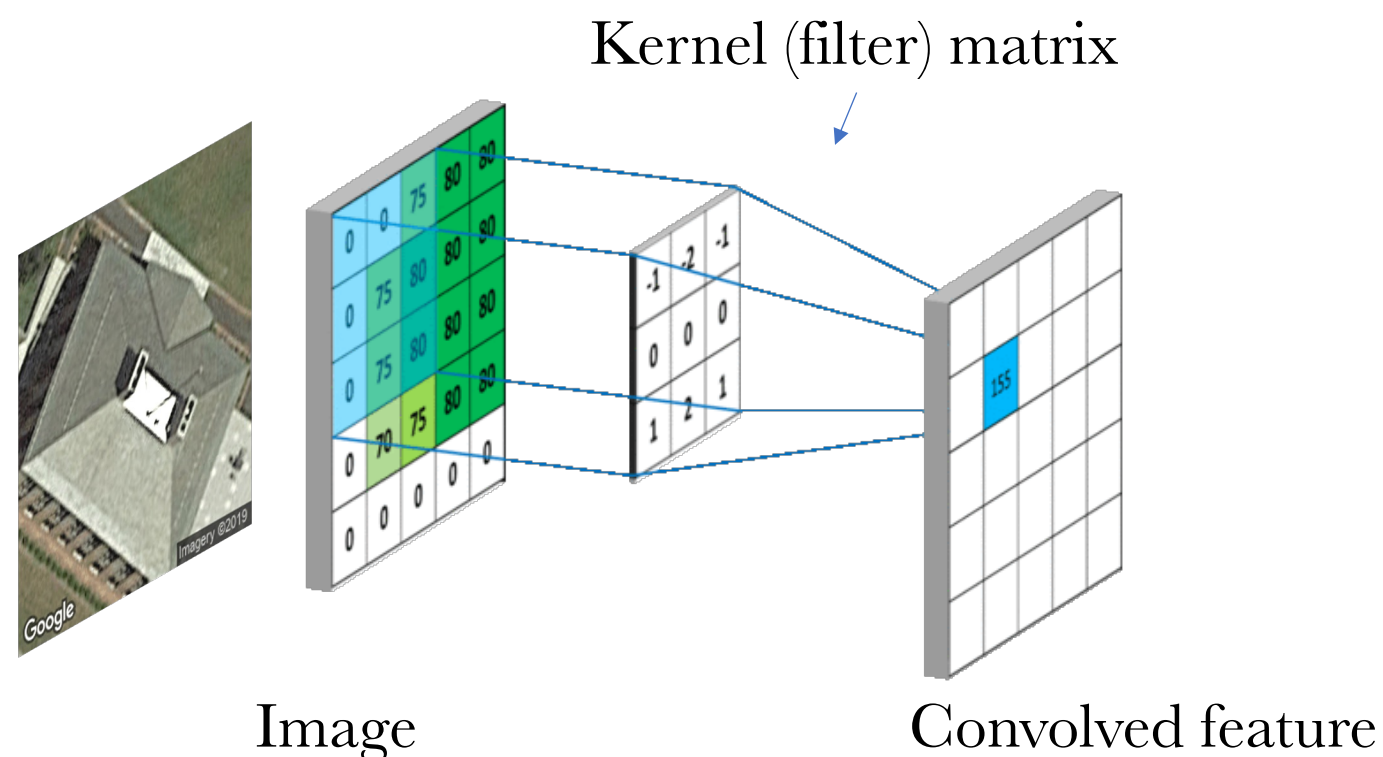


A 24x24 image can be expanded as a vector
 $[x_1, x_2, \dots, x_{576}]$

A brute way...



Convolutional layer

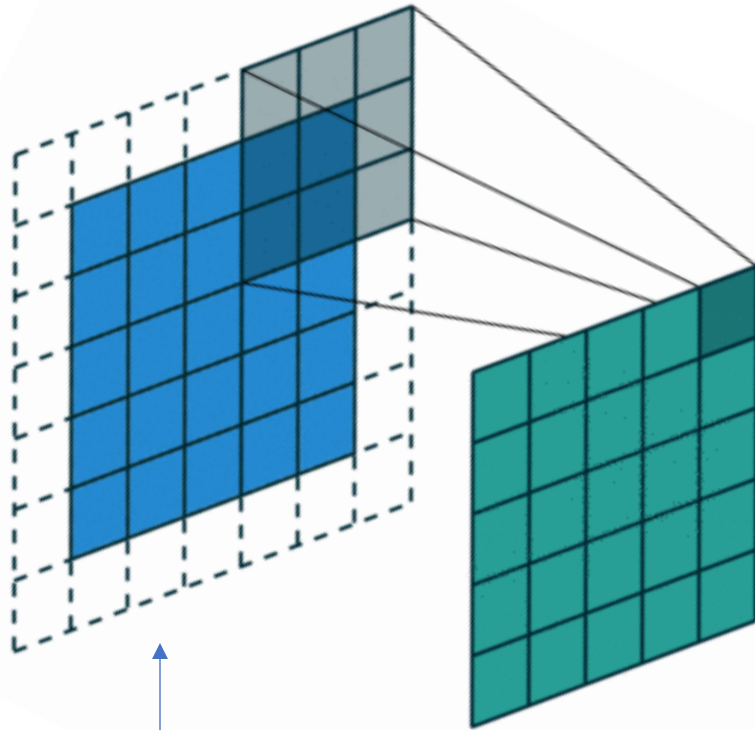


Input: 5x5x1
Kernel: 3x3
Stride: 1 (size of the 'slide')
Padding: 0
Output: 3x3x1

Purpose: extracting features.

A 2D convolution operation

Convolutional layer



Padded

Input: $5 \times 5 \times 1$

Kernel: 3×3

Stride: 1 (size of the 'slide')

Padding: 1

Output: $5 \times 5 \times 1$

Purpose: extracting features.

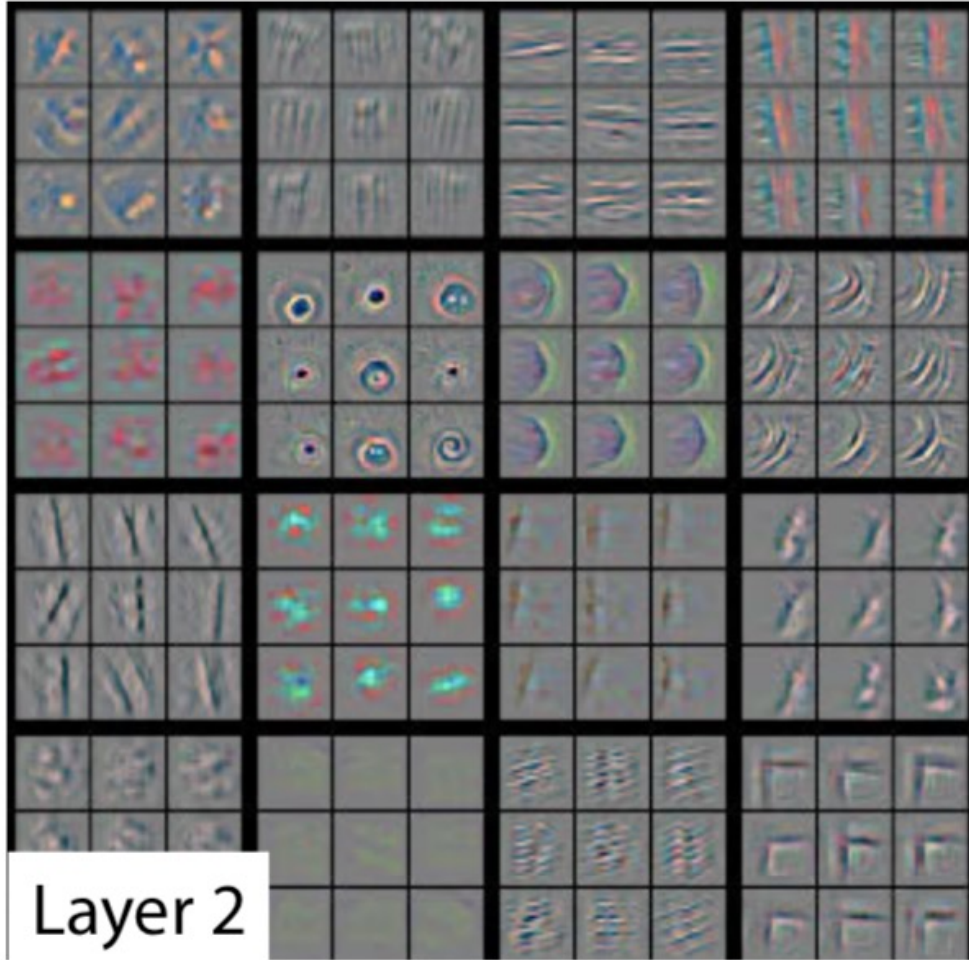
https://github.com/vdumoulin/conv_arithmetic

Learn features hierarchically

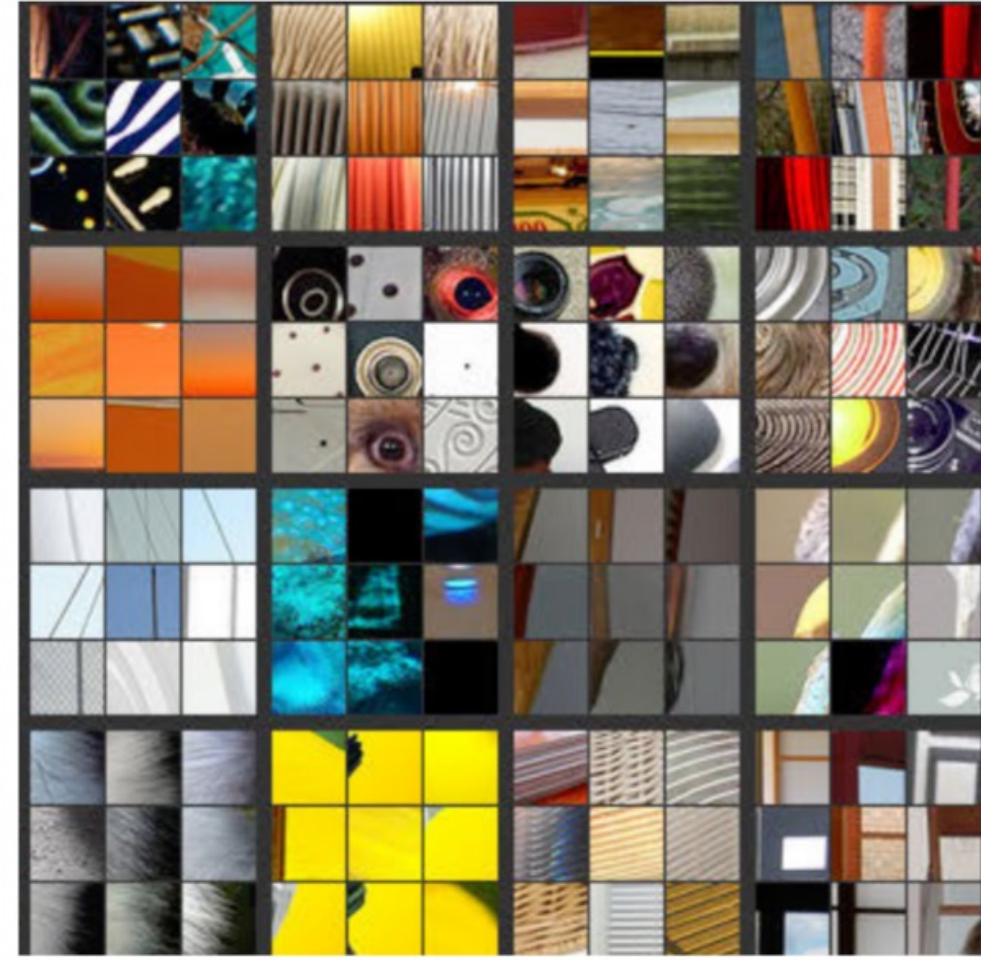
The first layers of CNN detect general features: Edges, Corners, Circles, Blobs colors, ...



Layer 1



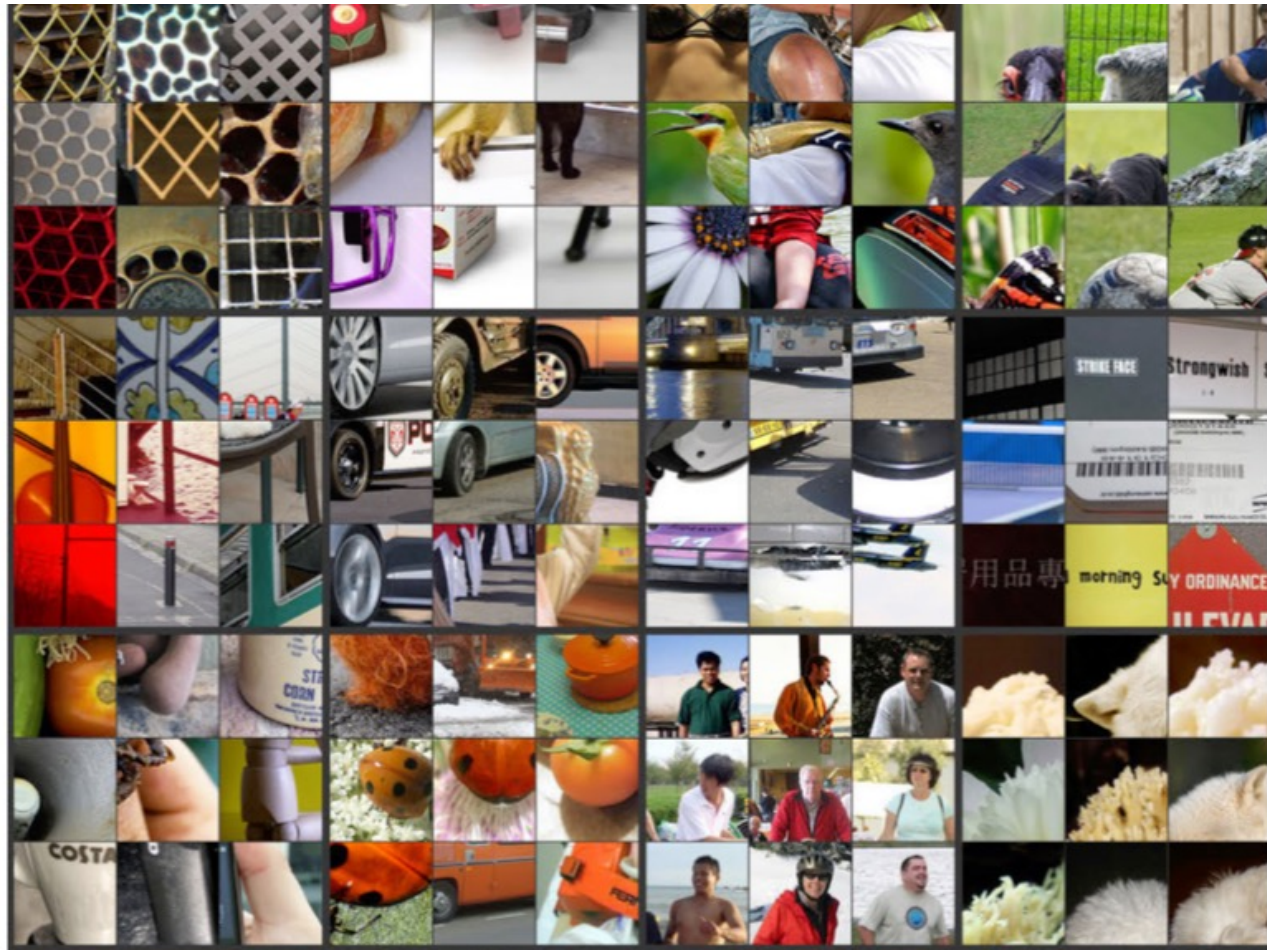
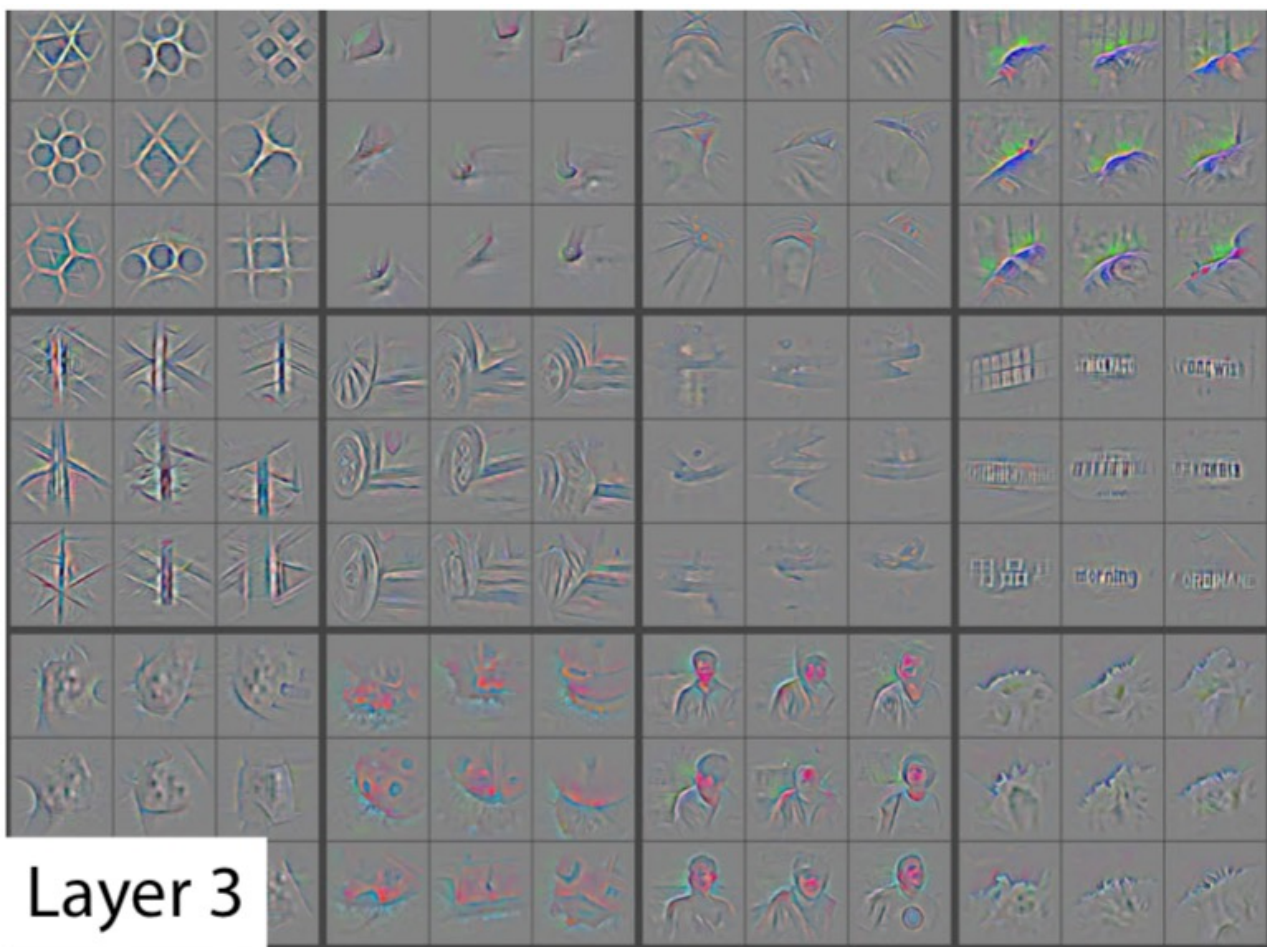
Layer 2



Zeiler, Matthew D., and Rob Fergus. "Visualizing and understanding convolutional networks." European conference on computer vision. Springer, Cham, 2014.

Learn features hierarchically

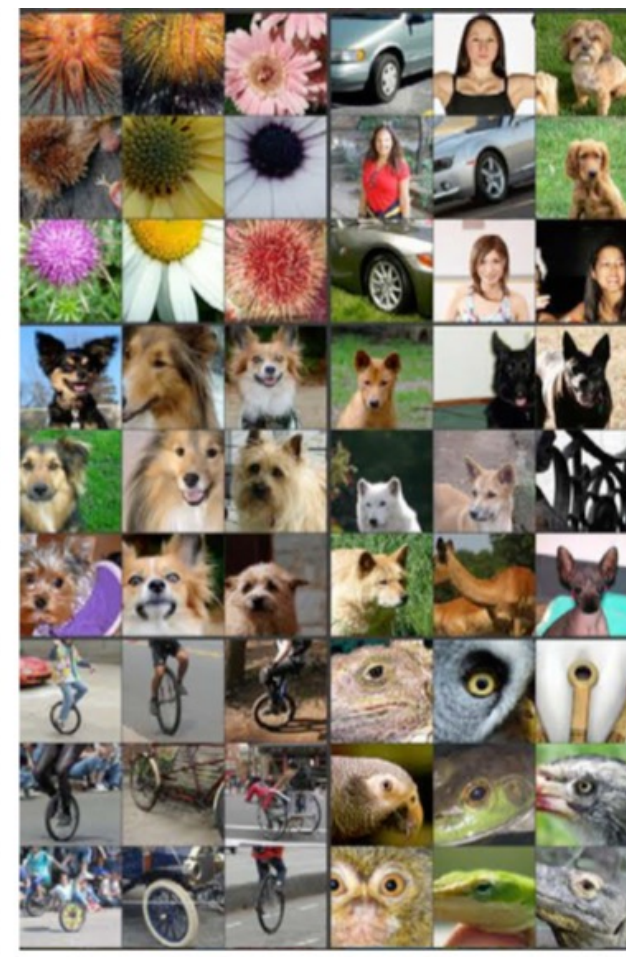
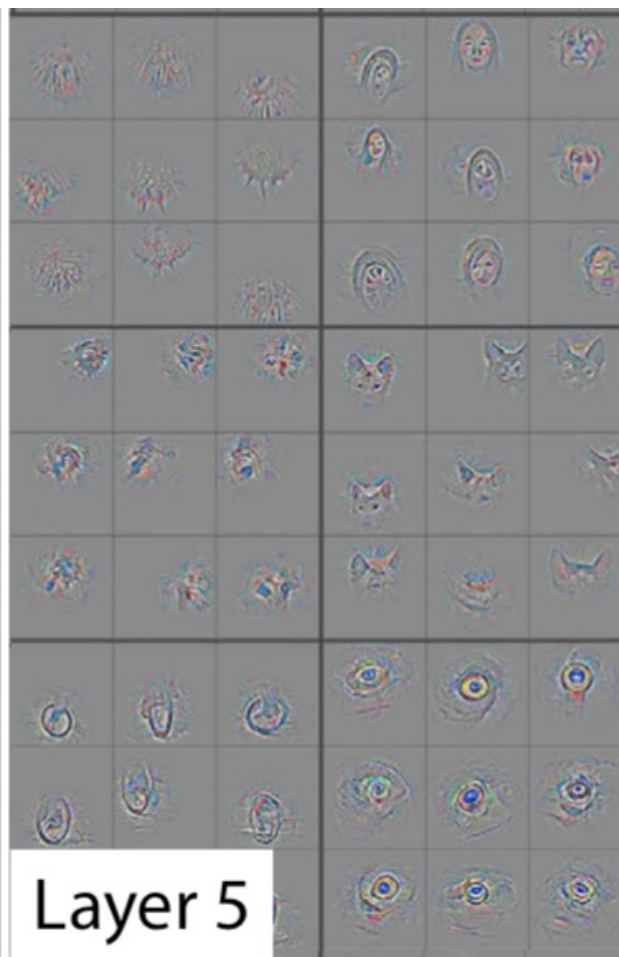
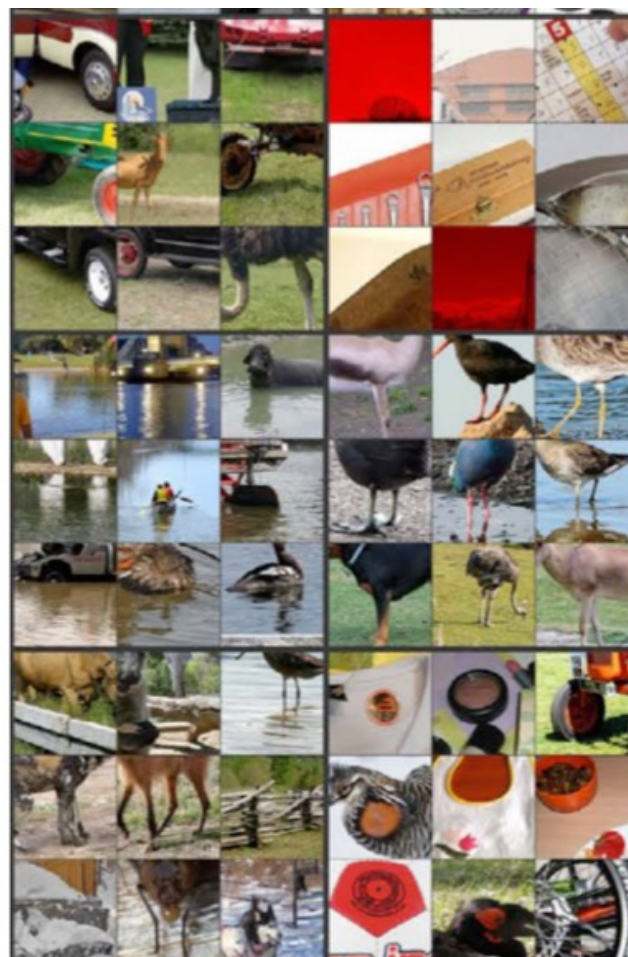
As it goes deeper into the CNN, it starts to detect more concrete things such as eyes, faces, and full objects.



Zeiler, Matthew D., and Rob Fergus. "Visualizing and understanding convolutional networks." European conference on computer vision. Springer, Cham, 2014.

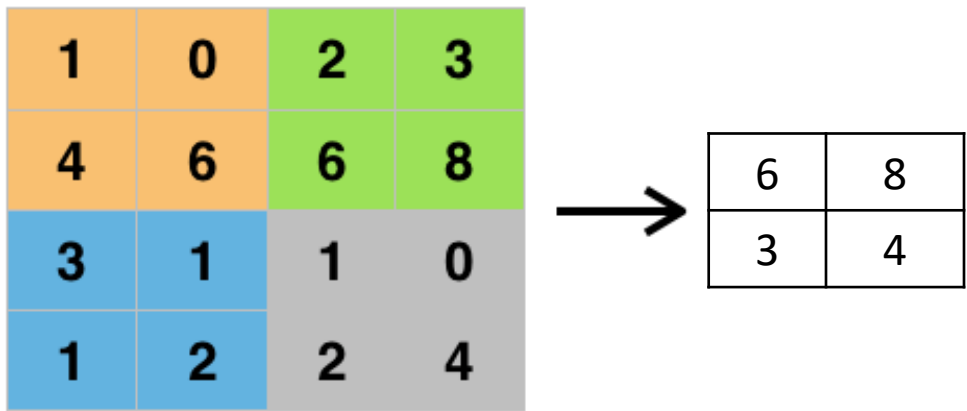
Learn features hierarchically

More concrete things ...



Zeiler, Matthew D., and Rob Fergus. "Visualizing and understanding convolutional networks." European conference on computer vision. Springer, Cham, 2014.

Pooling layer

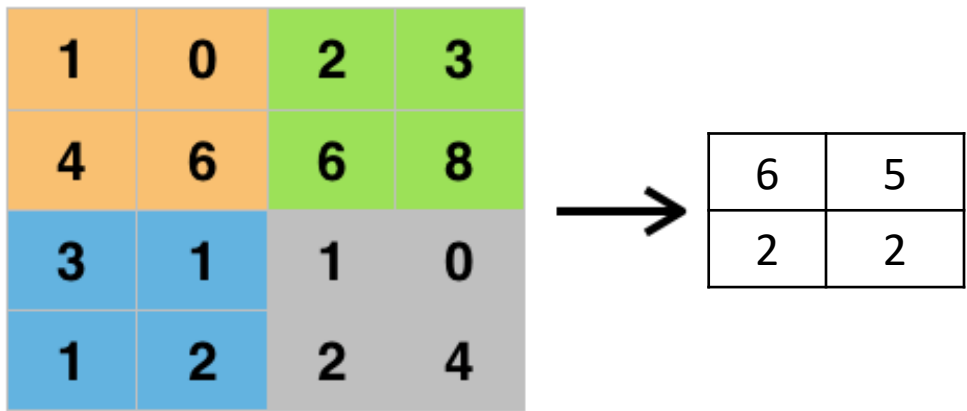


- Max pooling
- Average pooling
- L2-norm pooling
- ...

Max pooling

Purpose: extracting dominant feature and reduce dimensionality

Pooling layer

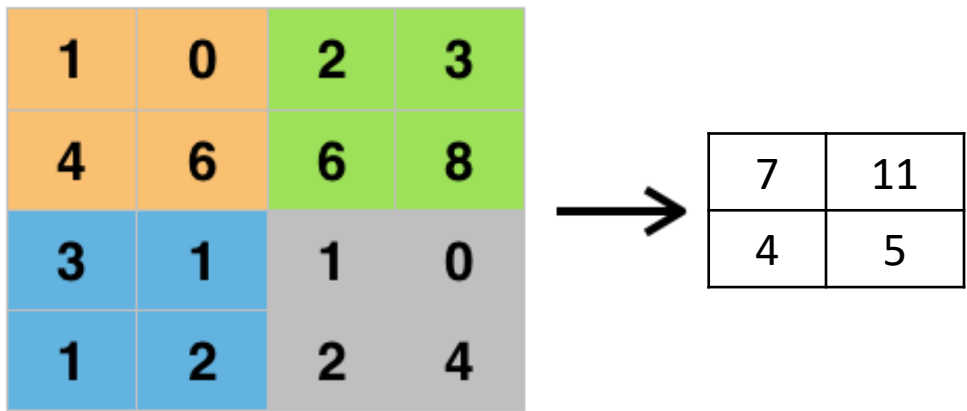


- Max pooling
- Average pooling
- L2-norm pooling
- ...

Average pooling

Purpose: extracting dominant feature and reduce dimensionality

Pooling layer

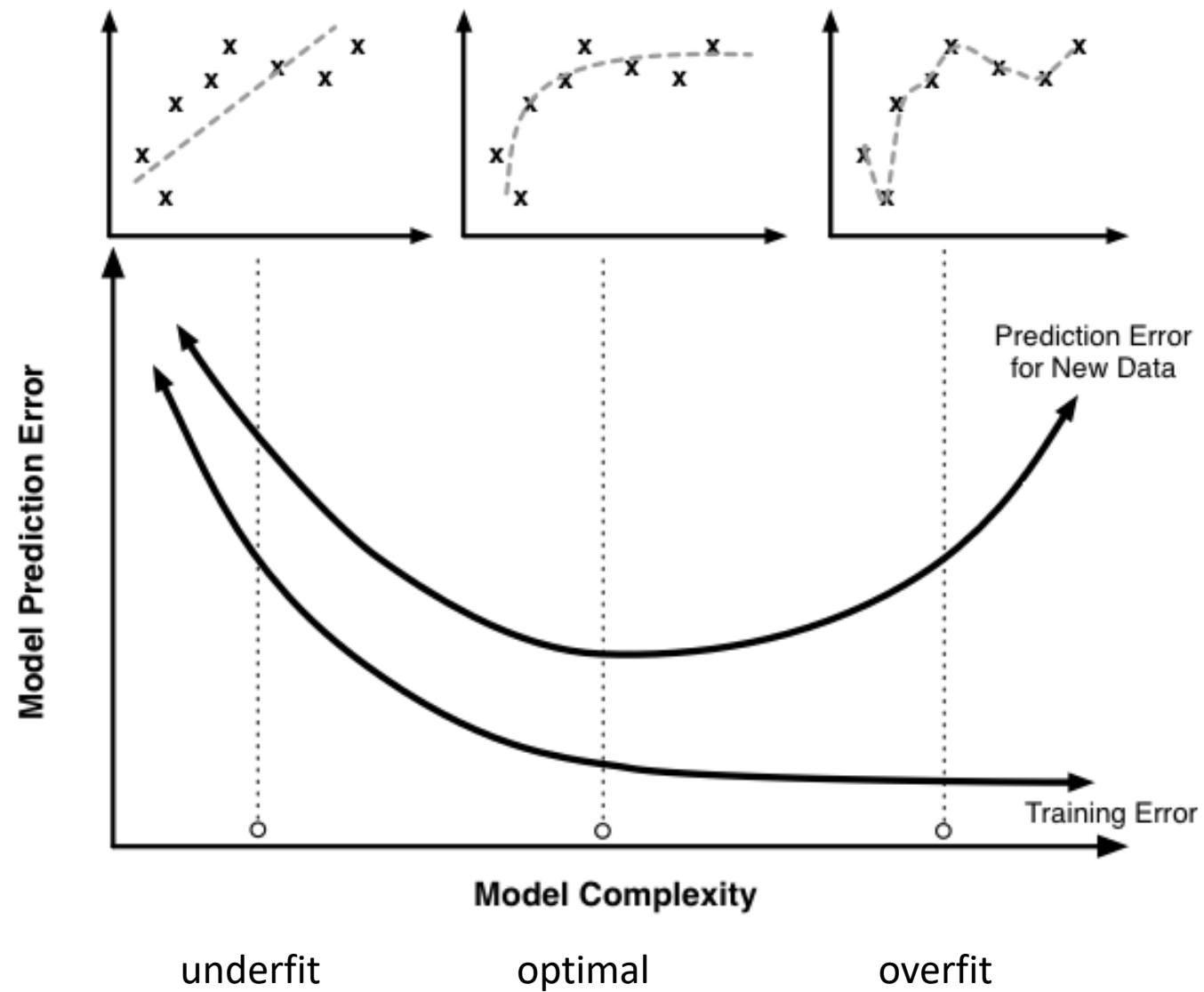


- Max pooling
- Average pooling
- L2-norm pooling
- ...

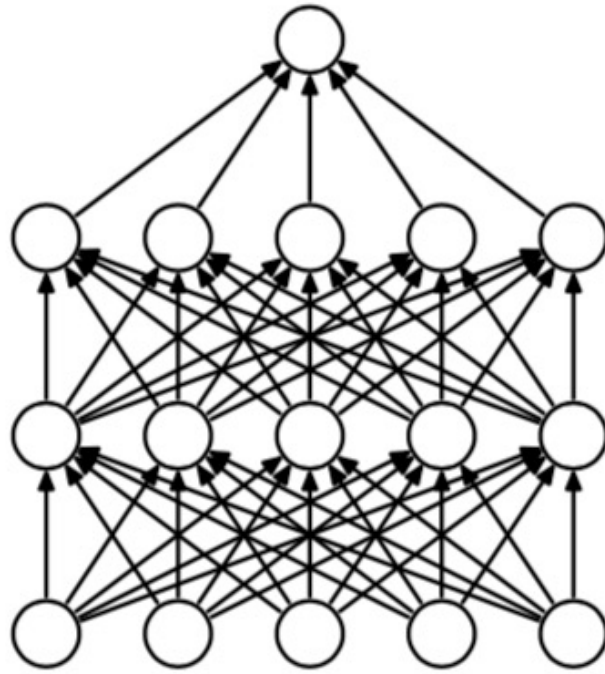
L2-norm pooling

Purpose: extracting dominant feature and reduce dimensionality

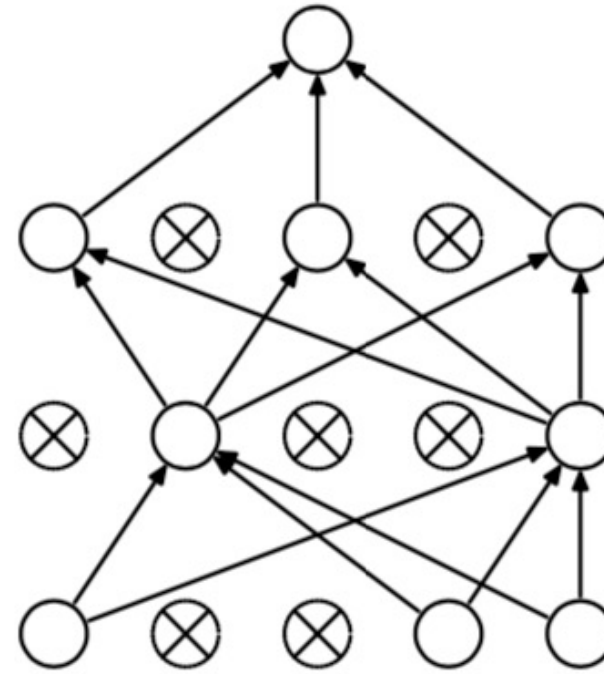
What is a good model?



Dropout layer



(a) Standard Neural Net



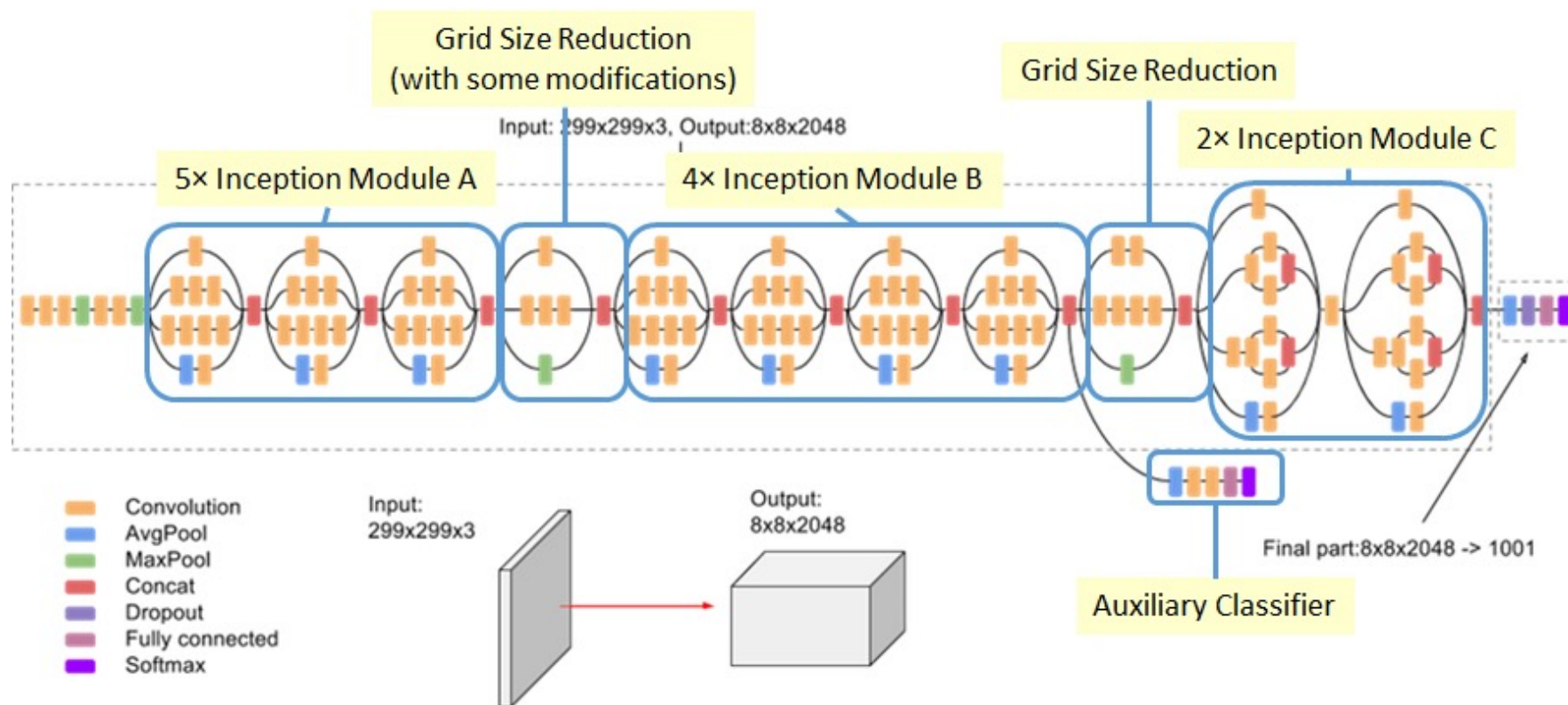
(b) After applying dropout.

Srivastava, N., Hinton, G., Krizhevsky, A., Sutskever, I., & Salakhutdinov, R. (2014). Dropout: a simple way to prevent neural networks from overfitting. The journal of machine learning research, 15(1), 1929-1958. <https://www.cs.toronto.edu/~hinton/absps/JMLRdropout.pdf>

Purpose: fight overfitting

Popular deep CNN architectures

- AlexNet
- VGGNet
- GoogLeNet
- Microsoft ResNet
- Google Inception
- ...



Example: Inception v3, <https://arxiv.org/abs/1512.00567>

Build one from scratch (ResNet)

<https://www.analyticsvidhya.com/blog/2021/08/how-to-code-your-resnet-from-scratch-in-tensorflow/>

Transfer Learning

The weights in a pretrained neural network is the learned knowledge.

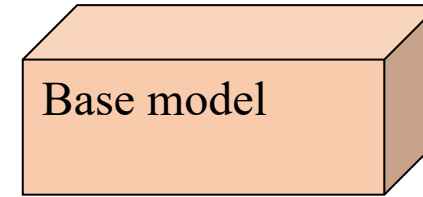
So a deep CNN trained on a large dataset contains knowledge (weights) that can be used to understand basic features in any given new image. This is the concept of transfer learning.

To do transfer learning, we

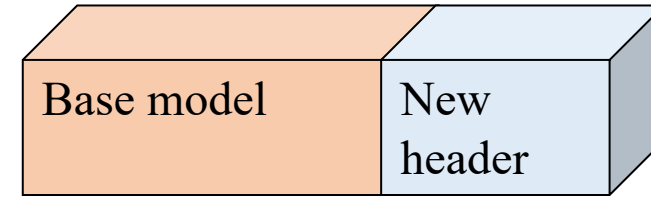
- Freeze the first layers of the pretrained neural network. These are the layers that detect general features that are common across all domains.
- Then we finetune the deeper layers with our own training data and add new layers to classify new categories included in our training dataset.

Transfer Learning: Fine tuning

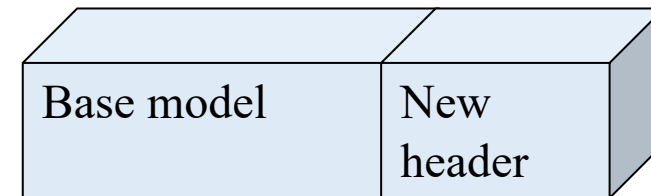
Take a pre-trained model (with learned weights) as base model



Add a header and train with the base model's weights frozen



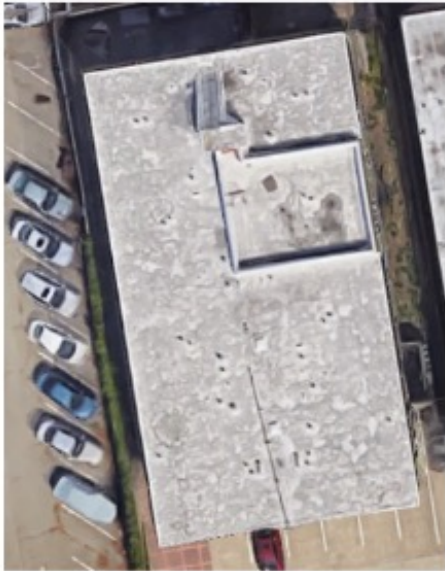
Unfreeze the base model and train



Demo: Classification of satellite images

Will do this demo in a Jupyter notebook on Google Colab:

<https://colab.research.google.com/drive/1EKUEZEVgtWTfDTdR1grtAorMq3ZGLxmR?usp=sharing>



Flat



Gabled



Hipped